# Direct Preference Optimization: Your Language Model is Secretly a Reward Model

Autores paper: Rafael Rafailov, Archit Sharma, Eric Mitchell, Stefano Ermon, Christopher D. Manning y Chelsea Finn.

Mayo 2023

Presentado por: Sebastián Burgos Martínez

```
python

def sum_of_first_n_even_numbers_method1(N):
   total = 0
   for i in range(1, N + 1):
       even_number = 2 * i
       total += even_number
   return total
```

```
python

def sum_of_first_n_even_numbers_method2(N):
    if N < 1:
        return 0
    return N * (N + 1)</pre>
```



Give me a Python function that calculates the sum of the first N even numbers



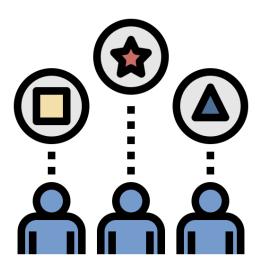
You can create a Python function to calculate the sum of the first N even numbers using a loop. Here's a simple example of such a function:



```
Copy code
python
def sum_of_first_n_even_numbers(N):
    if N <= 0:
        return 0 # If N is zero or negative, the sum is zero.
    even_sum = 0
    count = 0
    num = 2 # Start with the first even number, 2.
    while count < N:</pre>
        even_sum += num
        num += 2 # Increment to the next even number.
        count += 1
    return even_sum
# Example usage:
N = 5
result = sum_of_first_n_even_numbers(N)
print(f"The sum of the first {N} even numbers is: {result}")
```

#### Problema

- Entrenamiento con data generada por humanos con distintos objetivos, prioridades y competencias.
- ► Algunos de estos objetivos y competencias no son deseables de imitar.
- Queremos establecer preferencias en nuestro modelo.



#### Problema

- Código eficiente de alta calidad.
- Información correcta y certera.
- Generación de sentimientos (que la respuesta sea positiva y alentadora).

- Problema
- Trabajo previo
- Solución: Direct Preference Optimization (DPO)
- Resultados
- Discusión: conclusion y trabajo futuro



Reinforcement learning from human feedback (RLHF) pipeline<sup>1</sup>

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1) Supervised fine-tuning (SFT) phase

1) Collect demonstration data, and train a supervised policy

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1) Collect demonstration data, and train a supervised policy

2) Reward modelling phase

2) Collect comparison data, and train a reward model

Reinforcement learning from human feedback (RLHF) pipeline<sup>1</sup>

1) Supervised fine-tuning (SFT) phase

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2) Collect comparison data, and train a reward model

3) Reinforcement learning (RL) finetuning phase 3) Optimize a policy against the reward model using proximal policy optimization (PPO)

### 1) Supervised fine-tuning (SFT) phase

Step 1

Collect demonstration data, and train a supervised policy.

A prompt is sampled from our prompt dataset.

A labeler demonstrates the desired output behavior.

This data is used to fine-tune GPT-3 with supervised learning.



2) Reward modelling phase

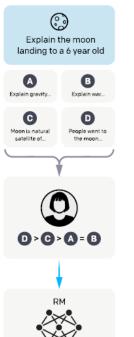
Step 2

Collect comparison data, and train a reward model.

A prompt and several model outputs are sampled.

A labeler ranks the outputs from best to worst.

This data is used to train our reward model.



## 3) Reinforcement learning (RL) fine-tuning phase

Step 3

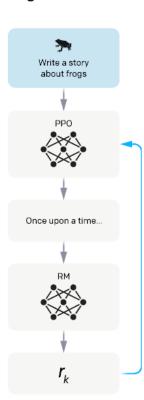
Optimize a policy against the reward model using reinforcement learning.

A new prompt is sampled from the dataset.

The policy generates an output.

The reward model calculates a reward for the output.

The reward is used to update the policy using PPO.



## Solución: Direct Preference Optimization (DPO)

- Ocupa un enfoque sencillo para la optimización de la política.
- Evita el modelo de recompensa y el aprendizaje reforzado para optimizar directamente el modelo de lenguaje.
- Se pasa de una función de pérdida de recompensa a una función de pérdida sobre políticas.

