



## Raytracing

*Rendered by  
PovRay 3.5*

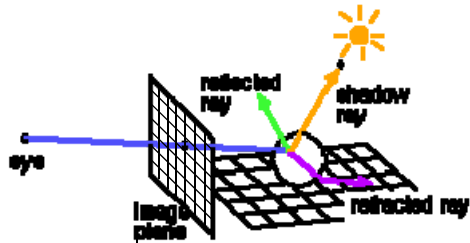


# Raytracing

*Tuned for specular and transparent objects*

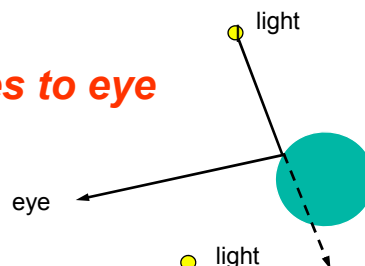
*Partly physics: geometric optics*

*A pixel should have the color of the object point that projects to it*

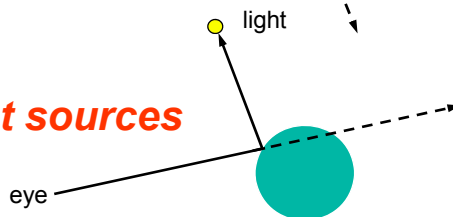


## Forward and Backward Methods

*Forward:  
from light sources to eye*

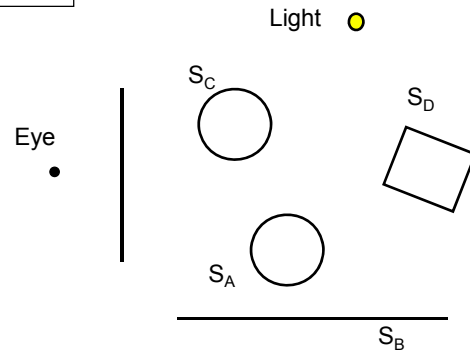


*Backward:  
from eye to light sources*



## Scene

$S_A$	shiny, transparent
$S_B, S_D$	diffuse, opaque
$S_C$	shiny, opaque



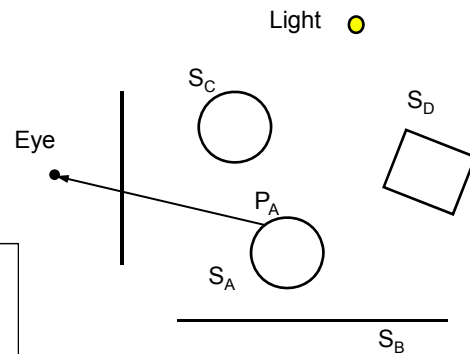
## Three Sources of Light

The light that point  $P_A$  emits to the eye comes from:

Light sources

Reflection from other objects

Refraction from other objects

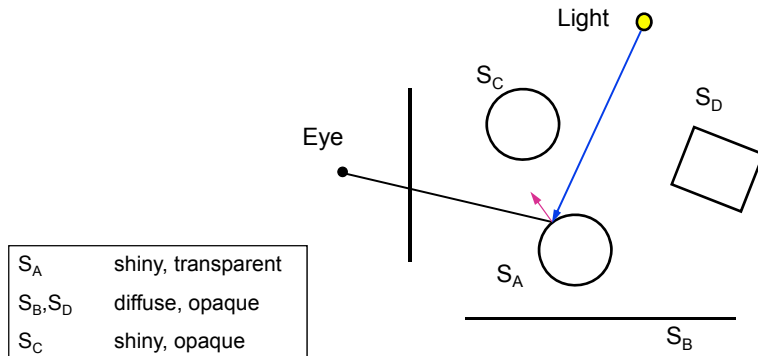


$S_A$	shiny, transparent
$S_B, S_D$	diffuse, opaque
$S_C$	shiny, opaque

## Directly From Light Source

Local illumination model:

