

20. Probabilistic Model Checking



Computer-Aided Verification

Dave Parker

University of Birmingham

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Reminders & updates

- No lectures next week
- Assessment 4 (SPIN)
 - due 12 noon Thur 22 Mar
 - help: Facebook, email, office hours, ...
- Exam & revision
 - revision lecture at start of summer term
 - see message next week about content/resources

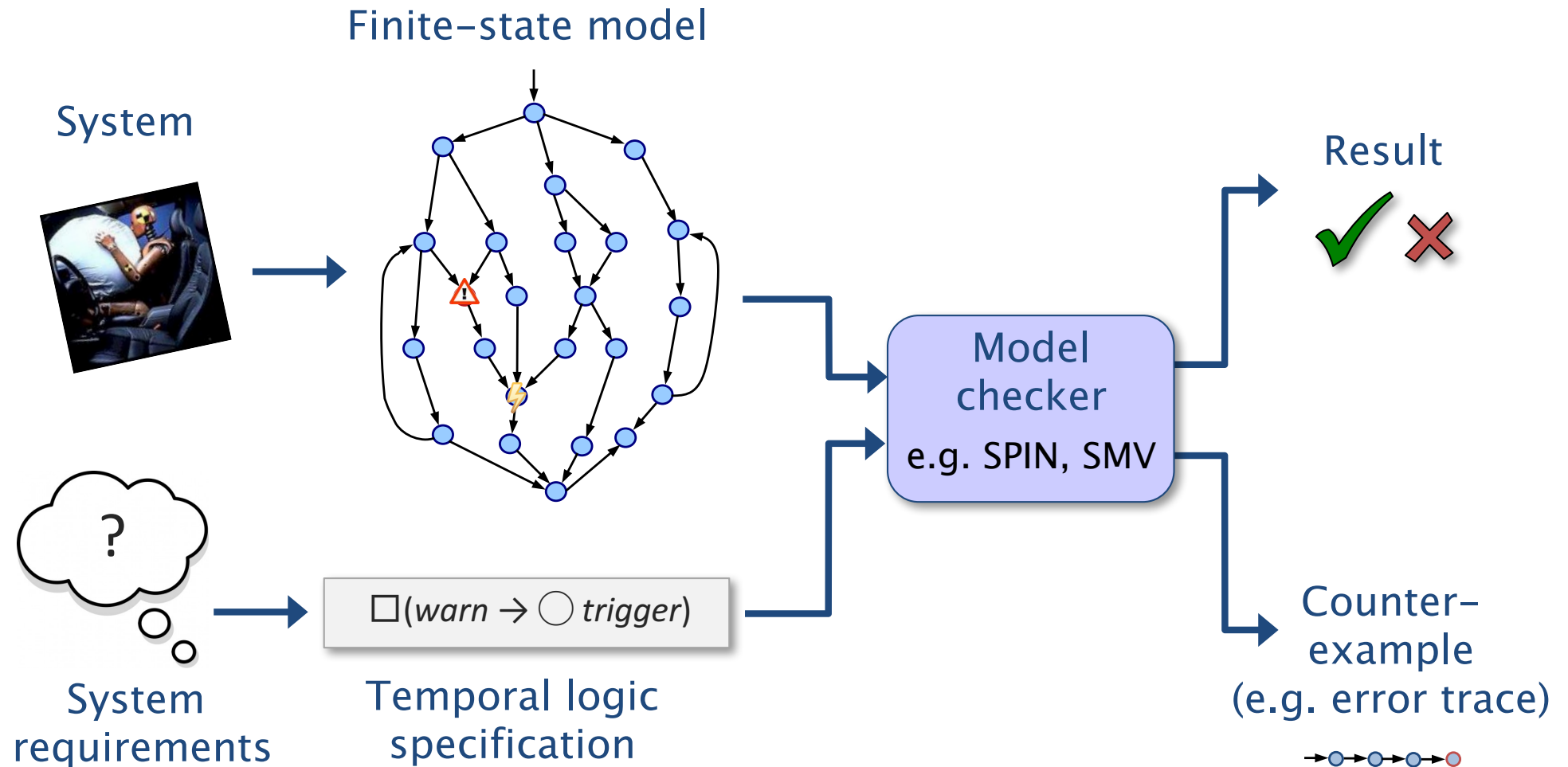
Module syllabus

- Modelling sequential and parallel systems
 - labelled transitions systems, parallel composition
- Temporal logic
 - LTL, CTL and CTL*, etc.
- Model checking
 - CTL model checking algorithms
 - automata-theoretic model checking (LTL)
- Verification tools: SPIN
- Advanced verification techniques
 - bounded model checking via propositional satisfiability
 - symbolic model checking
 - probabilistic model checking

