For October 1st 2019

Your task is to code a basic drivetrain using the FRC Java API. This drive train should:

* Take input from the joysticks of the controller and push it through to the motor controllers
* Set one of the motors on each side to be a master, and take control of the other

It Shouldn’t:

* Use a PID controller
* Do any computations on the inputted data

Info on the Robot:

The robot has 2 VictorSPX motor controls from Vex Robotics on each side, controlling each drive motor individually.

Resources:

* Many of the important features of the robot are documented well in the 2019 competition drive
* For Java tips, go to https://first.wpi.edu/FRC/roborio/release/docs/java/