

com.\_604robotics.robot2012.configuration

## Interface SensorConfiguration

public interface **SensorConfiguration**

Sensor configuration.

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Nested Class Summary

Nested Classes

Modifier and Type	Interface and Description
static interface	<a href="#">SensorConfiguration.Encoders</a>

Field Summary

Fields

Modifier and Type	Field and Description
static double	<a href="#">ACCELEROMETER_SENSITIVITY</a>
static double	<a href="#">ACCELEROMETER_UPPER_RADIANS</a>
static double	<a href="#">GYRO_DRIFT</a>
static int	<a href="#">TURRET_CALIBRATION_OFFSET</a>

Field Detail

GYRO\_DRIFT

```
static final double GYRO_DRIFT
```

See Also:

Constant Field Values

ACCELEROMETER\_SENSITIVITY

```
static final double ACCELEROMETER_SENSITIVITY
```

See Also:

Constant Field Values

ACCELEROMETER\_UPPER\_RADIANS

```
static final double ACCELEROMETER_UPPER_RADIANS
```

See Also:

Constant Field Values

TURRET\_CALIBRATION\_OFFSET

```
static final int TURRET_CALIBRATION_OFFSET
```

See Also:

Constant Field Values