Overview

- Quantitative verification
 - motivation
 - application areas
- Probabilistic model checking
 - discrete-time Markov chains (DTMCs)
 - probabilistic temporal logic (PCTL)
- Background reading:
 - "[Quantitative Verification: Formal Guarantees for Timeliness, Reliability and Performance](#)"
 - PRISM: <http://www.prismmodelchecker.org/>
 - [BK08] Chapter 10

Verification via model checking

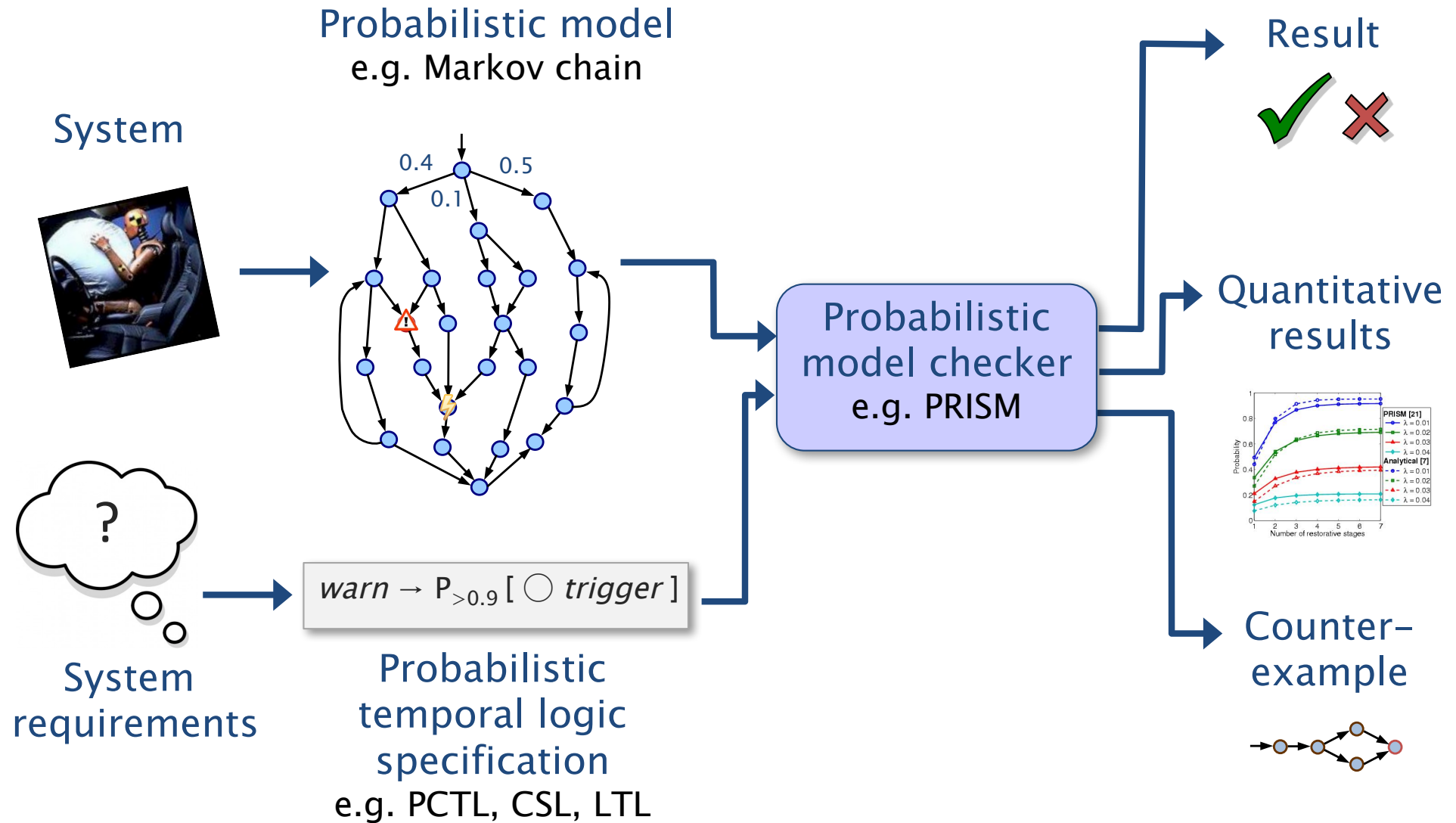


Motivation

- Verifying probabilistic systems...
 - **unreliable** or **unpredictable** behaviour
 - failures of physical components
 - unreliable sensors/actuators
 - message loss in wireless communication
 - **randomisation** in algorithms/protocols
 - random back-off in communication protocols
 - random routing to reduce flooding or provide anonymity
- We need to verify **quantitative** system properties
 - “the probability of the airbag failing to deploy within 0.02 seconds of being triggered is at most 0.001”
 - “with probability 0.99, the packet arrives within 10 ms”



Probabilistic model checking



Probabilistic model checking

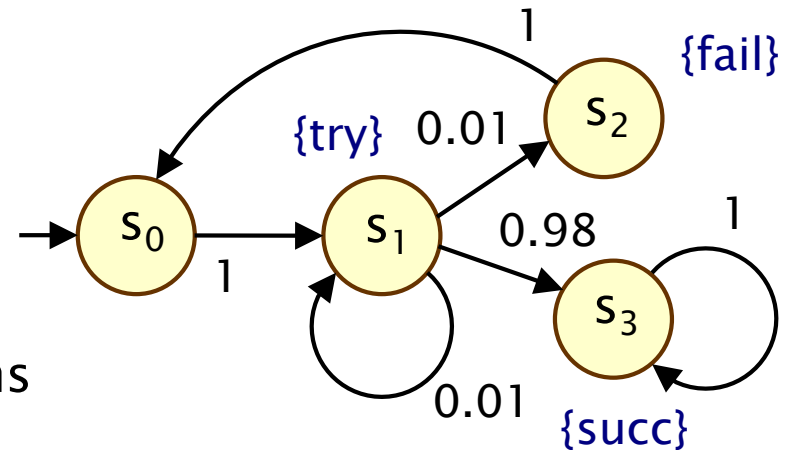
- Construction and analysis of finite probabilistic models
 - e.g. Markov chains, Markov decision processes, ...
 - specified in high-level modelling formalisms
 - **exhaustive** model exploration (all possible states/executions)
- Automated analysis of wide range of quantitative properties
 - properties specified using temporal logic
 - **“exact” results** obtained via numerical computation
 - linear equation systems, iterative methods, uniformisation, ...
 - as opposed to, for example, Monte Carlo simulations
 - efficient techniques from verification + performance analysis
 - mature tool support available, e.g. PRISM

Case studies

- Randomised communication protocols
 - Bluetooth, FireWire, Zeroconf, 802.11, Zigbee, gossiping, ...
- Security protocols/systems
 - pin cracking, anonymity, quantum crypto, contract signing, ...
- Performance & reliability
 - airbag controller, nanotechnology, cloud computing, ...
- Planning & controller synthesis
 - robotics, autonomous driving, dynamic power management, ...
- And many more
 - cell signalling pathways, DNA computing, randomised algorithms
 - see: www.prismmodelchecker.org/casestudies

