

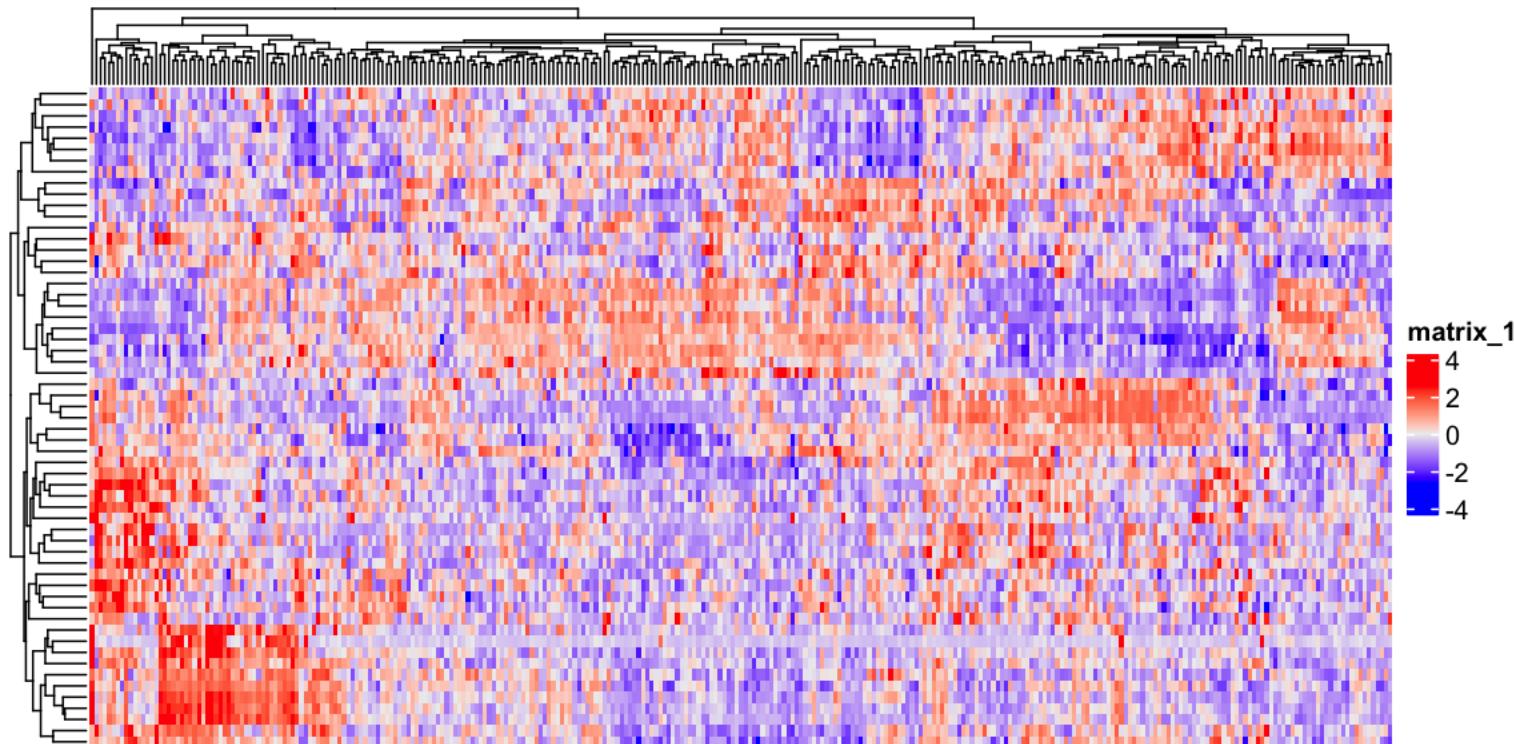
L8

Dimensionality Reduction & Data Visualization

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Heatmap



Heatmap

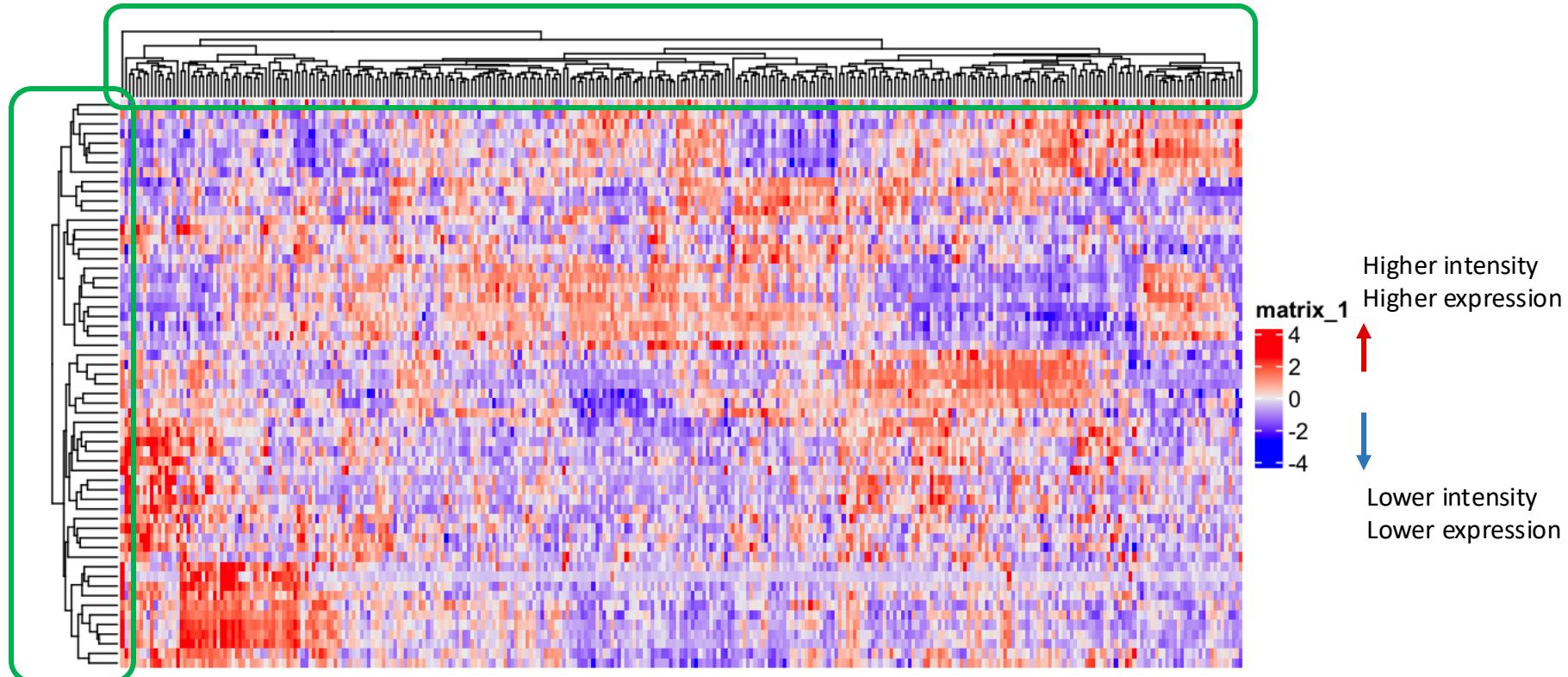
- Gene expression data are 2D matrix
 - Rows are genes/features and columns are observations/samples.
 - Note: this is the opposite of conventional data representation
- Gene expression data are often visualized in heatmap
 - Data are often normalized across rows (=genes) or columns (=samples) to highlight the difference across samples or genes.
- Available R Packages:
 - ComplexHeatmap
 - pheatmap

Heatmap

- Display the expression of many genes across many samples
- Often used together with hierarchical clustering to reveal expression patterns
 - Row-wise clustering to group genes with similar expression patterns
 - Column-wise clustering to group samples with similar expression patterns
- Color and intensity of tiles represent gene expression, often changes of gene expression

Heatmap

Column-wise hierarchical clustering (samples)



Challenges in RNAseq Data Visualization

- High dimensionality: >10,000 features (genes)
- Dimensionality reduction can help reduce computational complexity but still retain most of underlying structure in the data

Dimensionality Reduction

- What is the objective?
 - Choose an optimum set of features d^* of lower dimensionality with most of underlying structure in the data retained
 - Data with reduced dimensionality can be used for visualization and discovery of underlying patterns/structure
- Different methods can be used to reduce dimensionality:
 - Feature extraction
 - Feature selection

Dimensionality Reduction (cont'd)

Feature extraction: computes a new set of features from the **original** features through some transformation f().

