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- debug_Print** - Variable in class [com._604robotics.robot2012.vision.config.Config](#)
Should debug info be shown? This includes time per frame, number of visible targets, and estimated position of visible targets.
- debug_SaveImagesToFiles** - Variable in class [com._604robotics.robot2012.vision.config.Config](#)
Should camera images be stored onto disk, for debug purposes?
- debug_ShowDisplay** - Variable in class [com._604robotics.robot2012.vision.config.Config](#)
Should the fancy display be shown, with green and red tiles indicating matching and non-matching tiles, with blue lines and dots indicating target sides and corners?
- defaultProcessing** - Static variable in class [com._604robotics.robot2012.vision.VisionProcessing](#)
The default VisionProcessing to use; this should be where the root of all of the vision processing is done
- display** - Variable in class [com._604robotics.robot2012.vision.VisionProcessing](#)
The display for showing the image as well as some debug data.
- DistanceCalculations** - Class in [com._604robotics.robot2012.vision](#)
This code does the 2D-to-3D calculations
- DistanceCalculations()** - Constructor for class [com._604robotics.robot2012.vision.DistanceCalculations](#)
- down()** - Method in class [com._604robotics.tcpcommunicator.TcpCommunicator](#)
Disables the TcpCommunicator.

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