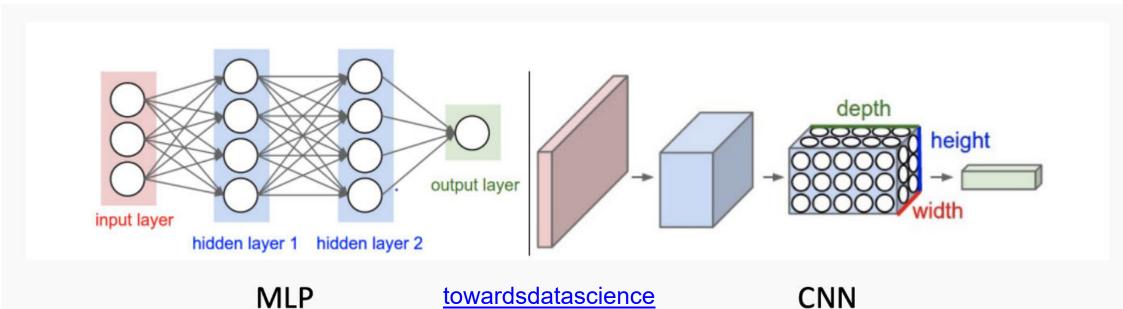
# Machine Learning Multilayer Networks

Jian Liu

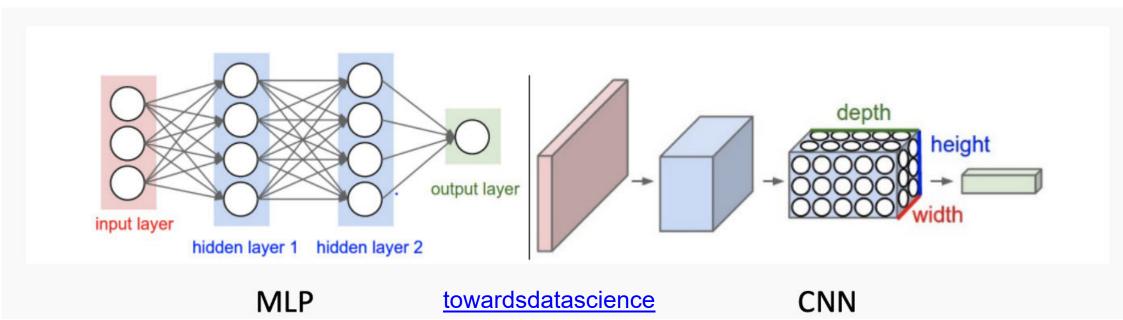
Part 1: MLP Part 2: CNN



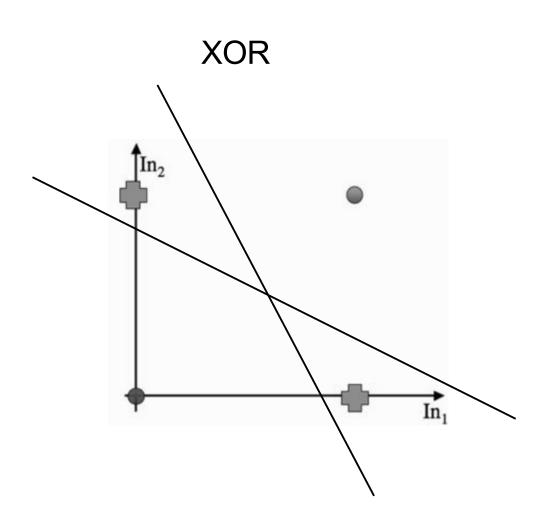
## Machine Learning Multilayer Networks

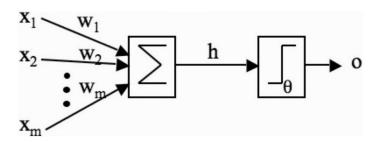
Jian Liu

Part 1: MLP

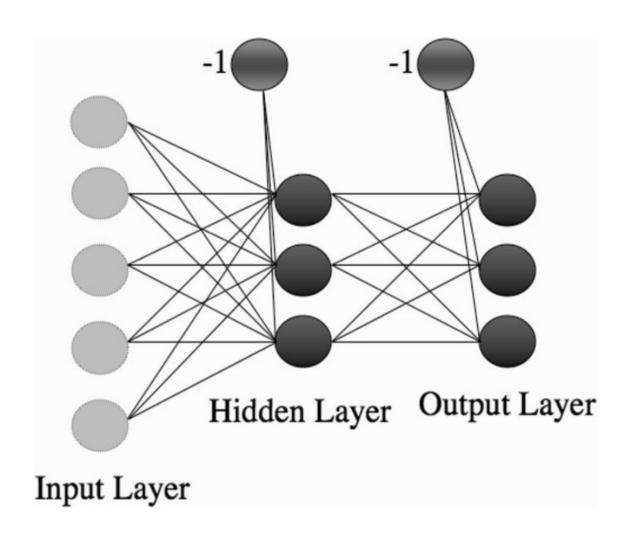


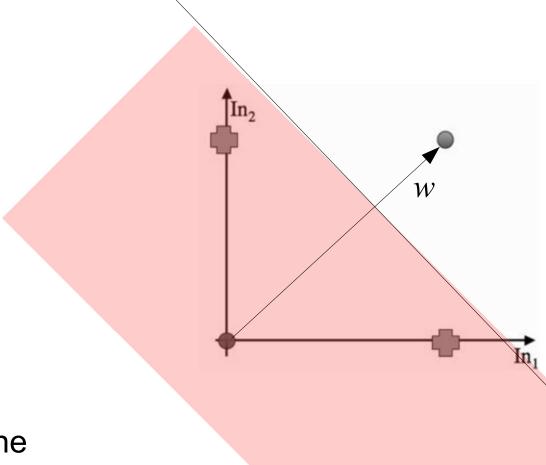
## Perceptron limitations



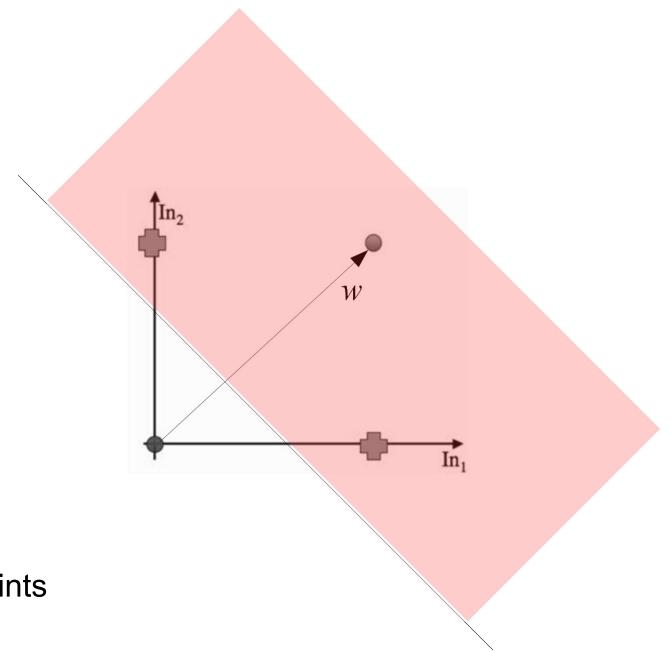


