



# **CHALLENGES (UR): FUTURE CAPABILITIES, ETHICS, AND SUSTAINABILITY ISSUES.**

# SAAB SEAEDGE FALCON



## Future Capabilities:

- Currently reliant on manual operation, limiting mission scope and endurance.
- Needs advancement in AI integration for autonomous inspections, especially in offshore energy and deep-sea exploration.
- Potential for real-time machine vision and object recognition to assist pilots in identifying defects or marine objects.

## Ethical Challenges:

- Often used in offshore oil & gas industries. Raises ethical concerns over enabling further fossil fuel exploitation.
- Dual-use risk: Can be equipped for covert surveillance or military reconnaissance.

# SAAB SEAEDGE FALCON

## Sustainability Issues:

- Deployment may disturb benthic habitats (e.g., seabed ecosystems).
- Electronic waste from outdated models or harsh underwater failures could contribute to marine pollution if not recovered properly.



# BLUEROV2



## Future Capabilities:

- Designed to be modular and programmable, but lacks native AI-driven autonomy.
- Major challenge: Upgrading low-cost sensors for precise navigation without increasing cost.
- Scope to develop real-time data streaming and cloud-based mission control for citizen science and academic use.

## Ethical Challenges:

- Being open-source and accessible, BlueROV2 can be repurposed for unethical use, such as unauthorized surveillance or illegal fishing.
- Risk of violating marine protected areas due to operator inexperience.

# BLUEROV2



# BLUEROV2

## Sustainability Issues:

- Prone to plastic hull and tether degradation in saltwater over time.
- Shipping lithium batteries to remote deployment areas raises carbon footprint and hazardous material handling concerns.



# REMUS 600 (HYDROID/KONGSBERG)



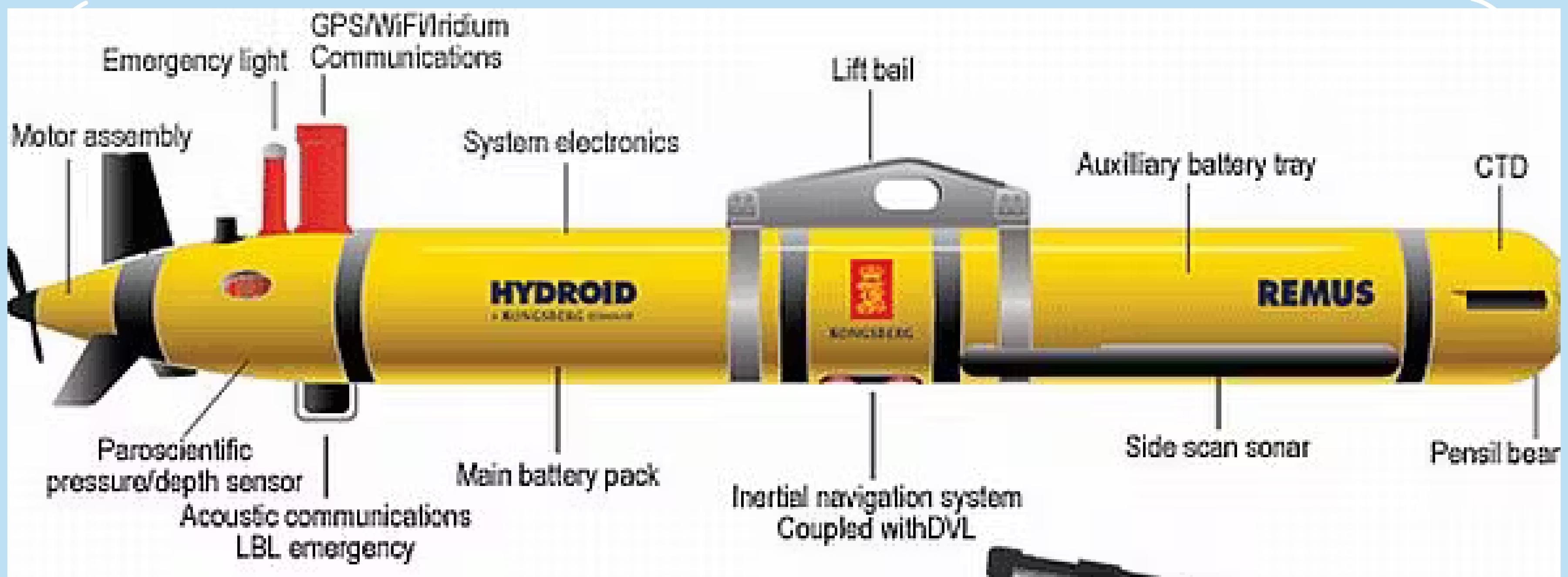
## Future Capabilities:

