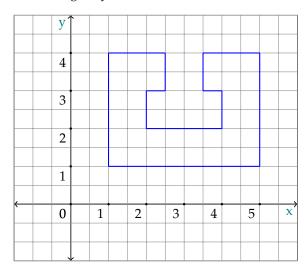
Técnicas de simulación por computadora

Grupo O

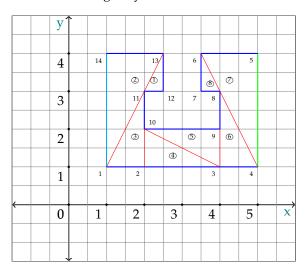
3 de junio de 2018

Dada la figura y ecuación diferencial:



$$\nabla(10\nabla T) = -100$$

Mallado de la figura y establecimiento de contornos para condiciones de Dirichlet y Neumann:



Neumann
O Dirichlet

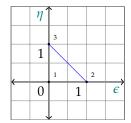
Tabla de conectividad:

elemento	1	2	3
<u> (1)</u>	11	12	13
2	1	13	14
3	1	2	11
4	2	3	10
5	10	3	9
6	3	4	8 5
	3 6	4	5
8	6	7	8

Condiciones a utilizar:

$$\Gamma_D = \\ \Gamma_N =$$

Aproximación en el plano isoparamétrico:



$$T \approx f_1 T_1 + f_2 T_2 + f_3 T_3$$

$$\approx N_1 T_1 + N_2 T_2 + N_3 T_3$$

$$\approx \begin{bmatrix} N_1 & N_2 & N_3 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \end{bmatrix}$$

$$\approx \underline{N} \vec{T}$$

$$con N_1 = 1 - \epsilon - \eta, N_2 = \epsilon, N_3 = \eta$$

$$x \approx (x_2 - x_1)\epsilon + (x_3 - x_1)\eta + x_1$$

 $y \approx (y_2 - y_1)\epsilon + (y_3 - y_1)\eta + y_1$

Sustitución de la función por su aproximación:

$$\begin{split} &\nabla(10\nabla T) = -100 \\ &\nabla(10\nabla\underline{\underline{N}}\vec{T}) \approx -100 \\ &\nabla(10\nabla\underline{\underline{N}}\vec{T}) + 100 \neq 0 \\ &\nabla(10\nabla\underline{\underline{N}}\vec{T}) + 100 = \Re \end{split}$$

W.R.M.:

$$\begin{split} &\int_{\Omega} \underline{\underline{W}} \mathcal{R} \, d\Omega = 0 \\ &\int_{A} \underline{\underline{W}} \mathcal{R} \, dA = 0 \\ &\int_{A} \underline{\underline{W}} (\nabla (10 \nabla \underline{\underline{N}} \vec{T}) + 100) \, dA = 0 \end{split}$$

Galerkin:

$$\begin{split} & \underline{\underline{W}} = \underline{\underline{N}}^T \\ & \int_A \underline{\underline{N}}^T (\nabla (10 \nabla \underline{\underline{N}} \vec{T}) + 100) \, dA = 0 \\ & \int_A \underline{\underline{N}}^T (\nabla (10 \nabla \underline{\underline{N}} \vec{T})) \, dA + \int_A \underline{\underline{N}}^T (100) \, dA = 0 \end{split}$$

Integración por partes:

sea
$$U = \underline{\underline{N}}^T$$
, $dU = \nabla \underline{\underline{N}}^T$
sea $dV = \nabla (10\nabla \underline{\underline{N}}\vec{T})$, $V = 10\nabla (\underline{\underline{N}}\vec{T})$

$$\int_A \underline{\underline{N}}^T (\nabla (10\nabla \underline{\underline{N}}\vec{T})) dA = [\underline{\underline{N}}^T 10\nabla (\underline{\underline{N}}\vec{T})]_{\Gamma_N} - \int_A \nabla \underline{\underline{N}}^t 10\nabla (\underline{\underline{N}}\vec{T}) dA$$

