

## Package com.\_604robotics.robot2012.configuration

### Interface Summary

Interface	Description
<b>ActuatorConfiguration</b>	Actuator polarity and power configuration.
<b>ActuatorConfiguration.ELEVATOR</b>	
<b>ActuatorConfiguration.ELEVATOR.DEADBAND</b>	
<b>ActuatorConfiguration.ELEVATOR.TOLERANCE</b>	
<b>ActuatorConfiguration.RING_LIGHT</b>	
<b>ActuatorConfiguration.SOLENOID_HOPPER</b>	
<b>ActuatorConfiguration.SOLENOID_PICKUP</b>	
<b>ActuatorConfiguration.SOLENOID_SHIFTER</b>	
<b>ActuatorConfiguration.SOLENOID_SHOOTER</b>	
<b>ActuatorConfiguration.TURRET_POSITION</b>	
<b>AutonomousConfiguration</b>	Autonomous mode configuration.
<b>ButtonConfiguration</b>	Button configuration.
<b>ButtonConfiguration.Driver</b>	
<b>ButtonConfiguration.Manipulator</b>	
<b>ButtonConfiguration.Manipulator.Elevator</b>	
<b>PortConfiguration</b>	Port configuration.
<b>PortConfiguration.Controllers</b>	
<b>PortConfiguration.Encoders</b>	
<b>PortConfiguration.Encoders.Drive</b>	
<b>PortConfiguration.Motors</b>	
<b>PortConfiguration.Pneumatics</b>	
<b>PortConfiguration.Pneumatics.HOPPER_SOLENOID</b>	
<b>PortConfiguration.Pneumatics.PICKUP_SOLENOID</b>	
<b>PortConfiguration.Pneumatics.SHIFTER_SOLENOID</b>	
<b>PortConfiguration.Pneumatics.SHOOTER_SOLENOID</b>	
<b>PortConfiguration.Relays</b>	
<b>PortConfiguration.Sensors</b>	
<b>SensorConfiguration</b>	Sensor configuration.
<b>SensorConfiguration.Encoders</b>	