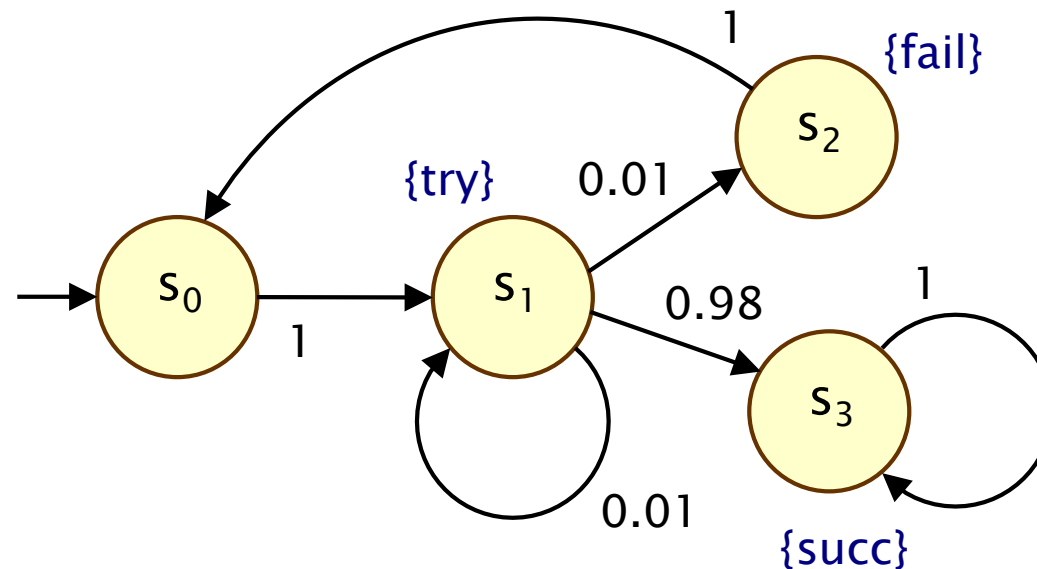
Discrete-time Markov chains

- Discrete-time Markov chains (DTMCs)
 - labelled transition systems augmented with probabilities
- States
 - set of states representing possible configurations of the system being modelled
- Transitions
 - transitions between states model evolution of systems state; occur in discrete time-steps
- Probabilities
 - probabilities of making transitions between states are given by discrete probability distributions



Simple DTMC example

- Modelling a very simple communication protocol
 - after one step, process starts **trying** to send a message
 - with probability 0.01, channel unready so wait a step
 - with probability 0.98, send message **successfully** and stop
 - with probability 0.01, message sending **fails**, restart

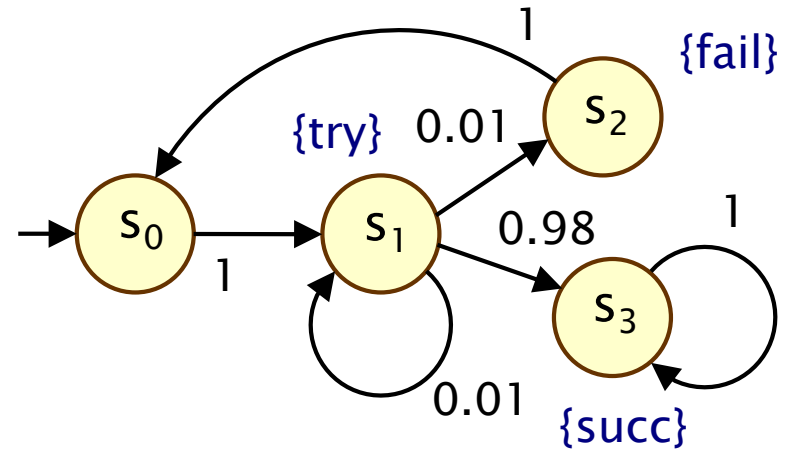


Discrete-time Markov chains

- Formally, a DTMC D is
 - a tuple (S, s_{init}, P, L)
 - where:
 - S is a set of **states** (“state space”)
 - $s_{init} \in S$ is the **initial state**
 - $P : S \times S \rightarrow [0, 1]$ is the **transition probability matrix**
 - where $\sum_{s' \in S} P(s, s') = 1$ for all $s \in S$
 - AP is a set of **atomic propositions**
 - $L : S \rightarrow 2^{AP}$ is a **labelling function**
 - Transition probabilities
 - $P(s, s')$ gives the probability of moving from s to s'
-
- ```

graph LR
 start(()) --> s0((s0))
 s0 -- 1 --> s0
 s0 -- 1 --> s1((s1))
 s1 -- "{try}" --> s1
 s1 --> s0