## Solución: Direct Preference Optimization (DPO)

RLHF: 
$$p^*(y_1 \succ y_2 \mid x) = \frac{\exp(r^*(x, y_1))}{\exp(r^*(x, y_1)) + \exp(r^*(x, y_2))}.$$

DPO: 
$$p^*(y_1 \succ y_2 \mid x) = \frac{1}{1 + \exp\left(\beta \log \frac{\pi^*(y_2 \mid x)}{\pi_{\text{ref}}(y_2 \mid x)} - \beta \log \frac{\pi^*(y_1 \mid x)}{\pi_{\text{ref}}(y_1 \mid x)}\right)}$$

## Solución: Direct Preference Optimization (DPO)

RLHF: 
$$\mathcal{L}_R(r_\phi, \mathcal{D}) = -\mathbb{E}_{(x, y_w, y_l) \sim \mathcal{D}} \left[ \log \sigma(r_\phi(x, y_w) - r_\phi(x, y_l)) \right]$$

DPO: 
$$\mathcal{L}_{DPO}(\pi_{\theta}; \pi_{ref}) = -\mathbb{E}_{(x, y_w, y_l) \sim \mathcal{D}} \left[ \log \sigma \left( \beta \log \frac{\pi_{\theta}(y_w \mid x)}{\pi_{ref}(y_w \mid x)} - \beta \log \frac{\pi_{\theta}(y_l \mid x)}{\pi_{ref}(y_l \mid x)} \right) \right]$$

## Solución: ¿qué hace DPO?

$$\nabla_{\theta} \mathcal{L}_{\mathrm{DPO}}(\pi_{\theta}; \pi_{\mathrm{ref}}) = \\ -\beta \mathbb{E}_{(x, y_w, y_l) \sim \mathcal{D}} \left[ \underbrace{\sigma(\hat{r}_{\theta}(x, y_l) - \hat{r}_{\theta}(x, y_w))}_{\text{higher weight when reward estimate is wrong}} \left[ \underbrace{\nabla_{\theta} \log \pi(y_w \mid x)}_{\text{increase likelihood of } y_w} - \underbrace{\nabla_{\theta} \log \pi(y_l \mid x)}_{\text{decrease likelihood of } y_l} \right] \right]$$

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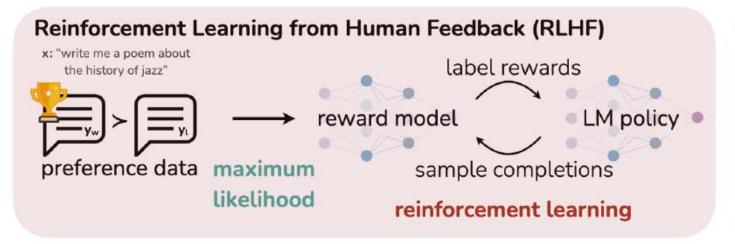
$$\hat{r}_{\theta}(x,y) = \beta \log \frac{\pi_{\theta}(y|x)}{\pi_{\text{ref}}(y|x)}$$

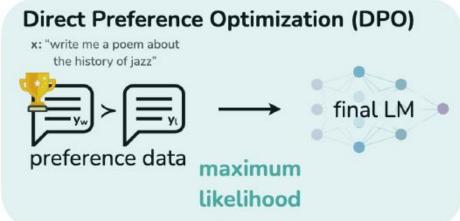
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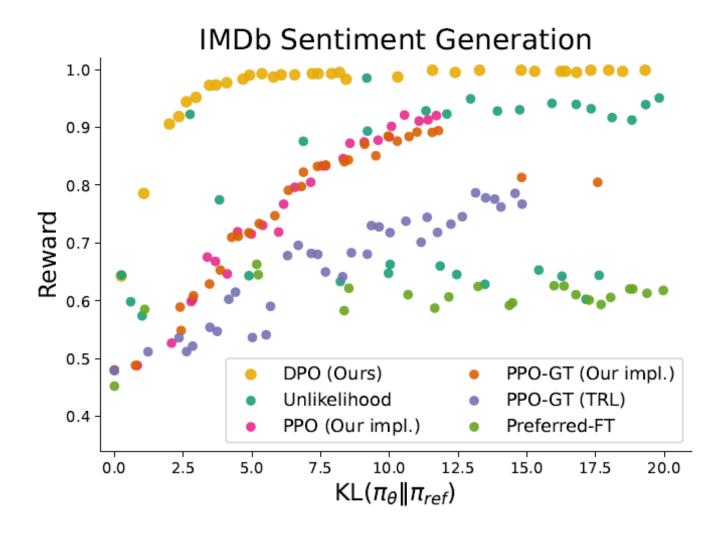
$$\hat{r}_{\theta}(x,y) = \beta \log \frac{\pi_{\theta}(y|x)}{\pi_{\text{ref}}(y|x)}$$
 Sour language model is secretly a reward model

