

com.\_604robotics.robot2012.configuration

## Interface ActuatorConfiguration.SOLENOID\_SHIFTER

Enclosing interface:  
ActuatorConfiguration

```
public static interface ActuatorConfiguration.SOLENOID_SHIFTER
```

Field Summary

Fields

Modifier and Type	Field and Description
static DoubleSolenoid.Value	HIGH_GEAR
static DoubleSolenoid.Value	LOW_GEAR

Field Detail

LOW\_GEAR

static final DoubleSolenoid.Value LOW\_GEAR

HIGH\_GEAR

static final DoubleSolenoid.Value HIGH\_GEAR