

# Unit 3: Stationarity

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# Readings for Unit 3

Textbook chapter 1.5, 1.6.

# Last Unit

- 1 White noise.
- 2 Random walk model.
- 3 Autoregressive model.
- 4 Moving average model.
- 5 Mean function.
- 6 Measures of Dependence.

# This Unit

- 1 Stationarity
- 2 Autocovariance and Autocorrelation of Stationary Time Series
- 3 Estimating the ACF

# Motivation

In time series analysis, we frequently would prefer to analyze a stationary sequence. This allows us to \_\_\_\_\_ autocorrelation and other quantities of interest. One feature of stationary sequences is that they are identically distributed—but often not independent. (Though, certainly an iid sequence is stationary.) There are two types of stationarity: **strictly stationary** and **weakly stationary**.

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# Strictly Stationary

A time series is **strictly stationary** if for a sequence of times  $t_1, t_2, \dots, t_k$

$$\{x_{t_1}, \dots, x_{t_k}\}$$

has the same distributions as

$$\{x_{t_1+h}, \dots, x_{t_k+h}\}$$

for every integer  $h$ . In other words,

$$P\{x_{t_1} \leq c_1, \dots, x_{t_k} \leq c_k\} = P\{x_{t_1+h} \leq c_1, \dots, x_{t_k+h} \leq c_k\}.$$

Location does not matter—ONLY distance.

# Weakly Stationary

A time series  $\{x_t\}$  is **weakly stationary** if  $\mu_t$  is \_\_\_\_\_  
\_\_\_\_\_, and  $\gamma(s, t)$  \_\_\_\_\_  
\_\_\_\_\_.

From now on when we say stationary, we'll mean weakly stationary. All strongly stationary time series are also weakly stationary, but the reverse may not be the case. Most of the time we are going to be working with Gaussian time series, and in this case the two concepts coincide.



1 Stationarity

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# Autocovariance of Stationary Time Series

With a stationary time series, we have the following property:

$$\gamma(t + h, t) = \gamma(h, 0).$$

So, for stationary processes we write

$$\gamma(h) = E(x_{t+h} - \mu)(x_t - \mu). \quad (1)$$

We simply use the rule  $\gamma(s, t) = \gamma(s - t)$ . Another property of the autocovariance function when the time series is stationary is

$$\gamma(h) = \gamma(-h).$$

# Autocorrelation of Stationary Time Series

For the autocorrelation function, we have

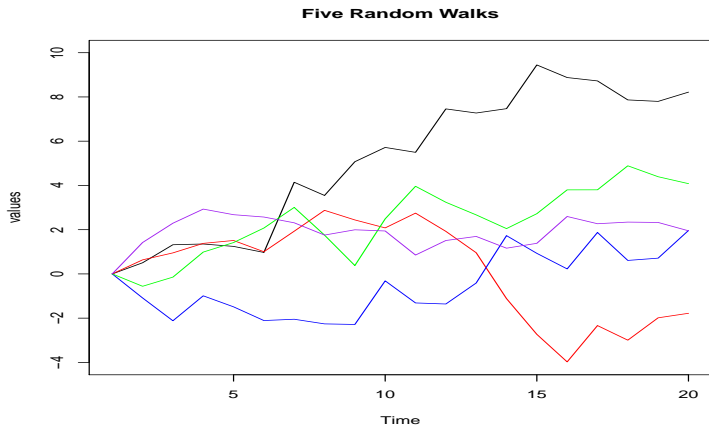
$$\rho(h) = \frac{\gamma(h)}{\gamma(0)}. \quad (2)$$

# White Noise

**Question:** Show that white noise is stationary.

# Random Walk Process

**Question:** Is a random walk process  $\{x_t\}$  stationary? Recall from last unit I simulated three realizations of a random walk.



