

Module 1- Assignment

1)

a) $\textcircled{*} \int_0^t \frac{\partial F}{\partial w} dw_r = \int_0^t r^2 \sin(w) dw_r$

$\cdot \frac{\partial F}{\partial w} = t^2 \sin(w)$

$\int \partial F = \int t^2 \sin(w) dw$

$\cdot F = -t^2 \cos(w)$

$\cdot \frac{\partial^2 F}{\partial w^2} = r^2 \cos(w)$

$\cdot \frac{\partial F}{\partial t} = 2t \sin(w)$

$\textcircled{*}$ Itô Integral:

$\int_0^t \frac{\partial F}{\partial w} dw_r = -t^2 \cos(w_t) - (-w_0^2) - \int_0^t \left(2r \sin(w) + \frac{1}{2} r^2 \cos(w) \right) dr$

$\therefore \int_0^t r^2 \sin(w_r) dw_r = -t^2 \cos(w_t) - \int_0^t \left(2r \sin(w) + \frac{1}{2} r^2 \cos(w) \right) dr$

b)

i. Itô IV:

$\cdot f(s, t) = \alpha^t + \beta t s^n$

$\textcircled{*} \frac{\partial f}{\partial s} = \beta t n s^{n-1} \quad \textcircled{*} \frac{\partial^2 f}{\partial s^2} = \beta t n(n-1) s^{n-2} \quad \textcircled{*} \frac{\partial f}{\partial t} = t \cdot \alpha^{t-1} + \beta s^n$

$\Rightarrow df = \left[(t \cdot \alpha^{t-1} + \beta s^n) + \cancel{\nu \beta t n s^{n-1}} + \frac{1}{2} \cdot \cancel{\sigma^2 \beta t n(n-1) s^{n-2}} \right] dt + \cancel{\sigma \beta t n s^{n-1}} ds$

$\therefore df = (t \cdot \alpha^{t-1} + \beta s^n + \cancel{\nu \beta t n s^n} + \frac{1}{2} (\cancel{\sigma^2 \beta t n(n-1) s^n}) dt + (\cancel{\sigma \beta t n s^n}) ds$

pp. Itô IV:

• $f = \log(ts) + \cos(ts)$... Δ I'm assuming the whole term "t.s" belongs to the log and cosine functions!

$$\bullet \frac{\partial f}{\partial s} = \frac{1}{s} - \sin(ts)t \quad \bullet \frac{\partial^2 f}{\partial s^2} = -\frac{1}{s^2} - \cos(ts)t^2$$

$$\bullet \frac{\partial f}{\partial t} = \frac{1}{t} - \sin(ts)s$$

$$\Rightarrow df = \left[\left(\frac{1}{t} - \sin(ts)s \right) + \nu \cdot s \left(\frac{1}{s} - \sin(ts)t \right) + \frac{1}{2} \sigma^2 s^2 \left(-\frac{1}{s^2} - \cos(ts)t^2 \right) \right] dt + \sigma \cdot s \left[\frac{1}{s} - \sin(ts)t \right] ds$$

$$\therefore df = \left(\frac{1}{t} - \sin(ts)s + \nu - \sin(ts)t \cdot \nu \cdot s - \frac{\sigma^2}{2} - \frac{\cos(ts)(t \cdot \sigma \cdot s)^2}{2} \right) dt + (\sigma - \sin(ts)t \cdot \sigma \cdot s) ds$$

2) Deducing a general form for "Itô VI":

* let: $ds_1 = a_1(t, s_1)dt + b_1(t, s_1)dW_t^{(1)}$ \wedge $ds_2 = a_2(t, s_2)dt + b_2(t, s_2)dW_t^{(2)}$

• From TSE of $V(t, s_1, s_2)$ for $V(t+\Delta t, s_1+\Delta s_1, s_2+\Delta s_2) = V'$:

$$V' = V + \frac{\partial V}{\partial t} \Delta t + \frac{\partial V}{\partial s_1} \Delta s_1 + \frac{\partial V}{\partial s_2} \Delta s_2 + \frac{1}{2} \left(\frac{\partial^2 V}{\partial t^2} \Delta t^2 + \frac{\partial^2 V}{\partial s_1^2} \Delta s_1^2 + \frac{\partial^2 V}{\partial s_2^2} \Delta s_2^2 + 2 \frac{\partial^2 V}{\partial s_1 \partial s_2} \Delta s_1 \Delta s_2 + \dots \right)$$