## Multi-layer Perceptron (MLP)

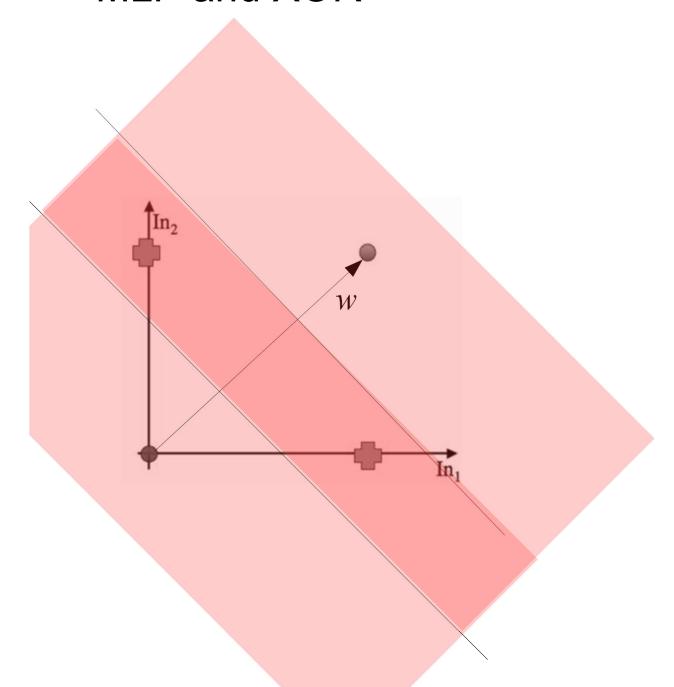




Choose a straight line that separates the points as in the figure, and whose corresponding perceptron returns 1 in the highlighted area



Now for the other points



Possible solution:

$$-x_1-x_2+2.5=0$$

$$w = \langle -1, -1 \rangle$$

$$x_1 + x_2 - 0.5 = 0$$

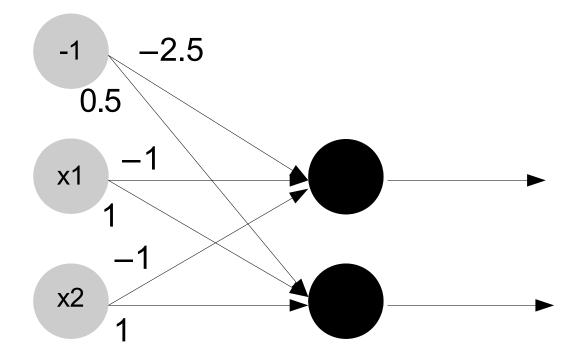
$$w = \langle 1, 1 \rangle$$

$$-x_1-x_2+2.5\ge 0$$

$$x_1 + x_2 - 0.5 \ge 0$$

These are 2 perceptrons with weights:

