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readConfig(File) - Static method in class `com._604robotics.robot2012.vision.config.Config`

Read a Config from a file

readDefaultConfig() - Static method in class `com._604robotics.robot2012.vision.config.Config`

Reads the default Config file

readHeaders() - Method in class `com.charliemouse.cambozola.shared.StreamSplit`

readHeaders(URLConnection) - Static method in class `com.charliemouse.cambozola.shared.StreamSplit`

recursiveTraceBlobs(img, int, int, int) - Static method in class `com._604robotics.robot2012.vision.VisionProcessing`

RelHoopY - Static variable in class `com._604robotics.robot2012.vision.Target`

The distance from the center of the target to the Y (vertical) value of the hoop.

RelHoopZ - Static variable in class `com._604robotics.robot2012.vision.Target`

The distance from the center of the target to the Z (depth) value of the hoop.

Result - Class in `com._604robotics.robot2012.vision`

This class stores one tile of "is in target" data.

Result() - Constructor for class `com._604robotics.robot2012.vision.Result`

Result.AntiResult - Class in `com._604robotics.robot2012.vision`

A result indicating that it is unlikely that the target lies in the indicated tile

Result.AntiResult() - Constructor for class `com._604robotics.robot2012.vision.Result.AntiResult`

Result.PlusResult - Class in `com._604robotics.robot2012.vision`

A result indicating that it is likely that the target lies in the indicated tile

Result.PlusResult(int, byte[]) - Constructor for class `com._604robotics.robot2012.vision.Result.PlusResult`

A simple constructor to make a PlusResult.

ResultImage - Class in `com._604robotics.robot2012.vision`

A result image that holds an image of how well pixels match the expected color of the vision target.

ResultImage(int, int) - Constructor for class `com._604robotics.robot2012.vision.ResultImage`

A constructor to create a new ResultImage.

results - Variable in class `com._604robotics.robot2012.vision.ResultImage`

run() - Method in class `com._604robotics.tcpcommunicator.TcpCommunicator`

Don't use this to launch the server; use `up()` instead.

run() - Method in class `com.charliemouse.cambozola.shared.CamStream`

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