```

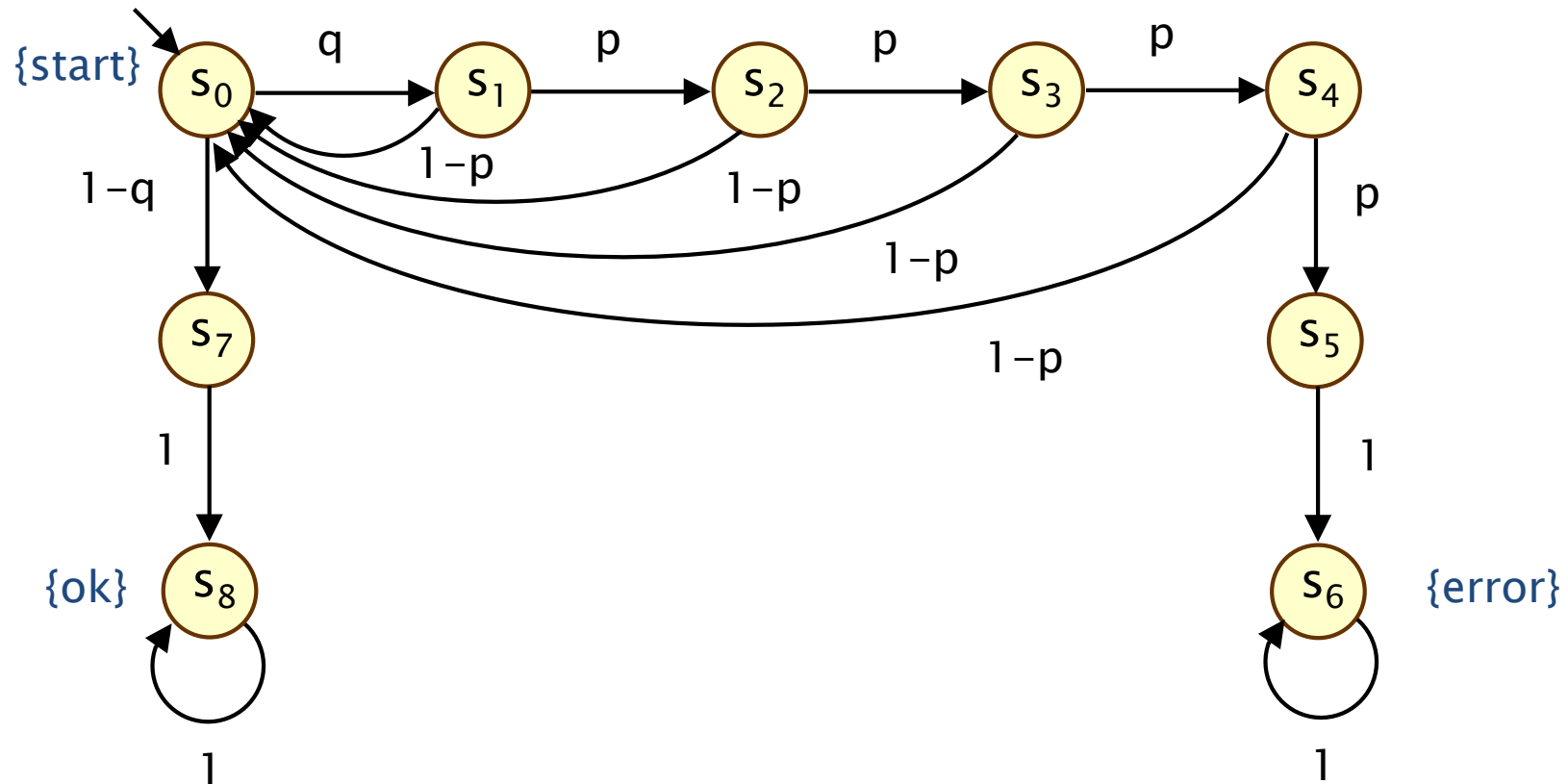


# DTMC example – Zeroconf

- Zeroconf = “Zero configuration networking”
  - self-configuration for local, ad-hoc networks
  - automatic configuration of unique IP for new devices
  - simple; no DHCP, DNS, ...
- Basic idea:
  - 65,024 available IP addresses (IANA-specified range)
  - new node picks address U at random
  - broadcasts “probe” messages: “Who is using U?”
  - any node already using U replies; protocol restarts
  - messages may not get sent (transmission fails, host busy, ...)
  - so: nodes send multiple (n) probes, waiting after each one

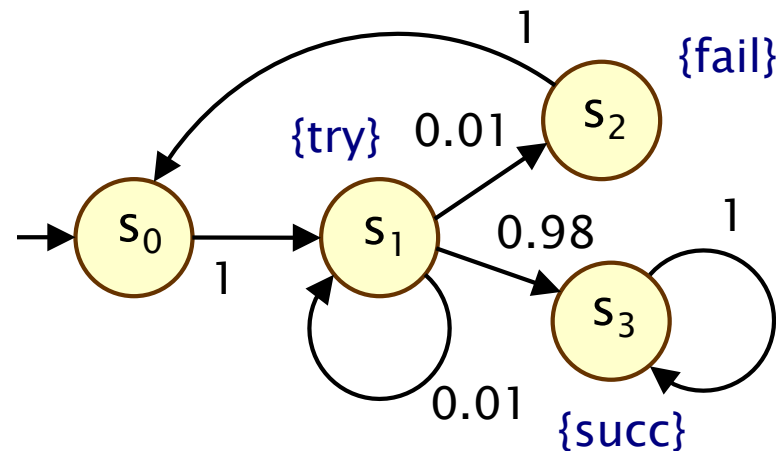
# DTMC for Zeroconf

- $n=4$  probes,  $m$  existing nodes in network
- probability of message loss:  $p$
- probability that new address is in use:  $q = m/65024$



