

Two-Phase Progressive Multiple Exposure Fusion via Intermediate Exposure Generation

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Introduction

Problem Definition

- Real-world scenes: $10^{-3} \sim 10^5$
- Display limitation: 8 bits $\rightarrow 2^8 = 256$

Introduction

Problem Definition

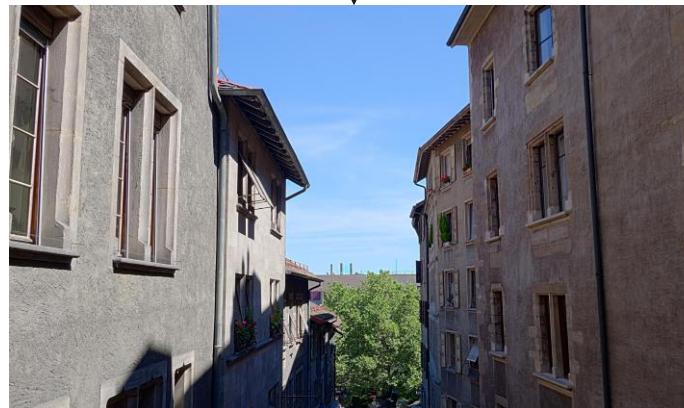
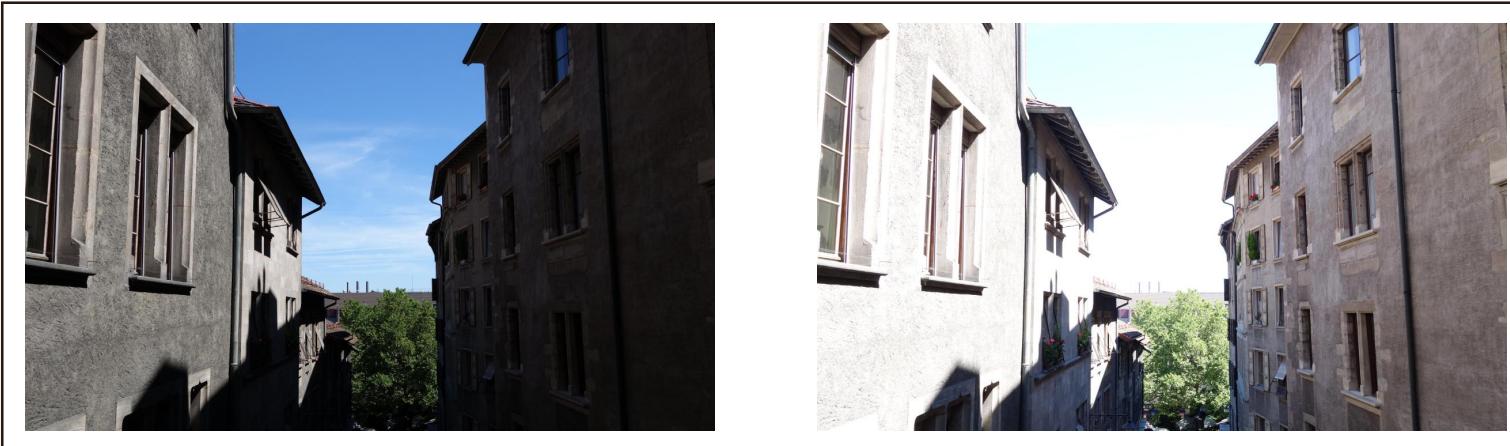
- Real-world scenes: $10^{-3} \sim 10^5$
- Display limitation: 8 bits $\rightarrow 2^8 = 256$
- Result: Detail loss in extremely dark/bright regions



Introduction

Problem Definition

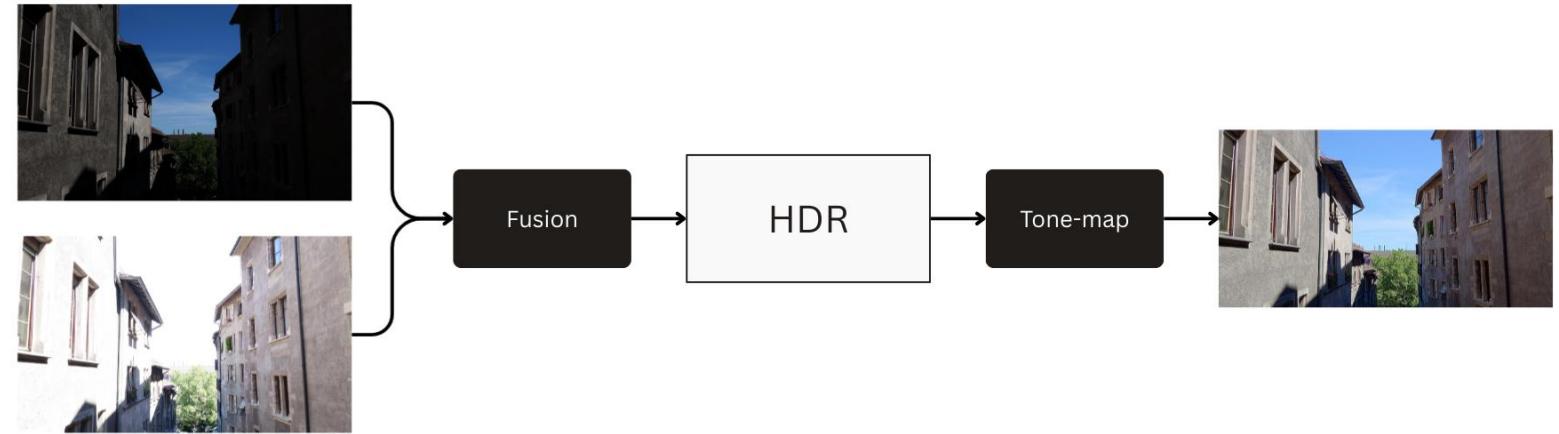
- Solution: Multiple exposure capture



Introduction

HDR vs. MEF

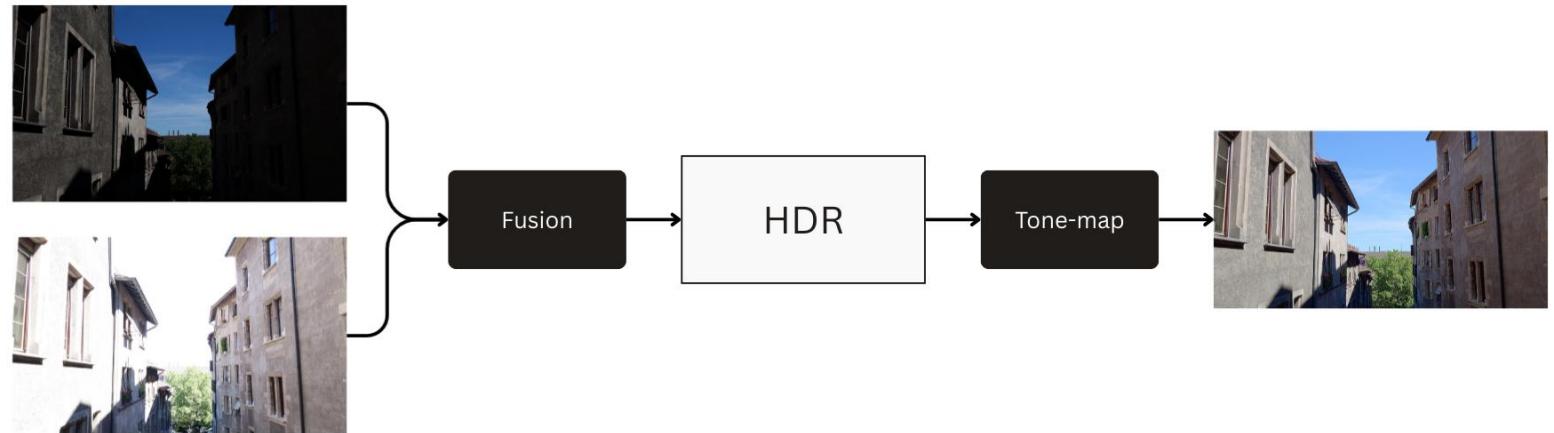
- HDR Reconstruction:



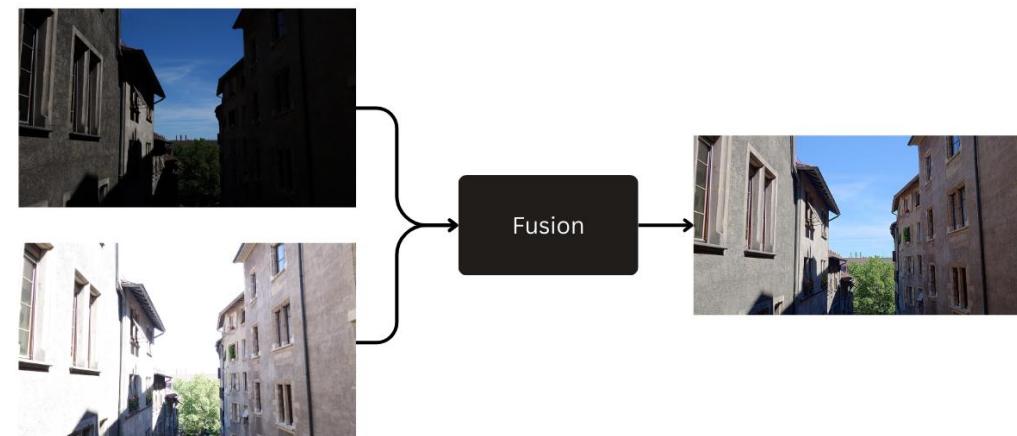
Introduction

HDR vs. MEF

- HDR Reconstruction:



