

Moderovacie a renderovacie techniky

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<https://github.com/frantisekdracek/Prezentacie/tree/main>

Tone mapping

- ▶ HDR merging: LDR \rightarrow HDR e.g: combine several pictures with different exposure into HDR image
- ▶ tone mapping: HDR \rightarrow LDR , HDR image to display's dynamic range
- ▶ Paper
- ▶ Tutorial

Debevec algorithm

The exposure, or "amount of light" hitting camera can be assumed to follow relation

$$X_{ij} = E_i \delta t_j, \quad (1)$$

where E_i radiance, δt_j exposure time, i spatial index and j time index. Photographic film response is a function of exposure:

$$Z_{ij} = f(E_i \delta t_j). \quad (2)$$

We can invert the relation and simplify by taking logarithm:

$$g(Z_{ij}) = \ln(f^{-1}(Z_{ij})) = \ln(E_i) + \ln(\Delta t_j). \quad (3)$$

What are we trying to do?

Our goal is to recover original exposures E_j , so we can construct HDR image. To achieve this, we need to know camera response curves $g(Z)$ for every channel.. Since Z takes on only integer values in range $\{0, \dots, 255\}$, we can transform this to optimization problem.

Minimalization in least squares sense:

$$\mathcal{O} = \sum_{i=1}^N \sum_{j=1}^P (g(Z_{ij}) - \ln(E_i) - \ln(\Delta t_j))^2, \quad (4)$$

N number of pixels, P number of images.

Debevec algorithm

Regularization term to prevent excessive curliness:

$$\mathcal{O} = \sum_{i=1}^N \sum_{j=1}^P (g(Z_{ij}) - \ln(E_i) - \ln(\Delta t_j))^2 + \lambda \sum_{Z_{min}+1}^{Z_{max}-1} g''(x)^2 \quad (5)$$

Weight term ensuring better fit:

$$\mathcal{O} = \sum_{i=1}^N \sum_{j=1}^P w(Z_{ij}) (g(Z_{ij}) - \ln(E_i) - \ln(\Delta t_j))^2 + \lambda \sum_{Z_{min}+1}^{Z_{max}-1} w(Z_{ij}) g''(x)^2 \quad (6)$$

$$w(z) = \begin{cases} z - Z_{min} & \text{if } z \leq \frac{1}{2}(Z_{min} + Z_{max}) \\ Z_{max} - z & \text{if } z \geq \frac{1}{2}(Z_{min} + Z_{max}) \end{cases} \quad (7)$$

Sampling

We don't have to use all pixels:

$$NP \geq Z_{\max} - Z_{\min} + N \quad (8)$$

Sampling matrix:

$$S = 256 \underbrace{\left\{ \begin{bmatrix} \dots & \dots & \dots \\ \dots & S_{zj} & \dots \\ \dots & \dots & \dots \end{bmatrix} \right\}}_P \quad (9)$$

- ▶ Select middle exposure image .
- ▶ for selected z localize position of all pixels with intensity z .
[$(k_1, l_1), (k_2, l_2), \dots$]
- ▶ select one random pair (k, l) .
- ▶ find intensity values on other images corresponding to (k, l)
- ▶ $S_{z,j} = Z_{i(k,l),j}$

Least squares

Standard linear regression

Linear regression problem:

$$Ax = b, \quad (10)$$

Least squares solution:

$$\mathcal{O} = \min \|Ax - b\|^2 \quad (11)$$

By taking gradient of condition and setting it to zero $\nabla_x \mathcal{O} \stackrel{!}{=} 0$:

$$x = (A^T A)^{-1} A^T b \quad (12)$$

Least squares

Standard linear regression - how to formulate optimization condition as matrix problem

We aim to formulate

$$\mathcal{O} = \sum_{i=1}^N \sum_{j=1}^P (g(Z_{ij}) - \ln(E_i) - \ln(\Delta t_j))^2 \quad (13)$$

as

$$\mathcal{O} = \min ||\mathbf{Ax} - \mathbf{b}||^2 = \min || \sum_l A_{kl} x_l - b_k ||^2 \quad (14)$$

This can be realized by choosing

$$\mathbf{x} = \begin{bmatrix} g(0) \\ g(1) \\ \vdots \\ g(255) \\ \ln(E_1) \\ \vdots \\ \ln(E_P) \end{bmatrix}, \quad (15)$$

$$\mathbf{b} = \begin{bmatrix} \ln(\Delta t_1) \\ \vdots \\ \ln(\Delta t_P) \\ \ln(\Delta t_1) \\ \vdots \\ \ln(\Delta t_P) \\ \vdots \\ \ln(\Delta t_1) \\ \vdots \\ \ln(\Delta t_P) \end{bmatrix}. \quad (16)$$

Where \mathbf{x} is a vector of size $256 + N$, with N is number of pixel locations.

