

com.\_604robotics.robot2012.configuration

# Interface ActuatorConfiguration.ELEVATOR.DEADBAND

Enclosing interface:

[ActuatorConfiguration.ELEVATOR](#)

```
public static interface ActuatorConfiguration.ELEVATOR.DEADBAND
```

## Field Summary

Fields	
Modifier and Type	Field and Description
static int	<b>HIGH</b>
static int	<b>LOW</b>
static int	<b>MEDIUM_LOWER</b>
static int	<b>MEDIUM_UPPER</b>

## Field Detail

**HIGH**

```
static final int HIGH
```

**See Also:**  
[Constant Field Values](#)

**MEDIUM\_UPPER**

```
static final int MEDIUM_UPPER
```

**See Also:**  
[Constant Field Values](#)

**MEDIUM\_LOWER**

```
static final int MEDIUM_LOWER
```

**See Also:**  
[Constant Field Values](#)

**LOW**

```
static final int LOW
```

**See Also:**  
[Constant Field Values](#)