# Frank Zhou

1200 E California Blvd, Pasadena, California 91126 frank.li.zhou@gmail.com • (781) 535-4909 • http://franklizhou.github.io

#### **EDUCATION**

### Caltech, Pasadena, California

■ Bachelor of Science (B.S.) in Electrical Engineering

Oct 2013 - Jun 2017

- Cumulative GPA: 3.9 / 4.0
- Embedded Systems, Digital Design (FPGA), Analog Design, RF Design, Machine Learning, Circuits, Signals, Control Systems, Semiconductor Devices, Biodevices, Electromagnetic Engineering, Mechatronic Design

### WORK EXPERIENCE

#### Caltech, Pasadena, California

Undergraduate Research Fellow

Jan 2016 - Present

- Redesigned wireless feedback for wireless power transfer system under Professor Ali Hajimiri
- Designed receiver controller capable of transmitting data, load switching, and charging USB devices
- · Designed generator controller capable of receiving data, communicating over SPI, and optimizing power transfer
- Implemented protocols and designed algorithms to quickly optimize power transfer regardless of the receiver's location

■ Teaching Assistant

Oct 2015 - Present

- Taught undergraduate students about software and hardware design for microprocessor systems
- Topics include x86 assembly, schematic drawing, PCB design, timing analysis, hardware design, debugging, and soldering

### Honeybee Robotics, Pasadena, California

Electrical Engineering Intern

Feb 2015 - Oct 2015

- Designed and implemented electrical systems on various robotic systems intended for extraterrestrial sample collection
- Worked on electrical schematics, electrical assembly, PCB design and fabrication, and PLC design

### Jet Propulsion Lab, Pasadena, California

Undergraduate Research Fellow

Jun 2014 – Aug 2014

- Wrote Python scripts that parse the Curiosity Rover's telemetry data and automatically generate photorealistic animations in Blender
- Implemented a GUI for an application that reduces meshes of 2.5D objects to create models of Martian terrain (C++)

# PROJECTS

### Caltech Robotics Team, Electrical Subteam Lead

Oct 2013 - Present

- · Team designs and builds a new underwater autonomous vehicle to navigate an obstacle course each year
- Won 1st place out of over 50 teams at the International AUVSI Underwater Vehicle Competition in 2016
- Designed entire electrical architecture from scratch to power all devices and to establish communication between computer and sensors/actuators
- · Used a CAN bus communication network to pass messages between different ARM microcontroller modules

### **Acoustic Communication System**

Sep 2016 – Dec 2016

- Designed a system with ARM microcontrollers to facilitate communication between two computers through acoustic pings
- Microcontroller simultaneously samples the filtered outputs of four microphones and analyzes the phase differences between the signals at a specific frequency to calculate the 3D direction of the sound
- System reports direction of sound to the computer as a unit vector through RS232 connection

### **Blackfin MP3 Player**

Jan 2015 - Jul 2015

- Created a fully functional MP3 player controlled by a Blackfin microprocessor
- Fully designed schematics for microprocessor, display, keypad, audio, IDE, DRAM, SRAM, and ROM sections and designed PCB
- · Wrote firmware for the completed system in C and assembly

# **Power Grid Visualization**, Electrical Lead

Dec 2014 - Mar 2015

- Visualized research on the optimization of distributed power networks under Professor Steven Low
- Constructed an LED table of 150 individually addressable LEDs that change colors based on the time varying nodal voltages of a real power network
- Presented work at the 2015 ARPA-E Energy Summit

### Caltech ME72 Design Competition, Electrical Lead

Sep 2015 – Mar 2016

- Designed three teleoperated robots capable of gathering and shooting soccer balls for Caltech design course
- Implemented control system using gamepads, Teensy microprocessors, and XBee radios

### **SKILLS** Electrical

- Schematic and PCB design using Altium
- Designing and debugging embedded systems
- Designing and debugging FPGA systems
- Debugging using test equipment (scope, logic analyzer, etc.)
- Soldering
- CAN, RS232, TTL, RS485, SPI, and USB communication protocols

# **Programming Languages**

• C, C++, Python, VHDL, x86 assembly, Blackfin assembly, MATLAB, LABVIEW, and Mathematica

### Mechanical

- Mechanical design using Solidworks
- Machine shop tools (mill, lathe, drill press, waterjet, laser cutter, 3D printer)

### **INTERESTS**

Robotics, networks, consumer electronics, Internet of things, hiking, snowboarding, board games, video games

### **LANGUAGES**

- English: Native language.
- Chinese: Fluent (speaking, reading, writing).
- Spanish: Intermediate (speaking, reading, writing).

### REFERENCES

# ■ Professor Ali Hajimiri

Professor of Electrical Engineering Caltech hajimiri@caltech.edu • (626) 395-2312

# ■ Glen George

Lecturer in Electrical Engineering Caltech glen@caltech.com • (626) 395-2802