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Target - Class in com._604robotics.robot2012.vision
> This class represents a physical vision Target with four main attributes (x, y, z, angle).

Target() - Constructor for class com._604robotics.robot2012.vision.Target
> A blank constructor to easily make a Target

Target(double, double, double, double) - Constructor for class com._604robotics.robot2012.vision.Target

Target(double, double, double, double, double, double, double, double) - Constructor for class com._604robotics.robot2012.vision.Target

Target(Point3d, double) - Constructor for class com._604robotics.robot2012.vision.Target

TcpCommunicator - Class in com._604robotics.tcpcommunicator
> Server class for the vision data transfer protocol.

TcpCommunicator() - Constructor for class com._604robotics.tcpcommunicator.TcpCommunicator
> Initializes a new TcpCommunicator.

TcpCommunicator(String) - Constructor for class com._604robotics.tcpcommunicator.TcpCommunicator
> Initializes a new TcpCommunicator with the specified robot IP address.

TcpCommunicator(String, int) - Constructor for class com._604robotics.tcpcommunicator.TcpCommunicator
> Initializes a new TcpCommunicator with the specified robot IP address and port.

TcpCommunicator(String, int, boolean) - Constructor for class com._604robotics.tcpcommunicator.TcpCommunicator
> Initializes a new TcpCommunicator with the specified robot IP address, port, and debug mode.

tileSize - Variable in class com._604robotics.robot2012.vision.config.Config
> The size of each tile in the vision processing.

toString() - Method in class com._604robotics.robot2012.vision.config.Config

toString() - Method in class com._604robotics.robot2012.vision.LinearRegression.RegressionResult

toString() - Method in class com._604robotics.robot2012.vision.Point2d

toString() - Method in class com._604robotics.robot2012.vision.Quad

toString() - Method in class com._604robotics.robot2012.vision.Target

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