

com.\_604robotics.robot2012.configuration

## Interface PortConfiguration.Motors

Enclosing interface:  
PortConfiguration

```
public static interface PortConfiguration.Motors
```

Field Summary

Fields

Modifier and Type	Field and Description
static int	ELEVATOR_LEFT
static int	ELEVATOR_RIGHT
static int	HOPPER
static int	LEFT_DRIVE
static int	PICKUP
static int	RIGHT_DRIVE
static int	SHOOTER_LEFT
static int	SHOOTER_RIGHT
static int	TURRET_ROTATION

Field Detail

LEFT\_DRIVE

```
static final int LEFT_DRIVE
```

See Also:

Constant Field Values

RIGHT\_DRIVE

```
static final int RIGHT_DRIVE
```

See Also:

Constant Field Values

ELEVATOR\_LEFT

```
static final int ELEVATOR_LEFT
```

See Also:

Constant Field Values

ELEVATOR\_RIGHT

```
static final int ELEVATOR_RIGHT
```

See Also:

Constant Field Values

SHOOTER\_LEFT

```
static final int SHOOTER_LEFT
```

**See Also:**

[Constant Field Values](#)

**SHOOTER\_RIGHT**

```
static final int SHOOTER_RIGHT
```

**See Also:**

[Constant Field Values](#)

**HOPPER**

```
static final int HOPPER
```

**See Also:**

[Constant Field Values](#)

**PICKUP**

```
static final int PICKUP
```

**See Also:**

[Constant Field Values](#)

**TURRET\_ROTATION**

```
static final int TURRET_ROTATION
```

**See Also:**

[Constant Field Values](#)