Matrix \mathbf{A} is has $(N * P)$ rows and $256 + N$ columns. It is zero everywhere, except a column indexed by Z_{ij} , where it is 1 and column indexed by $256 + i$, where it is -1 . Rows of the matrix are index by i, j with row indices $r = N * i + j$.

Vector \mathbf{b} is just N times repeat exposure times $\ln(\delta t_j)$:

Least squares

Ridge regression

Linear regression problem:

$$Ax = b, \quad (17)$$

Least squares solution with Ridge regularization:

$$\mathcal{O} = \min ||Ax - b||^2 + \lambda ||x||^2 \quad (18)$$

Solution:

$$x = (A^T A + \lambda \mathbb{I})^{-1} A^T b \quad (19)$$

Equivalent to standard linear regression with modified matrix \tilde{A} .

$$\tilde{A} = \begin{bmatrix} A \\ \sqrt{\lambda} \mathbb{I} \end{bmatrix}. \quad (20)$$

Least squares

Second derivative regularization

Linear regression problem:

$$Ax = b, \quad (21)$$

Least squares solution with second derivative regularization:

$$\mathcal{O} = \min ||Ag(x) - b||^2 + \lambda ||g''(x)||^2 \quad (22)$$

Equivalent to:

$$\tilde{A} = \begin{bmatrix} A \\ \sqrt{\lambda}D \end{bmatrix}, \quad (23)$$

where:

$$D = \begin{bmatrix} 1 & -2 & 1 & 0 & \dots & \dots \\ 0 & 1 & -2 & 1 & \dots & \dots \\ 0 & 0 & 1 & -2 & 1 & \dots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \end{bmatrix} \quad (24)$$

Debevec to simple least squares

transform problem to matrix

$$\begin{bmatrix} A & E \\ D_w & 0 \end{bmatrix} \begin{bmatrix} g(0) \\ g(1) \\ \vdots \\ g(255) \\ \ln(E_1) \\ \vdots \end{bmatrix} = [\ln(\nabla t_1)], \quad (25)$$

where

$$D_w = \begin{bmatrix} w(1) & -2w(1) & w(1) & 0 & \dots & \dots \\ 0 & w(2) & -2w(2) & w(2) & \dots & \dots \\ 0 & 0 & w(3) & -2w(3) & w(1) & \dots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \end{bmatrix} \quad (26)$$

Debevec to simple least squares

$$\mathbf{b} = \begin{bmatrix} w(Z_{1,1}) \ln(\nabla t_1) \\ w(Z_{1,2}) \ln(\nabla t_2) \\ \vdots \\ w(Z_{1,P}) \ln(\nabla t_1) \\ w(Z_{2,1}) \ln(\nabla t_1) \\ \vdots \\ w(Z_{2,P}) \ln(\nabla t_P) \\ \vdots \\ w(Z_{N,1}) \ln(\nabla t_1) \\ \vdots \\ w(Z_{N,P}) \ln(\nabla t_P) \end{bmatrix} \quad (27)$$

Debevec to simple least squares

Matrix A is zero matrix except for following terms:

$$A_{P*(i-1)+j, Z_{i,j}} = w(Z_{i,j}) \quad (28)$$

Matrix E is zero matrix except for following terms:

$$E_{P*(i-1)+j,i} = w(Z_{i,j}) \quad (29)$$

Algorithm

1. Add data-fitting constraints:

$k = 0$

for i in range(num_samples):

 for j in range(num_images):

$z_{ij} = \text{intensity_samples}[i, j]$

$w_{ij} = \text{weighting_function}(z_{ij})$

$\text{mat_A}[k, z_{ij}] = w_{ij}$

$\text{mat_A}[k, (\text{intensity_range} + 1) + i] = -w_{ij}$

$\text{mat_b}[k, 0] = w_{ij} * \log_exposures[j]$

$k += 1$

2. Add smoothing constraints:

for z_k in range($z_{\min} + 1, z_{\max}$):

$w_k = \text{weighting_function}(z_k)$

$\text{mat_A}[k, z_k - 1] = w_k * \text{smoothing_lambda}$

$\text{mat_A}[k, z_k] = -2 * w_k * \text{smoothing_lambda}$

$\text{mat_A}[k, z_k + 1] = w_k * \text{smoothing_lambda}$

$k += 1$

3. Add color curve centering constraint:

$\text{mat_A}[k, (z_{\max} - z_{\min}) // 2] = 1$

Reconstructing radiance map

$$\ln(E_i) = \frac{1}{P} \sum_{j=1}^P (g(Z_{ij}) - \ln(\nabla t_j)) \quad (30)$$

With weights:

$$\ln(E_i) = \frac{\sum_{j=1}^P w(Z_{ij})(g(Z_{ij}) - \ln(\nabla t_j))}{\sum_{j=1}^P w(Z_{ij})} \quad (31)$$

Reconstructing radiance map

- ▶ Last step involves computing radiance map for every channel and combining them to a resulting HDR image.
- ▶ Follow with tone mapping techniques to map image to LDR for displaying purpose.

Thank you!