

com._604robotics.robot2012.camera

Interface CameraInterface

All Known Implementing Classes:

RemoteCameraTCP

public interface **CameraInterface**

Represents a method for obtaining processed vision data from the camera.

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Method Summary

Methods

Modifier and Type	Method and Description
void	begin() Launches the CameraInterface.
void	end() Disables the CameraInterface.
double	getRecordedTime() Gets the estimated time since the last packet was received.
Target[]	getTargets() Returns the most recently-obtained array of Target that represents the visible targets.

Method Detail

begin
<pre>void begin()</pre> <p>Launches the CameraInterface.</p>
end
<pre>void end()</pre> <p>Disables the CameraInterface.</p>
getTargets
<pre>Target[] getTargets()</pre> <p>Returns the most recently-obtained array of Target that represents the visible targets.</p> <p>Returns:</p> <p>An array of Target that represents the visible targets.</p>
getRecordedTime
<pre>double getRecordedTime()</pre> <p>Gets the estimated time since the last packet was received.</p> <p>Returns:</p> <p>The estimated time since the last packet was received.</p>

