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AABB - Class in `com._604robotics.robot2012.vision`

An Axis-Aligned Bounding Box.

AABB(int, int, int, int) - Constructor for class `com._604robotics.robot2012.vision.AABB`

addPropValue(String, Hashtable) - Static method in class `com.charliemouse.cambozola.shared.StreamSplit`

angle - Variable in class `com._604robotics.robot2012.vision.Target`

This is the angle of the target, relative to the camera.

angleUncertainty - Variable in class `com._604robotics.robot2012.vision.Target`

This is the uncertainty of the angle of the target.

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