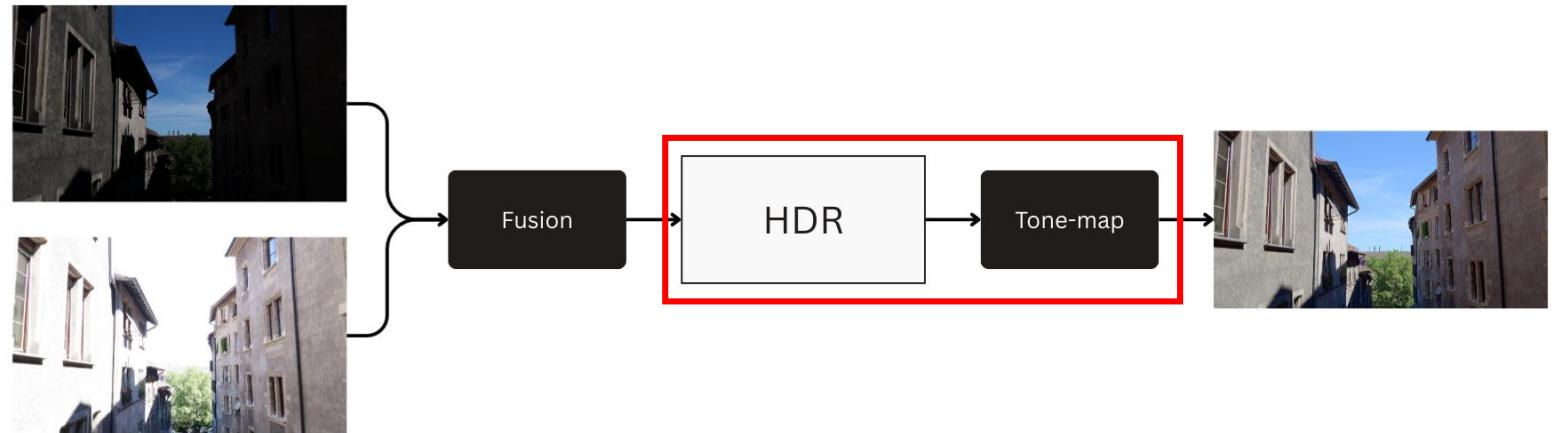
- Multiple Exposure Fusion (MEF)



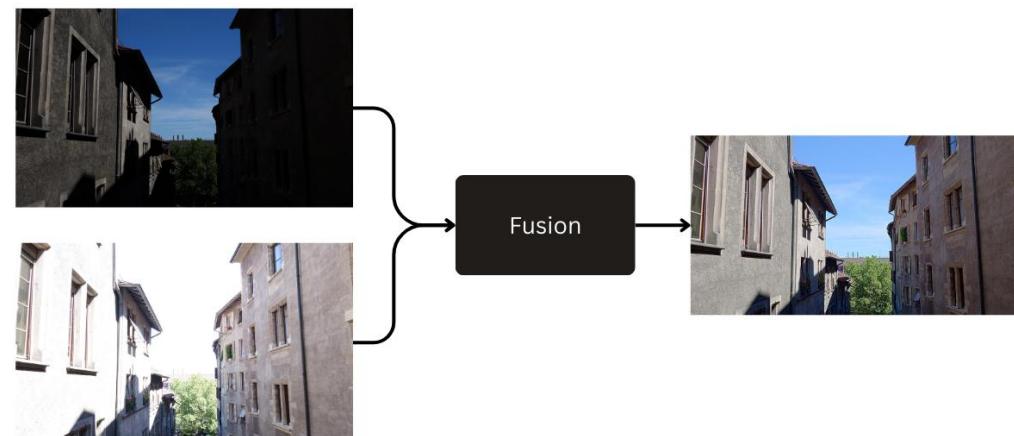
Introduction

HDR vs. MEF

- HDR Reconstruction:



- Multiple Exposure Fusion (MEF)



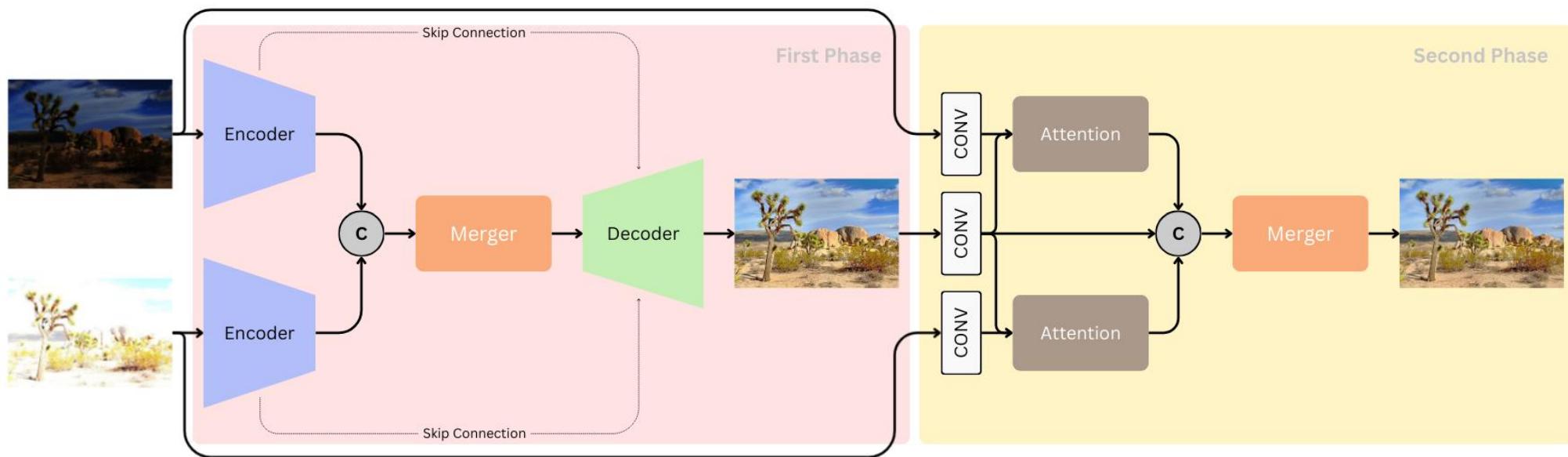
Introduction

Contribution

Novel Two-Phase Progressive Architecture with Decoupled Training

First to progressively fuse first-stage output with original inputs

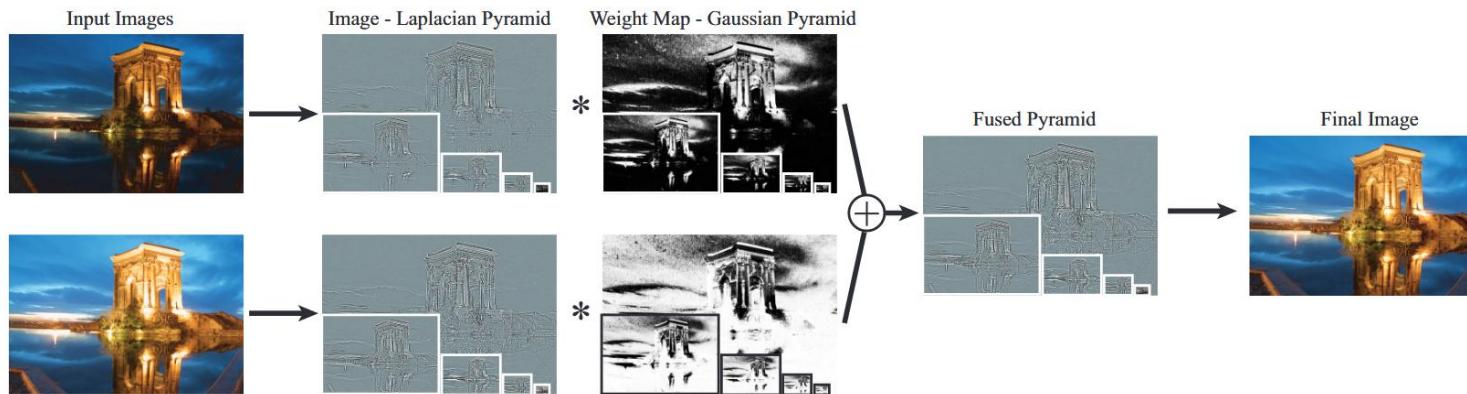
- Phase 1: Intermediate Exposure Generation with UNet for Global Information
- Phase 2: Final Result with Attention-Based Refinement for Local Information



Related Works

Traditional Methods

- Mertens et al. (2007) – Exposure Fusion
 - Laplacian pyramid decomposition
 - Quality measures: Contrast, Saturation, Well-exposedness



