

com._604robotics.robot2012.configuration

Interface ActuatorConfiguration.ELEVATOR.DEADBAND

Enclosing interface:

[ActuatorConfiguration.ELEVATOR](#)

```
public static interface ActuatorConfiguration.ELEVATOR.DEADBAND
```

Field Summary

Fields	
Modifier and Type	Field and Description
static int	HIGH
static int	LOW
static int	MEDIUM_LOWER
static int	MEDIUM_UPPER

Field Detail

HIGH

```
static final int HIGH
```

See Also:
[Constant Field Values](#)

MEDIUM_UPPER

```
static final int MEDIUM_UPPER
```

See Also:
[Constant Field Values](#)

MEDIUM_LOWER

```
static final int MEDIUM_LOWER
```

See Also:
[Constant Field Values](#)

LOW

```
static final int LOW
```

See Also:
[Constant Field Values](#)