## Moderovacie a renderovacie techniky

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https://github.com/frantisekdracek/Prezentacie/tree/main



## Tone mapping

- ► HDR merging: LDR -> HDR e.g: combine several pictures with different exposure into HDR image
- tone mapping: HDR -> LDR , HDR image to display's dynamic range
- ▶ Paper
- ► Tutorial

## Debevec algorithm

The exposure, or "amount of light" hitting camera can be assumed to follow relation

$$X_{ij} = E_i \delta t_j, \tag{1}$$

where  $E_i$  radiance,  $\delta t_j$  exposure time, i spatial index and j time index. Photographic film response is a function of exposure:

$$Z_{ij} = f(E_i \delta t_j). \tag{2}$$

We can invert the relation and simplify by taking logarithm:

$$g(Z_{ij}) = \ln(f^{-1}(Z_{ij})) = \ln(E_i)\ln(\Delta t_j).$$
 (3)

# What are we trying to do?

Our goal is to recover original exposures  $E_{ij}$ , so we can construct HDR image. To achieve this, we need to know camera response curves g(Z) for every channel. Since Z takes on only integer values in range  $\{0,\ldots,255\}$ , we can transform this to optimization problem.

Minimalization in least squares sense:

$$\mathcal{O} = \sum_{i=1}^{N} \sum_{j=1}^{P} (g(Z_{ij}) - \ln(E_i) - \ln(\Delta t_j))^2, \tag{4}$$

N number of pixels, P number of images.

# Debevec algorithm

Regularization term to prevent excessive curliness:

$$\mathcal{O} = \sum_{i=1}^{N} \sum_{j=1}^{P} (g(Z_{ij}) - \ln(E_i) - \ln(\Delta t_j))^2 + \lambda \sum_{Z_{min}+1}^{Z_{max}-1} g''(x)^2$$
 (5)

Weight term ensuring better fit:

$$\mathcal{O} = \sum_{i=1}^{N} \sum_{j=1}^{P} w(Z_{ij}) (g(Z_{ij}) - \ln(E_i) - \ln(\Delta t_j))^2 + \lambda \sum_{Z_{min}+1}^{Z_{max}-1} w(Z_{ij}) g''(x)^2$$
(6)

$$w(z) = \begin{cases} z - Z_{min} & \text{if } z \le \frac{1}{2}(Z_{min} + Z_{max}) \\ Z_{max} - z & \text{if } z \ge \frac{1}{2}(Z_{min} + Z_{max}) \end{cases}$$
(7)

## Sampling

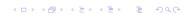
We dont have to use all pixels:

$$NP \ge Z_{max} - Z_{min} + N$$
 (8)

Sampling matrix:

$$S = 256 \left\{ \underbrace{\begin{bmatrix} \dots & \dots & \dots \\ \dots & S_{zj} & \dots \\ \dots & \dots & \dots \end{bmatrix}}_{P}$$
 (9)

- Select middle exposure image .
- for selected z localize position of all pixels with intensity z.  $[(k_1, l_1,), (k_2, l_2), \dots]$
- $\triangleright$  select one random pair (k, l).
- $\triangleright$  find intenisty values on other images correspoding to (k, l)
- $\triangleright$   $S_{z,j} = Z_{i(k,l),j}$



## Least squares

#### Standard linear regression

Linear regression problem:

$$Ax = b, (10)$$

Least squares solution:

$$\mathcal{O} = \min ||\mathsf{Ax} - \mathsf{b}||^2 \tag{11}$$

By taking gradient of condition and setting it to zero  $\nabla_x \mathcal{O} \stackrel{!}{=} 0$  :

$$x = (A^T A)^{-1} A^T b \tag{12}$$

## Least squares

Ridge regression

Linear regression problem:

$$Ax = b, (13)$$

Least squares solution with Ridge regularization:

$$\mathcal{O} = \min ||Ax - b||^2 + \lambda ||x||^2$$
 (14)

Solution:

$$\mathbf{x} = (\mathbf{A}^T \mathbf{A} + \lambda \mathbf{I})^{-1} \mathbf{A}^T \mathbf{b} \tag{15}$$

