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ABCDEFGHILMPQRSTUVWXYZ

Z

z - Variable in class com._604robotics.robot2012.vision.Point3d

The Z value

z - Variable in class com._604robotics.robot2012.vision.Target

x, y, and z represent the 3-d position of the target x will be positive when the target appears to be right of the center of the camera.

zUncertainty - Variable in class com._604robotics.robot2012.vision.Target

These are the uncertainties of the x, y, and z positions of the target.

ABCDEFGHILMPQRSTUVWXYZ