

com._604robotics.robot2012.configuration

Interface ActuatorConfiguration.ELEVATOR

Enclosing interface:

ActuatorConfiguration

```
public static interface ActuatorConfiguration.ELEVATOR
```

Nested Class Summary

Nested Classes

Modifier and Type	Interface and Description
static interface	ActuatorConfiguration.ELEVATOR.DEADBAND
static interface	ActuatorConfiguration.ELEVATOR.TOLERANCE

Field Summary

Fields

Modifier and Type	Field and Description
static int	HIGH
static int	LOW
static int	MEDIUM
static int	OKAY_TO_TURN

Field Detail

HIGH

```
static final int HIGH
```

See Also:

Constant Field Values

MEDIUM

```
static final int MEDIUM
```

See Also:

Constant Field Values

LOW

```
static final int LOW
```

See Also:

Constant Field Values

OKAY_TO_TURN

```
static final int OKAY_TO_TURN
```

See Also:

Constant Field Values

[Overview](#) [Package](#) **[Class](#)** [Tree](#) [Deprecated](#) [Index](#) [Help](#)

[Prev Class](#) **[Next Class](#)** [Frames](#) [No Frames](#) [All Classes](#)

Summary: [Nested](#) | [Field](#) | [Constr](#) | [Method](#) Detail: [Field](#) | [Constr](#) | [Method](#)