$$I = I\text{-diffuse} + I\text{-specular} + I\text{-ambient}$$

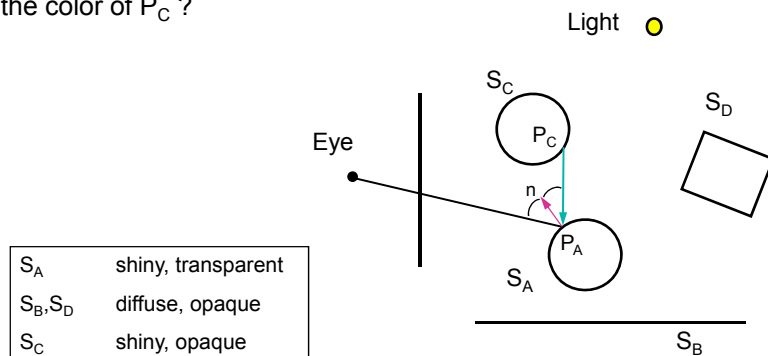


## Reflection

What is the color that is reflected to P<sub>A</sub> ?

*The color of P<sub>C</sub>*

What is the color of P<sub>C</sub> ?



# Reflection

What is the light that is reflected to  $P_A$  ?

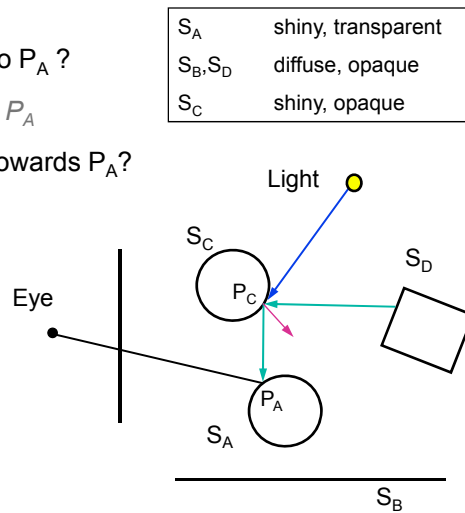
*The color of  $P_C$  as viewed by  $P_A$*

What is the color of  $P_C$  reflected towards  $P_A$  ?

*Just like  $P_A$  :*

*Raytrace  $P_C$  ; i.e., compute the contributions from*

1. Light sources
2. Reflection
3. Refraction



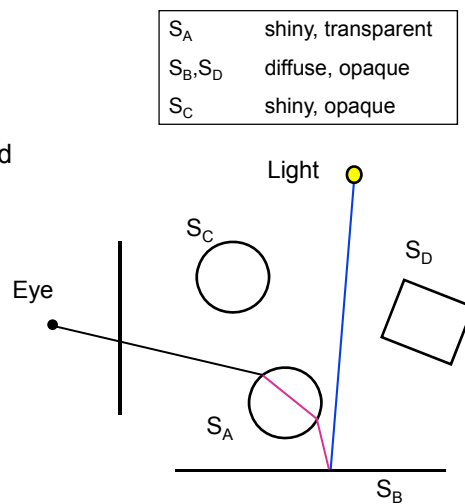
# Refraction

Transparent materials

How do you compute the refracted contribution?

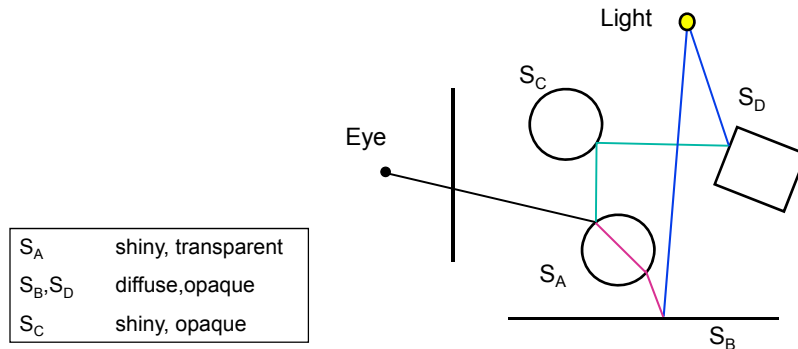
You raytrace the refracted ray

1. Light sources
2. Reflection
3. Refraction



## What Are We Missing?

*Diffuse objects do not receive light from other objects, only from light sources*

