7. Computational Tree Logic



Computer-Aided Verification

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Reminder

- Tutorials this week (Assignment 1 feedback)
 - Thur 4pm (surnames A-L, by default):
 - UG06, Murray Learning Centre
 - Fri 10am (surnames M-Z, by default):
 - Lecture Theatre 1, Sports and Exercise Sciences

Recap

- Linear Temporal Logic (LTL)
 - (next), U (until), ♦ (eventually), □ (always)
- Examples, common patterns
 - $-\Box a, \Box(a\rightarrow \Diamond b), \Box(a\rightarrow \bigcirc b), \Box \Diamond a, \Diamond \Box a$
 - invariants, safety properties, liveness properties
- Semantics
 - LTL evaluated over infinite paths/traces (and LTSs)
 - $-M \models \psi \Leftrightarrow \underline{all}$ paths of LTL M satisfy LTL formula ψ
- Equivalence of LTL formulas: $\psi_1 \equiv \psi_2$
 - proof using common simpler equivalences/dualities

Overview

- Linear temporal logic (LTL)
 - (non)equivalences, negation
- Computation tree logic (CTL)
 - syntax, semantics
 - examples
 - CTL vs. LTL

• See [BK08] sections 5.1.4 and 6-6.3

Example 1

Prove (or disprove):

```
\diamondsuit \psi \equiv \psi \lor \bigcirc \diamondsuit \psi ? Yes
```

- Can prove directly, using the relevant semantics for LTL:
- For any trace $\sigma \in (2^{AP})^{\omega}$...

```
\sigma \vDash \diamondsuit \psi \Leftrightarrow \exists k \geq 0 \text{ s.t. } \sigma[k...] \vDash \psi
\Leftrightarrow \sigma[0...] \vDash \psi \text{ or } \exists k \geq 1 \text{ s.t. } \sigma[k...] \vDash \psi
\Leftrightarrow \sigma \vDash \psi \text{ or } \exists k \geq 1 \text{ s.t. } \sigma[k...] \vDash \psi
\Leftrightarrow \sigma \vDash \psi \text{ or } \exists j \geq 0 \text{ } \sigma[1...][j...] \vDash \psi
\Leftrightarrow \sigma \vDash \psi \text{ or } \sigma[1...] \vDash \diamondsuit \psi
\Leftrightarrow \sigma \vDash \psi \text{ or } \sigma \vDash \bigcirc \diamondsuit \psi
\Leftrightarrow \sigma \vDash \psi \text{ or } \sigma \vDash \bigcirc \diamondsuit \psi
\Leftrightarrow \sigma \vDash \psi \vee \bigcirc \diamondsuit \psi
```

Example 2

Prove (or disprove):

$$\neg(\Box a \rightarrow \diamondsuit b) \equiv \Box a \land \Box \neg b$$
 ? Yes

Can prove by reusing simpler known equivalences

$$\neg(\Box a \rightarrow \Diamond b) \equiv \neg(\neg \Box a \lor \Diamond b) \qquad \text{since } \psi_1 \rightarrow \psi_2 \equiv \neg \psi_1 \lor \psi_2$$

$$\equiv \neg \neg \Box a \land \neg \Diamond b \qquad \text{since } \neg(\psi_1 \lor \psi_2) \equiv \neg \psi_1 \land \neg \psi_2$$

$$\equiv \Box a \land \neg \Diamond b \qquad \text{since } \neg \neg \psi \equiv \psi$$

$$\equiv \Box a \land \neg \Diamond \neg \neg b \qquad \text{since } \psi \equiv \neg \neg \psi$$

$$\equiv \Box a \land \Box \neg b \qquad \text{since } \neg \Diamond \neg \psi \equiv \Box \psi$$

Example 3

• Prove (or disprove):

$$\Box \diamondsuit a \land \Box \diamondsuit b \equiv \Box \diamondsuit (a \land b)$$
 ? No

- Just need to provide a single trace as a counterexample
 - e.g. {a} {b} {a} {b} ...
 - (which is satisfied by the left formula only)