# Paths in DTMCs

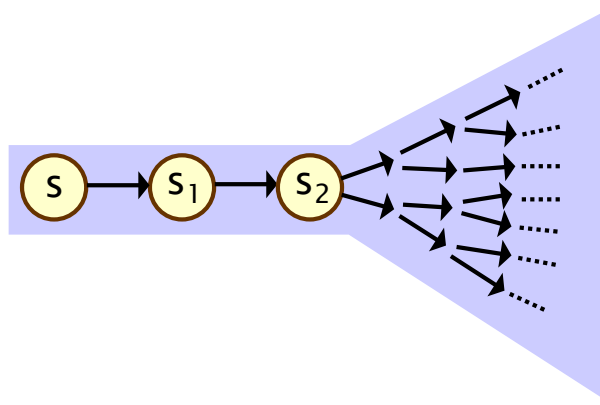
- A (finite or infinite) **path** through a DTMC
  - is a sequence of states  $s_0s_1s_2s_3\dots$  such that  $P(s_i, s_{i+1}) > 0 \ \forall i$
  - represents an execution (i.e. one possible behaviour) of the system which the DTMC is modelling
  - **Paths(s)** is the set of all (infinite) paths starting in  $s$



- Examples:
  - never succeeds:  $(s_0s_1s_2)^\omega$
  - tries, waits, fails, retries, succeeds:  $s_0s_1s_1s_2s_0s_1(s_3)^\omega$

# Paths and probabilities

- To reason (quantitatively) about this system
  - need to define a **probability measure** over paths
- More precisely:
  - probability measure  $\Pr_s$  over  $\text{Paths}(s)$
  - basic idea: defined on finite paths, extended to infinite paths
  - $\mathbf{P}(ss_1s_2) = \mathbf{P}(s,s_1)\mathbf{P}(s_1,s_2)$



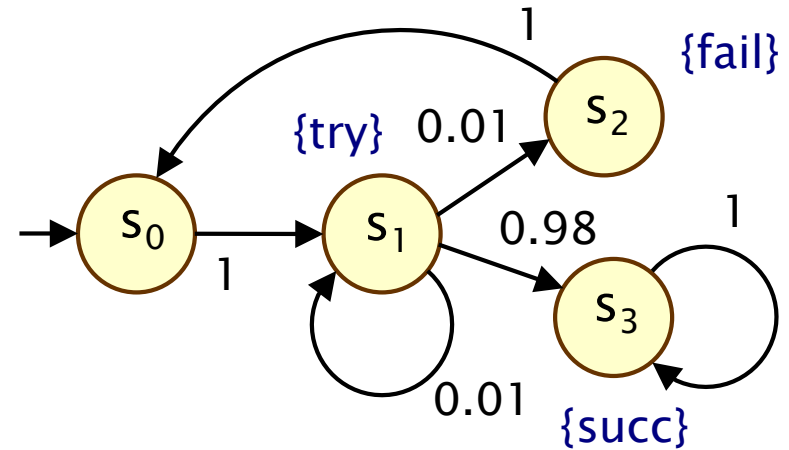


# Paths and probabilities

- Examples

- “try and fail immediately”

- paths starting with prefix  $s_0s_1s_2$
- probability :  $P(s_0s_1s_2)$   
 $= P(s_0, s_1)P(s_1, s_2) = 1 \cdot 0.01 = 0.01$



- “eventually successful and with no failures”

