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com._604robotics.robot2012.rotation

Interface RotationProvider

All Known Implementing Classes:

DummyRotationProvider, NaiveRotationProvider, SlightlySmarterRotationProvider, SlowbroRotationProvider

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public interface **RotationProvider**

Based on external feedback, aims the turret at the target.

Author:

Michael Smith

Method Summary

Methods	
Modifier and Type	**Method and Description**
void	**setDefaultPosition**(double defaultPosition) Sets the "default" position, if no targets can be located.
boolean	**update**() Updates the aiming of the turret.

Method Detail

setDefaultPosition

void setDefaultPosition(double defaultPosition)

Sets the "default" position, if no targets can be located.

update

boolean update()

Updates the aiming of the turret.

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