• As long as $V' - V = dV$ and $\Delta t = dt$, $\Delta s_1 = ds_1$, $\Delta s_2 = ds_2$, and $\frac{\partial^2 V}{\partial t^2} \Delta t^2 \rightarrow 0$:

$$\Rightarrow dV = \frac{\partial V}{\partial t} dt + \frac{\partial V}{\partial s_1} ds_1 + \frac{\partial V}{\partial s_2} ds_2 + \frac{1}{2} \frac{\partial^2 V}{\partial s_1^2} ds_1^2 + \frac{1}{2} \frac{\partial^2 V}{\partial s_2^2} ds_2^2 + \frac{\partial^2 V}{\partial s_1 \partial s_2} ds_1 ds_2$$

• Replacing eq., simplifying and applying $ds_{(n)}^2 = b_{(n)}^2 dt$ \wedge $ds_1 ds_2 = \rho b_1 \cdot b_2 dt$.

$$(*) dV = \left(\frac{\partial V}{\partial t} + a_1 \frac{\partial V}{\partial s_1} + a_2 \frac{\partial V}{\partial s_2} + \frac{1}{2} b_1^2 \frac{\partial^2 V}{\partial s_1^2} + \frac{1}{2} b_2^2 \frac{\partial^2 V}{\partial s_2^2} + \rho b_1 \cdot b_2 \frac{\partial^2 V}{\partial s_1 \partial s_2} \right) dt + b_1 \frac{\partial V}{\partial s_1} dW_t^{(1)} + b_2 \frac{\partial V}{\partial s_2} dW_t^{(2)}$$

\Rightarrow Approximate general form for Itô VI !

• Using $\textcircled{*}$ for dS_t & dr_t in $V(t, s, r)$:

$$dV = \left(\frac{\partial V}{\partial t} + (\nu s_t) \frac{\partial V}{\partial s} + (\gamma(m-r)) \frac{\partial V}{\partial r} + \frac{1}{2} (6s)^2 \frac{\partial^2 V}{\partial s^2} + \frac{1}{2} (cd)^2 \frac{\partial^2 V}{\partial r^2} + \rho(6s)(cd) \frac{\partial^2 V}{\partial s \partial r} \right) dt + (6s \frac{\partial V}{\partial s}) dW_t^{(1)} - (cd \frac{\partial V}{\partial r}) dW_t^{(2)}$$

• Applying Integration over $(T, 0)$:

$$\int_0^T dV = \int_0^T \left(\frac{\partial V}{\partial t} + (\nu s) \frac{\partial V}{\partial s} + (\gamma(m-r)) \frac{\partial V}{\partial r} + \frac{1}{2} (6s)^2 \frac{\partial^2 V}{\partial s^2} + \frac{1}{2} (cd)^2 \frac{\partial^2 V}{\partial r^2} + \rho(6s)(cd) \frac{\partial^2 V}{\partial s \partial r} \right) dt + \int_0^T (6s \frac{\partial V}{\partial s}) dW_t^{(1)} + \int_0^T (cd \frac{\partial V}{\partial r}) dW_t^{(2)}$$

$$V|_0^T = \int_0^T (...) dt + \int_0^T (6s \frac{\partial V}{\partial s}) dW_t^{(1)} + \int_0^T (cd \frac{\partial V}{\partial r}) dW_t^{(2)}$$

• Assuming $V(0, s_0, r_0) = v$:

$$\therefore V(T, s_T, r_T) = v + \int_0^T \left(\frac{\partial V}{\partial t} + (\nu s) \frac{\partial V}{\partial s} + (\gamma(m-r)) \frac{\partial V}{\partial r} + \frac{1}{2} (6s)^2 \frac{\partial^2 V}{\partial s^2} + \frac{1}{2} (cd)^2 \frac{\partial^2 V}{\partial r^2} + \rho(6s)(cd) \frac{\partial^2 V}{\partial s \partial r} \right) dt + \int_0^T (6s \frac{\partial V}{\partial s}) dW_t^{(1)} + \int_0^T (cd \frac{\partial V}{\partial r}) dW_t^{(2)}$$