Related Works

Traditional Methods

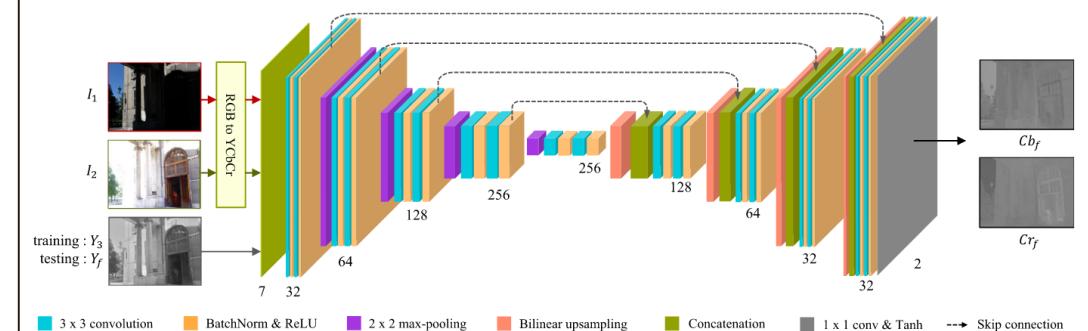
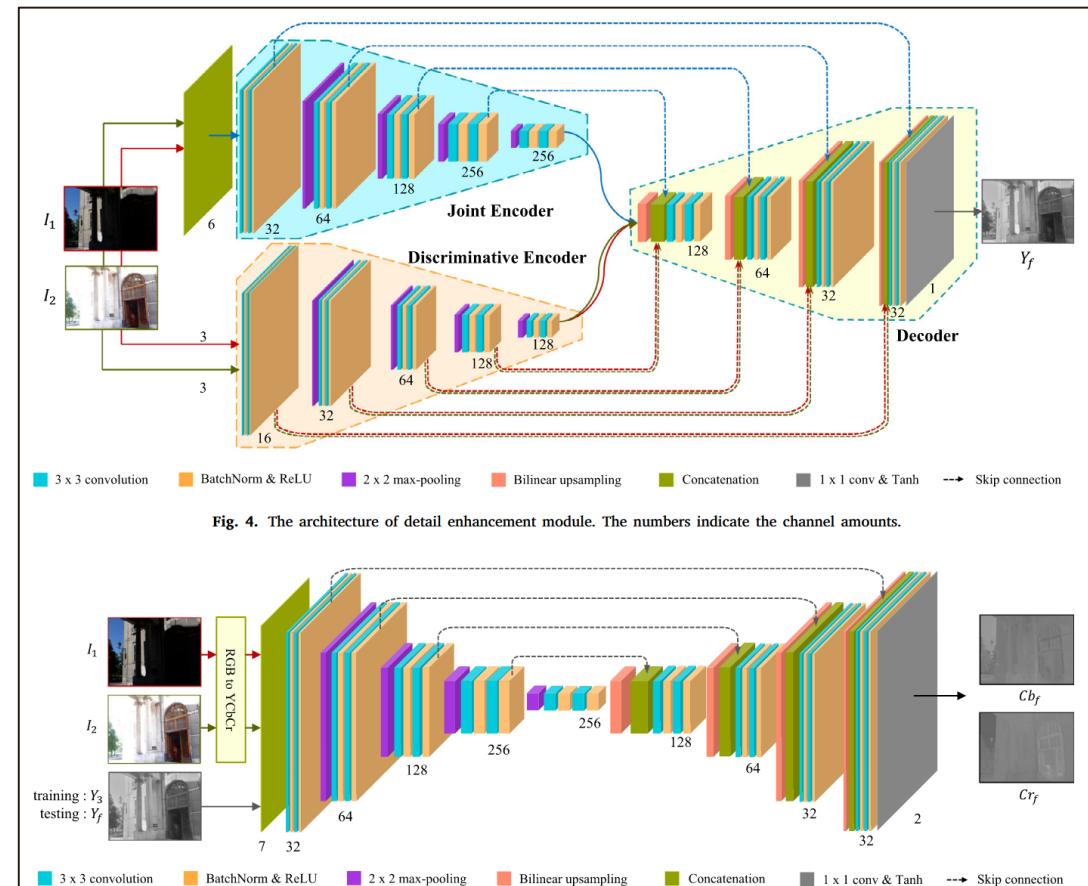
- Mertens et al. (2007) – Exposure Fusion
 - Laplacian pyramid decomposition
 - Quality measures: Contrast, Saturation, Well-exposedness
- Ma et al. (2017) – Structural Patch Decomposition
 - Patch level instead of pixel level
 - Decomposes into 3 components: signal strength, signal structure, mean intensity

$$\begin{aligned}\mathbf{x}_k &= \|\mathbf{x}_k - \mu_{\mathbf{x}_k}\| \cdot \frac{\mathbf{x}_k - \mu_{\mathbf{x}_k}}{\|\mathbf{x}_k - \mu_{\mathbf{x}_k}\|} + \mu_{\mathbf{x}_k} \\ &= \|\tilde{\mathbf{x}}_k\| \cdot \frac{\tilde{\mathbf{x}}_k}{\|\tilde{\mathbf{x}}_k\|} + \mu_{\mathbf{x}_k} \\ &= c_k \cdot \mathbf{s}_k + l_k\end{aligned}$$

Related Works

Deep Learning Methods

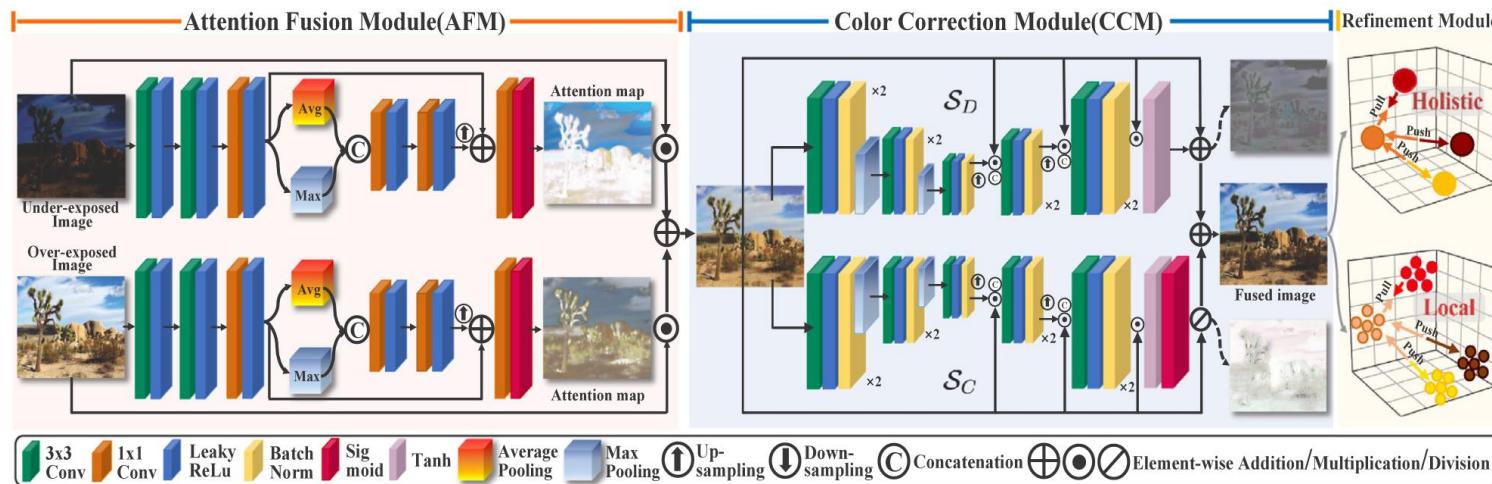
- DPE-MEF: Multi-exposure image fusion via deep perceptual enhancement
 - Output in YCbCr space



Related Works

Deep Learning Methods

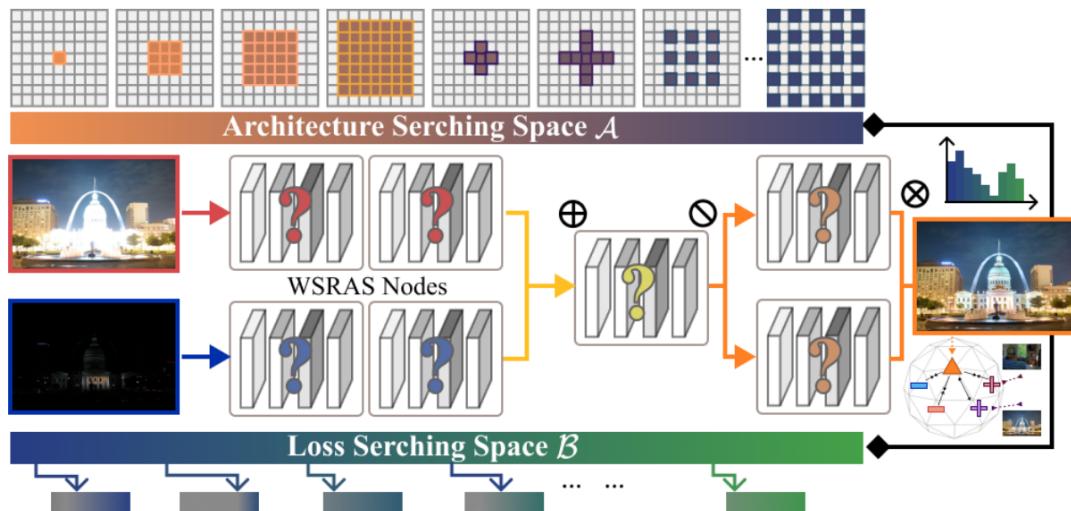
- DPE-MEF: Multi-exposure image fusion via deep perceptual enhancement
 - Output in YCbCr space
- HoLoCo: Holistic and local contrastive learning network for multi-exposure image fusion
 - Attention Map + UNet based on Retinex Theory
 - Contrastive Learning



Related Works

Deep Learning Methods – Automated Design

- HSDS-MEF: Hybrid-Supervised Dual-Search: Leveraging Automatic Learning for Loss-Free Multi-Exposure Image Fusion
 - Search for optimized loss parameters and network layers



Algorithm 1: Dual Search for Structure and Loss Function

Require: Fusion loss \mathcal{L}^f , hybrid-supervised contrast constraint Γ_h , search spaces \mathcal{A} and \mathcal{B} , and other necessary hyper-parameters.

Ensure: Optimal parameters α^* and β^* .