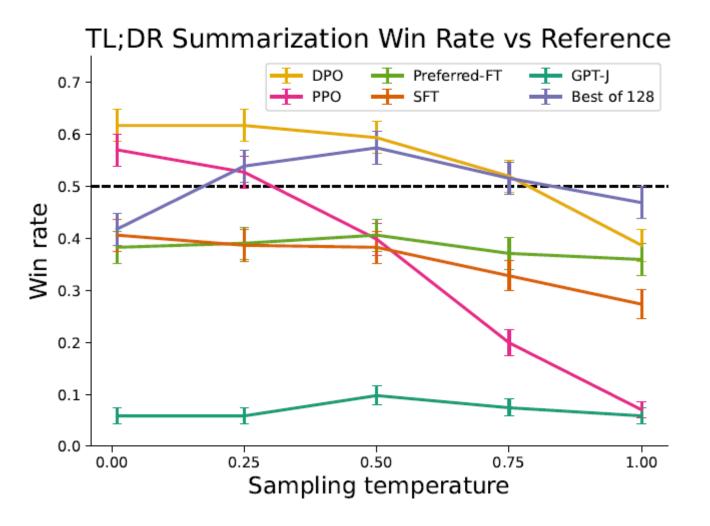
#### Solución: RLHF v/s DPO

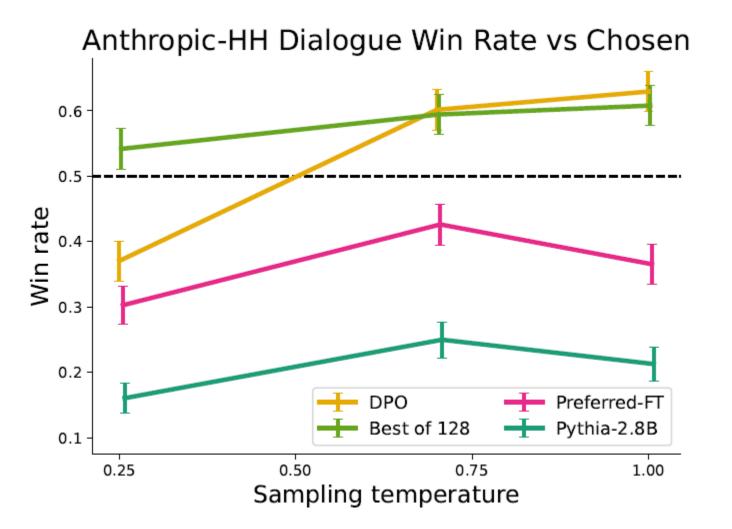




- ► Generación de sentimientos controlados: IMBd dataset (finetuned GPT-2).
- Resumen de texto: Reddit TL;DR summarization dataset (fine-tuned SFT).
- "Single-turn dialogue": Anthropic Helpful and Harmless dialogue dataset (fine-tuned off-the-shelf language model).







#### Discusión: conclusión

- > DPO simplifica el entrenamiento de modelos con preferencias.
- ▶ DPO entrena directamente las preferencias con una simple cross-entropy loss, sin aprendizaje reforzado o pérdida de generalidad.
- ► DPO tiene un rendimiento similar o mejor que los algoritmos RLHF existentes (PPO).

### Discusión: trabajo futuro

- ¿Cómo DPO rinde en otro tipo de tareas y en tareas distintas a las de entrenamiento, en comparación a los modelos de recompensa explícita?
- ¿Puede DPO entrenar con data no etiquetada haciendo un uso efectivo de esta?
- ► En la experimentación se ocuparon modelos con parámetros de hasta 6B, ¿cómo sería el rendimiento de DPO con modelos más grandes?

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