3) * Rearranging:

$$\Rightarrow dS_t = S_t (\nu dt + 6 dW_t)$$

$$\frac{1}{S_t} dS_t = \nu dt + 6 dW_t$$

* Integrating over $(t, 0)$:

$$\Rightarrow \int_0^t \frac{1}{S_t} dS_t = \int_0^t \nu dt + \int_0^t 6 dW_t$$

$$\ln(s)|_0^t = \nu(t-0) + \int_0^t 6 dW_t$$

$$\Rightarrow \ln\left(\frac{S_t}{S_0}\right) = \nu t + 6 \int_0^t dW_t$$

$$\Rightarrow \ln\left(\frac{S_t}{S_0}\right) = \nu t + 6 \int_0^t dW_t$$

$$\ln(S_t/S_0) = e^{\nu t} \cdot e^{6 \int_0^t dW_t}$$

$$S_t = S_0 e^{\nu t} \cdot e^{6 \int_0^t dW_t}$$

* Finding $E[S_t | S_0]$, where S_0 is known.

$$E[S_t | S_0] = S_0 E[e^{\nu t} \cdot e^{6 \int_0^t dW_t}]$$

$$= S_0 E[e^{\nu t}] \cdot E[e^{6 \int_0^t dW_t}] \quad \dots \text{by Martingala}$$

$$E[S_t | S_0] = S_0 E[e^{\nu t}] \cdot (1)$$

$$\therefore E[S_t | S_0] = S_0 e^{\nu t}$$

4) * Knowing the SSD distribution satisfies: $\frac{1}{2} \frac{d^2}{dy'^2} (P_{\infty}) = \frac{d}{dy'} (A P_{\infty})$, where $y' = u'$

$$\Rightarrow \frac{1}{2} (\sigma^2) \frac{d^2 P_{\infty}}{du'^2} - (-\theta \frac{d}{du'} (u P_{\infty})) = 0$$

* Replacing $u' = u \wedge P_{\infty} = P$ for simplicity:

$$\Rightarrow \frac{1}{2} (\sigma^2) \frac{d^2 P}{du^2} + \theta \frac{d}{du} (u P) = 0$$

$$\frac{1}{2} (\sigma^2) \frac{d^2 P}{du^2} = -\theta \frac{d}{du} (u P)$$

$$\frac{1}{2} (\sigma^2) \int \frac{d^2 P}{du^2} = -\theta \int \frac{d}{du} (u P)$$

$$\frac{1}{2} (\sigma^2) dP/du = -\theta (u P) + K, \quad K = 0 \begin{cases} u \rightarrow 0 \\ P \rightarrow 0 \\ dP/du \rightarrow 0 \end{cases}$$

$$\Rightarrow \frac{1}{P} dP = -2\theta/\sigma^2 \cdot (u) du$$

$$\int \frac{1}{P} dP = -2\theta/\sigma^2 \int u du$$

$$\ln(P) = -\theta/\sigma^2 \cdot \frac{1}{2} u^2$$

$$\ln(P) = -\theta/\sigma^2 u^2$$

$$e^{\ln(P)} = e^{-\theta/\sigma^2 u^2}$$

$$\Rightarrow P = A \cdot e^{-\theta/\sigma^2 (u)^2}$$

* Knowing that $\int_{\mathbb{R}} P = 1$, thus:

$$\int_{\mathbb{R}} P = \int_{\mathbb{R}} e^{-\frac{\theta}{\sigma^2} (u)^2} du = 1 \quad \left\{ \begin{array}{l} \text{say } x = \sqrt{\theta/\sigma^2} \cdot u \\ x' = \sqrt{\theta/\sigma^2} \end{array} \right. \Rightarrow \begin{array}{l} dx = x' du \\ \frac{\sigma}{\sqrt{\theta}} dx = du \end{array}$$

