

com.\_604robotics.robot2012.configuration

# Interface AutonomousConfiguration

public interface **AutonomousConfiguration**

Autonomous mode configuration.

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## Field Summary

Fields	
Modifier and Type	Field and Description
static double	<a href="#">BACKWARD_DISTANCE</a>
static double	<a href="#">BACKWARD_DISTANCE_SIDES</a>
static double	<a href="#">BACKWARD_DRIVE_POWER</a>
static double	<a href="#">FORWARD_DISTANCE</a>
static double	<a href="#">FORWARD_DRIVE_POWER</a>

## Field Detail

FORWARD\_DISTANCE

```
static final double FORWARD_DISTANCE
```

**See Also:**

[Constant Field Values](#)

BACKWARD\_DISTANCE

```
static final double BACKWARD_DISTANCE
```

**See Also:**

[Constant Field Values](#)

BACKWARD\_DISTANCE\_SIDES

```
static final double BACKWARD_DISTANCE_SIDES
```

**See Also:**

[Constant Field Values](#)

FORWARD\_DRIVE\_POWER

```
static final double FORWARD_DRIVE_POWER
```

**See Also:**

[Constant Field Values](#)

BACKWARD\_DRIVE\_POWER

```
static final double BACKWARD_DRIVE_POWER
```

**See Also:**

[Constant Field Values](#)