Trabajando en la ecuación:

$$-\int_{A} \nabla \underline{\underline{N}}^{T} 10 \nabla (\underline{\underline{N}} \vec{T}) dA + \int_{A} \underline{\underline{N}}^{T} (100) dA = 0$$

$$\int_{A} \nabla \underline{\underline{N}}^{T} 10 \nabla (\underline{\underline{N}} \vec{T}) dA = \int_{A} \underline{\underline{N}}^{T} (100) dA$$

$$10 \int_{A} \nabla \underline{\underline{N}}^{T} \nabla (\underline{\underline{N}}) dA (\vec{T}) = 100 \int_{A} \underline{\underline{N}}^{T} dA$$

Lado derecho:

$$100 \int_{A} \underline{\underline{N}}^{T} dA = 100 \int_{A} \begin{bmatrix} 1 - \epsilon - \eta \\ \epsilon \\ \eta \end{bmatrix} dA$$
$$= 100 \int_{A} \begin{bmatrix} 1 - \epsilon - \eta \\ \epsilon \\ \eta \end{bmatrix} dx dy$$

Llevando la integral al plano isoparamétrico con un jacobiano:

$$\begin{aligned} dx \, dy &= D \, d\epsilon \, d\eta \\ J &= \begin{bmatrix} \frac{\delta x}{\delta \epsilon} & \frac{\delta x}{\delta \eta} \\ \frac{\delta y}{\delta \epsilon} & \frac{\delta y}{\delta \eta} \end{bmatrix} \\ &= \begin{bmatrix} (x_2 - x_1) & (x_3 - x_1) \\ (y_2 - y_1) & (y_3 - y_1) \end{bmatrix} \\ D &= |J| \\ &= (x_2 - x_1)(y_3 - y_1) - (x_3 - x_1)(y_2 - y_1) \end{aligned}$$

Sustituyendo en la integral:

$$100 \int_{A} \begin{bmatrix} 1 - \epsilon - \eta \\ \epsilon \\ \eta \end{bmatrix} dA = 100 \int_{0}^{1} \int_{0}^{1} \begin{bmatrix} 1 - \epsilon - \eta \\ \epsilon \\ \eta \end{bmatrix} \begin{vmatrix} (x_{2} - x_{1}) & (x_{3} - x_{1}) \\ (y_{2} - y_{1}) & (y_{3} - y_{1}) \end{vmatrix} d\epsilon d\eta$$

$$= 100 \begin{vmatrix} (x_{2} - x_{1}) & (x_{3} - x_{1}) \\ (y_{2} - y_{1}) & (y_{3} - y_{1}) \end{vmatrix} \int_{0}^{1} \int_{0}^{1} \begin{bmatrix} 1 - \epsilon - \eta \\ \epsilon \\ \eta \end{bmatrix} d\epsilon d\eta$$

$$= 100 \begin{vmatrix} (x_{2} - x_{1}) & (x_{3} - x_{1}) \\ (y_{2} - y_{1}) & (y_{3} - y_{1}) \end{vmatrix} \begin{bmatrix} \int_{0}^{1} \int_{0}^{1} (1 - \epsilon - \eta) d\epsilon d\eta \\ \int_{0}^{1} \int_{0}^{1} \epsilon d\epsilon d\eta \\ \int_{0}^{1} \int_{0}^{1} \eta d\epsilon d\eta \end{bmatrix}$$

$$= 100 \begin{vmatrix} (x_{2} - x_{1}) & (x_{3} - x_{1}) \\ (y_{2} - y_{1}) & (y_{3} - y_{1}) \end{vmatrix} \begin{bmatrix} 0 \\ 1/2 \\ 1/2 \end{bmatrix}$$

