

com.\_604robotics.robot2012.configuration

# Interface **ActuatorConfiguration.SOLENOID\_PICKUP**

Enclosing interface:  
[ActuatorConfiguration](#)

```
public static interface ActuatorConfiguration.SOLENOID_PICKUP
```

**Field Summary**

Fields

Modifier and Type	Field and Description
static <a href="#">DoubleSolenoid.Value</a>	<b>IN</b>
static <a href="#">DoubleSolenoid.Value</a>	<b>OUT</b>

**Field Detail**

**IN**

```
static final DoubleSolenoid.Value IN
```

**OUT**

```
static final DoubleSolenoid.Value OUT
```