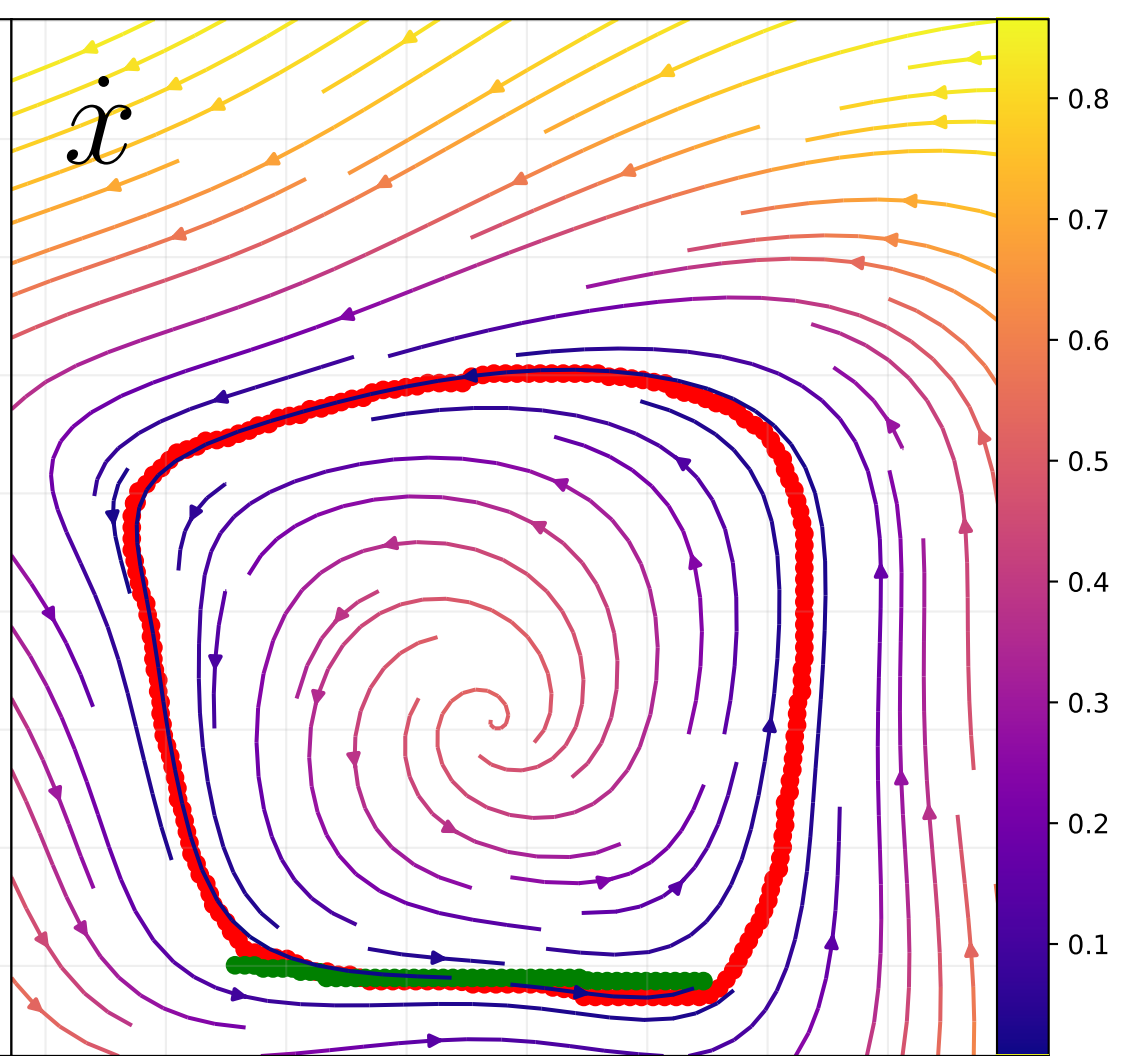
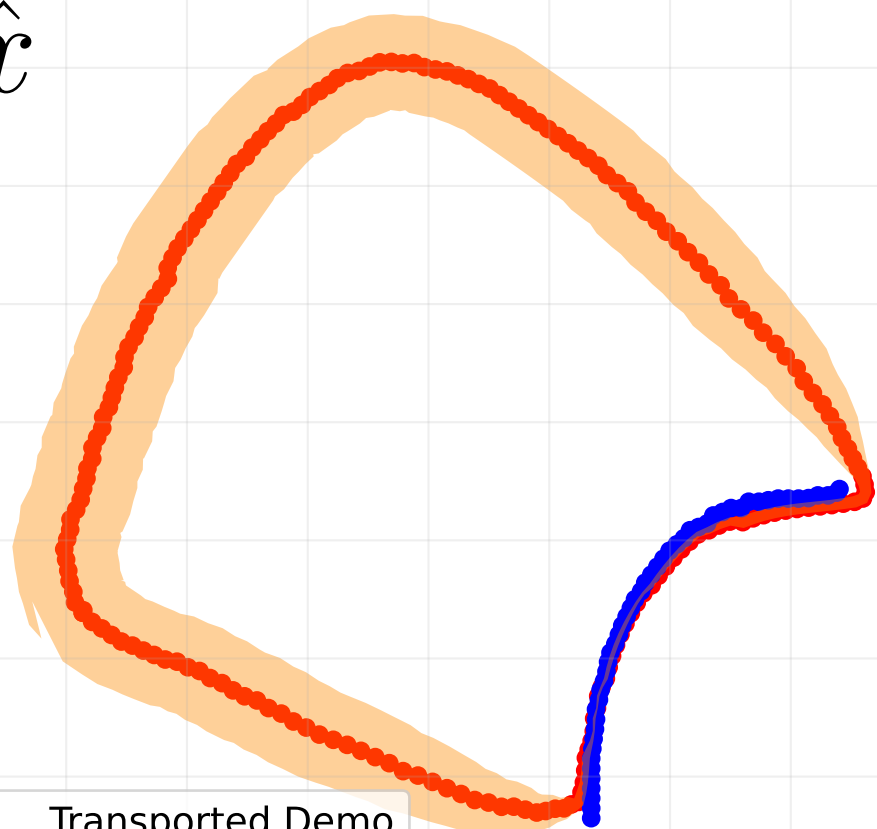


$x$ 

- Demonstration
- Source Distribution

 $\dot{x}$  $\hat{x}$ 

- Transported Demo
- Target Distribution
- Uncertainty

 $\dot{\hat{x}}$ 