* Replacing:

$$\Rightarrow \text{Being } (x)^2 = \frac{\theta}{\sigma^2} (u)^2$$

$$k \int e^{-\frac{(x)^2}{\sigma^2}} \frac{\sigma}{\sqrt{\theta}} dx = 1$$

$$k \frac{\sigma}{\sqrt{\theta}} \underbrace{\int e^{-x^2} dx}_{\sqrt{\pi}} = 1$$

$$k \cdot \frac{\sigma}{\sqrt{\theta}} \cdot \sqrt{\pi} = 1$$

$$\Rightarrow k = \sqrt{\frac{\theta}{\pi}} \cdot \frac{1}{\sigma} = \sqrt{\frac{\theta}{\sigma^2 \pi}}$$

* Finally:

$$\therefore P_{\infty}(u) = \sqrt{\frac{\theta}{\sigma^2 \pi}} e^{-\frac{\theta}{\sigma^2} u'^2}$$

* Comparing to $N(u, \sigma^2)$:

$$\sqrt{\frac{\theta}{\pi}} \cdot \frac{1}{\sigma} e^{-\frac{\theta}{\sigma^2} u'^2} = \frac{1}{\sigma} \cdot \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2} \frac{(x-\mu)^2}{\sigma^2}}$$

$\Rightarrow \theta = 1/2$ to fits the equality, so:

$$e^{-\frac{1}{2} \left(\frac{1}{\sigma^2} \cdot u'^2 \right)} = e^{-\frac{1}{2} \left(\frac{1}{\sigma^2} \cdot (x-\mu)^2 \right)}$$

$$\frac{1}{\sigma^2} u'^2 = \frac{1}{\sigma^2} (x-\mu)^2 \leadsto \underline{u'^2 = (x-\mu)^2} \quad \left\{ \begin{array}{l} \text{"}\mu\text{" should} \\ \text{be 0!} \end{array} \right.$$

* Thus, mean and std for $P_{\infty}(u')$ becomes:

$$\therefore \mu = 0 \wedge \text{std} = \sigma$$

5) * knowing that SSD-FKE is " $\frac{1}{2} \frac{d^2}{dy^2} (B^2 P_{\infty}) - \frac{d}{dy} (A P_{\infty}) = 0$ ", thus:

$$\Rightarrow A = U_r \wedge B = v \cdot r^{\beta}$$

* Solving to find U_r :

$$\Rightarrow \frac{1}{2} v^2 \cdot \frac{d^2}{dr^2} (r^{\beta})^2 \cdot p - \frac{d}{dr} (U p) = 0$$

$$\frac{1}{2} v^2 \frac{d^2}{dr^2} (r^{2\beta}) p = \frac{d}{dr} (U p)$$

$$\frac{1}{2} v^2 \int \frac{d^2}{dr^2} (r^{2\beta}) p = \int \frac{d}{dr} (U p)$$

$$\frac{1}{2} v^2 \frac{d}{dr} (r^{2\beta}) \cdot p = U p$$

$$\frac{1}{2} v^2 \left(\frac{d}{dr} (r^{2\beta}) \cdot p + r^{2\beta} \cdot \left(\frac{d}{dr} p \right) \right) = U p$$

$$\frac{1}{2} v^2 (2\beta \cdot r^{2\beta-1} \cdot p + r^{2\beta} \cdot \frac{d}{dr} p) = U p$$

$$\Rightarrow v^2 \cdot \beta r^{2\beta-1} \cdot p + \frac{1}{2} v^2 r^{2\beta} \frac{d}{dr} p = U p$$

* Simplifying 'p':

$$\Rightarrow v^2 \beta r^{2\beta-1} + \frac{1}{2} v^2 r^{2\beta} \left(\frac{d}{dr} p \right) \left(\frac{1}{p} \right) = U$$

$$v^2 \beta r^{2\beta-1} + \frac{1}{2} v^2 r^{2\beta} \left(\frac{d}{dr} p \right) \left(\frac{d}{dp} \ln(p) \right) = U$$

$$v^2 \beta r^{2\beta} + \frac{1}{2} v^2 r^{2\beta} \left(\frac{d}{dr} \ln(p) \right) \left(\frac{d}{dp} p \right) = U$$

