

## Package com.\_604robotics.robot2012.configuration

### Interface Summary

Interface	Description
<b>ActuatorConfiguration</b>	Actuator polarity and power configuration.
ActuatorConfiguration.ELEVATOR	
ActuatorConfiguration.ELEVATOR.DEADBAND	
ActuatorConfiguration.ELEVATOR.TOLERANCE	
ActuatorConfiguration.RING_LIGHT	
ActuatorConfiguration.SOLENOID_HOPPER	
ActuatorConfiguration.SOLENOID_PICKUP	
ActuatorConfiguration.SOLENOID_SHIFTER	
ActuatorConfiguration.SOLENOID_SHOOTER	
ActuatorConfiguration.TURRET_POSITION	
<b>AutonomousConfiguration</b>	Autonomous mode configuration.
<b>ButtonConfiguration</b>	Button configuration.
ButtonConfiguration.Driver	
ButtonConfiguration.Manipulator	
ButtonConfiguration.Manipulator.Elevator	
<b>PortConfiguration</b>	Port configuration.
PortConfiguration.Controllers	
PortConfiguration.Encoders	
PortConfiguration.Encoders.Drive	
PortConfiguration.Motors	
PortConfiguration.Pneumatics	
PortConfiguration.Pneumatics.HOPPER_SOLENOID	
PortConfiguration.Pneumatics.PICKUP_SOLENOID	
PortConfiguration.Pneumatics.SHIFTER_SOLENOID	
PortConfiguration.Pneumatics.SHOOTER_SOLENOID	
PortConfiguration.Relays	
PortConfiguration.Sensors	
<b>SensorConfiguration</b>	Sensor configuration.
SensorConfiguration.Encoders	