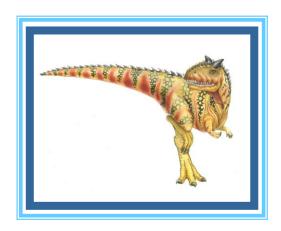
# **Chapter 9: Main Memory**

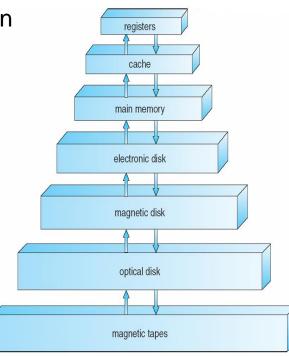
Section 9.1-9.2,9.3.1





# **Background**

- Program must be brought (from disk) into memory and placed within a process for it to be run
- Main memory and registers are only storage CPU can access directly
- Memory unit only sees a stream of:
  - read requests & addresses, or
  - write requests & address + data
- Register access is done in one CPU cycle (or less)
- Main memory access can take many CPU cycles, causing processor to stall
- Cache is typically added on CPU chip to speedup memory access

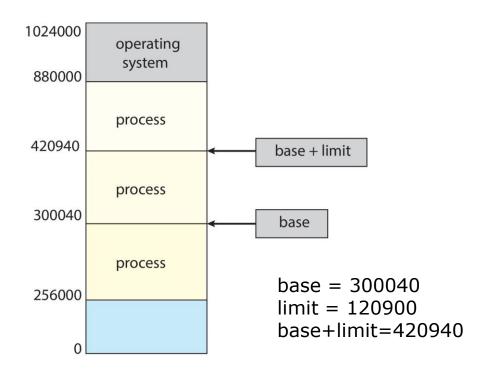






# **Memory Protection**

- Need to ensure that a process can access only those memory addresses in its address space
- We can provide this protection using base and limit registers that define the range of legal memory addresses that a process may access
  - Base register holds the smallest legal memory address
  - Limit register specifies the size of the range

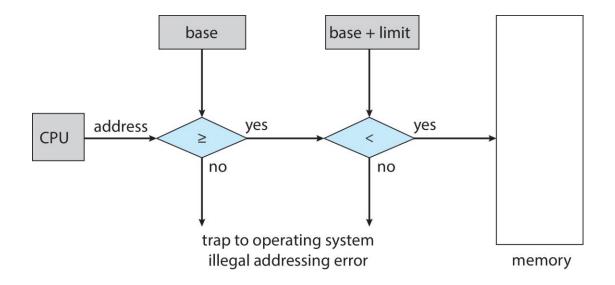






### **Memory Protection Hardware**

☐ CPU hardware must compare every memory access generated in user mode with base and limit registers



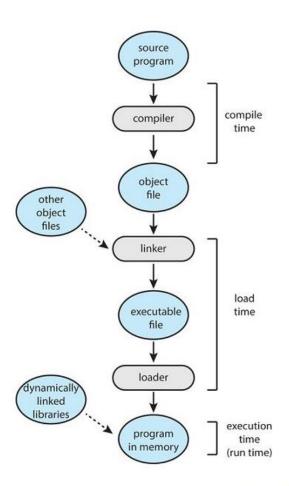
Instructions to load base and limit registers are privileged instructions





# **Address Binding (1)**

- A user process may reside in any part of the physical memory
  - The first address of a user process need not be 0000
- Addresses represented in different ways at different stages of a program's life
  - Addresses in source program usually symbolic (e.g., int count)
  - A compiler binds symbolic addresses to relocatable addresses (e.g. "14 bytes from beginning of this module")
  - Linker or loader binds relocatable addresses to absolute addresses
    - e.g., relocatable address 14 is bound to absolute address 74014
  - Each binding maps one address space to another

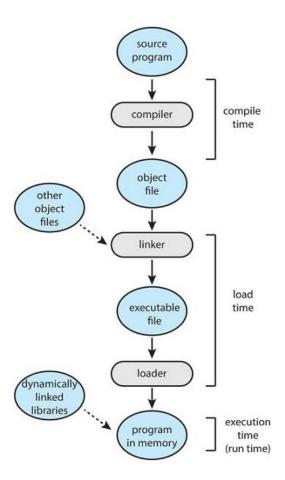






#### **Address Binding (2)**

- Binding of instructions and data to memory addresses can happen at three different stages:
  - Compile time: If memory location of process known a priori, absolute code can be generated;
    - Must recompile code if starting location changes
  - Load time: Compiler must generate relocatable code if memory location of process is not known at compile time; final address binding is delayed until load time
    - If starting address changes, need reload the user code
  - Execution time: Binding delayed until run time if the process can be moved during its execution from one memory segment to another
    - Need hardware support for address mapping (e.g., relocation register)
    - Used by most operating systems