LTL & Negation

• Are these statements equivalent? (for trace σ and LTL formula ψ)

```
- \sigma \vDash \neg \psi
```

$$- \sigma \not\models \psi$$

- Yes
 - in fact, this is just the semantics of LTL
- Are these statements equivalent? (for LTS M and LTL formula ψ)
 - $M \models \neg \psi$
 - M ⊭ ψ
- No:
 - M $\vDash \neg \psi$ means no trace satisfies ψ
 - $M \not\models \psi$ means it is not true that all traces satisfy ψ
 - i.e. there exists some trace that does not satisfy ψ

Existential properties

- Can we verify this, using LTL?
 - "there exists an execution that reaches program location l₂"
- Yes: $M \not\models \Box \neg I_2$
- Can we verify this, using LTL?
 - "there exists an execution that visits I_2 infinitely often, and never passes through program location I_4 "
- Yes: $M \not\models \neg((\Box \diamondsuit I_2) \land (\Box \neg I_4))$
- Can we verify this, using LTL?
 - "for every execution, it is always possible to return to the initial state of the program"
- No...

CTL

- CTL Computation Tree Logic
 - branching notion of time (compared to linear time for LTL)
 - infinite trees of states, not infinite sequences of states
- Two path quantifiers: ∀ (for all paths), ∃ (there exists a path)
 - LTL implicitly uses ∀
- Example
 - $-\exists \Diamond I_2$ "does there exist an execution that reaches I_2 ?"
- CTL model checking
 - quite different to (and simpler than) LTL model checking

CTL syntax

- Syntax split into state and path formulas
 - specify properties of states/paths, respectively
 - a CTL formula is a state formula •
- State formulae:
 - $\varphi ::= true | a | \varphi \wedge \varphi | \neg \varphi | \forall \psi | \exists \psi$
 - where $a \in AP$ and ψ is a path formula
- Path formulae
 - $\psi ::= \bigcirc \phi | \phi \cup \phi | \Diamond \phi | \Box \phi$
 - where ϕ is a state formula
- Examples (note the pairing of quantifiers/temporal operators)
 - $-\exists \Diamond I_2, \forall \bigcirc b, \forall \Box \exists \Diamond initial$

CTL – Alternative styles

Temporal operators:

```
    - ○ a ≡ X a ("next")
    - ◇ a ≡ F a ("future", "finally")
    - □ a ≡ G a ("globally")
```

Path quantifiers:

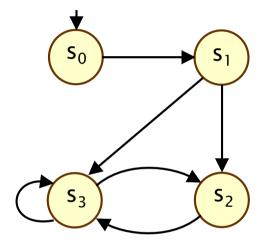
```
- \forall \psi \equiv A \psi- \exists \psi \equiv E \psi
```

• Brackets for quantifier scope: none/round/square

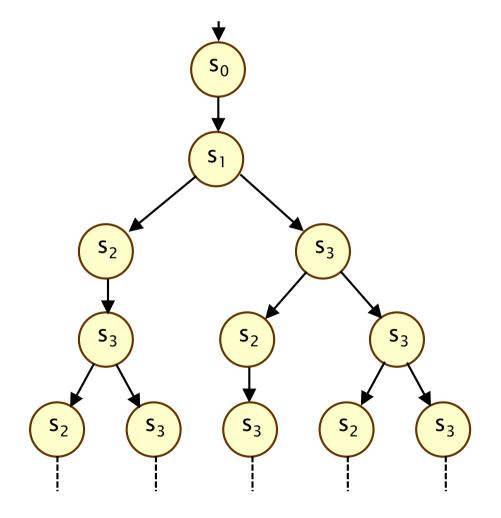
```
- \forall \diamondsuit \psi
- \forall (\psi_1 \cup \psi_2)
- \forall [\psi_1 \cup \psi_2]
```

