

com.\_604robotics.robot2012.configuration

## Interface ActuatorConfiguration

public interface **ActuatorConfiguration**

Actuator polarity and power configuration.

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### Nested Class Summary

Nested Classes

Modifier and Type	Interface and Description
static interface	<a href="#">ActuatorConfiguration.ELEVATOR</a>
static interface	<a href="#">ActuatorConfiguration.RING_LIGHT</a>
static interface	<a href="#">ActuatorConfiguration.SOLENOID_HOPPER</a>
static interface	<a href="#">ActuatorConfiguration.SOLENOID_PICKUP</a>
static interface	<a href="#">ActuatorConfiguration.SOLENOID_SHIFTER</a>
static interface	<a href="#">ActuatorConfiguration.SOLENOID_SHOOTER</a>
static interface	<a href="#">ActuatorConfiguration.TURRET_POSITION</a>

### Field Summary

Fields

Modifier and Type	Field and Description
static double	<a href="#">ACCELEROMETER_DRIVE_POWER</a>
static double	<a href="#">ELEVATOR_POWER_MAX</a>
static double	<a href="#">ELEVATOR_POWER_MIN</a>
static double	<a href="#">HOPPER_POWER</a>
static double	<a href="#">HOPPER_POWER_REVERSE</a>
static double	<a href="#">PICKUP_POWER</a>
static double	<a href="#">TURRET_ROTATION_POWER_MAX</a>
static double	<a href="#">TURRET_ROTATION_POWER_MIN</a>

### Field Detail

#### ACCELEROMETER\_DRIVE\_POWER

static final double ACCELEROMETER\_DRIVE\_POWER

See Also:

[Constant Field Values](#)

#### HOPPER\_POWER

static final double HOPPER\_POWER

See Also:

[Constant Field Values](#)

#### HOPPER\_POWER\_REVERSE

static final double HOPPER\_POWER\_REVERSE

**See Also:**  
[Constant Field Values](#)

**PICKUP\_POWER**

static final double PICKUP\_POWER

**See Also:**  
[Constant Field Values](#)

**ELEVATOR\_POWER\_MIN**

static final double ELEVATOR\_POWER\_MIN

**See Also:**  
[Constant Field Values](#)

**ELEVATOR\_POWER\_MAX**

static final double ELEVATOR\_POWER\_MAX

**See Also:**  
[Constant Field Values](#)

**TURRET\_ROTATION\_POWER\_MIN**

static final double TURRET\_ROTATION\_POWER\_MIN

**See Also:**  
[Constant Field Values](#)

**TURRET\_ROTATION\_POWER\_MAX**

static final double TURRET\_ROTATION\_POWER\_MAX

**See Also:**  
[Constant Field Values](#)