Santino Galati, Daniel Fleming, Frank Figueroa

Professor Eckert

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CS-104

Algorithm

1. Start Robot
2. Input robot color to “Green”
3. Input speech “Ready set go”
4. Input robot movement roll 0 degrees degrees at speed “60” for 10 seconds
5. Input spin 90 degrees for 1 second
6. Input robot movement roll 0 degrees degrees at speed “60” for 6 seconds
7. Input spin 90 degrees for 1 second
8. Input robot movement roll 0 degrees degrees at speed “60” for 10 seconds
9. Input spin 90 degrees for 1 second
10. Input robot movement roll 0 degrees degrees at speed “60” for 6 seconds
11. Input spin 90 degrees for 1 second
12. Input robot color to “Red”
13. Input speech “Im done and I need water”
14. End program