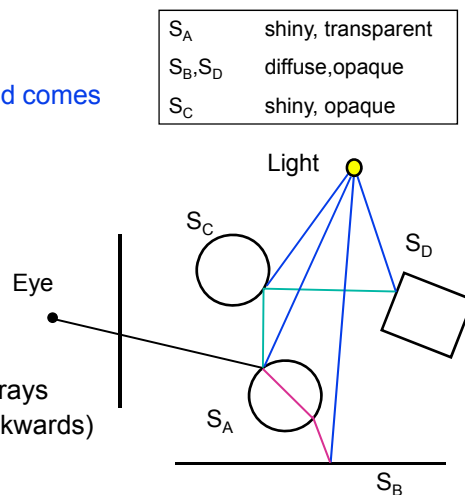


## Three Contributions Together

The color that the pixel is assigned comes from:

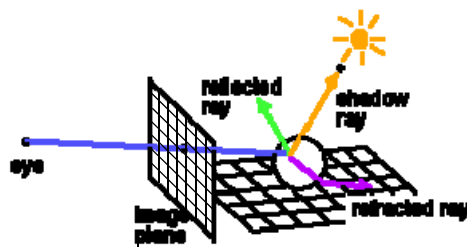
- Light sources
- Reflection from other objects
- Refraction from other objects

It is more convenient to trace the rays from the eye to the scene (backwards)



# Raytracing

*for each pixel on screen*  
*determine ray from eye through pixel*  
*find closest intersection of ray with an object*  
*cast shadow ray(s) to the light source(s)*  
*recursively cast reflected and refracted ray*  
*calculate pixel color*  
*paint pixel*  
*end*

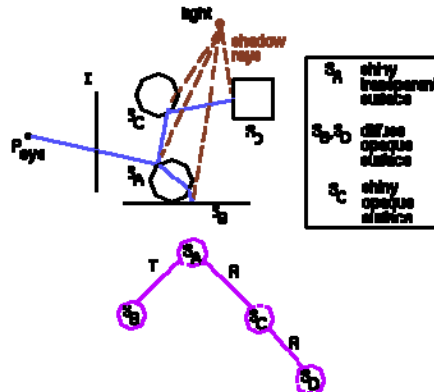


## Backwards Raytracing Algorithm

*For each pixel construct a ray: eye  $\rightarrow$  pixel*

```

raytrace( ray )
    P = closest intersection
    color_local = ShadowRay(light1, P) + ...
                  + ShadowRay(lightN, P)
    color_reflect = raytrace(reflected_ray )
    color_refract = raytrace(refracted_ray )
    color = color_local +
            + krfl * color_reflect
            + krfa * color_refract
    return( color )
    
```



## How Many Levels of Recursion Should We Use?

*The more the better*

*Infinite reflections at the limit*

## Stages of Raytracing

*Setting the camera and the image plane*

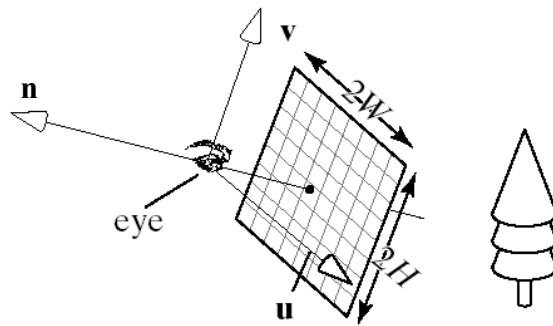
*Computing a ray from the eye to every pixel  
and trace it in the scene*

*Computing object-ray intersections*

*Computing shadow, reflected, and refracted  
rays at each intersection*



## Setting Up the Camera



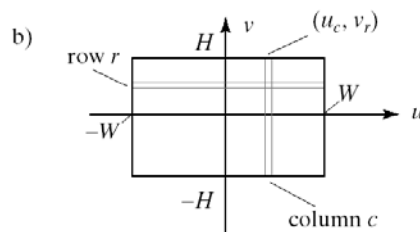
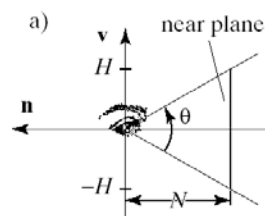
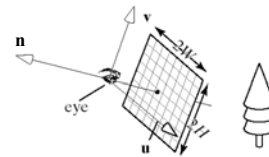
## Image Parameters

