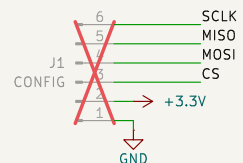


Rev 1: Initial Design
Rev 2: PCB rounded to fit inside bearing
Rev 3: Locating pins changed to 3mm.
Board cut under SL connector.
Rev 4: Add OR gate to disable outputs
when mag field is weak.



H2
MountingHole



971 SPARTAN ROBOTICS

Sheet: /
File: mag-encoder.kicad_sch

Title: Mag Encoder

Size: B	Date: 2024-11-25
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Rev: 4

KiCad E.D.A. 8.0.6

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