Trabajando lado izquierdo de la ecuación:

$$10 \int_{A} \nabla \underline{N}^{T} \nabla (\underline{N}) dA(\vec{T}) = 10 \int_{c}^{d} \int_{a}^{b} \nabla \underline{N}^{T} \nabla (\underline{N}) dx dy(\vec{T})$$

$$con \nabla_{x} \underline{N} = (\nabla_{\epsilon} \underline{x})^{-1} \nabla_{\epsilon} \underline{N}$$

$$= \begin{bmatrix} (x_{2} - x_{1}) & (y_{2} - y_{1}) \\ (x_{3} - x_{1}) & (y_{3} - y_{1}) \end{bmatrix}^{-1} \begin{bmatrix} -1 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix}$$

$$= \frac{1}{\begin{vmatrix} (x_{2} - x_{1}) & (y_{2} - y_{1}) \\ (x_{3} - x_{1}) & (y_{3} - y_{1}) \end{vmatrix}} \begin{bmatrix} (y_{3} - y_{1}) & (y_{1} - y_{2}) \\ (x_{1} - x_{3}) & (x_{2} - x_{1}) \end{bmatrix} \begin{bmatrix} -1 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix}$$

$$= \frac{1}{\begin{vmatrix} (x_{2} - x_{1}) & (y_{2} - y_{1}) \\ (x_{3} - x_{1}) & (y_{3} - y_{1}) \end{vmatrix}} \begin{bmatrix} (y_{2} - y_{3}) & (y_{3} - y_{1}) & (y_{1} - y_{2}) \\ (x_{3} - x_{2}) & (x_{1} - x_{3}) & (x_{2} - x_{1}) \end{bmatrix}$$

$$\nabla \underline{N}^{T} = \frac{1}{\begin{vmatrix} (x_{2} - x_{1}) & (y_{2} - y_{1}) \\ (x_{3} - x_{1}) & (y_{3} - y_{1}) \end{vmatrix}} \begin{bmatrix} (y_{2} - y_{3}) & (x_{3} - x_{2}) \\ (y_{3} - y_{1}) & (x_{1} - x_{3}) \\ (y_{3} - y_{1}) & (x_{1} - x_{3}) \\ (y_{1} - y_{2}) & (x_{2} - x_{1}) \end{bmatrix}$$

Sustituyendo en la integral:

$$= 10 \int_{c}^{d} \int_{a}^{b} \frac{1}{\begin{vmatrix} (x_{2} - x_{1}) & (y_{2} - y_{1}) \\ (x_{3} - x_{1}) & (y_{3} - y_{1}) \end{vmatrix}^{2}} \begin{bmatrix} (y_{2} - y_{3}) & (x_{3} - x_{2}) \\ (y_{3} - y_{1}) & (x_{1} - x_{3}) \\ (y_{1} - y_{2}) & (x_{2} - x_{1}) \end{bmatrix} \begin{bmatrix} (y_{2} - y_{3}) & (y_{3} - y_{1}) & (y_{1} - y_{2}) \\ (x_{3} - x_{2}) & (x_{1} - x_{3}) & (x_{2} - x_{1}) \end{bmatrix} dx dy (\vec{T})$$

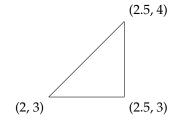
$$= 10 \frac{(x \begin{vmatrix} b \\ a \end{pmatrix})(y \begin{vmatrix} d \\ c \end{pmatrix}}{\begin{vmatrix} (x_{2} - x_{1}) & (y_{2} - y_{1}) \\ (x_{3} - x_{1}) & (y_{2} - y_{1}) \end{vmatrix}^{2}} \begin{bmatrix} (y_{2} - y_{3}) & (x_{3} - x_{2}) \\ (y_{3} - y_{1}) & (x_{1} - x_{3}) \\ (y_{1} - y_{2}) & (x_{2} - x_{1}) \end{bmatrix} \begin{bmatrix} (y_{2} - y_{3}) & (y_{3} - y_{1}) & (y_{1} - y_{2}) \\ (x_{3} - x_{2}) & (x_{1} - x_{3}) & (x_{2} - x_{1}) \end{bmatrix} \begin{bmatrix} T_{1} \\ T_{2} \\ T_{3} \end{bmatrix}$$