 $\langle 1, 1, 0.5 \rangle$ 

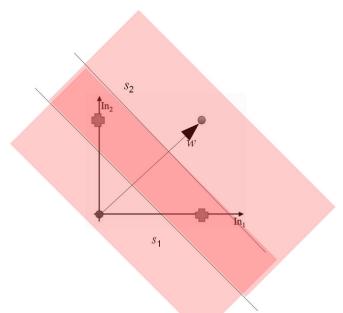


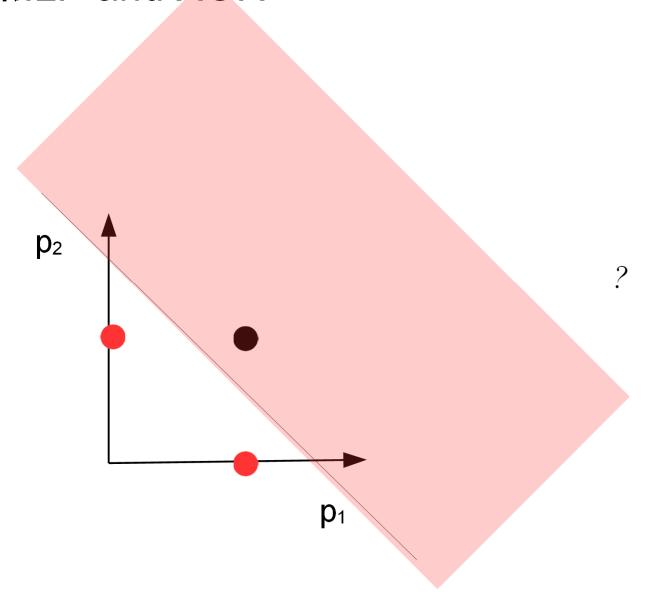
Their outputs are:

What	we	want
------	----	------

x1	x2	p1	p2	0
0	0	1	0	0
0	1	1	1	1
1	0	1	1	1
1	1	0	1	0

$$p_1 = -x_1 - x_2 + 2.5 \ge 0$$
$$p_2 = x_1 + x_2 - 0.5 \ge 0$$

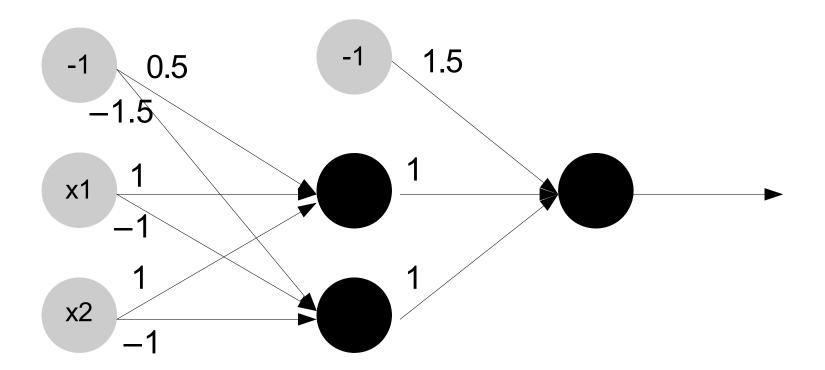




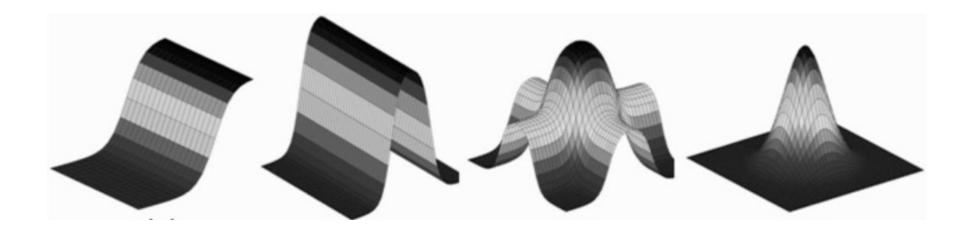
$$p_1 \equiv x_1 + x_2 - 0.5 \ge 0$$

$$p_2 \equiv -x_1 - x_2 + 1.5 \ge 0$$

$$o \equiv p_1 + p_2 - 1.5 \ge 0$$



## A Universal Approximator



$$g(x) = \sum_{j=1}^{N} w_{j} \sigma(y_{j}^{T} x + \theta_{j}) \qquad \text{given} \qquad q(x) \qquad \epsilon > 0$$

$$|g(x)-q(x)|<\epsilon$$

#### Error definition

$$E(X) = \sum_{x_n \in X} |y_n - t_n|$$

$$E_p(\boldsymbol{X}) = \sum_{\boldsymbol{x}_n \in \boldsymbol{X}} \boldsymbol{w}^T \boldsymbol{x}_n (y_n - t_n)$$

$$E_m(X) = \frac{1}{2} \sum_{x_n \in X} (y_n - t_n)^2$$

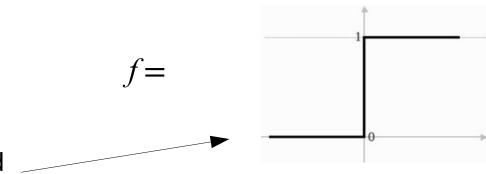
$$y = f\left(\sum_{i=1}^{M} w_i x_i\right)$$

