

Hierarchy For Package com._604robotics.utils

Package Hierarchies:
All Packages

Class Hierarchy

- java.lang.**Object**
 - com._604robotics.utils.**DeadbandedSource** (implements edu.wpi.first.wpilibj.PIDSource)
 - com._604robotics.utils.**DualVictor** (implements edu.wpi.first.wpilibj.PIDOutput)
 - com._604robotics.utils.**LinearController**
 - edu.wpi.first.wpilibj.**PIDController** (implements edu.wpi.first.wpilibj.parsing.IUtility)
 - com._604robotics.utils.**ConvertingPIDController**
 - com._604robotics.utils.**UpDownPIDController**
 - edu.wpi.first.wpilibj.**SensorBase**
 - edu.wpi.first.wpilibj.**Encoder** (implements edu.wpi.first.wpilibj.CounterBase, edu.wpi.first.wpilibj.parsing.ISensor, edu.wpi.first.wpilibj.PIDSource)
 - com._604robotics.utils.**EncoderOffset**
 - com._604robotics.utils.**EncoderPIDSource**
 - edu.wpi.first.wpilibj.**Gyro** (implements edu.wpi.first.wpilibj.parsing.ISensor, edu.wpi.first.wpilibj.PIDSource)
 - com._604robotics.utils.**Gyro360** (implements edu.wpi.first.wpilibj.PIDSource)
 - edu.wpi.first.wpilibj.**GyroHax**
 - com._604robotics.utils.**CompensatingGyro**
 - edu.wpi.first.wpilibj.**PWM**
 - edu.wpi.first.wpilibj.**SafePWM** (implements edu.wpi.first.wpilibj.MotorSafety)
 - edu.wpi.first.wpilibj.**Victor** (implements edu.wpi.first.wpilibj.parsing.IDeviceController, edu.wpi.first.wpilibj.SpeedController)
 - com._604robotics.utils.**SpringableVictor**
 - edu.wpi.first.wpilibj.**Relay** (implements edu.wpi.first.wpilibj.parsing.IDeviceController)
 - com._604robotics.utils.**SpringableRelay**
 - edu.wpi.first.wpilibj.**SolenoidBase** (implements edu.wpi.first.wpilibj.parsing.IDeviceController)
 - edu.wpi.first.wpilibj.**DoubleSolenoid**
 - com._604robotics.utils.**SpringableDoubleSolenoid**
 - com._604robotics.utils.**UpDownPIDController.Gains**
 - com._604robotics.utils.**VelocityController**
 - com._604robotics.utils.**XboxController**

Interface Hierarchy

- com._604robotics.utils.**XboxController.Axis**
- com._604robotics.utils.**XboxController.Button**
- com._604robotics.utils.**XboxController.Button.DPad**
- com._604robotics.utils.**XboxController.Stick**