

com.\_604robotics.robot2012.configuration

## Interface PortConfiguration.Pneumatics.PICKUP\_SOLENOID

**Enclosing interface:**

[PortConfiguration.Pneumatics](#)

```
public static interface PortConfiguration.Pneumatics.PICKUP_SOLENOID
```

### Field Summary

**Fields**

Modifier and Type	Field and Description
static int	<b>IN</b>
static int	<b>OUT</b>

### Field Detail

**IN**

```
static final int IN
```

**See Also:**

[Constant Field Values](#)

**OUT**

```
static final int OUT
```

**See Also:**

[Constant Field Values](#)