Number of errors on the training set

The Perceptron error

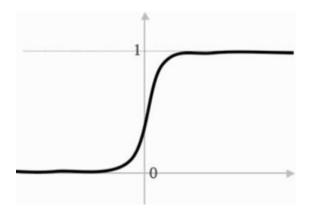
Squared error function (differentiable!)
Usually known as the Mean Squared Error (MSE)

Output is differentiable if f is



Not good

#### A different activation function



The sigmoid function: 
$$f(x) = \frac{1}{1 + e^{-\beta x}} \equiv \sigma_{\beta}$$

$$\sigma_{\beta}'(x)=?$$

## The derivative of the sigmoid

The sigmoid function: 
$$f(x) = \frac{1}{1 + e^{-\beta x}} \equiv \sigma_{\beta}$$

$$\sigma_{\beta}'(x) = ?$$

Two useful properties of derivatives:

$$f(x)=e^x \qquad f'(x)=e^x$$

Example:  $(e^{x^2})' = e^{x^2} \cdot 2x$ 

Chain rule:  $(f \circ g)'(x) = f'(g(x)) \cdot g'(x)$ 

Hint: 
$$\frac{1}{1+e^{-\beta x}} = (1+e^{-\beta x})^{-1}$$

#### The derivative of the sigmoid

The sigmoid function:  $f(x) = \frac{1}{1 + e^{-x}} \equiv \sigma$  where  $\beta = 1$  for simplicity

We derive the most external function first 
$$\sigma'(x) = ((1+e^{-x})^{-1})' = -1(1+e^{-x})^{-2} \cdot (1+e^{-x})' = -1(1+e^{-x})^{-2} \cdot (-x)' = -1(1+e^{-x})^{-2} \cdot e^{-x} \cdot (-1)$$
 and finally this one

$$\sigma'(x) = -1(1+e^{-x})^{-2} \cdot e^{-x} \cdot (-1) = \frac{e^{-x}}{(1+e^{-x})^2}$$

Let's note that:

$$1 - \sigma = 1 - \frac{1}{1 + e^{-x}} = \frac{1 + e^{-x} - 1}{1 + e^{-x}} = \frac{e^{-x}}{1 + e^{-x}} \Rightarrow \sigma' = \sigma(1 - \sigma)$$

## The same thing with β, FYI

The sigmoid function: 
$$h(x) = \frac{1}{1 + e^{-\beta x}} \equiv \sigma_{\beta}$$

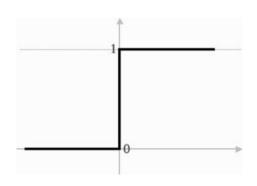
We derive the most external function first  $\sigma_{\beta}'(x) = ((1 + e^{-\beta x})^{-1})' = (1 + e^{-\beta x})^{-2} \cdot (1 + e^{-\beta x})' = (1 + e^$ Then this  $=-1(1+e^{-\beta x})^{-2} \cdot e^{-\beta x} \cdot (-\beta x)' = -1(1+e^{-\beta x})^{-2} \cdot e^{-\beta x} \cdot (-\beta)$ and finally this one

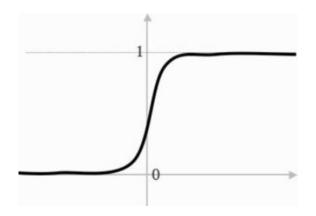
$$\sigma_{\beta}'(x) = -1 (1 + e^{-\beta x})^{-2} \cdot e^{-\beta x} \cdot (-\beta) = \frac{\beta e^{-\beta x}}{(1 + e^{-\beta x})^2}$$

Let's note that:

$$1 - \sigma_{\beta} = 1 - \frac{1}{1 + e^{-\beta x}} = \frac{1 + e^{-\beta x} - 1}{1 + e^{-\beta x}} = \frac{e^{-\beta x}}{1 + e^{-\beta x}} \Rightarrow \sigma_{\beta}' = \beta \sigma_{\beta} (1 - \sigma_{\beta})$$

#### A different activation function





before

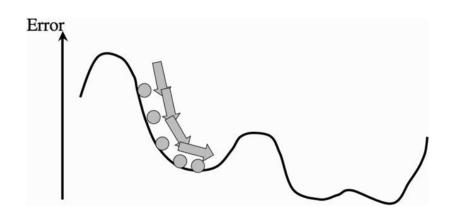
$$y(\mathbf{w}^T \mathbf{x}) = \begin{cases} 1 & \text{if } \mathbf{w}^T \mathbf{x} > 0 \\ 0 & \text{if } \mathbf{w}^T \mathbf{x} \le 0 \end{cases}$$

after

$$y(\mathbf{w}^T \mathbf{x}) = \frac{1}{1 + e^{-\beta \mathbf{w}^T \mathbf{x}}}$$

$$\sigma_{\beta}'(x) = \beta \frac{e^{-\beta x}}{(1 + e^{-\beta x})^2} = \beta \sigma_{\beta}(x)(1 - \sigma_{\beta}(x))$$

