

com._604robotics.robot2012.configuration

Interface PortConfiguration.Controllers

Enclosing interface:

[PortConfiguration](#)

```
public static interface PortConfiguration.Controllers
```

Field Summary

Fields	
Modifier and Type	Field and Description
static int	DRIVE
static int	MANIPULATOR

Field Detail

DRIVE

```
static final int DRIVE
```

See Also:
[Constant Field Values](#)

MANIPULATOR

```
static final int MANIPULATOR
```

See Also:
[Constant Field Values](#)