- · -> picking a pre-trained model to reuse
  - -> this is one from google which is called mobile net v2 which is built into tensor flow
  - -> he's defined the base model -> then the image shape which was defined above it
    - -> the architecture of what we want
    - -> weather we include the classifier or not
    - -> i.e the model which we're importing works for 1,000 different classes of objects -> we're not including the top
    - -> we're just loading the weights for what we want
  - -> then printing out the base model

- -> aka like the head of the dataset
- -> the architecture and the data
  - -> the architecture is like which rows and columns the matrix will have and the data is what fills it
- -> converting that imported model (to reuse) into a tensor

## -> freezing the base

- -> we are reusing a model and adding our points onto the top of it
- -> the model we are reusing is the 'base' -> freezing it means it doesn't change
- -> the only parts we are training are our data which we are adding over the top of it

- -> then printing out another summary of the data
- -> adding another classifier on top of it
  - taking the average of all the layers and inputting them into a 1D tensor
  - -> this is the global average pooling
    - moving the points into a 1D tensor
    - -> converting the borrowed model into one dense node

- · -> and then adding a prediction layer
  - -> the prediction layer creates the final model
  - -> running another summary then returns the number of trainable data
- -> then combining it with our data to create a new model

```
[ ] global_average_layer = tf.keras.layers.GlobalAveragePooling2D()
Finally we will add the prediction layer that will be a single dense neuron. We
prediction_layer = keras.layers.Dense(1)

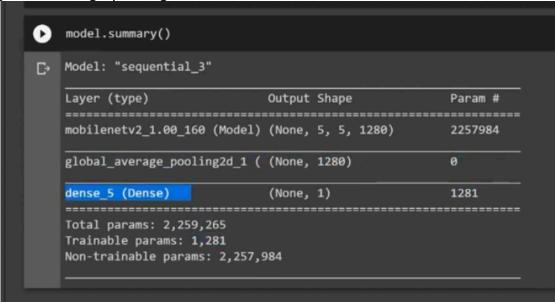
Now we will combine these layers together in a model.

[ ] model = tf.keras.Sequential([
    base_model,
    global_average_layer,
    prediction_layer
    ])

[ ] model.summary()
```

## -> then he's ran another summary

-> global average pooling



-> the only data which is trainable is our data (not the model we've borrowed)

# -> training the model

- -> the learning rate
  - -> he's picked one which is slow
  - -> not making major changes to the model
- -> then using binary cross entropy for the loss function because there are two input parameters
- -> evaluating the model currently without training it on our validation data
- -> it's returning the accuracy of the model as it trains it
- -> then running the training with the base layer

- -> it takes an hour to train with the base layer -> but has ~90% accuracy once it's been trained
- -> keras can be used to load the model -> rather than tensor flow
- · -> using the model
  - -> model.predict <- and it's suggesting the different parameters you could have</li>

### Object detection

- -> you can use tensor flow to do object detection and recognition
- -> there is an API for object detection
- o -> you can use this project using the documentation on its GitHub page from tensor flow
- -> Python also has a facial recognition module
- -> you need enough training data
  - -> then to create a model which uses mobile nets
  - -> mobile nets is the google training model which he's reused in this example

#### Next

-> recurrent neural networks