

A B C D E F G H I L M P Q R S T U V W X Y Z

## Y

**y** - Variable in class `com._604robotics.robot2012.vision.Point2d`

The Y value

**y** - Variable in class `com._604robotics.robot2012.vision.Point3d`

The Y value

**y** - Variable in class `com._604robotics.robot2012.vision.Target`

x, y, and z represent the 3-d position of the target x will be positive when the target appears to be right of the center of the camera.

**y1** - Variable in class `com._604robotics.robot2012.vision.AABB`

**y2** - Variable in class `com._604robotics.robot2012.vision.AABB`

**yUncertainty** - Variable in class `com._604robotics.robot2012.vision.Target`

These are the uncertainties of the x, y, and z positions of the target.

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