## Gradient descent (again)



$$\mathbf{w}_{t+1} = \mathbf{w}_t - \eta \nabla E(\mathbf{x})$$

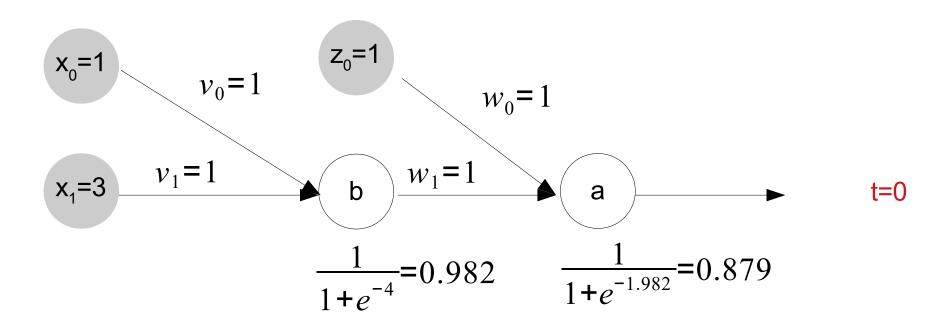
Perceptron

$$E_p(X) = \sum_{x_n \in X} \mathbf{w}^t x_n (y_n - t_n)$$

Multi-Layer P

$$E_m(\mathbf{X}) = \frac{1}{2} \sum_{\mathbf{x}_n \in \mathbf{X}} (y_n - t_n)^2$$

$$\mathbf{w}_{t+1} = \mathbf{w}_t - \eta \mathbf{x} (y-t)$$



$$x_{0}=1$$

$$x_{1}=3$$

$$v_{0}=1$$

$$v_{0}=1$$

$$v_{0}=1$$

$$b$$

$$w_{0}=1$$

$$a$$

$$b = v_{0} x_{0} + v_{1} x$$

$$z_{1}=\sigma(b) \quad a=w_{0} z_{0} + w_{1} z_{1} \quad y=\sigma(a)$$

$$\frac{\partial E}{\partial w_{0}} = \frac{\partial E}{\partial a} \frac{\partial a}{\partial w_{0}}$$

$$chain rule$$

$$\frac{\partial E}{\partial a} = \frac{\partial}{\partial a} \frac{1}{2} (\sigma(a) - t)^2 = (\sigma(a) - t) \cdot \sigma(a) (1 - \sigma(a))$$

$$\frac{\partial a}{\partial w_0} = \frac{\partial}{\partial w_0} w_0 z_0 + w_1 z = z_0$$

$$\frac{\partial E}{\partial w_0} = (y - t)y(1 - y)z_0$$

$$\frac{\partial E}{\partial w_1} = (y - t)y(1 - y)z_1$$

$$x_{0}=1$$

$$x_{1}=3$$

$$v_{0}=1$$

$$b$$

$$b=v_{0} x_{0}+v_{1}x \qquad z_{1}=\sigma(b) \qquad a=w_{0} z_{0}+w_{1}z_{1} \qquad y=\sigma(a)$$

$$a=w_{0} z_{0}+w_{1}\sigma(b)$$

$$\frac{\partial E}{\partial v_{0}}=\frac{\partial E}{\partial a}\frac{\partial a}{\partial b}\frac{\partial b}{\partial v_{0}} \qquad \frac{\partial E}{\partial a}=(y-t)y(1-y) \quad \text{from before}$$

$$\frac{\partial a}{\partial b}=\frac{\partial}{\partial b}w_{0}z_{0}+w_{1}\sigma(b)=w_{1}\sigma(b)(1-\sigma(b))=w_{1}z_{1}(1-z_{1})$$

$$\frac{\partial}{\partial v_{0}}v_{0}x_{0}+v_{1}x_{1}=x_{0}$$

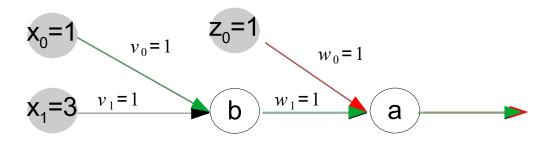
$$\frac{\partial E}{\partial v_{0}}=(y-t)y(1-y)w_{1}z_{1}(1-z_{1})x_{0}$$

$$\frac{\partial E}{\partial v_{1}}=(y-t)y(1-y)w_{1}z_{1}(1-z_{1})x_{1}$$

$$x_0=1$$
 $v_0=1$ 
 $v_0=$ 

$$\nabla E = \begin{bmatrix} \frac{\partial E}{\partial w_0} \\ \frac{\partial E}{\partial w_1} \\ \frac{\partial E}{\partial v_0} \\ \frac{\partial E}{\partial v_1} \end{bmatrix} = \begin{bmatrix} (y-t)y(1-y)z_0 \\ (y-t)y(1-y)z_1 \\ (y-t)y(1-y)w_1z_1(1-z_1)x_0 \\ (y-t)y(1-y)w_1z_1(1-z_1)x_1 \end{bmatrix} \nabla E(\mathbf{w}) = \begin{bmatrix} 0.09 \\ 0.09 \\ 0.002 \\ 0.002 \end{bmatrix}$$

