

com.\_604robotics.robot2012.configuration

# Interface ButtonConfiguration.Driver

Enclosing interface:

[ButtonConfiguration](#)

```
public static interface ButtonConfiguration.Driver
```

## Field Summary

Fields	
Modifier and Type	Field and Description
static int	<a href="#">AUTO_BALANCE</a>
static int	<a href="#">GYRO_RESET</a>
static int	<a href="#">SHIFT</a>
static int	<a href="#">TOGGLE_PICKUP</a>

## Field Detail

SHIFT

```
static final int SHIFT
```

See Also:

[Constant Field Values](#)

TOGGLE\_PICKUP

```
static final int TOGGLE_PICKUP
```

See Also:

[Constant Field Values](#)

AUTO\_BALANCE

```
static final int AUTO_BALANCE
```

See Also:

[Constant Field Values](#)

GYRO\_RESET

```
static final int GYRO_RESET
```

See Also:

[Constant Field Values](#)