

com.\_604robotics.robot2012.configuration

## Interface PortConfiguration.Controllers

Enclosing interface:

PortConfiguration

```
public static interface PortConfiguration.Controllers
```

Field Summary

Fields

Modifier and Type	Field and Description
static int	DRIVE
static int	MANIPULATOR

Field Detail

DRIVE

```
static final int DRIVE
```

**See Also:**

Constant Field Values

MANIPULATOR

```
static final int MANIPULATOR
```

**See Also:**

Constant Field Values