Sistema local final:

$$\frac{10(x \Big|_{a}^{b})(y \Big|_{c}^{d})}{\Big| \begin{matrix} (x_{2}-x_{1}) & (y_{2}-y_{1}) \\ (x_{3}-x_{1}) & (y_{3}-y_{1}) \end{matrix}|^{2}} \begin{bmatrix} \begin{matrix} (y_{2}-y_{3}) & (x_{3}-x_{2}) \\ (y_{3}-y_{1}) & (x_{1}-x_{3}) \\ (y_{1}-y_{2}) & (x_{2}-x_{1}) \end{bmatrix} \begin{bmatrix} (y_{2}-y_{3}) & (y_{3}-y_{1}) & (y_{1}-y_{2}) \\ (x_{3}-x_{2}) & (x_{1}-x_{3}) & (x_{2}-x_{1}) \end{bmatrix} \begin{bmatrix} T_{1} \\ T_{2} \\ T_{3} \end{bmatrix} = 100 \begin{vmatrix} (x_{2}-x_{1}) & (x_{3}-x_{1}) \\ (y_{2}-y_{1}) & (y_{3}-y_{1}) \end{vmatrix} \begin{bmatrix} 0 \\ 1/2 \\ 1/2 \end{bmatrix}$$

Calculando elementos:

1.

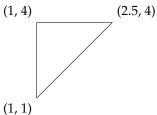


$$x_1 = 2$$
 $y_1 = 3$ $a = 2$
 $x_2 = 2.5$ $y_2 = 3$ $b = 2.5$
 $x_3 = 2.5$ $y_3 = 4$ $c = 3$
 $d = 4$

$$\frac{10(0,5)(1)}{\begin{vmatrix} 0,5 & 0 \\ 0,5 & 1 \end{vmatrix}^2} \begin{bmatrix} -1 & 0 \\ 1 & -0,5 \\ 0 & 0,5 \end{bmatrix} \begin{bmatrix} -1 & 1 & 0 \\ 0 & -0,5 & 0,5 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \end{bmatrix} = 100 \begin{vmatrix} 0,5 & 0,5 \\ 0 & 1 \end{vmatrix} \begin{bmatrix} 0 \\ 1/2 \\ 1/2 \end{bmatrix}$$

$$\begin{bmatrix} 20 & -20 & 0 \\ -20 & 25 & -5 \\ 0 & -5 & 5 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 25 \\ 25 \end{bmatrix}$$

2.

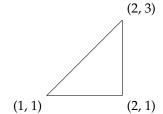


$$x_1 = 1$$
 $y_1 = 1$ $a = 1$
 $x_2 = 2.5$ $y_2 = 4$ $b = 2.5$
 $x_3 = 1$ $y_3 = 4$ $c = 1$
 $d = 4$

$$\frac{10(1,5)(3)}{\begin{vmatrix} 1,5 & 3 \\ 0 & 3 \end{vmatrix}^2} \begin{bmatrix} 0 & -1,5 \\ 3 & 0 \\ -3 & 1,5 \end{bmatrix} \begin{bmatrix} 0 & 3 & -3 \\ -1,5 & 0 & 1,5 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \end{bmatrix} = 100 \begin{vmatrix} 1,5 & 0 \\ 3 & 3 \end{vmatrix} \begin{bmatrix} 0 \\ 1/2 \\ 1/2 \end{bmatrix}$$

$$\begin{bmatrix} 5 & 0 & -5 \\ 0 & 20 & -20 \\ -5 & -20 & 25 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 255 \\ 255 \end{bmatrix}$$

3.