- Already highly autonomous, but mission durations are limited by energy capacity.
- Future development is needed in hybrid power systems, possibly nuclear microgenerators for ultra-long missions.
- Enhancing onboard AI decision-making and self-repair algorithms remains a challenge.

## Ethical Challenges:

- Widely used by navies (e.g., mine detection), creating concern around the militarization of ocean robotics.
- Ethical issues around privacy, sovereignty, and marine life disruption in sensitive geopolitical waters.

# REMUS 600 (HYDROID/KONGSBERG)



# REMUS 600 (HYDROID/KONGSBERG)

## Sustainability Issues:

- Deployed in deep-sea mining prospecting, which could lead to irreversible ecosystem destruction if commercialized.
- Use of exotic materials (e.g., titanium hulls) may have unsustainable extraction costs.



# HUGIN (KONGSBERG/OCEAN INFINITY)

## Future Capabilities:

- Top-tier AUV with advanced autonomy, but requires complex pre-mission setup.
- Limitations in real-time adaptation to unforeseen events, like under-ice entrapments or dynamic terrain shifts.
- Potential to integrate underwater wireless communication networks (e.g., optical/acoustic) for better swarming and navigation.

## Ethical Challenges:

- Deployed for subsea pipeline and seabed surveys, raises concerns of aiding in marine resource extraction in protected zones.
- Risk of AI bias in terrain recognition algorithms if trained on limited seafloor datasets.

# HUGIN (KONGSBERG/OCEAN INFINITY)



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## Sustainability Issues:

- Highly resource-intensive to manufacture and operate.
- Challenge of designing sustainable disposal methods for electronics and carbon-fiber composite parts after end-of-life.



# DEEP TREKKER DTG3



## Future Capabilities:

- Currently lacks autonomous capabilities; needs evolution into AI-assisted visual analysis and navigation.
- It could evolve into a low-cost swarm system for lake and coastal monitoring with modular sensors.
- Limited computing power onboard hinders the future integration of real-time data processing.

## Ethical Challenges:

- Accessible platforms may be misused for spying in civilian ports, aquaculture sabotage, or wildlife harassment.
- Lack of user licensing requirements makes traceability of operators difficult.

# DEEP TREKKER DTG3



# DEEP TREKKER DTG3

## Sustainability Issues:

- Short battery cycles → frequent charging → energy inefficiency.
- Improper disposal of tether cables and enclosures may lead to plastic entanglement risks for marine animals.



# CONCLUSION

Robot	Future Capabilities	Ethical Concerns	Sustainability Issues
<b>Saab Falcon</b>	AI-assisted inspections, real-time vision	Oil industry use, military dual-use	Marine habitat disruption, electronic waste
<b>BlueROV2</b>	AI autonomy, cloud control, better sensors	Misuse for illegal fishing, data misuse	Battery footprint, tether degradation
<b>REMUS 600</b>	Long missions, hybrid power, self-repair AI	Militarization, deep-sea mining ethics	Ecosystem damage from exploration
<b>HUGIN</b>	Real-time path correction, underwater networks	AI bias in mapping, aiding oil industry	Unsustainable material sourcing, disposal waste
<b>DTG3</b>	Swarming, navigation inspection	AI for traceability, possible misuse	Low power efficiency, marine plastic risks

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**THANK  
YOU**