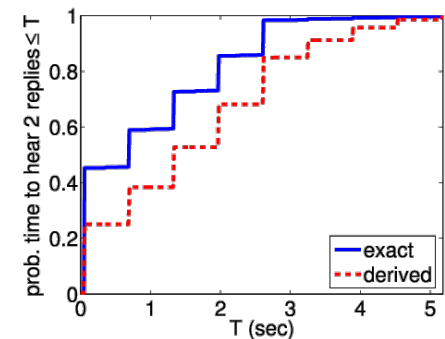
- paths  $s_0s_1s_3\dots$  ,  $s_0s_1s_1s_3\dots$  ,  $s_0s_1s_1s_1s_3\dots$  , ...
- probability:  
 $= P_{s_0}(s_0s_1s_3) + P_{s_0}(s_0s_1s_1s_3) + P_{s_0}(s_0s_1s_1s_1s_3) + \dots$   
 $= 1 \cdot 0.98 + 1 \cdot 0.01 \cdot 0.98 + 1 \cdot 0.01 \cdot 0.01 \cdot 0.98 + \dots$   
 $= 0.9898989898\dots$   
 $= 98/99$

In practice,  
computed by  
solving linear  
equation systems

# Case study: Bluetooth

- Device discovery between a pair of Bluetooth devices
  - performance essential for this phase
- Complex discovery process
  - two asynchronous 28-bit clocks
  - pseudo-random hopping between 32 frequencies
  - random waiting scheme to avoid collisions
  - 17,179,869,184 initial configurations
- Probabilistic model checking (PRISM)
  - “probability discovery time exceeds 6s is always  $< 0.001$ ”
  - “worst-case expected discovery time is at most 5.17s”

$$\text{freq} = [\text{CLK}_{16-12} + k + (\text{CLK}_{4-2,0} - \text{CLK}_{16-12}) \bmod 16] \bmod 32$$



# PCTL

- Temporal logic for describing properties of DTMCs
  - PCTL = Probabilistic Computation Tree Logic
- Extension of (non-probabilistic) temporal logic CTL
  - key addition is **probabilistic operator P**
  - quantitative extension of CTL's  $\forall$  and  $\exists$  operators
- Example
  - $\text{send} \rightarrow P_{\geq 0.95} [ \Diamond^{\leq 10} \text{deliver} ]$
  - “if a message is sent, then the probability of it being delivered within 10 steps is at least 0.95”

# CTL syntax

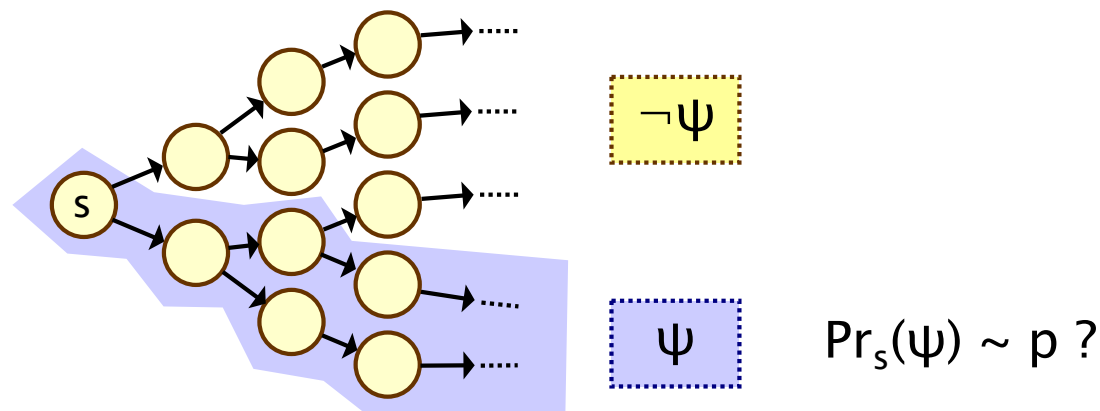
- Syntax split into state and path formulae
  - specify properties of states/paths, respectively
  - a CTL formula is a state formula  $\phi$
- State formulae:
  - $\phi ::= \text{true} \mid a \mid \phi \wedge \phi \mid \neg\phi \mid \forall \psi \mid \exists \psi$
  - where  $a \in AP$  and  $\psi$  is a path formula
- Path formulae
  - $\psi ::= \bigcirc \phi \mid \phi U \phi \mid \dots$
  - where  $\phi$  is a state formula

# PCTL syntax

- Syntax split into state and path formulae
  - specify properties of states/paths, respectively
  - a PCTL formula is a state formula  $\phi$
- State formulae:
  - $\phi ::= \text{true} \mid a \mid \phi \wedge \phi \mid \neg\phi \mid P_{\sim p} [\psi]$
  - where  $a \in AP$  and  $\psi$  is a path formula,  
 $p \in [0,1]$  is a probability bound,  $\sim \in \{<, >, \leq, \geq\}$
- Path formulae
  - $\psi ::= \bigcirc \phi \mid \phi U \phi \mid \phi U^{\leq k} \phi \mid \dots$
  - where  $\phi$  is a state formula,  $k \in \mathbb{N}$

