

com._604robotics.robot2012.configuration

Interface ActuatorConfiguration.TURRET_POSITION

Enclosing interface:
[ActuatorConfiguration](#)

```
public static interface ActuatorConfiguration.TURRET_POSITION
```

Field Summary

Fields

Modifier and Type	Field and Description
static double	FORWARD
static double	LEFT
static double	RIGHT
static double	TOLERANCE

Field Detail

FORWARD

```
static final double FORWARD
```

See Also:

[Constant Field Values](#)

LEFT

```
static final double LEFT
```

See Also:

[Constant Field Values](#)

RIGHT

```
static final double RIGHT
```

See Also:

[Constant Field Values](#)

TOLERANCE

```
static final double TOLERANCE
```

See Also:

[Constant Field Values](#)