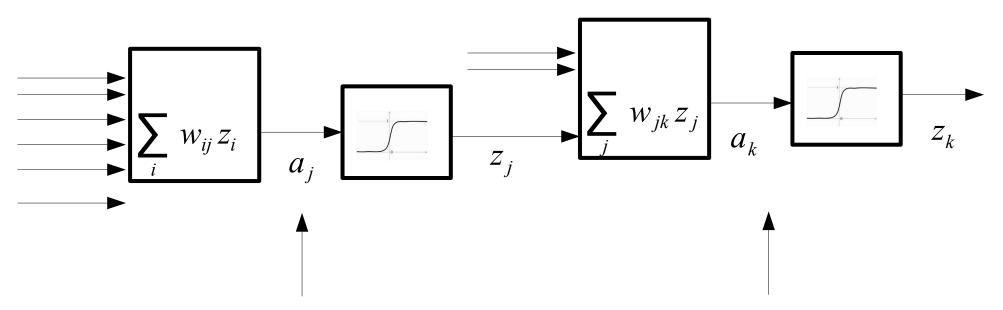
### Summary



$$\frac{\partial E}{\partial w_0} = \frac{\partial E}{\partial a} \frac{\partial a}{\partial w_0}$$

$$\frac{\partial E}{\partial v_0} = \frac{\partial E}{\partial a} \frac{\partial a}{\partial b} \frac{\partial b}{\partial v_0}$$

## Backpropagation of errors, notation

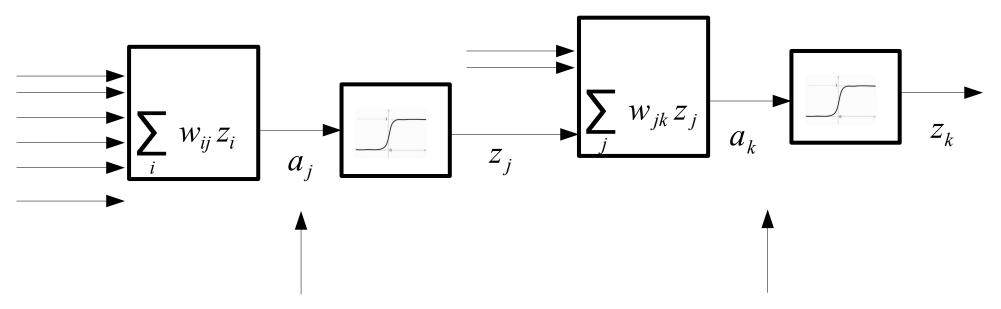


Neuron j is a hidden neuron

Neuron k is an **output** neuron

... 
$$a_j = \sum_{i=1}^{N} w_{ij} z_i$$
  $z_j = f(a_j)$   $a_k = \sum_{j=1}^{M} w_{jk} z_j$   $z_k = f(a_k)$ 

## Forward pass



Neuron j is a **hidden** neuron

Neuron k is an **output** neuron

... 
$$a_j = \sum_{i=1}^{N} w_{ij} z_i$$
  $z_j = f(a_j)$   $a_k = \sum_{j=1}^{M} w_{jk} z_j$   $z_k = f(a_k)$ 

Forward pass: compute all the z

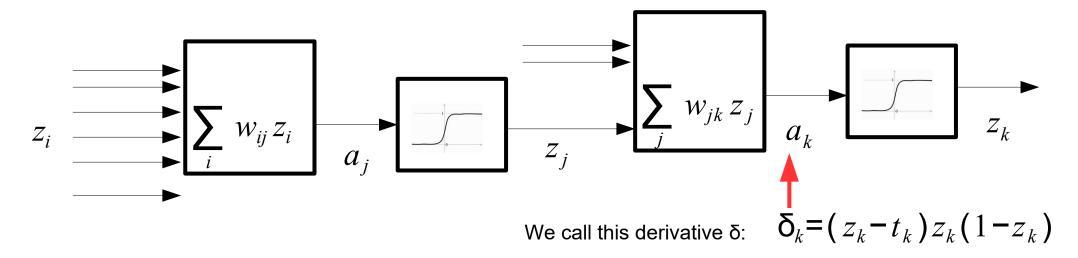
## Backward pass, output neuron

How does ak affect the error?

$$E(\mathbf{x}) = \frac{1}{2} (y-t)^2 = \frac{1}{2} (z_k - t)^2$$

$$\frac{\partial E}{\partial a_k} = \frac{\partial}{\partial a_k} \frac{1}{2} (z_k - t_k)^2 = \frac{\partial}{\partial a_k} \frac{1}{2} (\sigma(a_k) - t_k)^2 = (\sigma(a_k) - t_k) \sigma(a_k) (1 - \sigma(a_k))$$

Now this useful, because it cancels out the exponent in the derivation



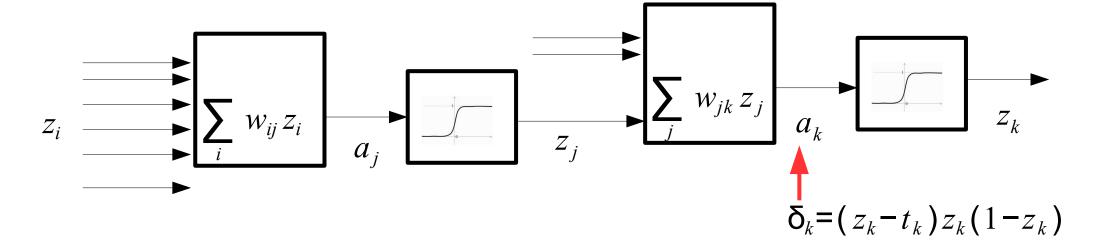
## Backward pass, output neuron

One step backward, inside the box: how does w<sub>jk</sub> affect the error?