**Width  $2W$ , Height  $2H$**

**Number of pixels  $N_c \times N_r$**

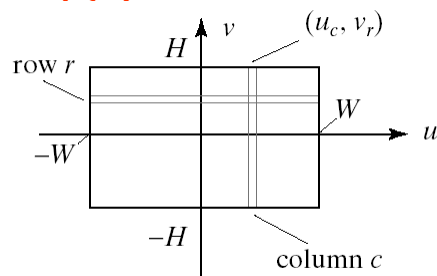
**Camera coordinate system (eye, u, v, n)**

**Image plane at  $n = -N$**



## Pixel Coordinates in Camera Coordinate System

**Lower left corner of pixel  $P(r,c)$  has coordinates in camera space:**



$$u_c = -W + W \frac{2c}{N_c - 1}, \quad c = 0, 1, \dots, N_c - 1,$$

$$v_r = -H + H \frac{2r}{N_r - 1}, \quad r = 0, 1, \dots, N_r - 1,$$

## Reminder: Lines

### Representations of a line (in 2D)

- Explicit

$$y = \frac{dy}{dx}(x - x_0) + y_0$$

- Implicit

$$F(x, y) = (x - x_0)dy - (y - y_0)dx$$

if  $F(x, y) = 0$  then  $(x, y)$  is on line  
 $F(x, y) > 0$   $(x, y)$  is below line  
 $F(x, y) < 0$   $(x, y)$  is above line

- Parametric

$$\begin{aligned} x(t) &= x_0 + t(x_1 - x_0) \\ y(t) &= y_0 + t(y_1 - y_0) \\ t &\in [0, 1] \end{aligned}$$

$$\begin{aligned} P(t) &= P_0 + t(P_1 - P_0), \text{ or} \\ P(t) &= (1 - t)P_0 + tP_1 \end{aligned}$$

## Ray Through Pixel

### *Lower left corner*

Camera coordinates:  $P(r, c) = (u_c, v_r, -N)$

World coordinates:  $P(r, c) = \text{eye} - N\mathbf{n} + u_c\mathbf{u} + v_r\mathbf{v}$

### *Ray through pixel:*

$\text{ray}(r, c, t) = \text{eye} + t(P(r, c) - \text{eye})$

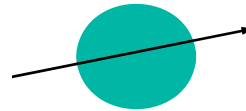
$$= \text{eye} + t \left( -N\mathbf{n} + W \left( \frac{2c}{N_c - 1} - 1 \right) \mathbf{u} + H \left( \frac{2r}{N_r - 1} - 1 \right) \mathbf{v} \right)$$

