

com._604robotics.robot2012.configuration

Interface SensorConfiguration.Encoders

Enclosing interface:
SensorConfiguration

```
public static interface SensorConfiguration.Encoders
```

Field Summary

Fields	
Modifier and Type	Field and Description
static double	LEFT_DRIVE_INCHES_PER_CLICK
static double	RIGHT_DRIVE_INCHES_PER_CLICK
static double	TURRET_DEGREES_PER_CLICK

Field Detail

TURRET_DEGREES_PER_CLICK

```
static final double TURRET_DEGREES_PER_CLICK
```

See Also:

[Constant Field Values](#)

LEFT_DRIVE_INCHES_PER_CLICK

```
static final double LEFT_DRIVE_INCHES_PER_CLICK
```

See Also:

[Constant Field Values](#)

RIGHT_DRIVE_INCHES_PER_CLICK

```
static final double RIGHT_DRIVE_INCHES_PER_CLICK
```

See Also:

[Constant Field Values](#)