### Logical vs. Physical Address Space

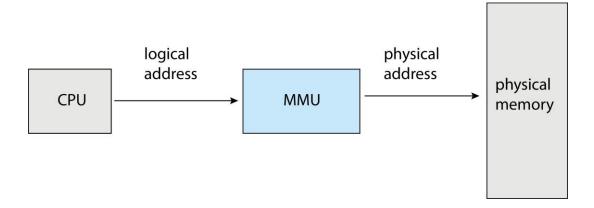
- The concept of a logical address space that is bound to a separate physical address space is central to proper memory management
  - Logical address generated by the CPU; also referred to as virtual address
  - Physical address address seen by the memory unit
- Logical address space is the set of all logical addresses generated by a program
- Physical address space is the set of all physical addresses generated by a program
- Logical and physical addresses are the same in compile-time and load-time address-binding schemes
- Logical and physical addresses differ in execution-time address-binding scheme





# **Memory-Management Unit (MMU)**

MMU is a hardware device that maps logical addresses to physical addresses at run time



Different mapping methods possible, covered in the rest of this chapter

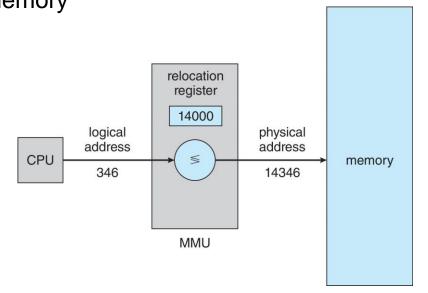




# Memory-Management Unit (Cont.)

- Consider a simple mapping scheme, which is a generalization of the base-register scheme
- ☐ The base register now called **relocation register**
- ☐ The value in the relocation register is added to every address generated by a user process at the time it is sent to memory
- The user program deals with logical addresses; it never sees the real physical addresses

Execution-time binding occurs when a reference is made to a location in memory

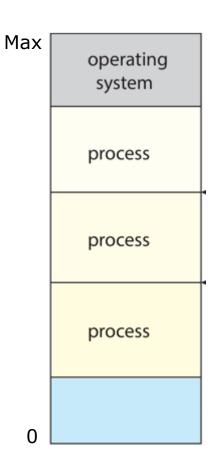






# **Contiguous Memory Allocation**

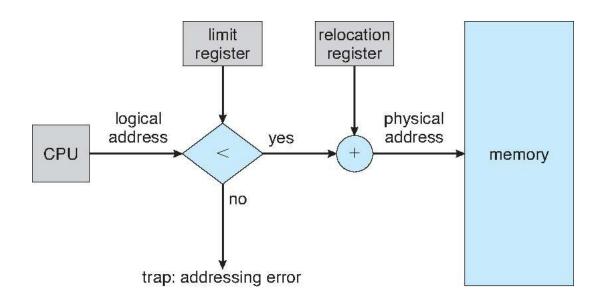
- Main memory must support both OS and user processes
- ☐ Limited resource, must allocate efficiently
- Contiguous allocation is one early method
- Main memory usually divided into two partitions: one for OS and one for user processes
  - OS usually held in high memory
  - Each user process contained in a single contiguous section of memory







- Relocation register and limit register used to protect user processes from each other, and from changing OS code and data
  - Relocation register contains value of smallest physical address
  - Limit register contains range of logical addresses each logical address must be less than the limit register
  - MMU maps logical address to physical address dynamically

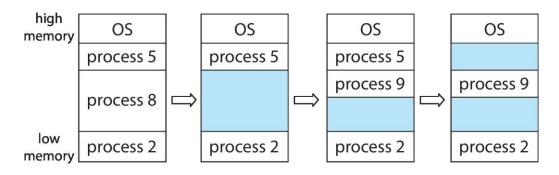






### **Memory Allocation**

- Initially, all memory is available and is considered one large hole
  - A hole a is block of available memory
- When a process arrives, it is allocated memory from a hole large enough to accommodate it
  - ☐ If the hole is too large, the unused part is returned to the set of holes
- When a process terminates, it releases its block of memory
  - If the new hole is adjacent to other holes, these holes are merged to form a larger hole
- ☐ In general, holes of various sizes are scattered throughout memory
- Operating system maintains information about a) allocated memory and b) free memory (holes)







# **Dynamic Storage-Allocation Problem**

How to satisfy a request of size *n* from a list of holes?

