Overview Package Class Use Tree Deprecated Index Help

Prev Letter Next Letter Frames No Frames All Classes

ABCDEFGHILMPQRSTUVWXYZ



x - Variable in class com._604robotics.robot2012.vision.Point2d

The X value

x - Variable in class com._604robotics.robot2012.vision.Point3d

The X value

x - Variable in class com._604robotics.robot2012.vision.Target

x, y, and z represent the 3-d position of the target x will be positive when the target appears to be right of the center of the camera.

x1 - Variable in class com._604robotics.robot2012.vision.AABB

x2 - Variable in class com._604robotics.robot2012.vision.AABB

xUncertainty - Variable in class com._604robotics.robot2012.vision.Target

These are the uncertainties of the x, y, and z positions of the target.

ABCDEFGHILMPQRSTUVWXYZ

Overview	Package	Class	Use	Tree	Deprecated	Index
Prev Letter	Next Lette	er	Frame	es No	o Frames	All Clas