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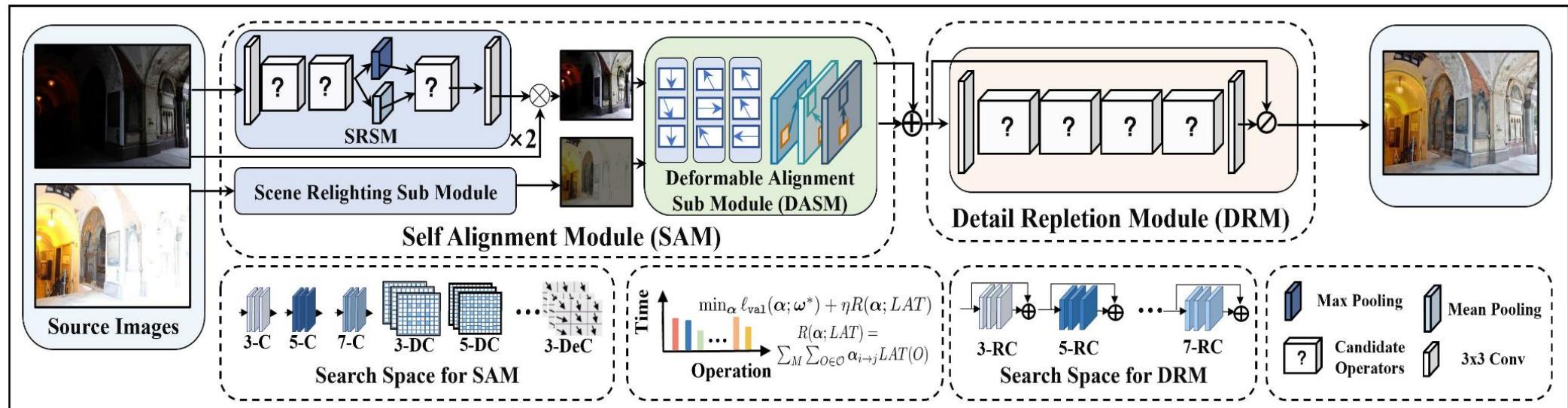
1: while not converged do
2:   % Optimizing the image fusion network
3:    $\omega \leftarrow \omega - \nabla \mathcal{L}_{\text{train}}^f \sim (\alpha; \omega; \beta)$ 
4:   % First-order approximation to optimize  $\beta$ 
5:    $\beta \leftarrow \beta - \nabla_\beta \Gamma_h \sim (\alpha; \omega)$ 
6:   % First-order approximation to optimize  $\alpha$ 
7:    $\alpha \leftarrow \alpha - \nabla_\alpha \mathcal{L}_{\text{val}}^f \sim (\alpha; \omega; \beta)$ 
8:   while  $|\mathcal{A}| > P$  do
9:     if  $\min \alpha_i < \theta$  then
10:       % Prune the operation with the smallest weight
11:       % in search space  $\mathcal{A}$ 
12:        $\mathcal{A} \leftarrow \text{RefineSmallestWeight}(\mathcal{A})$ 
13:     end if
14:   end while
15: end while
16: return Top- $P$  operations based on  $\alpha^*, \beta^*$ .

```

Related Works

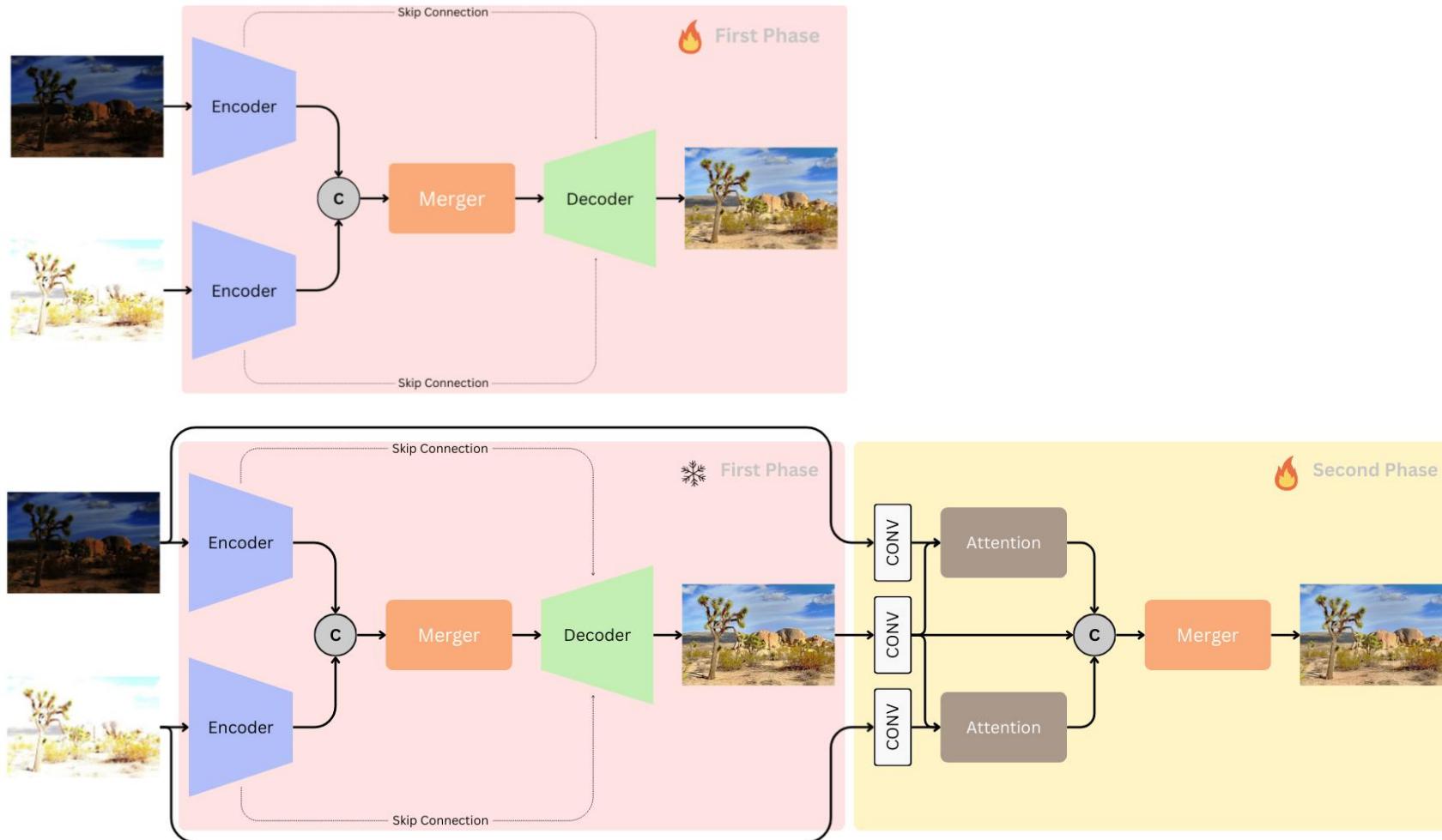
Deep Learning Methods – Automated Design

