

com._604robotics.robot2012.configuration

Interface SensorConfiguration.Encoders

Enclosing interface:
SensorConfiguration

public static interface **SensorConfiguration.Encoders**

Field Summary

Fields

Modifier and Type	Field and Description
static double	LEFT_DRIVE_INCHES_PER_CLICK
static double	RIGHT_DRIVE_INCHES_PER_CLICK
static double	TURRET_DEGREES_PER_CLICK

Field Detail

TURRET_DEGREES_PER_CLICK

static final double TURRET_DEGREES_PER_CLICK

See Also:
Constant Field Values

LEFT_DRIVE_INCHES_PER_CLICK

static final double LEFT_DRIVE_INCHES_PER_CLICK

See Also:
Constant Field Values

RIGHT_DRIVE_INCHES_PER_CLICK

static final double RIGHT_DRIVE_INCHES_PER_CLICK

See Also:
Constant Field Values