- Commonly used strategies:
  - First-fit: Allocate the first hole that is big enough
  - Best-fit: Allocate the smallest hole that is big enough; must search entire list, unless ordered by size
    - Produces the smallest leftover hole
  - Worst-fit: Allocate the *largest* hole; must also search entire list, unless ordered by size
    - Produces the largest leftover hole
- ☐ First-fit and best-fit better than worst-fit in terms of storage utilization
- First-fit generally faster than best-fit





#### **Example**

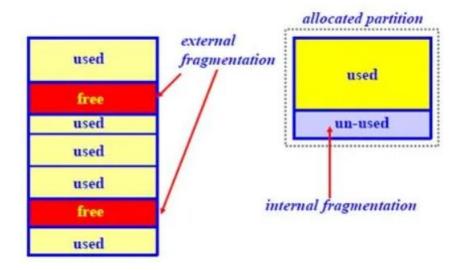
Given six memory holes of 300 KB, 600 KB, 350 KB, 200 KB, 750 KB, 125 KB (in order), how would the first-fit, best-fit, and worst-fit algorithms place a process of size 115 KB?

- □ First fit: The process is put in 300-KB hole, leaving
  185 KB (=300KB-115KB), 600 KB, 350 KB, 200 KB, 750 KB, 125 KB
- Best fit: 115 KB is put in 125-KB hole, leaving
  300 KB, 600 KB, 350 KB, 200 KB, 750 KB, 10 KB
- Worst fit: 115 KB is put in 750-KB hole, leaving 300 KB, 600 KB, 350 KB, 200 KB, 635 KB (=750KB-115KB), 125 KB how would the first-fit, best-fit, and worst-fit algorithms place another process of size 200 KB?



### **Fragmentation**

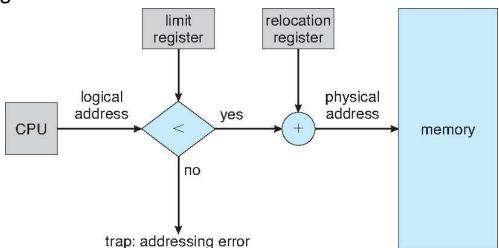
- External Fragmentation there is enough total memory space to satisfy a request, but the available spaces are not contiguous
  - Statistical analysis of first-fit reveals that given N allocated blocks, another 0.5
    N blocks will be lost to external fragmentation
  - □ That is, 1/3 of memory may be unusable -> 50-percent rule
- □ Internal Fragmentation allocated memory may be slightly larger than requested memory; the size difference is memory internal to a partition, but not being used
  - E.g., 4000 bytes requested, 4096 bytes (4KB) allocated



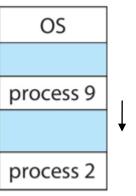




- One solution to external fragmentation is compaction
  - Shuffle memory contents to place all free memory together in one large block
  - Compaction is possible *only* if relocation is dynamic, i.e., address binding done at execution time using a relocation register



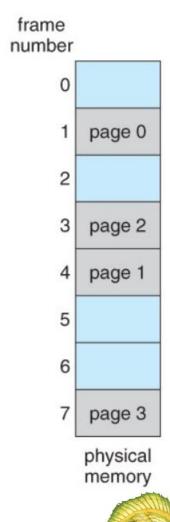
- Another solution is to permit the physical address space of a process to be noncontiguous
  - E.g., paging

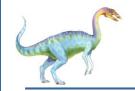




# **Paging**

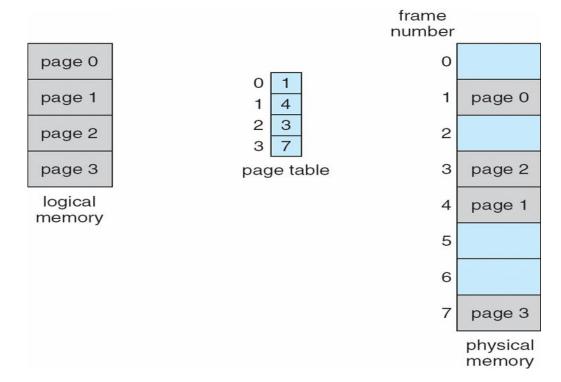
- Physical address space of a process can be noncontiguous; process is allocated physical memory whenever the latter is available
- Divide physical memory into fixed-sized blocks called frames
  - Frame size is power of 2, typically between 4KB (2<sup>12</sup> bytes) and 1GB (2<sup>30</sup> bytes)
- Divide logical memory into blocks of same size called pages
- □ To run a process of size N pages, need to find N free frames and load pages of process to frames
- OS keeps track of all free frames
- External fragmentation is avoided; still have internal fragmentation
- Paging is used in most operating systems