# MA(2) Process

**Question:** Show that the MA(2) process is stationary.

# ACF of MA(2) Process

# AR(1) Process

**Question:** Show that for the AR(1) process to be stationary, we require that  $|\phi_1| < 1$ .



# ACF of AR(1) Process

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# Recall Stationarity

Suppose  $\{x_t\}$  is a stationary time series. Then

- Its mean is \_\_\_\_\_.
- Its autocovariance function is  $\gamma(h) = E(x_{t+h} - \mu)(x_t - \mu)$ . It depends only on  $h = |s - t|$ . This also means that the variance,  $\gamma(0)$  is constant.
- Its autocorrelation function is  $\rho(h) = \frac{\gamma(h)}{\gamma(0)}$ .

# Estimating the ACF

Without stationarity, we have little hope of estimating the full  $\gamma(s, t)$ . With stationarity, we will have \_\_\_\_\_ that are  $h$  apart from one another (at least when  $h \ll n$ ). We now discuss how to estimate  $\rho(h)$  to produce ACF plots.

# Estimating the ACF

With stationarity, the (true) mean is constant. We can therefore estimate the mean using the \_\_\_\_\_

$$\bar{x} = \frac{\sum_{t=1}^n x_t}{n}.$$

This converges to  $\mu$ . In fact,

$$E(\bar{x}) = E\left(\frac{\sum_{t=1}^n x_t}{n}\right) = \frac{1}{n} \sum_{t=1}^n E(x_t) = \frac{1}{n} \sum_{t=1}^n \mu = \mu.$$

# Estimating the ACF

Consider the **sample autocovariance function**

$$\hat{\gamma}(h) = \frac{\sum_{t=1}^{n-h} (x_{t+h} - \bar{x})(x_t - \bar{x})}{n}. \quad (3)$$

for  $h = 0, 1, \dots, n-1$ .

For fixed  $h$ , all the random variables  $y_t = (x_{t+h} - \bar{x})(x_t - \bar{x})$  have the same distribution (\_\_\_\_\_). Therefore,  $\frac{\sum_{t=1}^n y_t}{n-h}$  converges to  $\gamma(h) = E(x_h - \mu)(x_0 - \mu)$ .

# Estimating the ACF

To obtain the **sample autocorrelation** we simply scale by the variance

$$\hat{\rho}(h) = \frac{\hat{\gamma}(h)}{\hat{\gamma}(0)}. \quad (4)$$

One thing to notice in the sample autocovariance function (3) is that we divide by  $n$  not  $n - h$  or  $n - 1$ . This ensures that if we calculate variances, they are all positive.

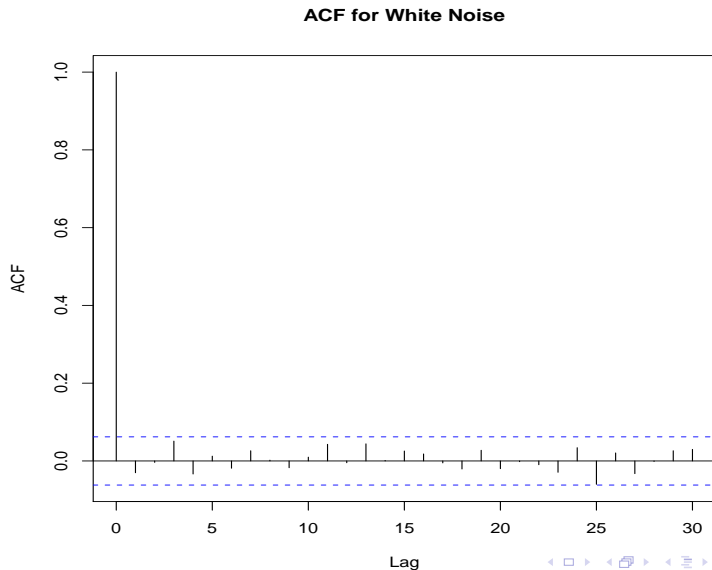
# Sample ACF

We can recognize the sample ACF of time series.