* Finally, for U_r :

$$\therefore v^2 \beta r^{2\beta} + \frac{1}{2} v^2 r^{2\beta} \left(\frac{d}{dr} \ln(p_{\infty}) \right) = U_r$$

a) i. Assuming $F = XY$, using TSE for F :

$$dF = \frac{\delta F}{\delta x} dx + \frac{\delta F}{\delta y} dy + \frac{1}{2} \left(\frac{\delta^2 F}{\delta x^2} dx^2 + \frac{\delta^2 F}{\delta y^2} dy^2 + 2 \frac{\delta^2 F}{\delta x \delta y} dx dy + \dots \right)$$

$$= y dx + x dy + \frac{1}{2} (0 dx^2 + 0 dy^2 + 2(1) dx dy)$$

$$\therefore dF = y dx + x dy + dx dy \dots \text{Itô Product Rule!}$$

ii. Integrating on Itô Product Rule over $(t, 0)$:

$$\Rightarrow \int_0^t dF = \int_0^t y dx + \int_0^t x dy + \int_0^t dx dy$$

$$F|_0^t = \int_0^t y dx + \int_0^t x dy + \int_0^t dx dy$$

$$(F_t - F_0) = \int_0^t y dx + \int_0^t x dy + \int_0^t dx dy$$

$$\Rightarrow X_t Y_t - X_0 Y_0 = \int_0^t Y dx + \int_0^t X dy + \int_0^t dx dy$$

* Thus:

$$\therefore X_t Y_t - X_0 Y_0 = \int_0^t Y_s dx_s + \int_0^t dx_s dy_s = \int_0^t X_s dy_s$$

iii. Using Ito for F , such as $F = X/Y$:

$$dF = \frac{1}{Y} dx - \frac{X}{Y^2} dy + \frac{1}{2} \left(\cancel{0 dx^2} - 2 \cdot \frac{1}{Y^2} dx dy + \frac{2X}{Y^3} dy^2 \right)$$

$$\Rightarrow dF = \frac{1}{Y} dx - \frac{X}{Y^2} dy - \frac{1}{Y^2} dx dy + \frac{X}{Y^3} dy^2$$

* Simplificando:

$$d\left(\frac{X}{Y}\right) = \frac{X}{Y} \left(\frac{dx}{X} - \frac{dy}{Y} - \frac{dx dy}{Y} + \frac{dy^2}{Y^2} \right) \Rightarrow \therefore d\left(\frac{X}{Y}\right) = \left(\frac{Y dx - X dy - dx dy + \frac{X}{Y} dy^2}{Y^2} \right)$$

b) Using general form for "Ito VI" deduced in question 2 (*):

$$(*) dV = \left(\frac{\partial V}{\partial t} + a_1 \frac{\partial V}{\partial S_1} + a_2 \frac{\partial V}{\partial S_2} + \frac{1}{2} b_1^2 \frac{\partial^2 V}{\partial S_1^2} + \frac{1}{2} b_2^2 \frac{\partial^2 V}{\partial S_2^2} + \rho b_1 b_2 \frac{\partial^2 V}{\partial S_1 \partial S_2} \right) dt + b_1 \frac{\partial V}{\partial S_1} dW_t^{(1)} + b_2 \frac{\partial V}{\partial S_2} dW_t^{(2)}$$

* Replacing: $a_1 = a(t, X_t) \wedge a_2 = c(t, Y_t)$

$b_1 = b(t, X_t) \wedge b_2 = d(t, Y_t)$

* And integrating for $V(t, X_t, Y_t)$ over $(T, 0)$, assuming $V(0, X_0, Y_0) = v$:

$$\therefore V(T, X_T, Y_T) = v + \int_0^T \left(\frac{\partial V}{\partial t} + (a) \frac{\partial V}{\partial X} + (c) \frac{\partial V}{\partial Y} + \frac{1}{2} (b)^2 \frac{\partial^2 V}{\partial X^2} + \frac{1}{2} (d)^2 \frac{\partial^2 V}{\partial Y^2} + \rho \cdot (b \cdot d) \frac{\partial^2 V}{\partial X \partial Y} \right) dt + \int_0^T (b \frac{\partial V}{\partial X}) dW_t^{(1)} + \int_0^T (d \frac{\partial V}{\partial Y}) dW_t^{(2)}$$

c) * Transforming $dX_t \wedge dY_t$ to discrete time, considering $E[W_t^{(1)} W_t^{(2)}] = \rho t$.

