

com.\_604robotics.robot2012.camera

## Interface CameraInterface

All Known Implementing Classes:

RemoteCameraTCP

public interface **CameraInterface**

Represents a method for obtaining processed vision data from the camera.

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### Method Summary

Methods

Modifier and Type	Method and Description
void	<b>begin()</b> Launches the CameraInterface.
void	<b>end()</b> Disables the CameraInterface.
double	<b>getRecordedTime()</b> Gets the estimated time since the last packet was received.
<b>Target[]</b>	<b>getTargets()</b> Returns the most recently-obtained array of Target that represents the visible targets.

### Method Detail

<b>begin</b>
<pre>void begin()</pre> <p>Launches the CameraInterface.</p>
<b>end</b>
<pre>void end()</pre> <p>Disables the CameraInterface.</p>
<b>getTargets</b>
<pre>Target[] getTargets()</pre> <p>Returns the most recently-obtained array of Target that represents the visible targets.</p> <p><b>Returns:</b></p> <p>An array of Target that represents the visible targets.</p>
<b>getRecordedTime</b>
<pre>double getRecordedTime()</pre> <p>Gets the estimated time since the last packet was received.</p> <p><b>Returns:</b></p> <p>The estimated time since the last packet was received.</p>

