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Summary: Nested | Field | Constr | Method Detail: Field | Constr | Method

com._604robotics.robot2012.vision

Class Point3d

java.lang.Object

com._604robotics.robot2012.vision.Point3d

public class Point3d
extends java.lang.Object

This represents a point in 3d space

Field Summary

Fields		
Modifier and Type	Field and Description	
double	x The X value	
double	y The Y value	
double	z The Z value	

Constructor Summary

Constructors

Constructor and Description

 $\textbf{Point3d} \, (\texttt{double x, double y, double z})$

Method Summary

м	et	h	o	d	s	

Modifier and Type	Method and Description
double	getX()
double	getY()
double	getZ()
void	setX (double x) Sets the X value of this Point
void	setY(double y) Sets the Y value of this Point
void	setZ (double z) Sets the Z value of this Point

Methods inherited from class java.lang.Object

clone, equals, finalize, getClass, hashCode, notify, notifyAll, toString, wait, wait, wait

Field Detail

X

public double x

The X value

У

public double y
The Y value

Z
public double z
The Z value

Constructor Detail

Point3d

Parameters:

- x The X value
- y The Y value
- z The Z value

Method Detail

getX

public double getX()

Returns:

The X value

setX

public void setX(double x)

Sets the X value of this Point

Parameters:

x - The X value

getY

public double getY()

Returns:

The Y value

setY

public void setY(double y)

Sets the Y value of this Point

Parameters:

y - The Y value

getZ

public double getZ()

Returns:

- - -

SetZ

public void setZ(double z)

Sets the Z value of this Point

Parameters:
 z - The Z value

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