

com._604robotics.robot2012.configuration

Interface ButtonConfiguration.Manipulator

Enclosing interface:

ButtonConfiguration

```
public static interface ButtonConfiguration.Manipulator
```

Nested Class Summary

Nested Classes

Modifier and Type	Interface and Description
static interface	ButtonConfiguration.Manipulator.Elevator

Field Summary

Fields

Modifier and Type	Field and Description
static int	AIM_AND_SHOOT
static int	PICKUP
static int	TOGGLE_ANGLE
static int	TOGGLE_HEIGHT
static int	TOGGLE_LIGHT

Field Detail

AIM_AND_SHOOT

```
static final int AIM_AND_SHOOT
```

See Also:

Constant Field Values

PICKUP

```
static final int PICKUP
```

See Also:

Constant Field Values

TOGGLE_HEIGHT

```
static final int TOGGLE_HEIGHT
```

See Also:

Constant Field Values

TOGGLE_ANGLE

```
static final int TOGGLE_ANGLE
```

See Also:

Constant Field Values

TOGGLE_LIGHT

```
static final int TOGGLE_LIGHT
```

See Also:

[Constant Field Values](#)