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \cdot \\ \cdot \\ \cdot \\ \cdot \\ \cdot \\ x_D \end{bmatrix} \xrightarrow{f(\mathbf{x})} \mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \\ \cdot \\ \cdot \\ \cdot \\ y_K \end{bmatrix}$$

K << D

f() could be linear or non-linear

Feature selection: chooses a subset of the **original** features.

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \cdot \\ \cdot \\ \cdot \\ \cdot \\ x_D \end{bmatrix} \rightarrow \mathbf{y} = \begin{bmatrix} x_{i_1} \\ x_{i_2} \\ \cdot \\ \cdot \\ \cdot \\ x_{i_K} \end{bmatrix}$$

K << D

Feature Extraction

- **Linear** transformations are particularly attractive because they are simpler to compute and analytically tractable.
- Given $\mathbf{x} \in \mathbb{R}^D$, find an $K \times D$ matrix \mathbf{T} such that:

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ \cdot \\ \cdot \\ \cdot \\ \cdot \\ \cdot \\ x_D \end{bmatrix} \xrightarrow{\mathbf{T}, f(\mathbf{x})} \mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ \cdot \\ \cdot \\ \cdot \\ \cdot \\ y_K \end{bmatrix} \quad \mathbf{y} = \mathbf{T}\mathbf{x} \in \mathbb{R}^K \text{ where } K << D$$

This is a **projection** transformation from **D** dimensions to **K** dimensions.

Each new feature y_i is a **linear combination** of the original features x_j

Feature Extraction (cont'd)

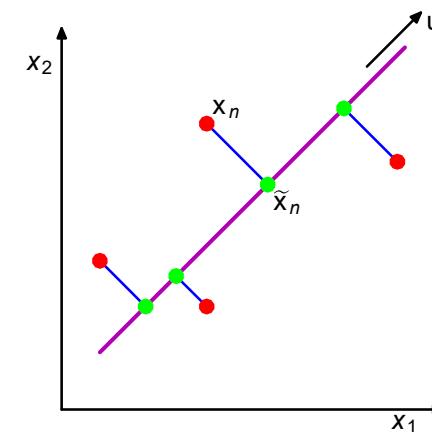
- From a mathematical point of view, finding an optimum mapping $y = f(x)$ can be formulated as an optimization problem (i.e., minimize or maximize an objective criterion).
- Commonly used objective criteria:
 - **Minimize Information Loss**: projection in the lower-dimensional space preserves as much information in the data as possible.
 - **Maximize Discriminatory Information**: projection in the lower-dimensional space increases class separability.

Feature Extraction (cont'd)

- Popular **linear** feature extraction methods:
 - **Principal Components Analysis (PCA)**: Seeks a projection that minimizes information loss.
 - **Linear Discriminant Analysis (LDA)**: Seeks a projection that maximizes discriminatory information.
- Many other methods:
 - Making features as independent as possible (**Independent Component Analysis**).
 - Retaining interesting directions (**Projection Pursuit**).
 - Embedding to lower dimensional manifolds (**Isomap, Locally Linear Embedding**).

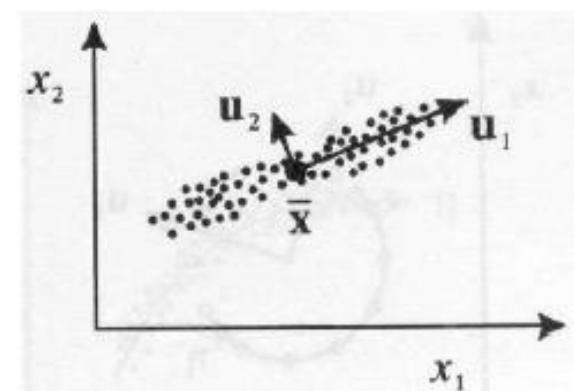
Principal Component Analysis

- PCA finds the linear subspace that
 - maximizes the explained variance
 - equivalently, minimizes the unexplained variance
- PCA can be applied to any multidimensional dataset
 - data do not have to be *Normally distributed*,
a.k.a., *Gaussian*



Principal Component Analysis

- PCA chooses the eigenvectors corresponding to the largest eigenvalues.
- The **eigenvalues** correspond to the **variance** of the data along the eigenvector directions.
- Therefore, PCA projects the data along the directions where the data varies **most**.
- PCA preserves as much **information** in the data by preserving as much **variance** in the data.



u_1 : direction of **max** variance

u_2 : orthogonal to u_1

How should we choose K ?

