

com.\_604robotics.robot2012.configuration

# Interface ActuatorConfiguration.SOLENOID\_HOPPER

### **Enclosing interface:**

ActuatorConfiguration

public static interface ActuatorConfiguration.SOLENOID\_HOPPER

# Field Summary Fields Modifier and Type Field and Description static DoubleSolenoid.Value PUSH static DoubleSolenoid.Value REGULAR

# **Field Detail**

## **REGULAR**

static final DoubleSolenoid.Value REGULAR

## **PUSH**

static final DoubleSolenoid.Value PUSH