<b>Time series</b>	<b>ACF</b>
White noise	0
Trend	Slow decay
Periodic	Periodic
MA( $q$ )	0 for $h > q$
AR( $p$ )	Decays to 0 exponentially



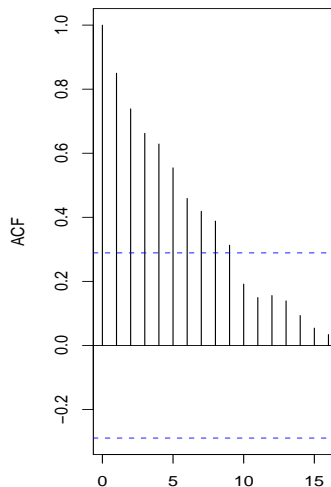
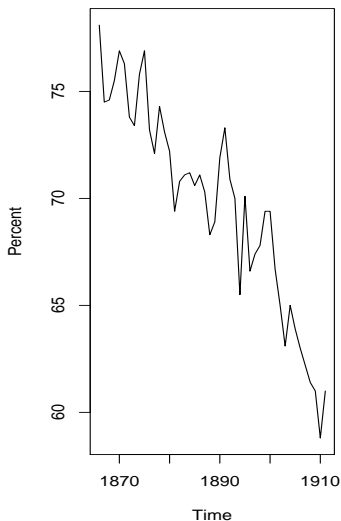
# Sample ACF for Gaussian White Noise



# Sample ACF for Gaussian White Noise

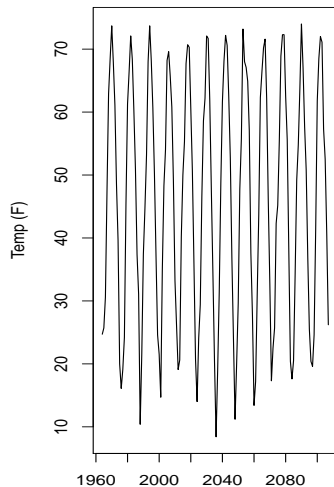
When the true model is white noise  $\hat{\rho}(h)$  is approximately normally distributed with zero mean and standard deviation of  $1/\sqrt{n}$ .

## ACF for Marriage

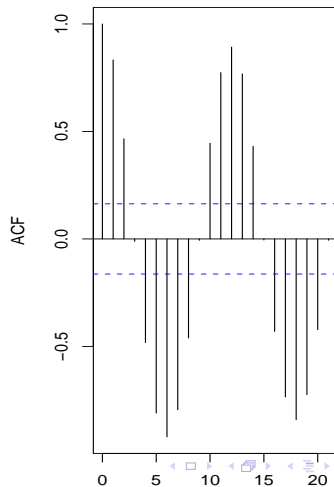


# Sample ACF: Average Monthly Temperature in Dubuque, IA

**Avg monthly temp in Dubuque, IA**

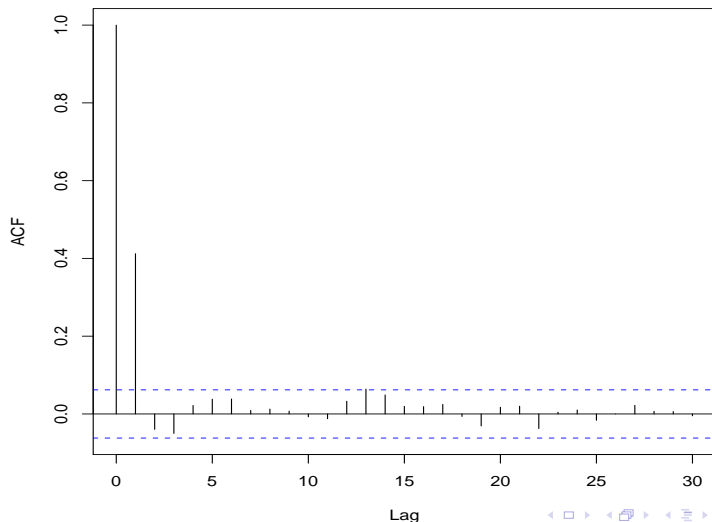


**ACF for avg temp**



# Sample ACF: MA(1) Process

**ACF for MA(1) Process**



# Sample ACF: AR(1) Process

**ACF for AR(1) Process**