- HSDS-MEF: Hybrid-Supervised Dual-Search: Leveraging Automatic Learning for Loss-Free Multi-Exposure Image Fusion
 - Search for optimized loss parameters and network layers
- Searching a Compact Architecture for Robust Multi-Exposure Image Fusion
 - Hardware constraint



Method

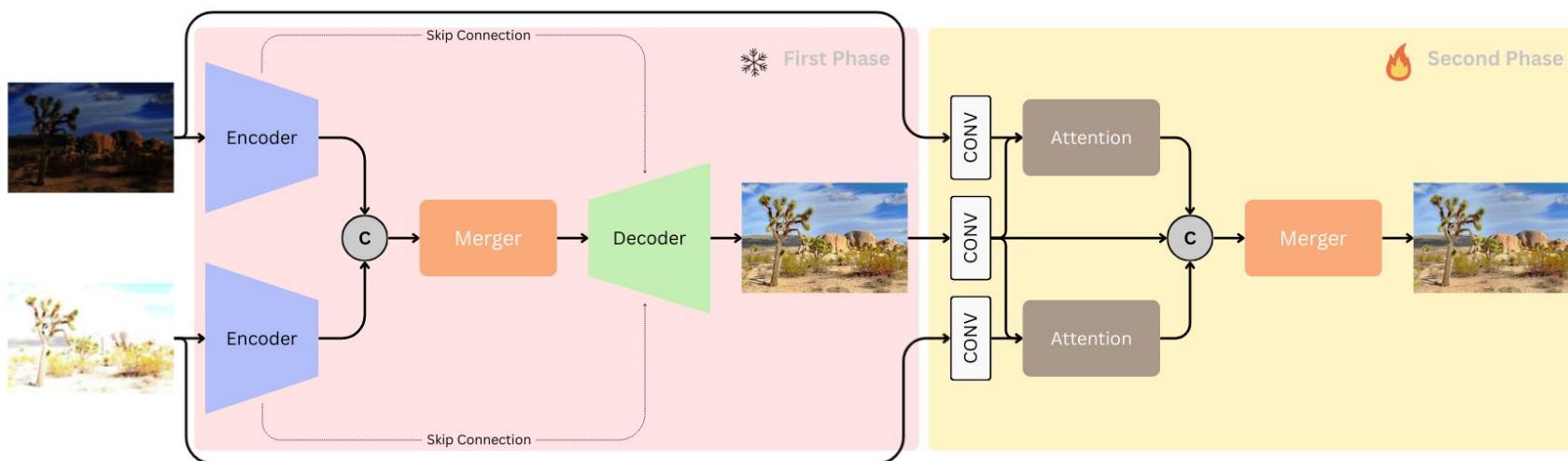
Overview



Method

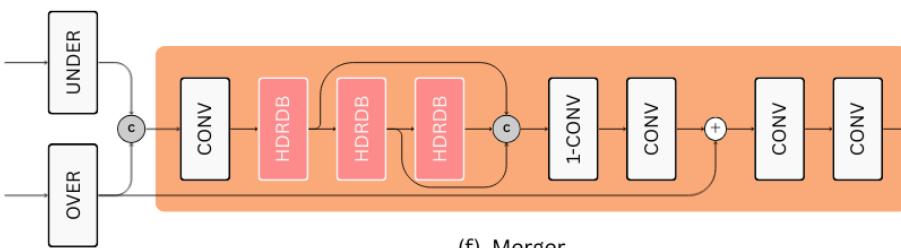
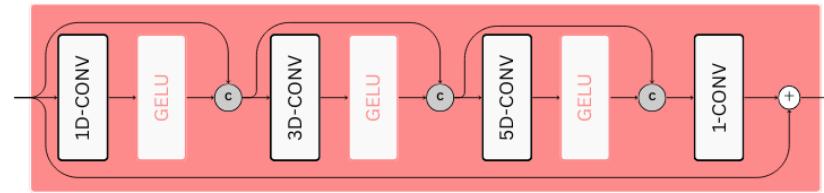
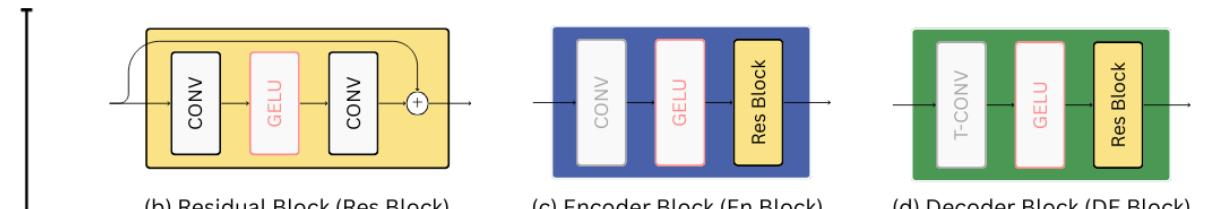
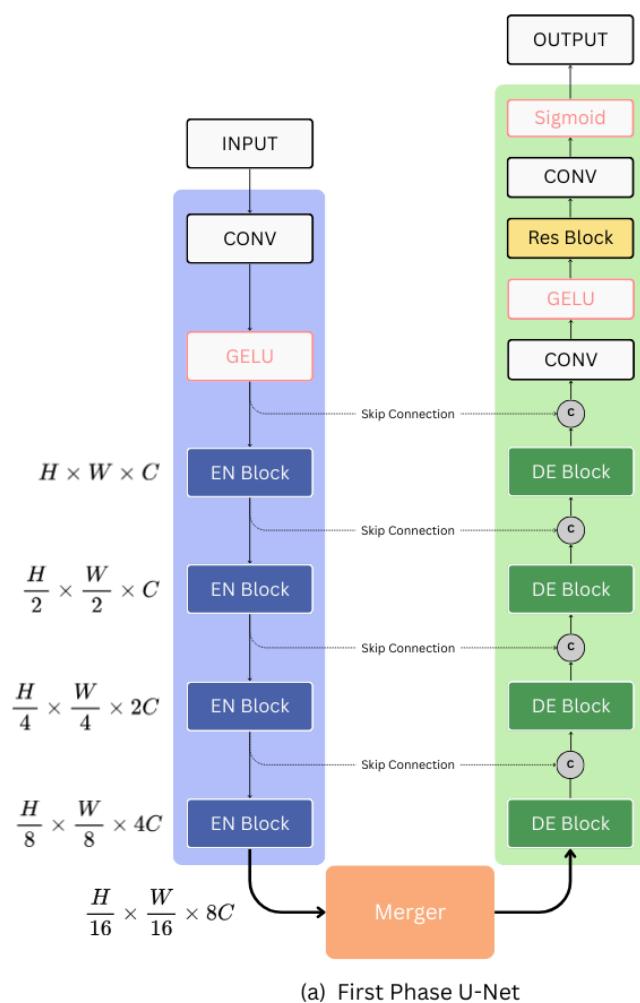
Overview

- Propose an architecture that explicitly separates global and local fusion
- Develop a decoupled training strategy for specialized optimizations.
- Introduce intermediate exposure generation to bridge extreme inputs
- Demonstrate that reduced exposure differences improve attention mechanism performance in MEF



Method

First Phase



CONV	CONV	χ D-CONV	1-CONV	T-CONV
3x3 Convolution Stride = 1	3x3 Convolution Stride = 2	3x3 Convolution Dilation = χ	4x4 Transposed Convolution Stride = 1	4x4 Transposed Convolution Stride = 2

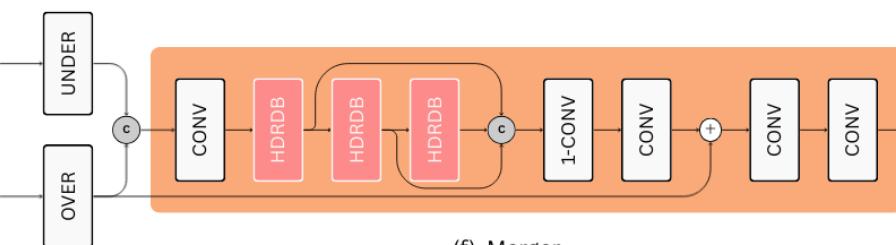