Computation trees

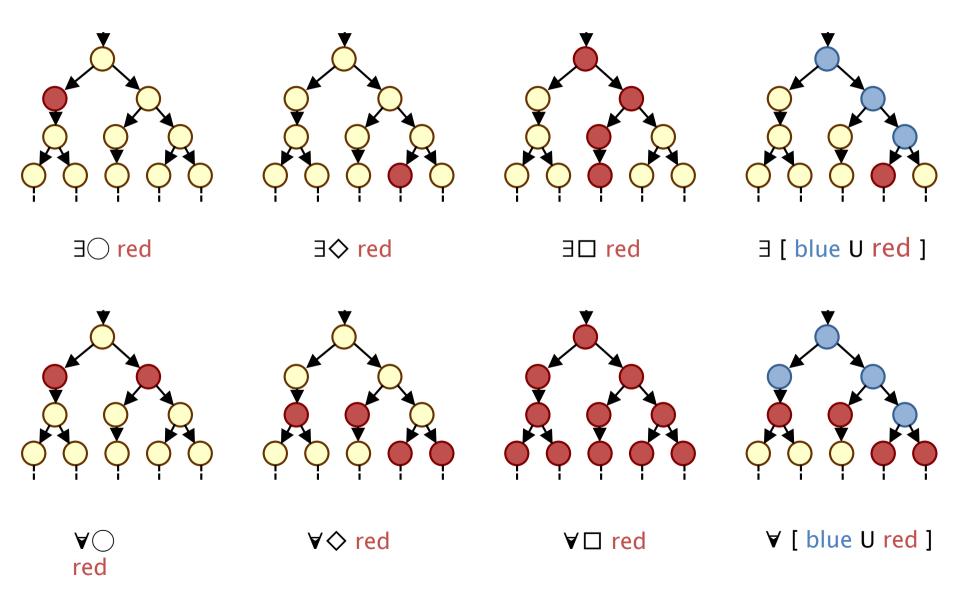
• LTS:



- (Prefix of) infinite computation tree
 - i.e. "unrolling of the LTS"



CTL – Intuitive semantics



CTL examples

- $\forall \Box (\neg(\operatorname{crit}_1 \land \operatorname{crit}_2))$
 - mutual exclusion
- ∀□ ∃♦ initial
 - for every computation, it is always possible to return to the initial state
- $\forall \Box$ (request $\rightarrow \forall \diamondsuit$ response)
 - every request will eventually be granted
- $\forall \Box \forall \diamondsuit \operatorname{crit}_1 \land \forall \Box \forall \diamondsuit \operatorname{crit}_2$
 - each process has access to the critical section infinitely often

CTL semantics

- Semantics of state formulae:
 - $-s \models \phi$ denotes "s satisfies ϕ " or " ϕ is true in s"
- For a state s of an LTS (S,Act,→,I,AP,L):
 - $s \models true$

always

- $-s \models a \Leftrightarrow a \in L(s)$
- $s \models \varphi_1 \land \varphi_2 \qquad \Leftrightarrow s \models \varphi_1 \text{ and } s \models \varphi_2$
- $s \vDash \neg \varphi \Leftrightarrow s \not\vDash \varphi$

- $-s \models \forall \psi \Leftrightarrow \pi \models \psi \text{ for all } \pi \in Path(s)$
- $-s \models \exists \psi \Leftrightarrow \pi \models \psi \text{ for some } \pi \in Path(s)$
- (i+1)th state of path π

- and for a path π :

 - $\pi \vDash \bigcirc \varphi \qquad \Leftrightarrow \pi[1] \vDash \varphi$

 - $-\pi \models \phi_1 \cup \phi_2 \Leftrightarrow \exists k \geq 0 \text{ s.t. } \pi[k] \models \phi_2 \text{ and } \forall i < k \pi[i] \models \phi_1$

Examples

- $s_0 \models \forall \bigcirc b$?
- $s_0 = \exists \bigcirc \neg b$?
- $s_0 = \exists (a \cup a \land b) ?$
- $s_0 \models \exists \bigcirc \forall \Box (a \land b)$?