# **Paging**

- □ Kernel maintains a page table for each process
  - Page table has an entry for each page of the process, entry indicates the memory frame allocated to the page
  - Page table is used to translate logical addresses to physical addresses







#### **Address Translation Scheme**

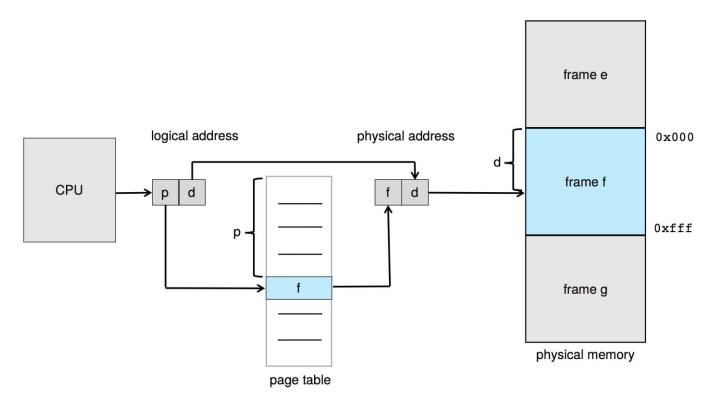
- □ Address generated by CPU (i.e., logical address) is divided into:
  - Page number (p) used as an index into a page table which contains base address of each frame in physical memory
  - □ Page offset (d) location in the frame
  - Base address of frame is combined with the page offset to define the physical memory address that is sent to the memory unit
- If size of logical address space =  $2^m$  bytes and page size =  $2^n$  bytes, then
  - High-order m-n bits of logical address represent the page number
  - Low-order n bits represent the page offset

page number	page offset
р	d
m -n	n



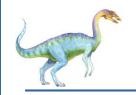


# **Paging Hardware**



MMU translates a logical address to a physical address



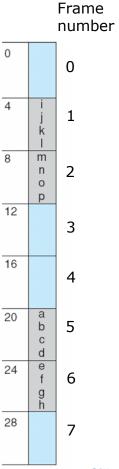


# **Paging Example**

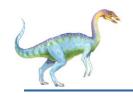
- □ Page size = 4 bytes, physical memory = 32 bytes (i.e., 8 frames), logical memory = 16 bytes (i.e., 4 pages)
  - □ 2-bit page offset (n = 2)
  - 4-bit logical address (m = 4), 2-bit page number (m n = 2)
  - 5-bit physical address, 3-bit frame number

			Pag	ge number
0 1 2 3	1	a b c d	0	
	(	e f g h	1	0 5 1 6
8 9 10 11		i j k l	2	2 1 3 2 page table
12 13 14 15	3 I	n n o p	3	
logical memory				

- Logical address 3 (page 0, offset 3) maps to physical address 5\*4+3=23
  - In binary, logical address 0011 maps to physical address 10111
- Logical address 13 (page 3, offset 1) maps to physical address 2\*4+1=9
  - In binary, logical address 1101 maps to physical address 01001



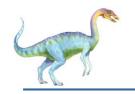
physical memory



# **Internal Fragmentation in Paging**

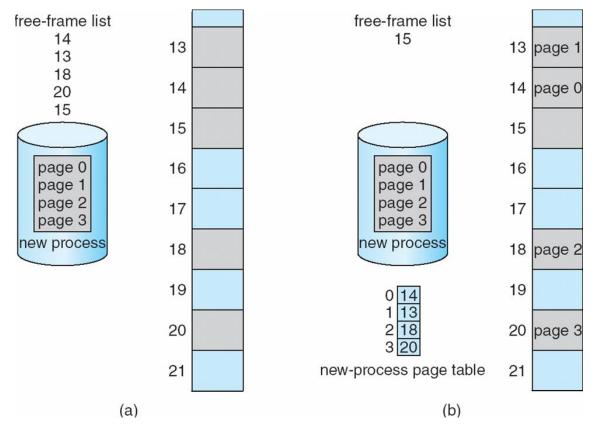
- Calculating internal fragmentation
  - □ Page size = 2,048 bytes
  - □ Process size = 72,766 bytes
  - □ 35 pages + 1,086 bytes
  - □ Internal fragmentation of 2,048 1,086 = 962 bytes
- Worst case happens when a process needs n pages plus 1 byte → internal fragmentation is almost 1 frame
  - On average internal fragmentation = 1/2 frame size
- □ So small page sizes desirable?
  - But each page table entry takes memory to track
  - Page sizes have grown over time
  - Today page sizes typically 4KB or 8KB





#### **Free Frames**

#### OS keeps track of free frames



Before allocation

After allocation