$$E(x) = \frac{1}{2} (z_k - t)^2 = \frac{1}{2} (\sigma(a_k) - t)^2 \qquad a_k = \sum_j w_{jk} z_j$$

We apply the chain rule again:  $\frac{\partial E}{\partial w_{jk}} = \frac{\partial E}{\partial a_k} \frac{\partial a_k}{\partial w_{jk}} = \delta_k ?$ 

$$\frac{\partial a_k}{\partial w_{jk}} = \frac{\partial}{\partial w_{jk}} w_{0k} z_0 + w_{1k} z_1 + w_{2k} z_2 + \dots + w_{jk} z_j = ?$$



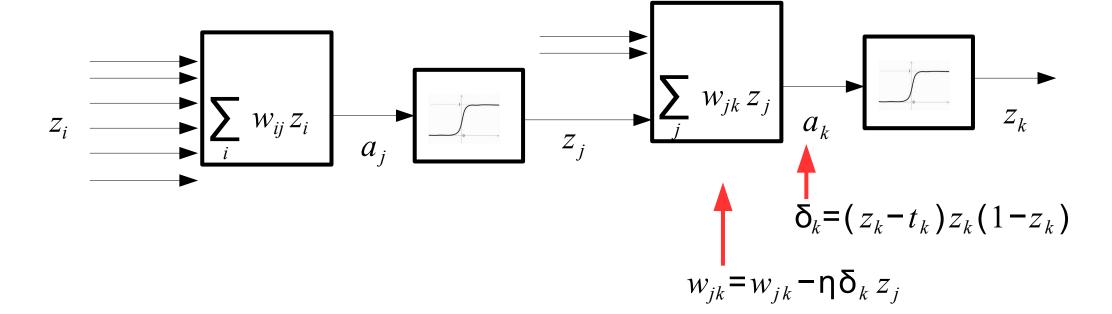
## Backward pass, output neuron

One step backward, inside the box: how does w<sub>jk</sub> affect the error?

We apply the chain rule again:

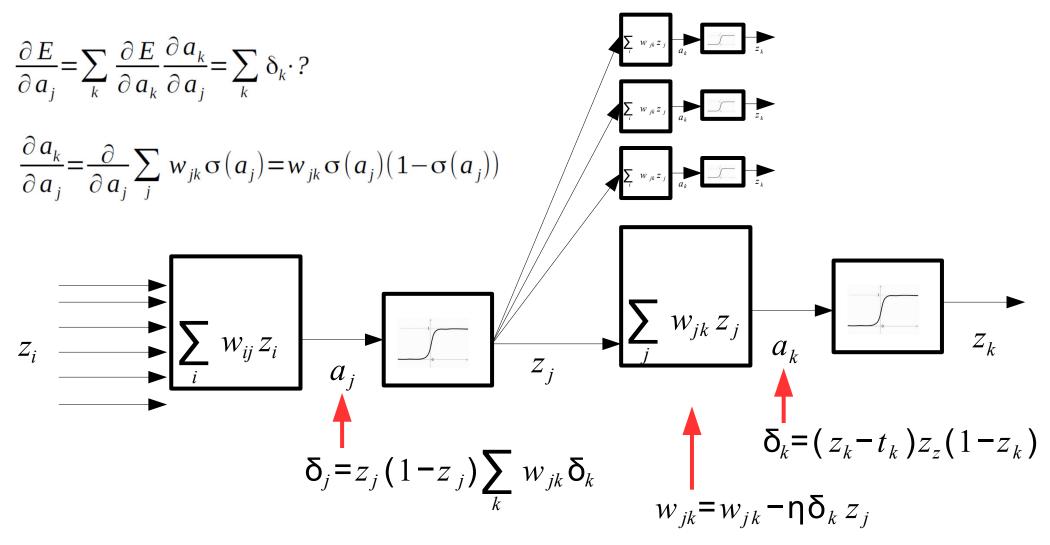
$$\frac{\partial E}{\partial w_{jk}} = \frac{\partial E}{\partial a_k} \frac{\partial a_k}{\partial w_{jk}} = \delta_k z_j$$

$$\frac{\partial a_k}{\partial w_{jk}} = \frac{\partial}{\partial w_{jk}} w_{0k} z_0 + w_{1k} z_1 + w_{2k} z_2 + \dots + w_{jk} z_j = z_j$$



## Backward pass, hidden neuron

One step backward: how does a<sub>j</sub> affect the error?



