Robot Functions:

d. (…) = drive controller

m. (…) = mechanism controller

* Drive
  + Turn d. right stick x
  + Move d. left stick x, d. left stick y
* Spinny wheel
  + Raise/lower m. left bumper
  + First phase m. back
  + Second phase m. start
* Ball intake
  + Lower and run d. A
  + (more) d. B, Y, X
* Shoot
  + Up against wall m. A
  + From start line m. B
  + Auto start line m. right bumper + B
  + From trench m. Y
  + Auto trench m. right bumper + Y
  + Reverse indexer X
  + #Turn on m. right trigger (maybe speed relative to amount trigger down)
* Climber
  + Release d. left bumper
  + Winch d. left trigger