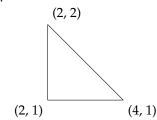


$$x_1 = 1$$
 $y_1 = 1$ $a = 1$
 $x_2 = 2$ $y_2 = 1$ $b = 2$
 $x_3 = 2$ $y_3 = 3$ $c = 1$
 $d = 3$

$$\frac{10(1)(2)}{\begin{vmatrix} 1 & 0 \\ 1 & 2 \end{vmatrix}^2} \begin{bmatrix} -2 & 0 \\ 2 & -1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} -2 & 2 & 0 \\ 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \end{bmatrix} = 100 \begin{vmatrix} 1 & 1 \\ 0 & 2 \end{vmatrix} \begin{bmatrix} 0 \\ 0.5 \\ 0.5 \end{bmatrix}$$

$$\begin{bmatrix} 20 & -20 & 0 \\ -20 & 25 & -5 \\ 0 & -5 & 5 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 100 \\ 100 \end{bmatrix}$$

4.

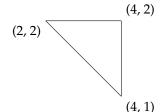


$$x_1 = 2$$
 $y_1 = 1$ $a = 2$
 $x_2 = 3$ $y_2 = 1$ $b = 4$
 $x_3 = 2$ $y_3 = 2$ $c = 1$
 $d = 2$

$$\frac{10(2)(1)}{\begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix}^2} \begin{bmatrix} -1 & -2 \\ 1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} -1 & 1 & 0 \\ -2 & 0 & 2 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \end{bmatrix} = 100 \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} \begin{bmatrix} 0 \\ 0.5 \\ 0.5 \end{bmatrix}$$

$$\begin{bmatrix} 25 & -5 & -20 \\ -5 & 5 & 0 \\ -20 & 0 & 20 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 100 \\ 100 \end{bmatrix}$$

5.

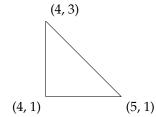


$$x_1 = 2$$
 $y_1 = 2$ $a = 2$
 $x_2 = 4$ $y_2 = 1$ $b = 4$
 $x_3 = 4$ $y_3 = 2$ $c = 1$
 $d = 2$

 $\frac{10(2)(1)}{\begin{vmatrix} 2 & -1 \\ 2 & 0 \end{vmatrix}^2} \begin{bmatrix} -1 & 0 \\ 0 & -2 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} -1 & 0 & 1 \\ 0 & -2 & 2 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \end{bmatrix} = 100 \begin{vmatrix} 2 & 2 \\ -1 & 0 \end{vmatrix} \begin{bmatrix} 0 \\ 0.5 \\ 0.5 \end{bmatrix}$

$$\begin{bmatrix} 5 & 0 & -5 \\ 0 & 20 & -20 \\ -5 & -20 & 25 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 100 \\ 100 \end{bmatrix}$$

6.

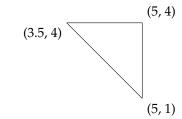


$$x_1 = 4$$
 $y_1 = 1$ $a = 4$
 $x_2 = 5$ $y_2 = 1$ $b = 5$
 $x_3 = 4$ $y_3 = 3$ $c = 1$
 $d = 3$

$$\frac{10(1)(2)}{\begin{vmatrix} 1 & 0 \\ 0 & 2 \end{vmatrix}^2} \begin{bmatrix} -2 & 1 \\ 2 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} -2 & 2 & 0 \\ -1 & 0 & 1 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \end{bmatrix} = 100 \begin{vmatrix} 1 & 0 \\ 0 & 2 \end{vmatrix} \begin{bmatrix} 0 \\ 0,5 \\ 0,5 \end{bmatrix}$$

$$\begin{bmatrix} 25 & -20 & -5 \\ -20 & 20 & 0 \\ -5 & 0 & 5 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 100 \\ 100 \end{bmatrix}$$

7.