- K is typically chosen based on how much **information (variance)** we want to preserve in the data:

Choose the **smallest** K that satisfies the following inequality:

$$\frac{\sum_i^K \lambda_i}{\sum_i^D \lambda_i} > T \text{ where } T \text{ is a threshold (e.g. 0.9)}$$

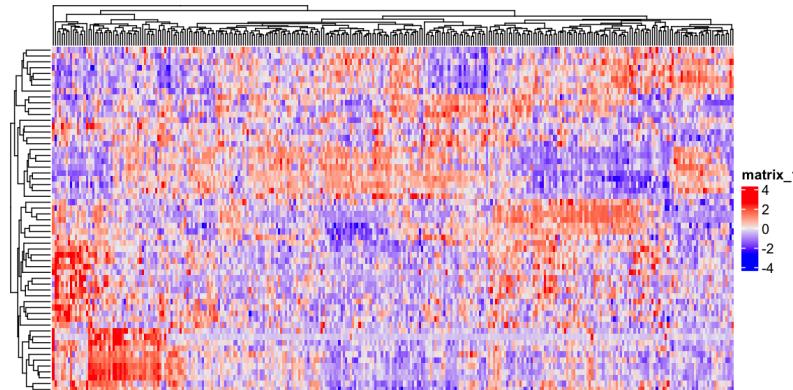
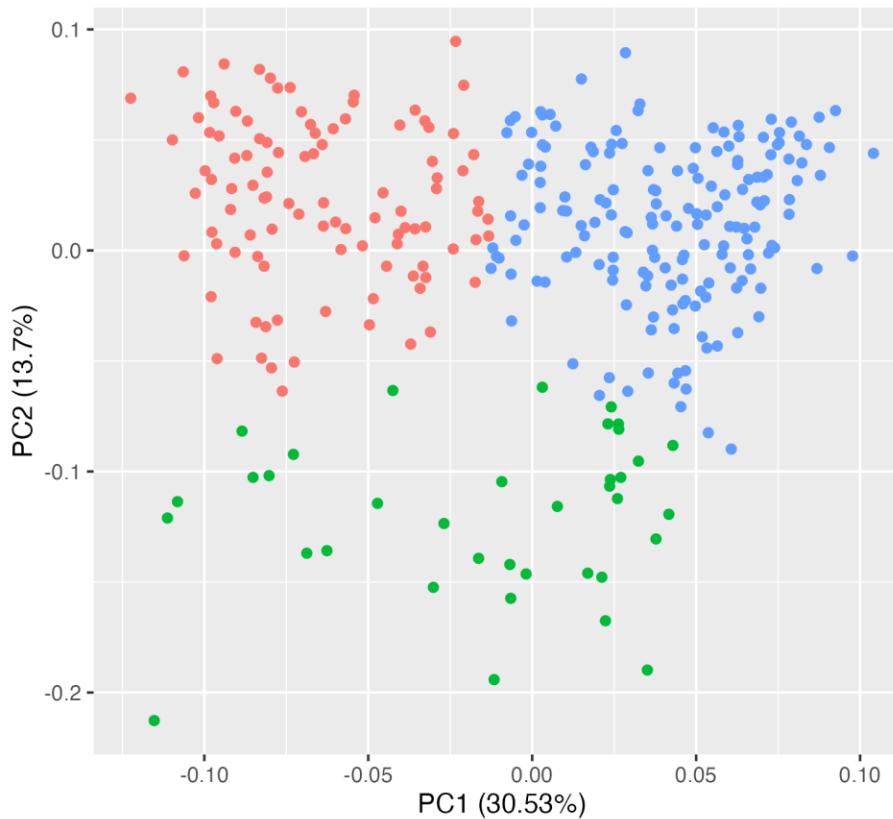
- If $T = 0.9$, for example, K is chosen to “**preserve**” 90% of the information (variance) in the data.
- If $K = D$, then we “**preserve**” 100% of the information in the data (i.e., just a “**change**” of basis and $\hat{\mathbf{x}} = \mathbf{x}$)

PCA plot for Gene Expression Data

- K (dimensionality) is typically set to 2 for visualization purpose
- However, for down-stream analysis, for example, to perform clustering analysis, it is set to retain the variability of the data as much as possible.

