com._604robotics.utils

Class UpDownPIDController.Gains

java.lang.Object

com._604robotics.utils.UpDownPIDController.Gains

Enclosing class:

UpDownPIDController

public static class UpDownPIDController.Gains
extends Object

A structure containing the P, I, and D gains.

Field Summary

Fields

Modifier and Type	Field and Description
double	D
double	I
double	P

Constructor Summary

Constructors

Constructor and Description

 $\label{thm:controller:Gains} \textbf{(double P, double I, double D)}$

Method Summary

Methods inherited from class java.lang.Object

clone, equals, finalize, getClass, hashCode, notify, notifyAll, toString, wait, wait, wait

Field Detail

Р

public double P

T

public double I

D

public double D

Constructor Detail

UpDownPIDController.Gains

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Summary: Nested | Field | Constr | Method Detail: Field | Constr | Method