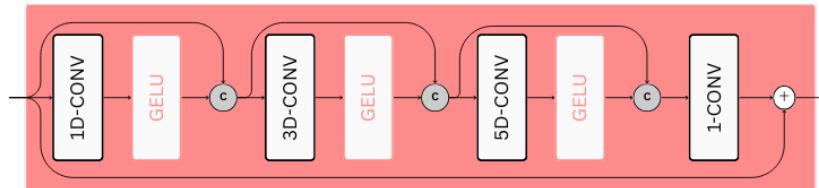
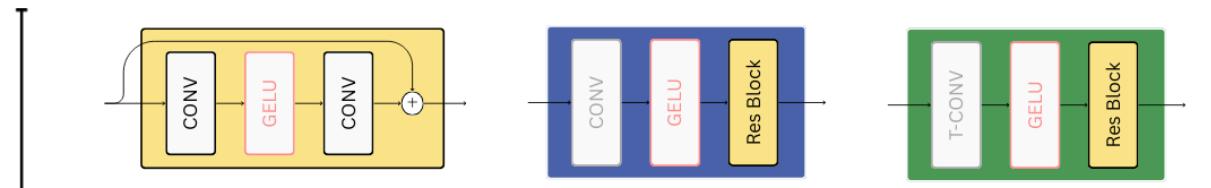
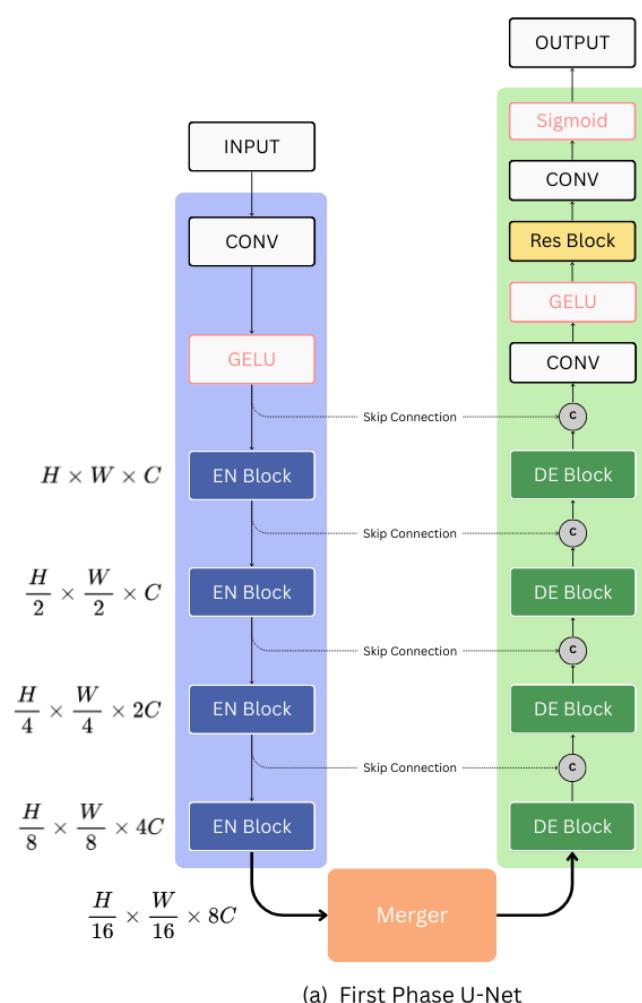
Method

First Phase



Method

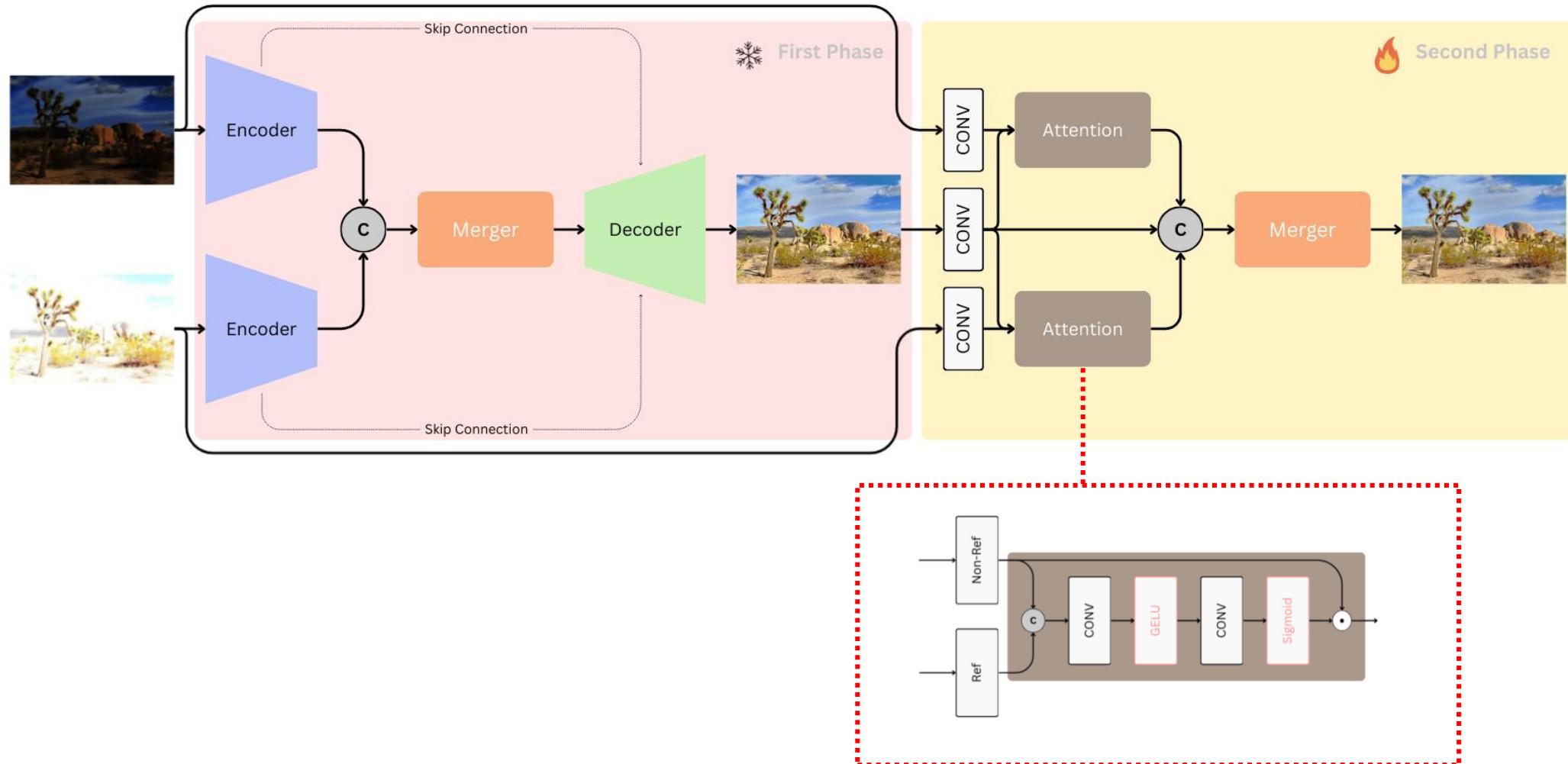
First Phase



CONV	CONV	χ D-CONV	1-CONV	T-CONV
3x3 Convolution Stride = 1	3x3 Convolution Stride = 2	3x3 Convolution Dilation = χ	4x4 Transposed Convolution Stride = 1	4x4 Transposed Convolution Stride = 2

Method

Second Phase



Method

Loss Function

- First Phase

$$I_{inter} = \text{UNet}(I_u, I_o)$$

$$\mathcal{L} = \mathcal{L}_{\text{L1}}(I_{inter}, I_{gt}) + \lambda_{vgg}\mathcal{L}_{\text{VGG}}(I_{inter}, I_{gt}) + \lambda_{ssim}\mathcal{L}_{\text{SSIM}}(I_{inter}, I_{gt})$$

Method

Loss Function

- First Phase

$$I_{inter} = \text{UNet}(I_u, I_o)$$

$$\mathcal{L} = \mathcal{L}_{\text{L1}}(I_{inter}, I_{gt}) + \lambda_{vgg} \mathcal{L}_{\text{VGG}}(I_{inter}, I_{gt}) + \lambda_{ssim} \mathcal{L}_{\text{SSIM}}(I_{inter}, I_{gt})$$

- Second Phase

$$I_{inter} = \text{UNet}_{frozen}(I_u, I_o)$$

$$I_{final} = \text{AMNet}(I_u, I_{inter}, I_o)$$