PCA: Example

PCA plot (CPM)



cluster



Other applications of PCA

- PCA reduces the dimensionality of the input space, hence, reducing the number of parameters that must be learned for classification or regression.
- This will help to reduce overlearning.
- However, there are other applications of PCA

Standardization

- Input vectors are often heterogeneous in that values might vary widely on some dimensions relative to others.
- This is particularly true when input vectors are composed of different kinds of measurements, perhaps measured in different units.
- Example:
 - We may try to classify a patient in a hospital setting based upon:
 - Age (years)
 - Resting pulse (beats per minute)
 - Body temperature (degrees Celsius)
 - ...
- For pattern recognition algorithms to work well, it is often important that the data be standardized along these different dimensions.

Pre-Whitening - decorrelation

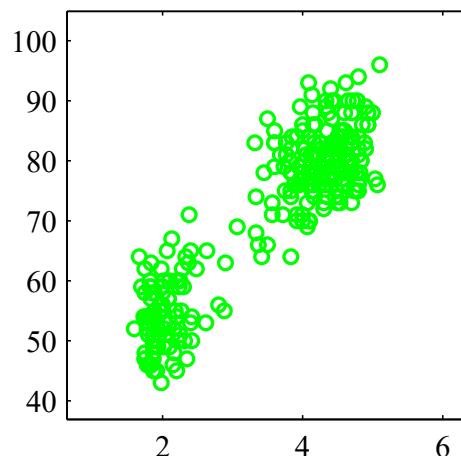
- Let U be the $D \times D$ matrix whose columns are the D orthonormal eigenvectors \mathbf{u}_i of \mathbf{S} .
- Let Λ be the $D \times D$ diagonal matrix whose diagonal elements Λ_{ii} are the associated eigenvalues λ_i .
- Then the transformation

$$\mathbf{y}_n = \Lambda^{-\frac{1}{2}} U^t (\mathbf{x}_n - \bar{\mathbf{x}})$$

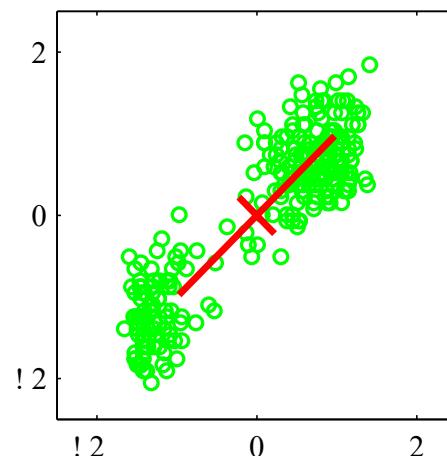
does three things:

- Shifts the data to the origin, so that the transformed data have zero mean.
- Rotates the data into the principal axes, **decorrelating the data** (diagonal covariance)
- Scales the data by the inverse standard deviation along each principal axis, thus normalizing the variance in all directions (covariance = identity matrix).

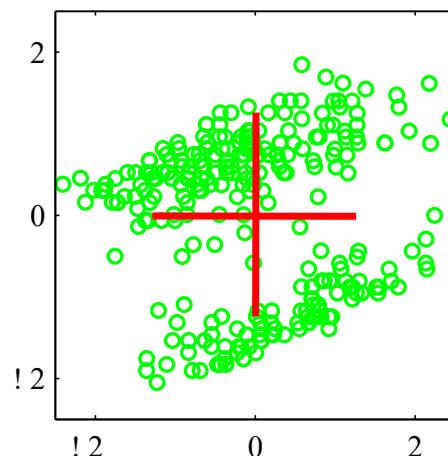
Pre-Whitening



Original Data



Normalized to 0-mean
and unit variances (z-scores)



