Overview Package Class Use Tree Deprecated Index Help

Prev Letter Next Letter Frames No Frames All Classes

## ABCDEFGHILMPQRSTUVWXYZ



y - Variable in class com.\_604robotics.robot2012.vision.Point2d

The Y value

y - Variable in class com.\_604robotics.robot2012.vision.Point3d

The Y value

y - Variable in class com.\_604robotics.robot2012.vision.Target

x, y, and z represent the 3-d position of the target x will be positive when the target appears to be right of the center of the camera.

y1 - Variable in class com.\_604robotics.robot2012.vision.AABB

y2 - Variable in class com.\_604robotics.robot2012.vision.AABB

yUncertainty - Variable in class com.\_604robotics.robot2012.vision.Target

These are the uncertainties of the x, y, and z positions of the target.

## ABCDEFGHILMPQRSTUVWXYZ