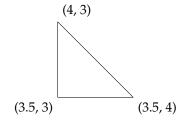


$$x_1 = 3.5$$
 $y_1 = 4$ $a = 3.5$
 $x_2 = 5$ $y_2 = 1$ $b = 5$
 $x_3 = 5$ $y_3 = 4$ $c = 1$
 $d = 4$

$$\frac{10(1,5)(3)}{\begin{vmatrix} 1,5 & -3 \\ 1,5 & 0 \end{vmatrix}^2} \begin{bmatrix} -3 & 0 \\ 0 & -1,5 \\ -3 & 1,5 \end{bmatrix} \begin{bmatrix} -3 & 0 & 3 \\ 0 & -1,5 & 1,5 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \end{bmatrix} = 100 \begin{vmatrix} 1,5 & 1,5 \\ -3 & 0 \end{vmatrix} \begin{bmatrix} 0 \\ 0,5 \\ 0,5 \end{bmatrix}$$

$$\begin{bmatrix} 20 & 0 & -20 \\ 0 & 5 & -5 \\ -20 & -5 & 25 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 225 \\ 225 \end{bmatrix}$$

8.



$$x_1 = 3.5$$
 $y_1 = 4$ $a = 3.5$
 $x_2 = 3.5$ $y_2 = 3$ $b = 4$
 $x_3 = 4$ $y_3 = 3$ $c = 3$
 $d = 4$

$$\frac{10(0,5)(1)}{\begin{vmatrix} 0 & -1 \\ 0,5 & -1 \end{vmatrix}^2} \begin{bmatrix} 0 & 0,5 \\ -1 & -0,5 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & -1 & 1 \\ 0-5 & -0,5 & 0 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \end{bmatrix} = 100 \begin{vmatrix} 0 & 0,5 \\ -1 & -1 \end{vmatrix} \begin{bmatrix} 0 \\ 0,5 \\ 0,5 \end{bmatrix}$$

$$\begin{bmatrix} 5 & -5 & 0 \\ -5 & 25 & -20 \\ 0 & -20 & 20 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 25 \\ 25 \end{bmatrix}$$