## Ray-Object Intersections

### *Intersection of ray with unit sphere at origin:*

$$\text{ray}(t) = S + tc$$

$$\text{Sphere}(P) = |P| - 1 = 0$$



$$\text{Sphere}(\text{ray}(t)) = 0 \Rightarrow$$

$$|S + tc| - 1 = 0 \Rightarrow$$

$$(S + tc) \cdot (S + tc) - 1 = 0 \Rightarrow$$

$$|c|^2 t^2 + 2(S \cdot tc) + |S|^2 - 1 = 0$$

*This is a quadratic equation*

## Solving a Quadratic Equation

$$|c|^2 t^2 + 2(S \cdot c)t + |S|^2 - 1 = 0$$
$$At^2 + 2Bt + C = 0$$

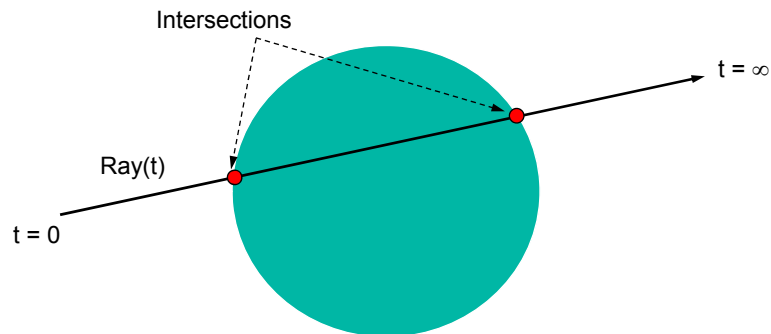
$$t_h = -\frac{B}{A} \pm \frac{\sqrt{B^2 - AC}}{A}$$
$$= -\frac{S \cdot c}{|c|^2} \pm \frac{\sqrt{(S \cdot c)^2 - |c|^2(|S|^2 - 1)}}{|c|^2}$$

If  $(B^2 - AC) = 0$  one solution

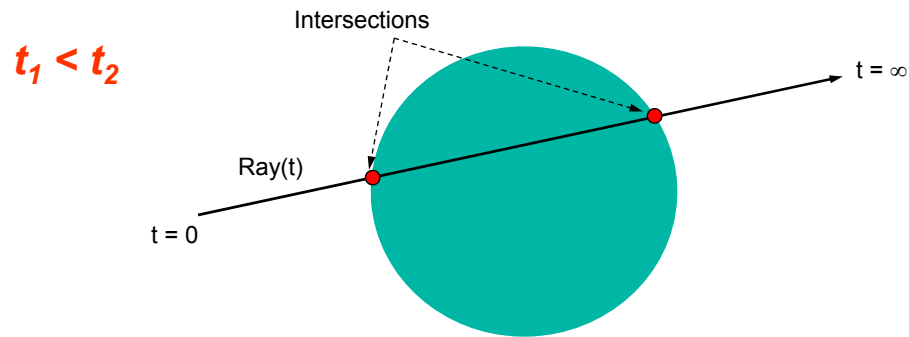
If  $(B^2 - AC) < 0$  no solution

If  $(B^2 - AC) > 0$  two solutions

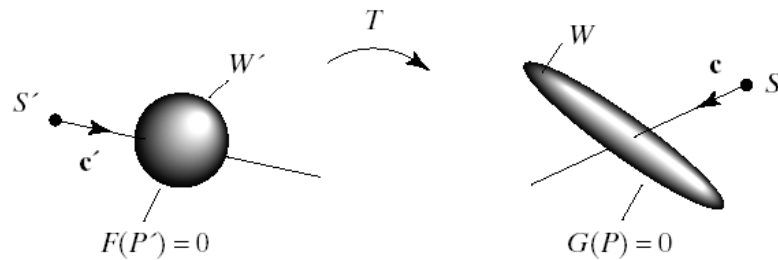
## First Intersection?



