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L

LinearRegression - Class in com._604robotics.robot2012.vision

Accepts a sequence of pairs of real numbers and computes the best fit (least squares) line y = ax + b through the set of points. **LinearRegression()** - Constructor for class com._604robotics.robot2012.vision.LinearRegression

 $\textbf{Linear Regression.} \textbf{Backwards Regression Result} - \textbf{Class in } com. _604 robotics. robot 2012. vision$

A regression result that, instead of having y as a function of x has x as a function of y. **LinearRegression.BackwardsRegressionResult(double, double, double)** - Constructor for class com._604robotics.robot2012.vision.LinearRegression.BackwardsRegressionResult

LinearRegression.RegressionResult - Class in com. 604robotics.robot2012.vision

A regression result that indicates the line that best matches a given set of data. **LinearRegression.RegressionResult(double, double)** - Constructor for class com._604robotics.robot2012.vision.LinearRegression.RegressionResult

LinkedSlider - Class in com._604robotics.robot2012.vision.config

A JSlider that displays its current position and name in JLabels next to it

LinkedSlider(String, int, int, int) - Constructor for class com_604robotics.robot2012.vision.config.LinkedSlider

A constructor for a LinkedSlider

 $\textbf{LinkedSlider.DoubleLinkedSlider-Class} \ in \ com. _604 robotics. robot 2012. vision. configuration of the control of the$

A LinkedSlider that can be set to floating-point values

LinkedSlider.DoubleLinkedSlider(String, double, double) - Constructor for class com._604robotics.robot2012.vision.config.LinkedSlider.DoubleLinkedSlider

A constructor for a DoubleLinkedSlider

LinkedSlider.ExponentialLinkedSlider - Class in com._604robotics.robot2012.vision.config

A LinkedSlider that has an exponential scale, so it is much easier to pick small values (close to zero) while still allowing a range up to 1

LinkedSlider.ExponentialLinkedSlider(String, double, double) - Constructor for class

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A constructor to make an ExponentialLinkedSlider

 $\textbf{LinkedSlider}. \textbf{ExponentialLinkedSlider} (\textbf{String}, \textbf{double}) - \textbf{Constructor} \ for \ class$

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A constructor to make an ExponentialLinkedSlider.

LinkedSlider.IntLinkedSlider - Class in com._604robotics.robot2012.vision.config

A LinkedSlider that can only be set to integers

LinkedSlider.IntLinkedSlider(String, int, int, int) - Constructor for class com._604robotics.robot2012.vision.config.LinkedSlider.IntLinkedSlider

A constructor

 $\textbf{loopAndProcessPics()} - \textbf{Method in class com.} \underline{-} 604 robotics. robot 2012. vision. Vision Processing$

This function waits for images from the image stream, processes them, and then sends results to the robot.

IoopAndProcessPreSavedPics() - Method in class com._604robotics.robot2012.vision.VisionProcessing

This function is just a simple debug function for testing with pre-saved images.

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