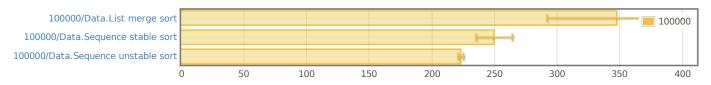
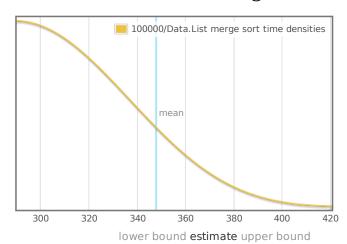
criterion performance measurements

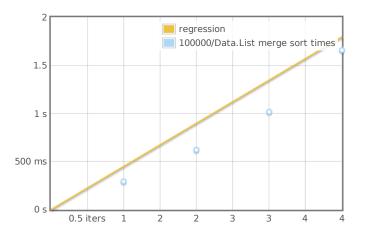
overview

want to understand this report?



100000/Data.List merge sort





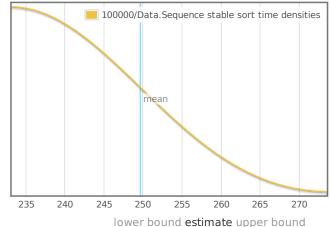
OLS regression 327 ms R² goodness-of-fit 0.965

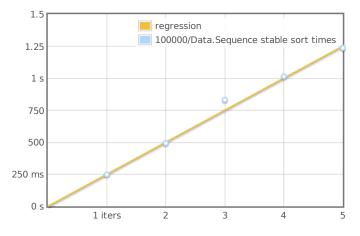
449 ms 641 ms 0.975 1.000 **348 ms** 384 ms

Mean execution time 301 ms Standard deviation 0 s 55.9 ms 62.7 ms

Outlying measurements have moderate (46.2%) effect on estimated standard deviation.

100000/Data. Sequence stable sort





OLS regression R² goodness-of-fit Mean execution time 240 ms

Standard deviation 3.94 ms

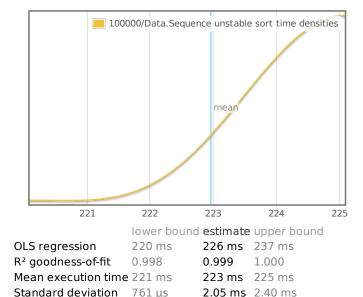
201 ms 0.969

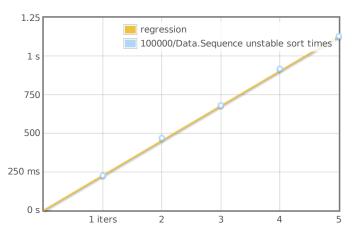
250 ms 292 ms 0.991 1.000

250 ms 263 ms 14.5 ms 19.4 ms

Outlying measurements have moderate (16.3%) effect on estimated standard deviation.

100000/Data. Sequence unstable sort





Outlying measurements have moderate (16.0%) effect on estimated standard deviation.

understanding this report

In this report, each function benchmarked by criterion is assigned a section of its own. The charts in each section are active; if you hover your mouse over data points and annotations, you will see more details.

- The chart on the left is a kernel density estimate (also known as a KDE) of time measurements. This graphs the probability of any
 given time measurement occurring. A spike indicates that a measurement of a particular time occurred; its height indicates how
 often that measurement was repeated.
- The chart on the right is the raw data from which the kernel density estimate is built. The x axis indicates the number of loop iterations, while the y axis shows measured execution time for the given number of loop iterations. The line behind the values is the linear regression prediction of execution time for a given number of iterations. Ideally, all measurements will be on (or very near) this line.

Under the charts is a small table. The first two rows are the results of a linear regression run on the measurements displayed in the right-hand chart.

- OLS regression indicates the time estimated for a single loop iteration using an ordinary least-squares regression model. This
 number is more accurate than the mean estimate below it, as it more effectively eliminates measurement overhead and other
 constant factors.
- R² goodness-of-fit is a measure of how accurately the linear regression model fits the observed measurements. If the measurements are not too noisy, R² should lie between 0.99 and 1, indicating an excellent fit. If the number is below 0.99, something is confounding the accuracy of the linear model.
- Mean execution time and standard deviation are statistics calculated from execution time divided by number of iterations.

We use a statistical technique called the bootstrap to provide confidence intervals on our estimates. The bootstrap-derived upper and lower bounds on estimates let you see how accurate we believe those estimates to be. (Hover the mouse over the table headers to see the confidence levels.)

A noisy benchmarking environment can cause some or many measurements to fall far from the mean. These outlying measurements can have a significant inflationary effect on the estimate of the standard deviation. We calculate and display an estimate of the extent to which the standard deviation has been inflated by outliers.

соторнон

This report was created using the <u>criterion</u> benchmark execution and performance analysis tool.

Criterion is developed and maintained by <u>Bryan O'Sullivan</u>.