## First Intersection?

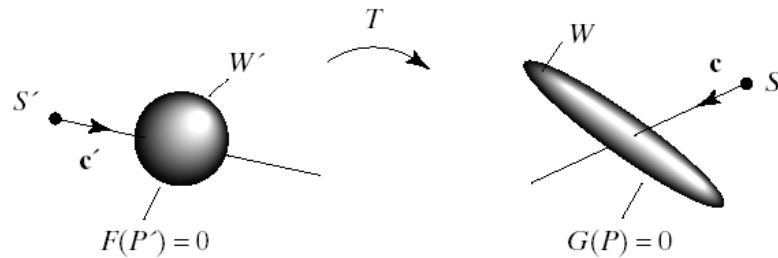


## Transformed Primitives?



*Where does  $S + tc$  intersect the transformed sphere  $G$  ?*

## Linear Transformation

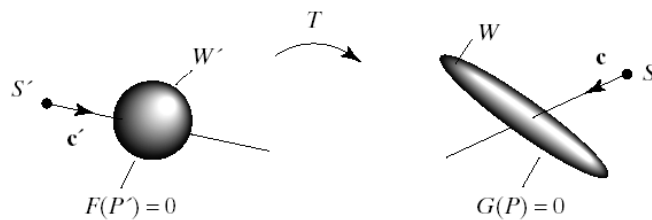


Implicit equation  $G(P) = 0$

Untransformed implicit equation  $F(P') = 0$

$$P = MP' \Rightarrow P' = M^{-1}P$$

## Linear Transformation



$$P = MP' \Rightarrow P' = M^{-1}P$$

$$F(P') = F(T^{-1}(P)) = 0 \Rightarrow \\ F(T^{-1}(S + tc)) = 0$$

**Which means that we can intersect the inverse-transformed ray with the untransformed primitive**

## Final Intersection

### *Inverse transformed ray*

$$\mathbf{r}'(t) = \mathbf{M}^{-1} \begin{bmatrix} S_x \\ S_y \\ S_z \\ 1 \end{bmatrix} + t\mathbf{M}^{-1} \begin{bmatrix} c_x \\ c_y \\ c_z \\ 0 \end{bmatrix} = \mathbf{S}' + t\mathbf{c}'$$

- Drop 1 and 0 to get  $\mathbf{r}'(t)$  in 3D space

### *For each object*

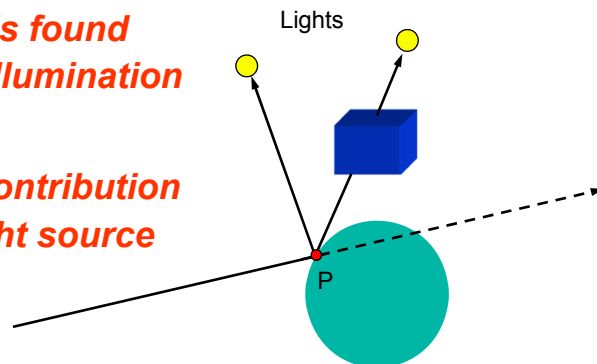
- Inverse transform ray, getting  $\mathbf{S}' + t\mathbf{c}'$
- Find  $t_h$  for intersection with the untransformed object
- Use  $t_h$  in the **untransformed ray**  $\mathbf{S} + t\mathbf{c}$  to find the point of intersection with the transformed object

## Shadow Ray

*For each light source, intersect shadow ray (from point P towards light source) with all objects*

*If no intersection is found  
apply local illumination  
at point P*

*If in shadow, no contribution  
from that light source*



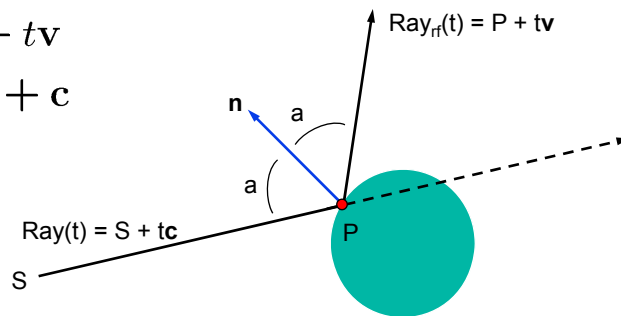
## Reflected Ray

*Raytrace the reflected ray*

$$\text{Ray}(t) = S + tc$$

$$\text{Ray}_{\text{rf}}(t) = P + tv$$

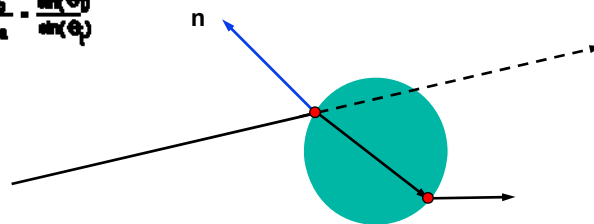
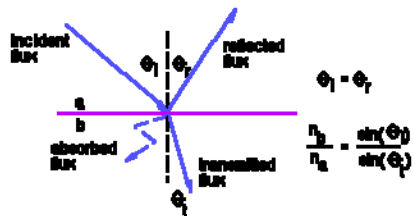
$$v = -2(n \cdot c)n + c$$



