

com._604robotics.robot2012.configuration

Interface PortConfiguration.Sensors

Enclosing interface:

[PortConfiguration](#)

```
public static interface PortConfiguration.Sensors
```

Field Summary

Fields	
Modifier and Type	Field and Description
static int	ACCELEROMETER
static int	ELEVATOR_LIMIT_SWITCH
static int	GYRO_BALANCE
static int	GYRO_HEADING

Field Detail

GYRO_HEADING

```
static final int GYRO_HEADING
```

See Also:
[Constant Field Values](#)

GYRO_BALANCE

```
static final int GYRO_BALANCE
```

See Also:
[Constant Field Values](#)

ACCELEROMETER

```
static final int ACCELEROMETER
```

See Also:
[Constant Field Values](#)

ELEVATOR_LIMIT_SWITCH

```
static final int ELEVATOR_LIMIT_SWITCH
```

See Also:
[Constant Field Values](#)