$$\mathcal{L} = \mathcal{L}_{\text{L1}}(I_{final}, I_{gt}) + \lambda_{vgg} \mathcal{L}_{\text{VGG}}(I_{final}, I_{gt}) + \lambda_{ssim} \mathcal{L}_{\text{SSIM}}(I_{final}, I_{gt})$$

Experiments

Dataset

- SICE Dataset:
 - Original: 589 sequences
 - After filtering: 453 high-quality sequences
- Ground Truth:
 - 13 fusion algorithms → user voting
 - Training Set: 360 sequences
 - 13 amateur photographers + 5 volunteers



Our Split: Training 360 sequences + Testing 93 sequences

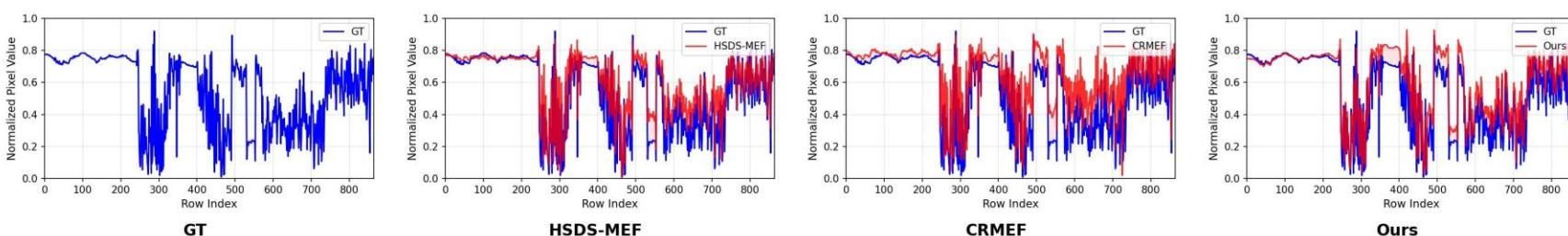
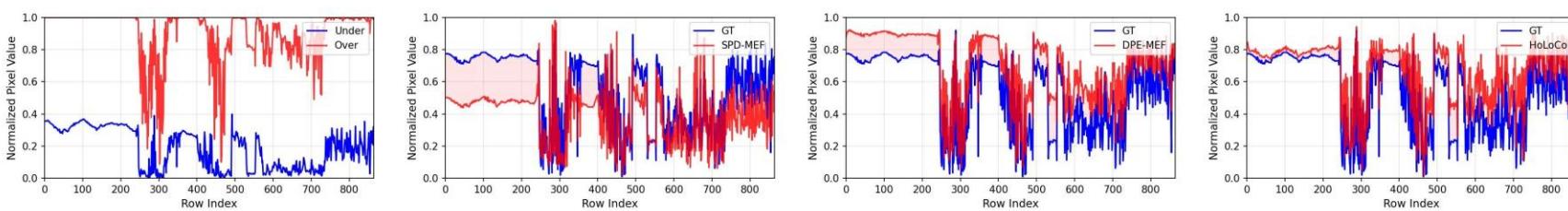
Experiments

Quantitative

Methods	PSNR	SSIM	MS-SSIM	VIF
SPD-MEF	17.5891	0.7643	0.8599	0.6294
DPE-MEF	18.4047	0.8065	0.8963	0.6716
HoLoCo	20.0829	0.8236	0.8822	0.4678
HSDS-MEF	20.0444	0.7771	0.9058	0.5661
CRMEF	20.0893	0.8273	0.8740	0.6570
Ours	22.9934	0.8768	0.9359	0.7761

Experiments

Qualitative



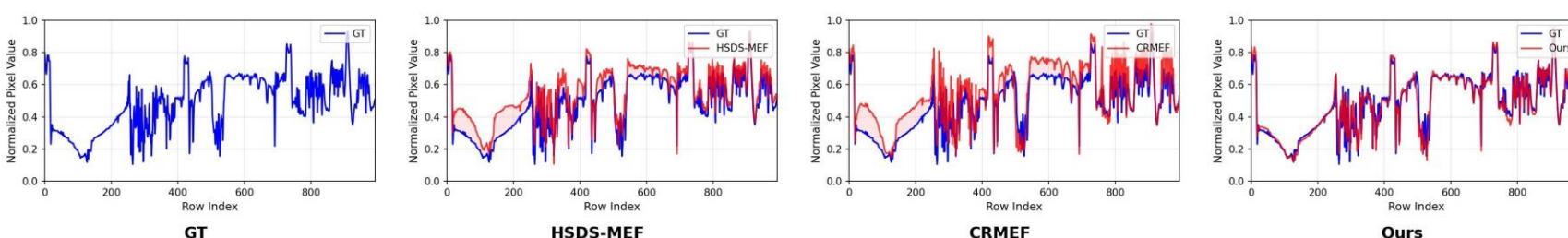
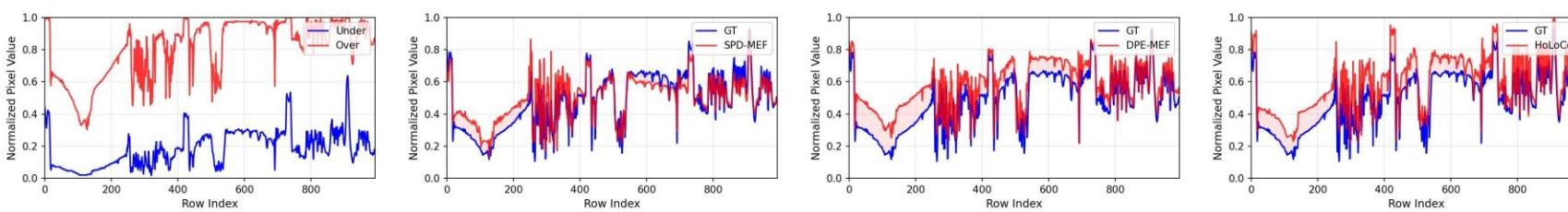
Experiments

Qualitative



Experiments

Qualitative



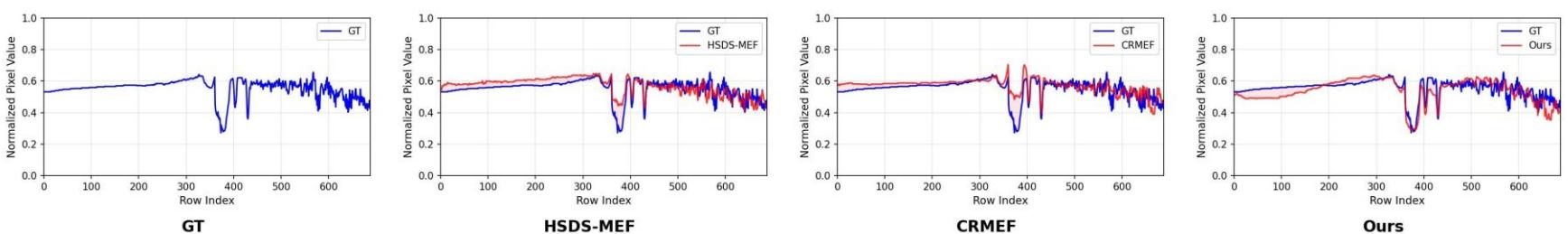
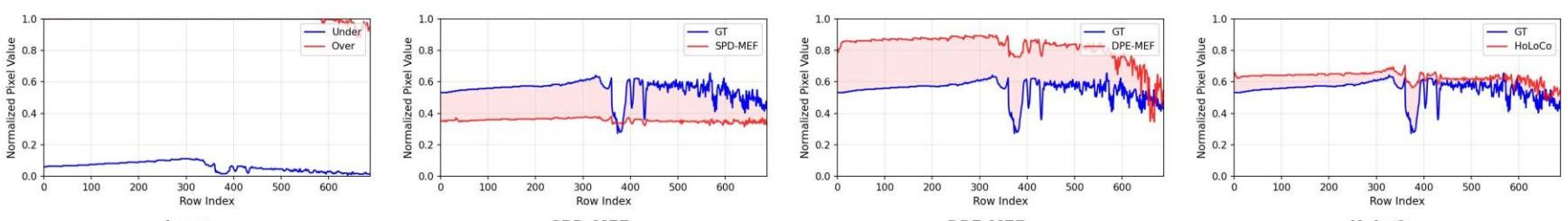
Experiments

