

Package com._604robotics.robot2012.autonomous

Class Summary	
Class	Description
PIDDriveEncoderDifference	This class implements a PIDSource, based on the difference of values between two encoders.
PIDDriveEncoderOutput	This class implements the default PIDOutput class provided in the WPILib API.
PIDDriveGyro	Driving shim for the gyro-based PID-turning controller thing.