

com._604robotics.robot2012.configuration

Interface ActuatorConfiguration.SOLENOID_HOPPER

Enclosing interface:
 ActuatorConfiguration

```
public static interface ActuatorConfiguration.SOLENOID_HOPPER
```

Field Summary

Fields

Modifier and Type	Field and Description
static <code>DoubleSolenoid.Value</code>	<code>PUSH</code>
static <code>DoubleSolenoid.Value</code>	<code>REGULAR</code>

Field Detail

REGULAR

```
static final DoubleSolenoid.Value REGULAR
```

PUSH

```
static final DoubleSolenoid.Value PUSH
```