Qualitative



Experiments

Qualitative



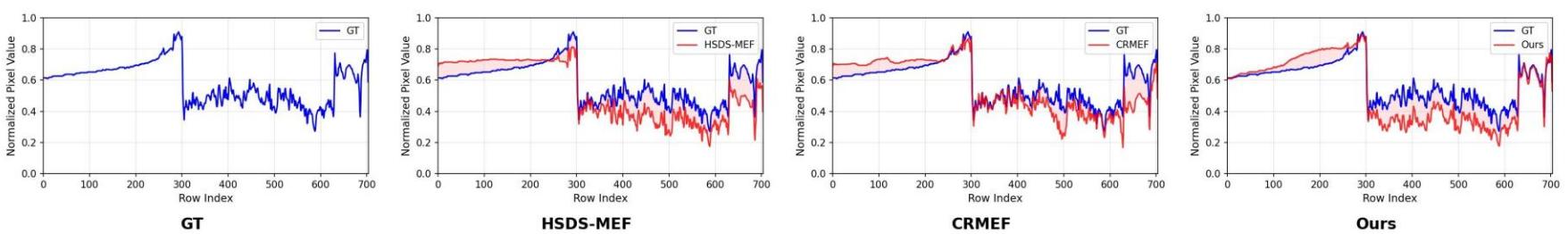
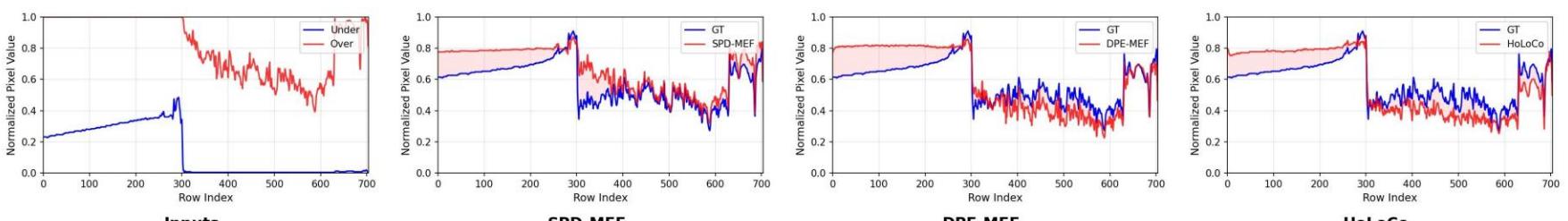
Experiments

Qualitative



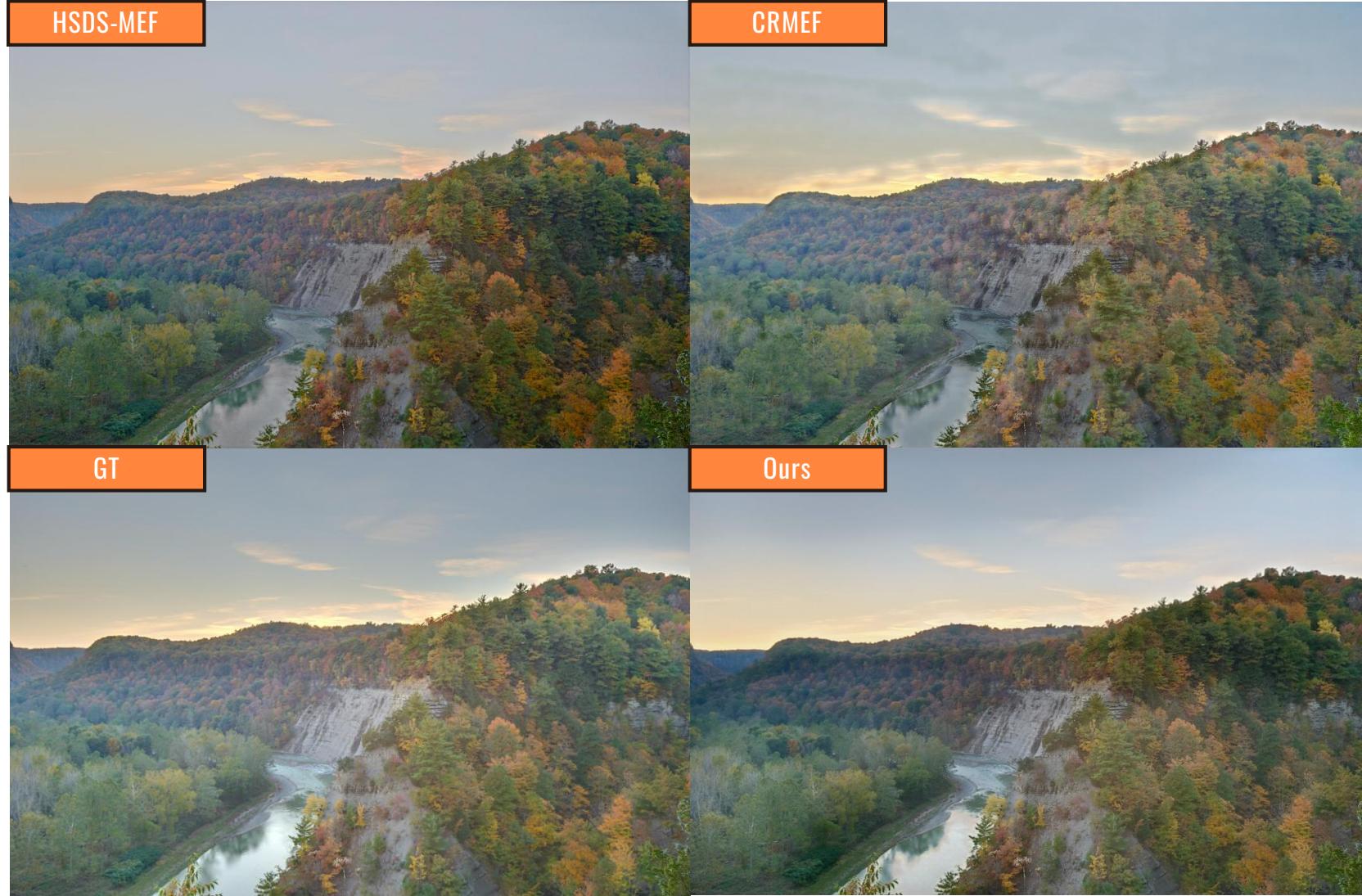
Experiments

Qualitative



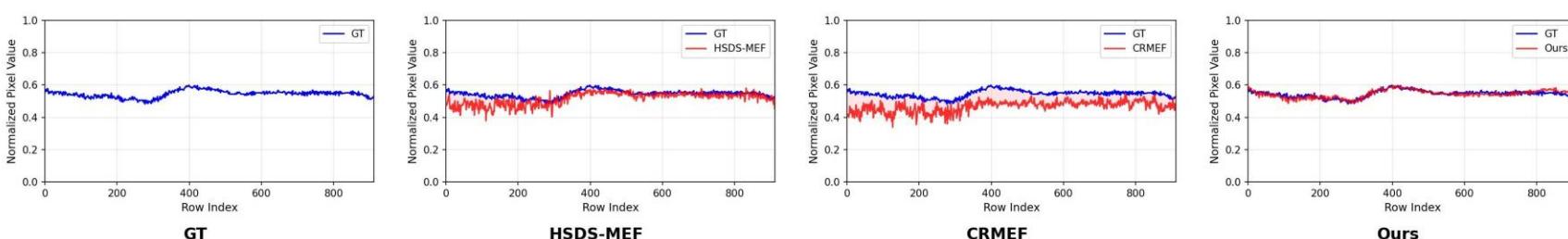
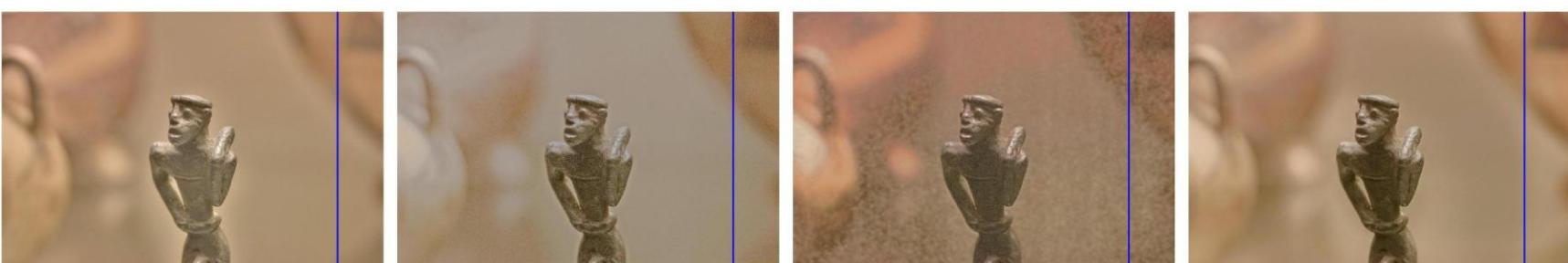
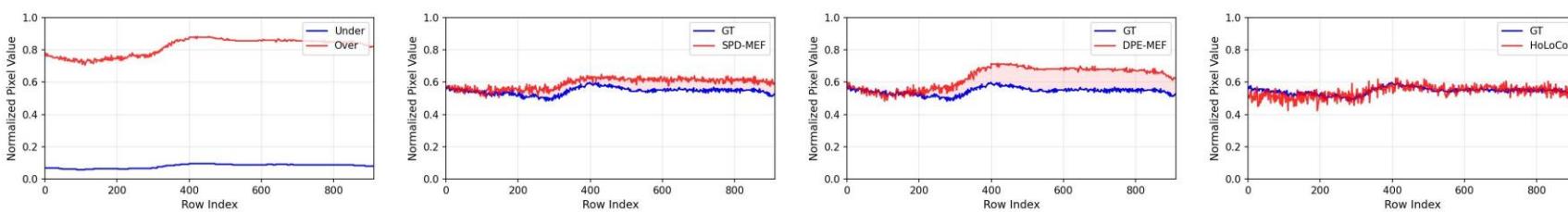
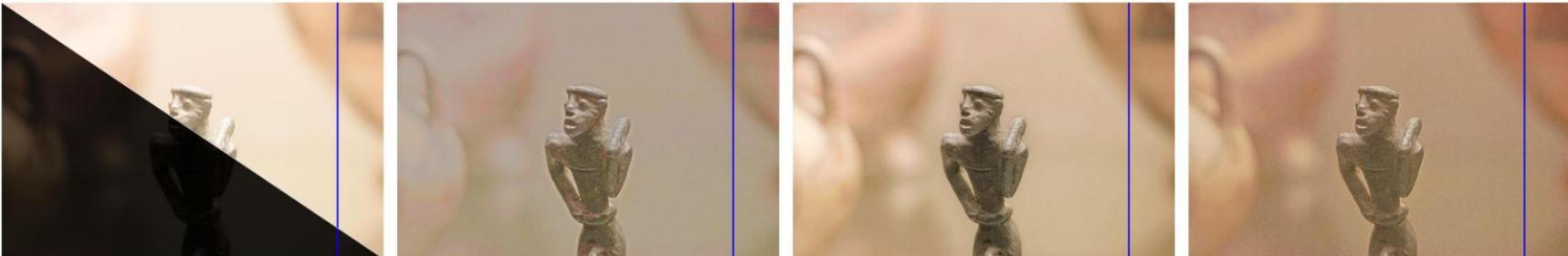
Experiments

Qualitative



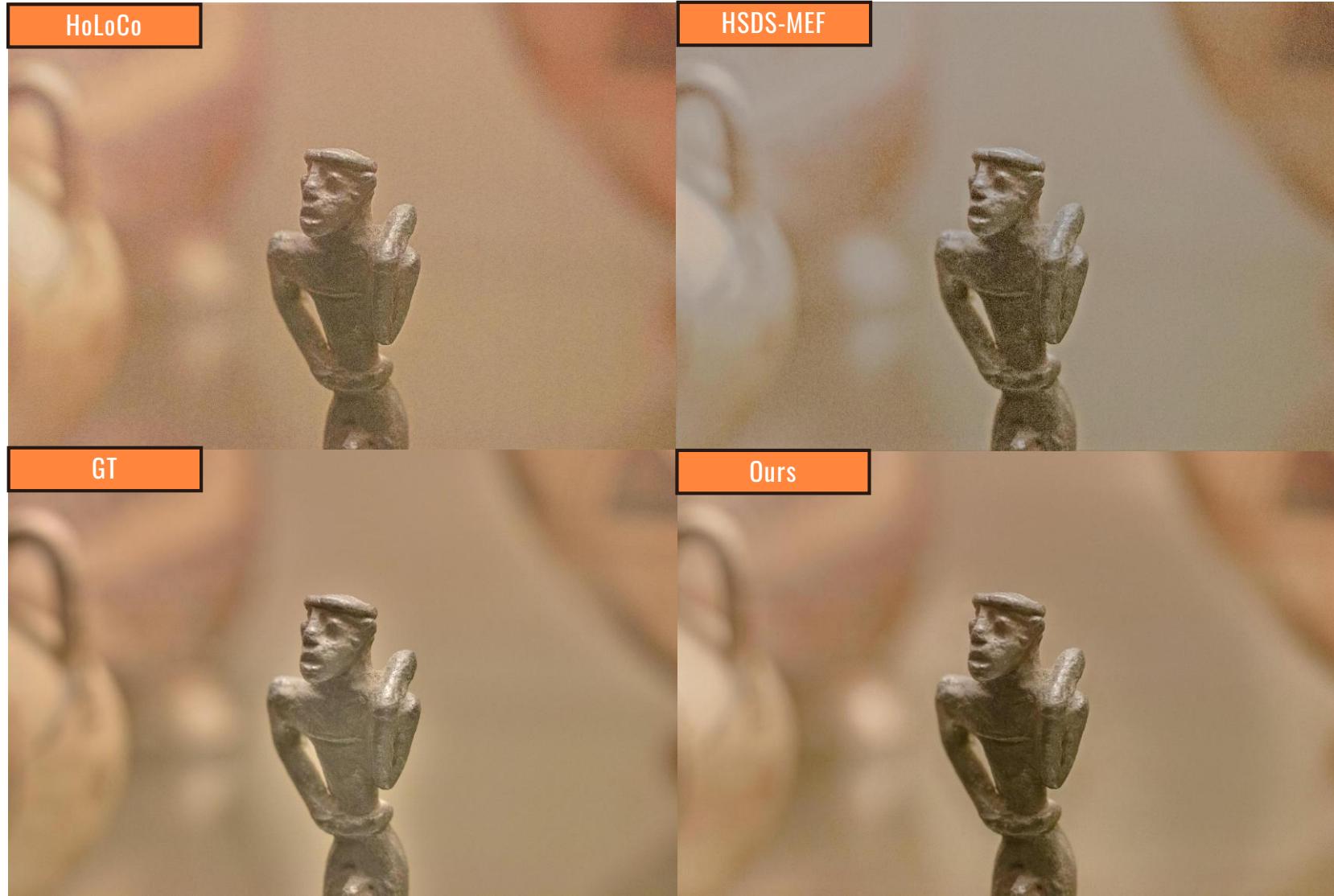
Experiments

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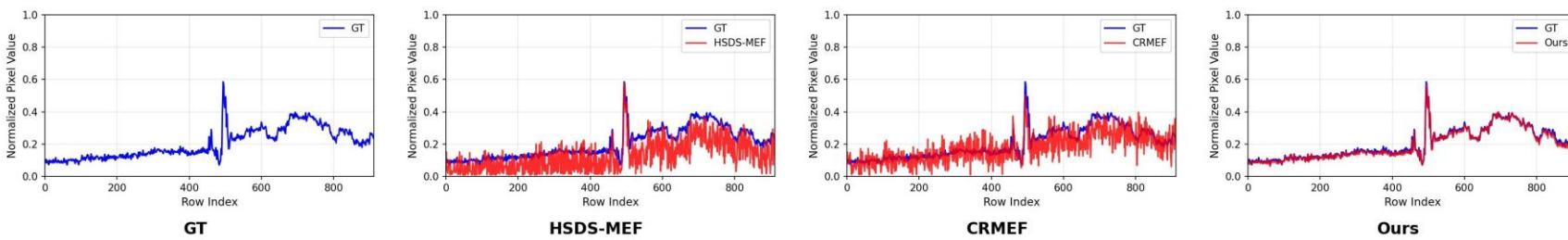
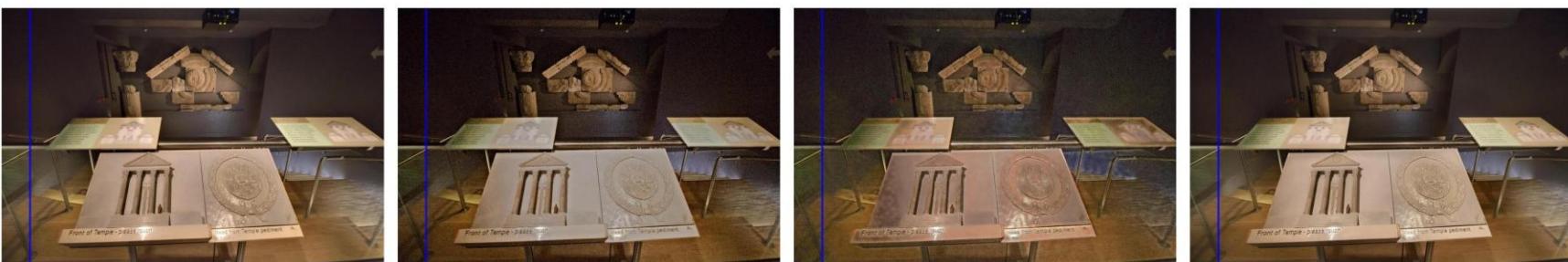
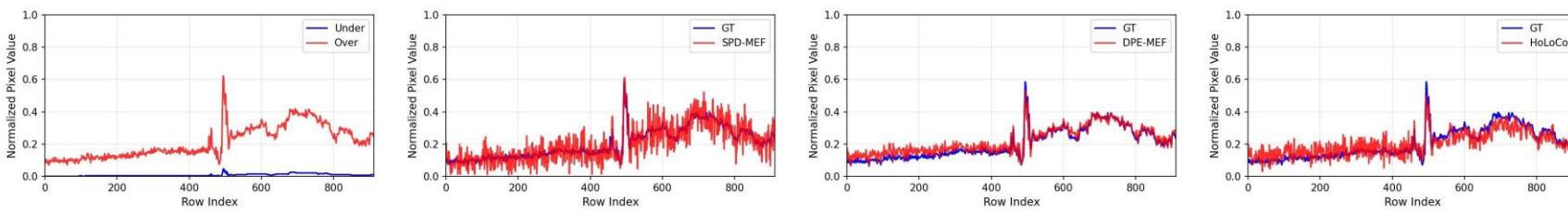
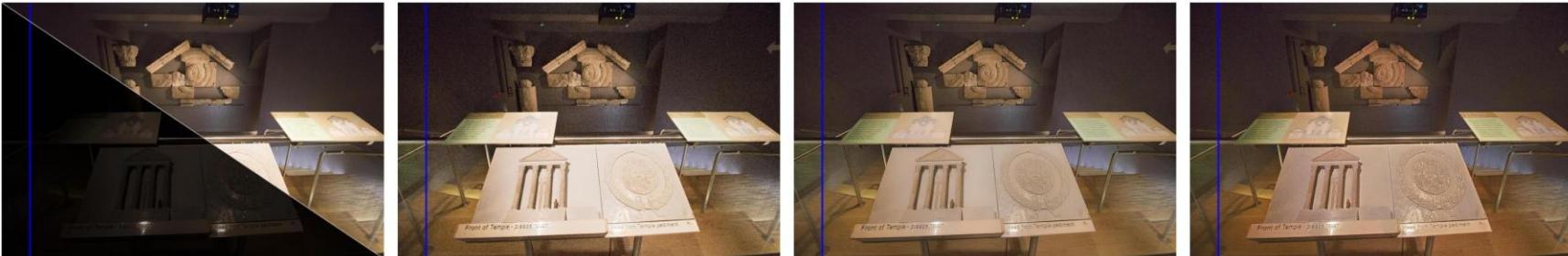
Experiments

Qualitative



Experiments

Qualitative



Experiments

Qualitative



Conclusion

- Insights
 - Reducing exposure differences improves attention weight computation
 - Decoupled training for specialized optimization
- Current Limitations
 - Static scenes only
- Future Directions:
 - Multi-Phase Progressive Architecture
 - Include motion detection in one of phases