

com.\_604robotics.utils

## Class CompensatingGyro

java.lang.Object  
  edu.wpi.first.wpilibj.SensorBase  
    edu.wpi.first.wpilibj.Gyro  
      edu.wpi.first.wpilibj.GyroHax  
        com.\_604robotics.utils.CompensatingGyro

All Implemented Interfaces:

IDevice, ISensor, PIDSource

```
public class CompensatingGyro
extends GyroHax
```

Gyro with manual compensation-setting support.

Author:

Michael Smith

Field Summary

Fields inherited from class edu.wpi.first.wpilibj.SensorBase

kAnalogChannels, kAnalogModules, kDigitalChannels, kPwmChannels, kRelayChannels, kSolenoidChannels, kSolenoidModules, kSystemClockTicksPerMicrosecond

Constructor Summary

Constructors

Constructor and Description

CompensatingGyro (AnalogChannel channel)

Initializes a new CompensatingGyro on the specified AnalogChannel.

CompensatingGyro (int port)

Initializes a new CompensatingGyro on the specified PWM port.

CompensatingGyro (int slot, int port)

Initializes a new CompensatingGyro on the specified PWM port on the specified module port.

Method Summary

Methods

Modifier and Type	Method and Description
void	<div>setAccumulatorCenter (int center)</div> <div>Manually sets the center for the accumulator.</div>

Methods inherited from class edu.wpi.first.wpilibj.GyroHax

getAnalogChannel

Methods inherited from class edu.wpi.first.wpilibj.Gyro

free, getAngle, pidGet, reset, setSensitivity

Methods inherited from class edu.wpi.first.wpilibj.SensorBase

checkAnalogChannel, checkAnalogModule, checkDigitalChannel, checkDigitalModule, checkPWMChannel, checkPWMModule, checkRelayChannel, checkRelayModule, checkSolenoidChannel, checkSolenoidModule, getDefaultAnalogModule, getDefaultDigitalModule, getDefaultSolenoidModule, setDefaultAnalogModule, setDefaultDigitalModule, setDefaultSolenoidModule

Methods inherited from class java.lang.Object

clone, equals, finalize, getClass, hashCode, notify, notifyAll, toString, wait, wait, wait

Constructor Detail

CompensatingGyro

public CompensatingGyro(int port)

Initializes a new CompensatingGyro on the specified PWM port. Note that port must be 1 or 2!

Parameters:

port - The PWM port the gyro is plugged into. Must be 1 or 2!

CompensatingGyro

public CompensatingGyro(int slot,
int port)

Initializes a new CompensatingGyro on the specified PWM port on the specified module port. Note that port must be 1 or 2!

Parameters:

slot - The module slot the gyro is plugged into.
port - The PWM port the gyro is plugged into. Must be 1 or 2!

CompensatingGyro

public CompensatingGyro(AnalogChannel channel)

Initializes a new CompensatingGyro on the specified AnalogChannel. Note that port must be 1 or 2!

Parameters:

channel - The AnalogChannel the gyro is plugged into.

Method Detail

setAccumulatorCenter

public void setAccumulatorCenter(int center)

Manually sets the center for the accumulator.

Parameters:

center - The center to set.