$$\underline{\underline{KT}} = \underline{\underline{b}}$$

ſ	$k_{1,1}^{(2)} + k_{1,1}^{(3)}$	$k_{1,2}^{(3)}$	0	0	0	0	0	0	0	0	$k_{1,3}^{(3)} \ k_{2,3}^{(3)}$	0	$k_{1,2}^{(2)}$	$k_{1,3}^{(2)}$]	$b_1^{(2)} + b_1^{(3)}$	7
	$k_{2,1}^{(3)}$	$k_{2,2}^{(3)} + k_{1,1}^{(4)}$	$k_{2,2}^{(4)} + k_{1,2}^{(5)} + k_{1,1}^{(6)} \\ k_{2,2}^{(6)} + k_{2,1}^{(6)}$	0	0	0	0	0	0	$k_{1,3}^{(4)}$	$k_{2,3}^{(3)}$	0	0	0		$b_1 + b_1 b_2^{(3)} + b_1^{(4)}$	
	0	$k_{2,1}^{(4)}$	$k_{2,2}^{(4)} + k_{2,2}^{(5)} + k_{1,1}^{(6)}$	$k_{1,2}^{(6)}$	0	0	0	$k_{1,3}^{(6)} \ k_{2,3}^{(6)}$	$k_{2,3}^{(5)}$	$k_{2,3}^{(4)} + k_{2,1}^{(5)}$	0	0	0	0	$\begin{bmatrix} T_1 \\ T_2 \end{bmatrix}$	$b_2^{(4)} + b_2^{(5)} + b_1^{(6)}$	
	0	0	$k_{2,1}^{(6)}$	$k_{2,2}^{(6)} + k_{2,2}^{(7)}$	$k_{2,3}^{(7)}$ $k_{3,3}^{(7)}$ $k_{1,3}^{(7)}$	$k_{2,1}^{(7)}$ $k_{3,1}^{(7)}$	0	$k_{2,3}^{(6)}$	0	0	0	0	0	0	T_3	$b_2^{(6)} + b_2^{(7)}$	
	0	0	0	$k_{3,2}^{(7)}$	$k_{3,3}^{(7)}$	$k_{3,1}^{(7)}$	0	0	0	0	0	0	0	0	T_4	$b_{3}^{(7)}$	
	0	0	0	$k_{3,2}^{(7)}$ $k_{1,2}^{(7)}$	$k_{1,3}^{(7)}$	$k_{1,1}^{(7)} + k_{1,1}^{(8)}$	$k_{1,2}^{(8)}$	$k_{1,3}^{(8)}$ $k_{2,3}^{(8)}$	0	0	0	0	0	0	T_5 T_6	$b_1^{(7)} + b_1^{(8)}$	
	0	0	0	0	0	$k_{2,1}^{(8)}$	$k_{2,2}^{(8)}$	$k_{2,3}^{(8)}$	0	0	0	0	0	0	T_7	$=$ $b_2^{(8)}$	
	0	0	$k_{3,1}^{(6)}$ $k_{3,2}^{(5)}$	$k_{3,2}^{(6)}$	0	$k_{2,1}^{(8)}$ $k_{3,1}^{(8)}$	$k_{1,2}^{(8)}$ $k_{2,2}^{(8)}$ $k_{3,2}^{(8)}$	$k_{3,3}^{(6)} + k_{3,3}^{(8)}$	0	0	0	0	0	0	T_8	$b_2^{(6)} + b_2^{(8)}$	
	0	0	$k_{3,2}^{(5)}$	0	0	0	0	0	$k_{3,3}^{(5)}$ $k_{1,3}^{(5)}$	$k_{3,1}^{(5)}$	0	0	0	0	T_9 T_{10}	$b_{2}^{(5)}$	
	0	$k_{3,1}^{(4)}$	$k_{3,2}^{(4)} + k_{1,2}^{(5)}$	0	0	0	0	0	$k_{1,3}^{(5)}$	$k_{3,3}^{(4)} + k_{1,1}^{(5)}$	0	0	0	0	T_{11}	$b_3^{(4)} + b_1^{(5)} \\ b_1^{(1)} + b_3^{(3)}$	
	$k_{3,1}^{(3)}$	$k_{3,1}^{(4)} \ k_{3,2}^{(3)}$	0	0	0	0	0	0	0	0	$k_{1,1}^{(1)} + k_{3,3}^{(3)}$	$k_{1,2}^{(1)}$ $k_{2,2}^{(1)}$ $k_{3,2}^{(1)}$	$k_{1,3}^{(1)}$ $k_{2,3}^{(1)}$	0	T_{12}	$b_1^{(1)} + b_3^{(3)}$	
	0	0	0	0	0	0	0	0	0	0	$k_{2,1}^{(1)}$	$k_{2,2}^{(1)}$	$k_{2,3}^{(1)}$	0	$\begin{bmatrix} T_{13} \\ T_{14} \end{bmatrix}$	$b_2^{(1)}$	
	$k_{2,1}^{(2)}$	0	0	0	0	0	0	0	0	0	$k_{2,1}^{(1)}$ $k_{3,1}^{(1)}$	$k_{3,2}^{(1)}$	$k_{3,3}^{(1)} + k_{2,2}^{(2)}$	$k_{2,3}^{(2)}$	[[14]	$b_3^{(1)} + b_2^{(2)}$	
	$k_{2,1}^{(2)} $ $k_{3,1}^{(2)}$	0	0	0	0	0	0	0	0	0	0	0	$k_{3,2}^{(2)}$	$k_{2,3}^{(2)}$ $k_{3,3}^{(2)}$	_	$b_3^{(2)}$	╛

9

Aplicaciones de condiciones de contorno

$$\Gamma_D = \{T_1, T_{14}\}$$

$$\Gamma_N = \left\{\frac{dT_4}{d\hat{n}}, \frac{dT_5}{d\hat{n}}\right\}$$