## Refracted Ray

*Raytrace the refracted ray*

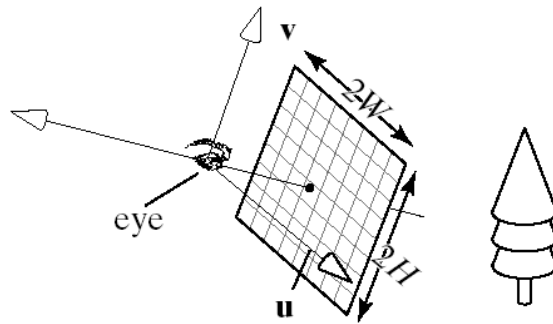
Snell's law





## All Together

$$\text{color}(r,c) = \text{color\_shadow\_ray} + k_{rfl} * \text{color\_reflected} + k_{rfa} * \text{color\_refracted}$$

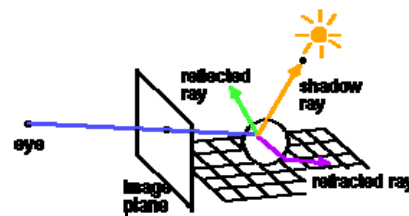


## Summary: Raytracing

### Recursive algorithm

```

function Main
  for each pixel (c,r) on screen
    determine ray  $r_{c,r}$  from eye through pixel
     $\text{color}(c,r) = \text{raytrace}(r_{c,r})$ 
  end for
end
function raytrace(r)
  find closest intersection P of ray r with objects
   $\text{clocal} = \text{Sum}(\text{shadowRays}(P, \text{Light}))$ 
   $c_{rfl} = \text{raytrace}(r_{rfl})$ 
   $c_{rfa} = \text{raytrace}(r_{rfa})$ 
  return  $c = \text{clocal} + k_{rfl} * c_{rfl} + k_{rfa} * c_{rfa}$ 
end
  
```



# A Ray Tracer in Postscript!

```
%! Tiny RayTracing by HAYAKAWA, Takashi (h-takasi@isea.is.titech.ac.jp)
/p/floor/S/add/A/copy/n/exch/i/index/J/iffelse/r/roll/e/sqrt/H{count 2 idiv exch
repeat}def/q/gt/h/exp/t/and/C/neg/T/dup/Y/pop/d/mul/w/div/s/cvi/R/rlineto{load
def}H/c(jlidj2id42rd)/G(140N7)/Q(31C85d4)/B(V0R0VRVC0R)/K(WCVW)/U(4C577d7)300
T translate/I(3STinTinTinY)/l(993dC99Cc96raN)/k(X&E9!&1!J)/z(blxC1SdC9n5dh)/j
(43r)/O(Y43d9rE3IaN96r63rvx2dcaN)/z(&93r6IQO2Z4o3AQYaNlxS2w!)/N(3A3Axe1nwc)/W
270 def/L(1i2A00053r45hNvQXz&vUX&UOvQXzFJ!FJ!J)/D(cjS5o32rS4oS3o)/v(6A)/b(7o)
/F(&vGYx4oGbxSd0nq&3IGbxSGY4Iwxca3AlvvUkbQkdbGYx4ofwnw!&v1x2w13wSb8Z4ws!J!)/X
(4I3Ax52r8Ia3A3Ax65rTdCS4iw5o5IxnwTTd32rCST0q&eCST0q&D1!&EYE0!J!&EYEO!J0q)/V
1 def/x(jd5o32rd4odSS)/a(1CD)/E(YYY)/o(1r)/f(nY9wn7wpSps1t1S){[n{( )T 0 4 3 r
put T(/)q(T(9)q{cvn}{s}J){($)q{[{}]}J}J cvx}forall]cvx def}H K{K{L setgray
moveto B fill}for Y}for showpage
```

## Efficiency Issues

### *Computationally expensive*

- avoid intersection calculations
  - Voxel grids
  - BSP trees
  - Octrees
  - Bounding volume trees
- optimize intersection calculations
  - try recent hit first
  - reuse info from numerical methods

## **Advanced Concepts**

*Participating media*

*Translucency*

*Sub-surface scattering (e.g., human skin)*

*Photon mapping*

## **Raytracing Summary**

*Recursive*

*Computationally expensive*

*Good for reflection and refraction effects*