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com._604robotics.utils

Class SpringableDoubleSolenoid

java.lang.Object
edu.wpi.first.wpilibj.SensorBase
edu.wpi.first.wpilibj.SolenoidBase
edu.wpi.first.wpilibj.DoubleSolenoid
com._604robotics.utils.SpringableDoubleSolenoid

All Implemented Interfaces:

IDevice, IDeviceController

public class SpringableDoubleSolenoid

extends DoubleSolenoid

Extender of a DoubleSolenoid providing an easier control flow. When an output is set for the DoubleSolenoid, it is considered "sprung". When the "reload" method is called, if the victor is sprung, it unsprings the DoubleSolenoid. If the DoubleSolenoid is not sprung, then the output is set to the default output. In this way, the DoubleSolenoid will only be moving when you tell it to. Use this in a loop or something, and call "reload" at the end. No more worries about code paths that don't update the DoubleSolenoids!

Author:

Michael Smith

Nested Class Summary

Nested classes/interfaces inherited from class edu.wpi.first.wpilibj.DoubleSolenoid

DoubleSolenoid. Value

Field Summary

Fields inherited from class edu.wpi.first.wpilibj.SolenoidBase

m allocated, m moduleNumber

Fields inherited from class edu.wpi.first.wpilibj.SensorBase

 $kAnalogChannels,\ kAnalogModules,\ kDigitalChannels,\ kPwmChannels,\ kRelayChannels,\ kSolenoidChannels,\ kSolenoidModules,\ kSystemClockTicksPerMicrosecond$

Constructor Summary

Constructors

Constructor and Description

SpringableDoubleSolenoid(int forwardChannel, int reverseChannel, DoubleSolenoid.Value defaultDirection) Initializes a new SpringableDoubleSolenoid.

SpringableDoubleSolenoid(int moduleNumber, int forwardChannel, int reverseChannel,
DoubleSolenoid.Value defaultDirection)

Initializes a new SpringableDoubleSolenoid.

Method Summary

Methods

memeas	
Modifier and Type	Method and Description
boolean	getSprung() Has the DoubleSolenoid been sprung?
void	<pre>reload() If the DoubleSolenoid has been sprung, unspring it; if not, set the output to the default output.</pre>

void set(DoubleSolenoid.Value direction)

Sets the direction of the DoubleSolenoid.

void spring()

Springs the DoubleSolenoid.

Methods inherited from class edu.wpi.first.wpilibj.DoubleSolenoid

free, get

Methods inherited from class edu.wpi.first.wpilibj.SolenoidBase

getAll, getAllFromDefaultModule, getAllFromModule, set

Methods inherited from class edu.wpi.first.wpilibj.SensorBase

checkAnalogChannel, checkAnalogModule, checkDigitalChannel, checkDigitalModule, checkPWMChannel, checkPWMModule, checkRelayChannel, checkRelayChannel, checkSolenoidChannel, checkSolenoidModule, getDefaultAnalogModule, getDefaultDigitalModule, getDefaultSolenoidModule, setDefaultAnalogModule, setDefaultSolenoidModule

Methods inherited from class java.lang.Object

clone, equals, finalize, getClass, hashCode, notify, notifyAll, toString, wait, wait, wait

Constructor Detail

SpringableDoubleSolenoid

Initializes a new SpringableDoubleSolenoid.

Parameters:

forwardChannel - The forward channel of the DoubleSolenoid.

 ${\tt reverseChannel} \ \hbox{-} \ \hbox{The reverse channel of the DoubleSolenoid}.$

defaultDirection - The default direction for reloads

SpringableDoubleSolenoid

Initializes a new SpringableDoubleSolenoid.

Parameters:

moduleNumber - The slot number of the solenoid module.

 ${\tt forwardChannel} \ \hbox{-} \ \textbf{The forward channel of the DoubleSolenoid}.$

reverseChannel - The reverse channel of the DoubleSolenoid.

 ${\tt default Direction} \textbf{-} \textbf{The default direction for reloads}.$

Method Detail

getSprung

public boolean getSprung()

Has the DoubleSolenoid been sprung?

Returns:

Whether or not the DoubleSolenoid has been sprung.

spring

public void spring()

Springs the DoubleSolenoid.

set

public void set(DoubleSolenoid.Value direction)

Sets the direction of the DoubleSolenoid.

Overrides:

set in class DoubleSolenoid

Parameters:

direction - The direction to set.

reload

public void reload()

If the DoubleSolenoid has been sprung, unspring it; if not, set the output to the default output.

