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S

save(File) - Method in class com._604robotics.robot2012.vision.config.Config
  Saves this Config to a given file
saveDefaultConfig() - Method in class com._604robotics.robot2012.vision.config.Config
  Saves this Config to the default file
scanWholeTile - Variable in class com._604robotics.robot2012.vision.config.Config
  Should all pixels be scanned in every tile be scanned, or just the corners (and possibly center)
sensitivity - Variable in class com._604robotics.robot2012.vision.config.Config
  A constant between -128 to +127 indicating how sensitive the color acceptance of the target should be.
set(int, int, int) - Method in class com._604robotics.robot2012.vision.Img

setAngle(double) - Method in class com._604robotics.robot2012.vision.Target

setAngleUncertainty(double) - Method in class com._604robotics.robot2012.vision.Target

setPoint(Point3d) - Method in class com._604robotics.robot2012.vision.Target

setValue(double) - Method in class com._604robotics.robot2012.vision.config.LinkedSlider.DoubleLinkedSlider

setValue(double) - Method in class com._604robotics.robot2012.vision.config.LinkedSlider.ExponentialLinkedSlider

setValue(double) - Method in class com._604robotics.robot2012.vision.config.LinkedSlider.IntLinkedSlider

setValue(double) - Method in class com._604robotics.robot2012.vision.config.LinkedSlider
  A setter for the value of the slider
setX(double) - Method in class com._604robotics.robot2012.vision.Point2d
  Sets the X value of this Point
setX(double) - Method in class com._604robotics.robot2012.vision.Point3d
  Sets the X value of this Point
setX(double) - Method in class com._604robotics.robot2012.vision.Target

setXUncertainty(double) - Method in class com._604robotics.robot2012.vision.Target

setY(double) - Method in class com._604robotics.robot2012.vision.Point2d
  Sets the Y value of this Point
setY(double) - Method in class com._604robotics.robot2012.vision.Point3d
  Sets the Y value of this Point
setY(double) - Method in class com._604robotics.robot2012.vision.Target

setYUncertainty(double) - Method in class com._604robotics.robot2012.vision.Target

setZ(double) - Method in class com._604robotics.robot2012.vision.Point3d
  Sets the Z value of this Point
setZ(double) - Method in class com._604robotics.robot2012.vision.Target

setZUncertainty(double) - Method in class com._604robotics.robot2012.vision.Target

Side_Bottom - Static variable in class com._604robotics.robot2012.vision.VisionProcessing
  Constants indicating the Left, Top, Right, and Bottom sides of a target or bounding box.
Side_Left - Static variable in class com._604robotics.robot2012.vision.VisionProcessing
  Constants indicating the Left, Top, Right, and Bottom sides of a target or bounding box.
Side_Right - Static variable in class com._604robotics.robot2012.vision.VisionProcessing
  Constants indicating the Left, Top, Right, and Bottom sides of a target or bounding box.
Side_Top - Static variable in class com._604robotics.robot2012.vision.VisionProcessing
  Constants indicating the Left, Top, Right, and Bottom sides of a target or bounding box.
skipToBoundary(String) - Method in class com.charliemouse.cambozola.shared.StreamSplit

slider - Variable in class com._604robotics.robot2012.vision.config.LinkedSlider
  The slider that the user interacts with
solve(LinearRegression.RegressionResult, LinearRegression.RegressionResult) - Static method in class
com._604robotics.robot2012.vision.LinearRegression
  Computes the intersection of two RegressionResults
stateChanged(ChangeEvent) - Method in class com._604robotics.robot2012.vision.config.LinkedSlider

StreamSplit - Class in com.charliemouse.cambozola.shared
  com/charliemouse/cambozola/shared/CamStream.java
  Copyright (C) Andy Wilcock, 2001.
StreamSplit(DataInputStream) - Constructor for class com.charliemouse.cambozola.shared.StreamSplit

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