Overview Package Class Use Tree Deprecated Index Help

Prev Letter Next Letter Frames No Frames All Classes

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image - Variable in class com._604robotics.robot2012.vision.VisionDisp

The background image, as received from the camera

Img - Class in com._604robotics.robot2012.vision

A simple class for accessing 2d data in a 1d array, with bounds checking.

Img(int[], int, int) - Constructor for class com._604robotics.robot2012.vision.lmg

A constructor to make an Img

Img(Raster, int[]) - Constructor for class com._604robotics.robot2012.vision.lmg

A constructor to make an Img

Img(Raster) - Constructor for class com._604robotics.robot2012.vision.lmg

A constructor to make an Img

Img(int, int) - Constructor for class com._604robotics.robot2012.vision.lmg

A constructor to make an Img

isAtStreamEnd() - Method in class com.charliemouse.cambozola.shared.StreamSplit

 $\textbf{isEnabled()} \textbf{-} \textbf{Method in class com.} \underline{-} 604 robotics.tcpcommunicator.TcpCommunicator$

Checks whether or not the TcpCommunicator has been enabled.

 $\textbf{isRunning()} \cdot \texttt{Method in class com.} \underline{-} 604 robotics.tcpcommunicator.TcpCommunicator$

Checks whether or not the TcpCommunicator thread is currently running.

 $\textbf{isTarget(int, int)} - \textbf{Method in class com.} \underline{-}604 robotics.robot 2012.vision.} ResultImage$

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Overview Packa	ge Class I	Jse Tree	Deprecated	Index	Help
Prev Letter Nex	Letter	Frames N	lo Frames	All Class	ses