## Computing delta

One step backward, inside the box: how does w<sub>ij</sub> affect the error?

$$\frac{\partial E}{\partial w_{ij}} = \frac{\partial E}{\partial a_{j}} \frac{\partial a_{j}}{\partial w_{ij}} = \delta_{j} ?$$

$$\frac{\partial a_{j}}{\partial w_{ij}} = \frac{\partial}{\partial w_{ij}} \sum_{i} w_{ij} z_{i} = ?$$

$$\sum_{i} w_{ij} z_{i}$$

$$\delta_{j} = z_{j} (1 - z_{j}) \sum_{k} w_{jk} \delta_{k}$$

$$w_{jk} = w_{jk} - \eta \delta_{k} z_{j}$$

## Computing delta

One step backward, inside the box: how does w<sub>ij</sub> affect the error?

$$\frac{\partial E}{\partial w_{ij}} = \frac{\partial E}{\partial a_{j}} \frac{\partial a_{j}}{\partial w_{ij}} = \delta_{j} z_{i}$$

$$\frac{\partial a_{j}}{\partial w_{ij}} = \frac{\partial}{\partial w_{ij}} \sum_{i} w_{ij} z_{i} = z_{i}$$

$$\sum_{i} w_{ij} z_{i}$$

$$\delta_{j} = z_{j} (1 - z_{j}) \sum_{k} w_{jk} \delta_{k}$$

$$w_{ij} = w_{ij} - \eta \delta_{j} z_{i}$$

$$\sum_{i} w_{jk} z_{j}$$

$$\delta_{k} = (z_{k} - t_{k}) z_{j} (1 - z_{k})$$

## Gradient descent (again)

$$\boldsymbol{w}_{t+1} = \boldsymbol{w}_t - \eta \nabla E(\boldsymbol{x})$$

Perceptron

$$E_p(\mathbf{X}) = \sum_{\mathbf{x}_n \in \mathbf{X}} \mathbf{w}^t \mathbf{x}_n (y_n - t_n)$$

$$\boldsymbol{w}_{t+1} = \boldsymbol{w}_t - \eta (y - t) \boldsymbol{x}$$

Multi-Layer P

$$E_m(\mathbf{X}) = \frac{1}{2} \sum_{\mathbf{x}_n \in \mathbf{X}} (y_n - t_n)^2$$

Output:

$$\delta_{\text{output}} = (y - t)y(1 - y)$$

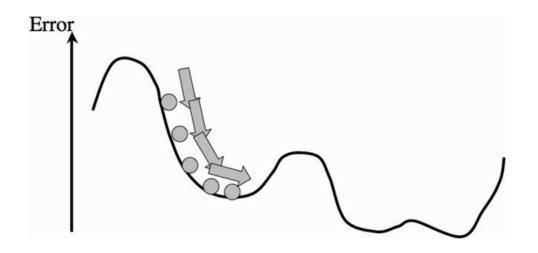
$$\boldsymbol{w}_{t+1} = \boldsymbol{w}_t - \eta \delta_{\text{output}} \boldsymbol{x}$$

Hidden:

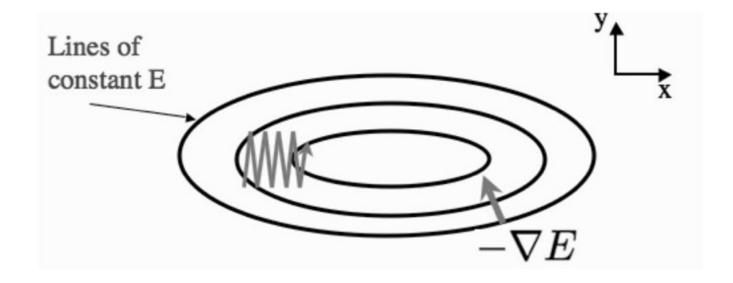
$$\delta_{\text{hidden}} = \sum_{k} w_{k} \delta_{k}$$

$$\boldsymbol{v}_{t+1} = \boldsymbol{v}_t - \eta \delta_{\text{hidden}} \boldsymbol{x}$$

#### **Local Minima**



Start with weights close to 0: where the decision is actually made



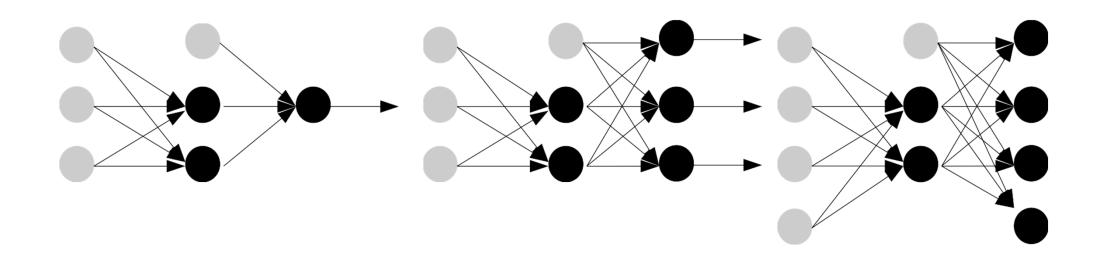
Multiple random restarts

#### Using MLPs

Regression

Classification

Compression (Autoencoder)



Last neuron linear

One output per class, pick highest

Middle "bottleneck" layer

## Training "recipe"

#### Choose features

Normalize (rescale) data:

$$x' = \frac{x - \overline{x}}{\sigma}$$
 or

$$x' = \frac{x - \overline{x}}{\sigma}$$
 or  $x' = \frac{x - min(x)}{max(x) - min(x)}$ 

in [0,1]

Zero mean, unit variance

Create training, validation, and test sets

Decide whether you need hidden layers and how big. Try several ones.

Train

**Test** 

## Deep learning

