Package com._604robotics.robot2012.rotation

Interface Summary

Interface	Description
RotationProvider	Based on external feedback, aims the turret at the target.

Class Summary

Class	Description
DummyRotationProvider	Dummy implementor of a RotationProvider, for testing purposes.
NaiveRotationProvider	A naive implementation of a RotationProvider,
SlightlySmarterRotationProvider	A slightly smarter implementation of a rotation provider, which tries to account for network delay, etc.
SlowbroRotationProvider	Implements a slow-er-ish, but more robust-ish, RotationProvider.