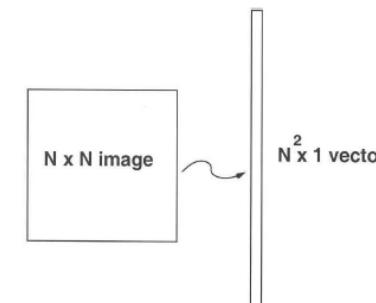
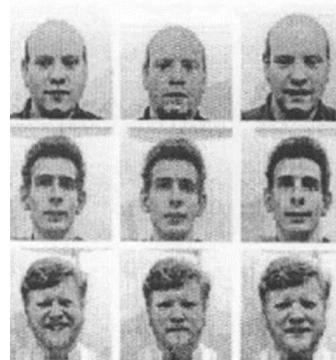
Whitened
(unit covariance)

$$y_i = \frac{x_i - \bar{x}_i}{\sigma_i}$$

$$\mathbf{y}_n = \mathbf{\Sigma}^{1/2} U^T (\mathbf{x}_n - \bar{\mathbf{x}})$$

Application to Images

- **Goal:** represent images in a space of lower dimensionality using PCA.
 - Useful for various applications, e.g., face recognition, image compression, etc.
- Given **M** images of size **N x N**, first represent each image as an $N^2 \times 1$ 1D vector (i.e., by stacking the rows together).



number of
features:

$$D=N^2$$

Example

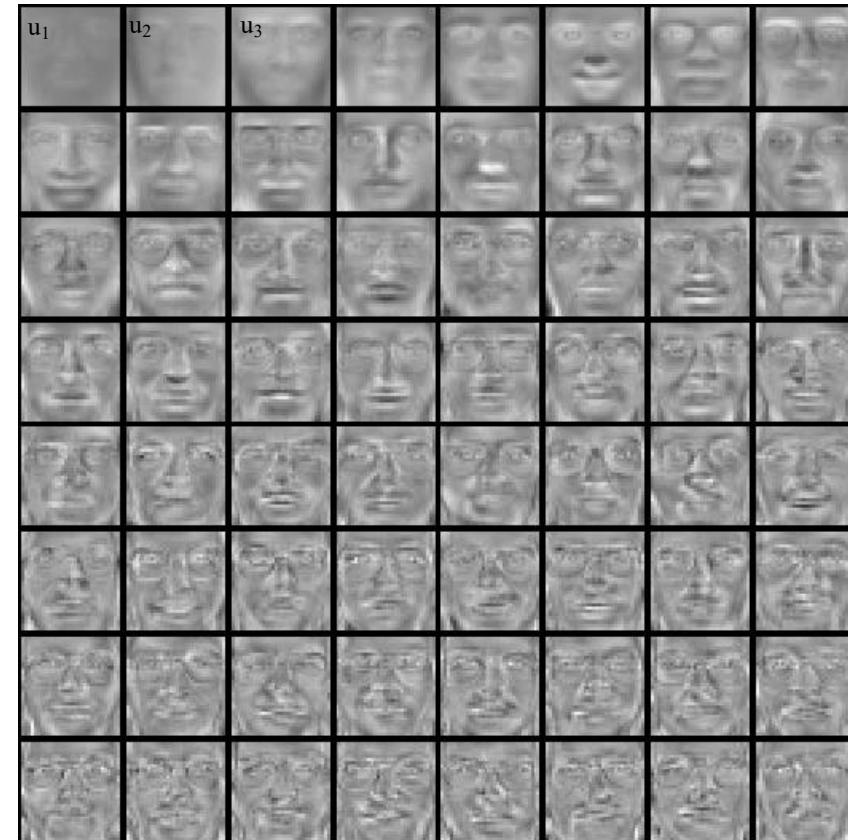
Dataset



Example (cont'd)

K largest eigenvectors: u_1, \dots, u_K
(visualized as images – called “eigenfaces”)

Mean face: \bar{x}



Application to Images (cont'd)

- **Interpretation:** approximate a face image using eigenfaces

K largest eigenvectors: u_1, \dots, u_K (basis vectors)



$$\hat{\mathbf{x}} = \sum_{i=1}^K y_i u_i = y_1 u_1 + y_2 u_2 + \dots + y_K u_K + \bar{\mathbf{x}}$$

eigen-coefficients



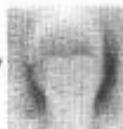
$$= 0.9571 *$$



$$- 0.1945 *$$



$$+ 0.0461 *$$



$$0.0586 *$$

$$+ \dots + \bar{\mathbf{x}}$$

$$\hat{\mathbf{x}} - \bar{\mathbf{x}} : \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_K \end{bmatrix}$$