Equivalent to standard linear regression with modified matrix  $\tilde{A}$ .

$$\tilde{\mathsf{A}} = \begin{bmatrix} \mathsf{A} \\ \sqrt{\lambda} \mathbb{I} \end{bmatrix}. \tag{16}$$

### Least squares

#### Second derivative regularization

Linear regression problem:

$$Ax = b, (17)$$

Least squares solution with second derivative regularization:

$$\mathcal{O} = \min ||Ag(x) - b||^2 + \lambda ||g''(x)||^2$$
 (18)

Equivalent to:

$$\tilde{A} = \begin{bmatrix} A \\ \sqrt{\lambda} D \end{bmatrix}, \tag{19}$$

where:

$$D = \begin{bmatrix} 1 & -2 & 1 & 0 & \cdots & \cdots \\ 0 & 1 & -2 & 1 & \cdots & \cdots \\ 0 & 0 & 1 & -2 & 1 & \cdots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \end{bmatrix}$$
(20)

## Debevec to simple least squares

transform problem to matrix

$$\begin{bmatrix} A & E \\ D_{w} & 0 \end{bmatrix} \begin{bmatrix} g(0) \\ g(1) \\ \vdots \\ g(255) \\ \ln(E_{1}) \\ \vdots \end{bmatrix} - \left[ \ln(\nabla t_{1}) \right], \tag{21}$$

where

$$D_{w} = \begin{bmatrix} w(1) & -2w(1) & w(1) & 0 & \cdots & \cdots \\ 0 & w(2) & -2w(2) & w(2) & \cdots & \cdots \\ 0 & 0 & w(3) & -2w(3) & w(1) & \cdots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \end{bmatrix}$$
(22)

## Debevec to simple least squares

$$b = \begin{bmatrix} w(Z_{1,1}) \ln(\nabla t_{1}) \\ w(Z_{1,2}) \ln(\nabla t_{2}) \\ \vdots \\ w(Z_{1,P}) \ln(\nabla t_{1}) \\ w(Z_{2,1}) \ln(\nabla t_{1}) \\ \vdots \\ w(Z_{2,P}) \ln(\nabla t_{P}) \\ \vdots \\ w(Z_{N,1}) \ln(\nabla t_{1}) \\ \vdots \\ w(Z_{N,P}) \ln(\nabla t_{P}) \end{bmatrix}$$

$$(23)$$

## Debevec to simple least squares

Matrix A is zero matrix except for following terms:

$$A_{P*(i-1)+j,Z_{i,j}} = w(Z_{i,j})$$
 (24)

Matrix E is zero matrix except for following terms:

$$\mathsf{E}_{P*(i-1)+j,i} = w(Z_{i,j}) \tag{25}$$

## Algorithm

```
# 1. Add data-fitting constraints:
k = 0
for i in range(num samples):
    for i in range(num images):
        z ij = intensity samples[i, j]
        w ij = weighting function(z ij)
        mat A[k, z ij] = w ij
        mat A[k, (intensity range + 1) + i] = -w ij
        mat b[k, 0] = w ij * log exposures[j]
        k += 1
# 2. Add smoothing constraints:
for z k in range(z_min + 1, z_max):
    w k = weighting function(z k)
    mat A[k, z k - 1] = w k * smoothing lambda
    mat A[k, z k] = -2 * w k * smoothing lambda
    mat A[k, z k + 1] = w k * smoothing lambda
    k += 1
# 3. Add color curve centering constraint:
```

mat A[k, (z max - z min) // 2] = 1

## Reconstructing radiance map

$$\ln(E_i) = \frac{1}{P} \sum_{i=1}^{P} (g(Z_{ij}) - \ln(\nabla t_j))$$
 (26)

With weights:

$$\ln(E_i) = \frac{\sum_{j=1}^{P} w(Z_{ij})(g(Z_{ij}) - \ln(\nabla t_j))}{\sum_{j=1}^{P} w(Z_{ij})}$$
(27)

## Reconstructing radiance map

- ► Last step involves computing radiance map for every channel and combining them to a resulting HDR image.
- Follow with tone mapping techniques to map image to LDR for displaying purpose.

# Thank you!