$$\therefore dX_t \Rightarrow X_{i+1} - X_i = X_i (a \delta t + b (\phi_x \sqrt{\delta t}))$$

$$\therefore dY_t \Rightarrow Y_{i+1} - Y_i = Y_i (c \delta t + d (\phi_y \sqrt{\delta t})), \quad \phi \sim N(0, 1)$$

$$* \text{Deducing } E[\phi_x \sqrt{\delta t} \cdot \phi_y \sqrt{\delta t}] = E[\phi_x \phi_y \delta t] = \rho \delta t = \rho \dots (1)$$

* Thus, in order to choose $\phi_x \wedge \phi_y$ to satisfy (1):

$$\phi_x = \varepsilon_1 \wedge \phi_y = \alpha \varepsilon_1 + \beta \varepsilon_2, \quad \text{where } \alpha, \beta \in \mathbb{R}.$$

* Solving to find α & β , knowing that $\phi_x \wedge \phi_y \sim N(0,1)$ (thus, ε_1 & ε_2 too):

$$\Rightarrow E[\phi_x \phi_y] = E[\varepsilon_1 (\alpha \varepsilon_1 + \beta \varepsilon_2)] = \alpha E[\varepsilon_1^2] + \beta E[\varepsilon_1] \cdot E[\varepsilon_2]$$

$$\therefore E[\phi_x \phi_y] = \alpha = \rho$$

$$\begin{aligned} \Rightarrow E[\phi_y^2] &= E[(\alpha \varepsilon_1 + \beta \varepsilon_2)^2] = E[(\alpha \varepsilon_1)^2 + 2\alpha \varepsilon_1 \beta \varepsilon_2 + (\beta \varepsilon_2)^2] \\ &= \alpha^2 E[\varepsilon_1^2] + 2\alpha \beta E[\varepsilon_1] \cdot E[\varepsilon_2] + \beta^2 E[\varepsilon_2^2] \\ &= \alpha^2 + \beta^2 E[\varepsilon_2^2] \end{aligned}$$

$$\therefore E[\phi_y^2] = \alpha^2 + \beta^2 = 1$$

$$\beta = \sqrt{1 - \alpha^2}$$

6) a) * Using "Ito II":

$$\cdot \frac{\delta y}{\delta t} = -6w^2 + 2kt \quad \cdot \frac{\delta y}{\delta w} = 4w^3 - 12tw \quad \cdot \frac{\delta^2 y}{\delta w^2} = 12w^2 - 12t$$

$$\Rightarrow dy = ((2kt - 6w^2) + \frac{1}{2}(12w^2 - 12t))dt + (4w^3 - 12tw)dW_t$$

$$dy = (2kt - 6t)dt + (4w^3 - 12tw)dW_t$$

* For be a Martingale: $2kt - 6t = 0$, $\therefore k = 3$

b) * Using "Ito II":

$$\cdot \frac{\delta x}{\delta t} = -\cosh(\theta w_t) \frac{\theta^2}{2} e^{-\theta^2 t/2} \quad \cdot \frac{\delta x}{\delta w} = e^{-\theta^2 t/2} \cdot \theta \cdot \sinh(\theta w_t) \quad \cdot \frac{\delta^2 x}{\delta w^2} = e^{-\theta^2 t/2} \cdot \theta^2 \cdot \cosh(\theta w_t)$$

$$\Rightarrow dx = \left[(-\cosh(\theta w_t) \frac{\theta^2}{2} e^{-\theta^2 t/2}) + \frac{1}{2} (e^{-\theta^2 t/2} \cdot \theta^2 \cdot \cosh(\theta w_t)) \right] dt + (e^{-\theta^2 t/2} \cdot \theta \cdot \sinh(\theta w_t)) dW_t$$

$$\Rightarrow dx = (0)dt + (e^{-\theta^2 t/2} \cdot \theta \cdot \sinh(\theta w_t)) dW_t, \text{ so as long as drift} = 0,$$

$\therefore X_t :=$ is a Martingale.