

A B C D E F G H I L M P Q R S T U V W X Y Z

Z

z - Variable in class com._604robotics.robot2012.vision.[Point3d](#)

The Z value

z - Variable in class com._604robotics.robot2012.vision.[Target](#)

x, y, and z represent the 3-d position of the target x will be positive when the target appears to be right of the center of the camera.

zUncertainty - Variable in class com._604robotics.robot2012.vision.[Target](#)

These are the uncertainties of the x, y, and z positions of the target.

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