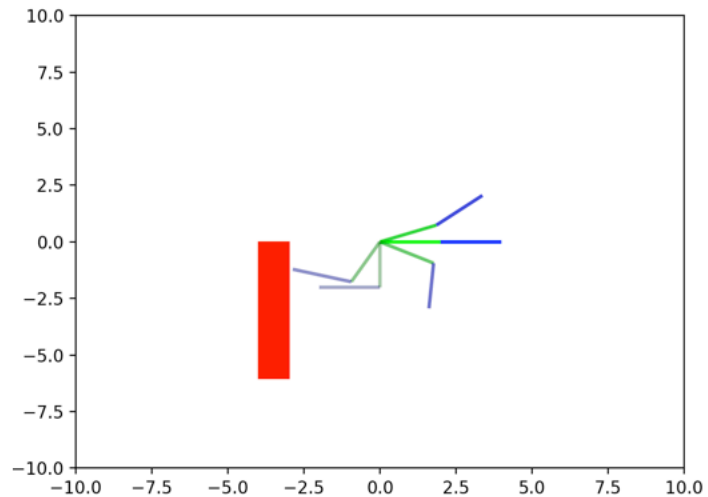
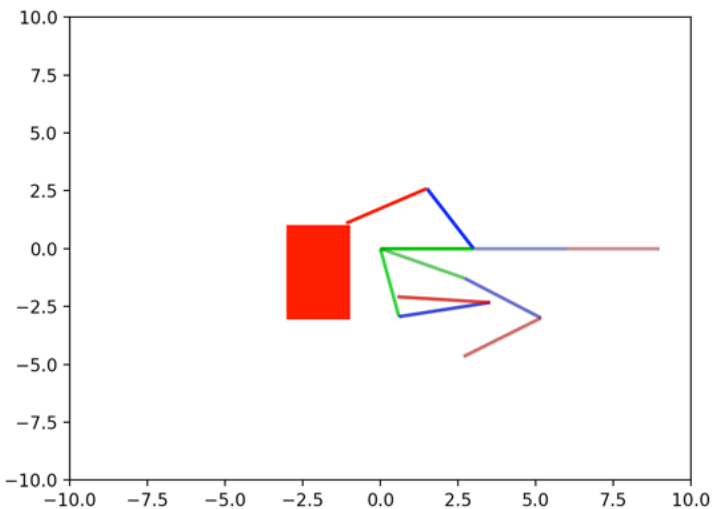


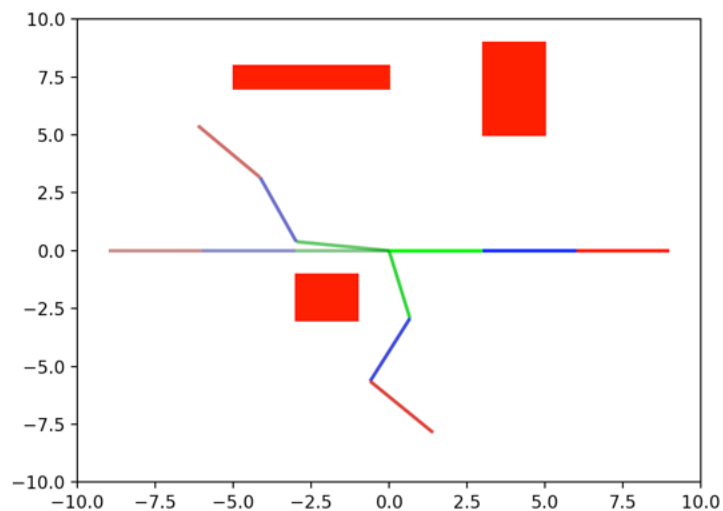
Robot arm motion for 2 arm segments



Robot arm motion for 2 arm segments



Robot arm motion for 3 arm segments



Robot arm motion for 3 arm segments