

com._604robotics.robot2012.configuration

Interface ButtonConfiguration.Driver

Enclosing interface:

[ButtonConfiguration](#)

```
public static interface ButtonConfiguration.Driver
```

Field Summary

Fields	
Modifier and Type	Field and Description
static int	AUTO_BALANCE
static int	GYRO_RESET
static int	SHIFT
static int	TOGGLE_PICKUP

Field Detail

SHIFT

```
static final int SHIFT
```

See Also:

[Constant Field Values](#)

TOGGLE_PICKUP

```
static final int TOGGLE_PICKUP
```

See Also:

[Constant Field Values](#)

AUTO_BALANCE

```
static final int AUTO_BALANCE
```

See Also:

[Constant Field Values](#)

GYRO_RESET

```
static final int GYRO_RESET
```

See Also:

[Constant Field Values](#)