# PCTL semantics for DTMCs

- Semantics of the probabilistic operator  $P$ 
  - example:  $s \models P_{<0.25} [\bigcirc \text{fail}] \Leftrightarrow$  “the probability of atomic proposition fail being true in the next state of outgoing paths from  $s$  is less than 0.25”
  - informal definition:  $s \models P_{\sim p} [\psi]$  means that “the probability, from state  $s$ , that  $\psi$  is true for an outgoing path satisfies  $\sim p$ ”
  - formally:  $s \models P_{\sim p} [\psi] \Leftrightarrow \Pr_s \{ \pi \in \text{Path}(s) \mid \pi \models \psi \} \sim p$



# PCTL examples

- $P_{\leq 0.05} [ \Diamond \text{err/total} > 0.1 ]$ 
  - “with probability at most 0.05, more than 10% of the NAND gate outputs are erroneous”
- $P_{\geq 0.8} [ \Diamond^{\leq k} \text{reply\_count} = n ]$ 
  - “the probability that the sender has received  $n$  acknowledgements within  $k$  clock-ticks is at least 0.8”
- $P_{< 0.4} [ \neg \text{fail}_A \text{ U } \text{fail}_B ]$ 
  - “the probability that component B fails before component A is less than 0.4”
- $\neg \text{oper} \rightarrow P_{\geq 1} [ \Diamond ( P_{> 0.99} [ \Box^{\leq 100} \text{oper} ] ) ]$ 
  - “if the system is not operational, it almost surely reaches a state from which it has a greater than 0.99 chance of staying operational for 100 time units”

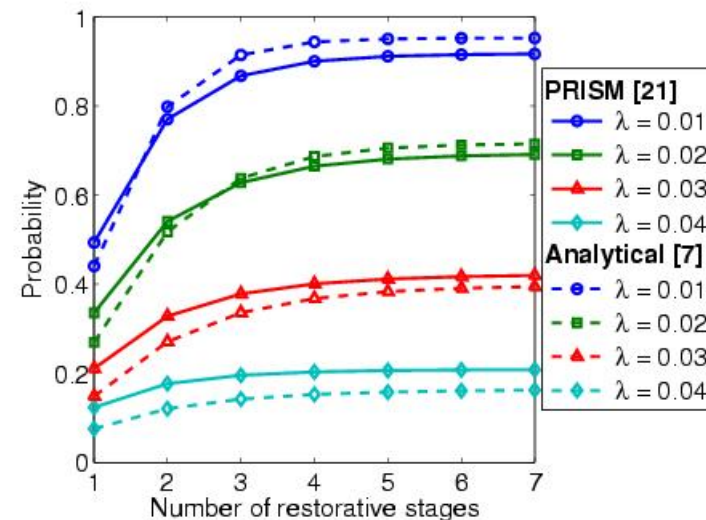
# Qualitative vs. quantitative properties

- P operator of PCTL can be seen as a **quantitative** analogue of the CTL operators  $\forall$  (for all) and  $\exists$  (there exists)
- **Qualitative** PCTL properties
  - $P_{\sim p} [\psi]$  where  $p$  is either 0 or 1
- **Quantitative** PCTL properties
  - $P_{\sim p} [\psi]$  where  $p$  is in the range  $(0,1)$
- $P_{>0} [\Diamond\phi]$  is identical to  $\exists\Diamond\phi$ 
  - there exists a finite path to a  $\phi$ -state
- $P_{\geq 1} [\Diamond\phi]$  is (similar to but) weaker than  $\forall\Diamond\phi$ 
  - a  $\phi$ -state is reached “almost surely”



# Numerical properties

- Consider a PCTL formula  $P_{\sim p} [\psi]$ 
  - if the probability is **unknown**, how to choose the bound  $p$ ?
- When the outermost operator of a PTCL formula is  $P$ 
  - PRISM allows formulae of the form  $P_{=?} [\psi]$
  - “**what is the probability that path formula  $\psi$  is true?**”
- Model checking is no harder: compute the values anyway
- Useful to spot patterns, trends
- Example
  - $P_{=?} [\Diamond \text{err}/\text{total} > 0.1]$
  - “what is the probability that 10% of the NAND gate outputs are erroneous?”

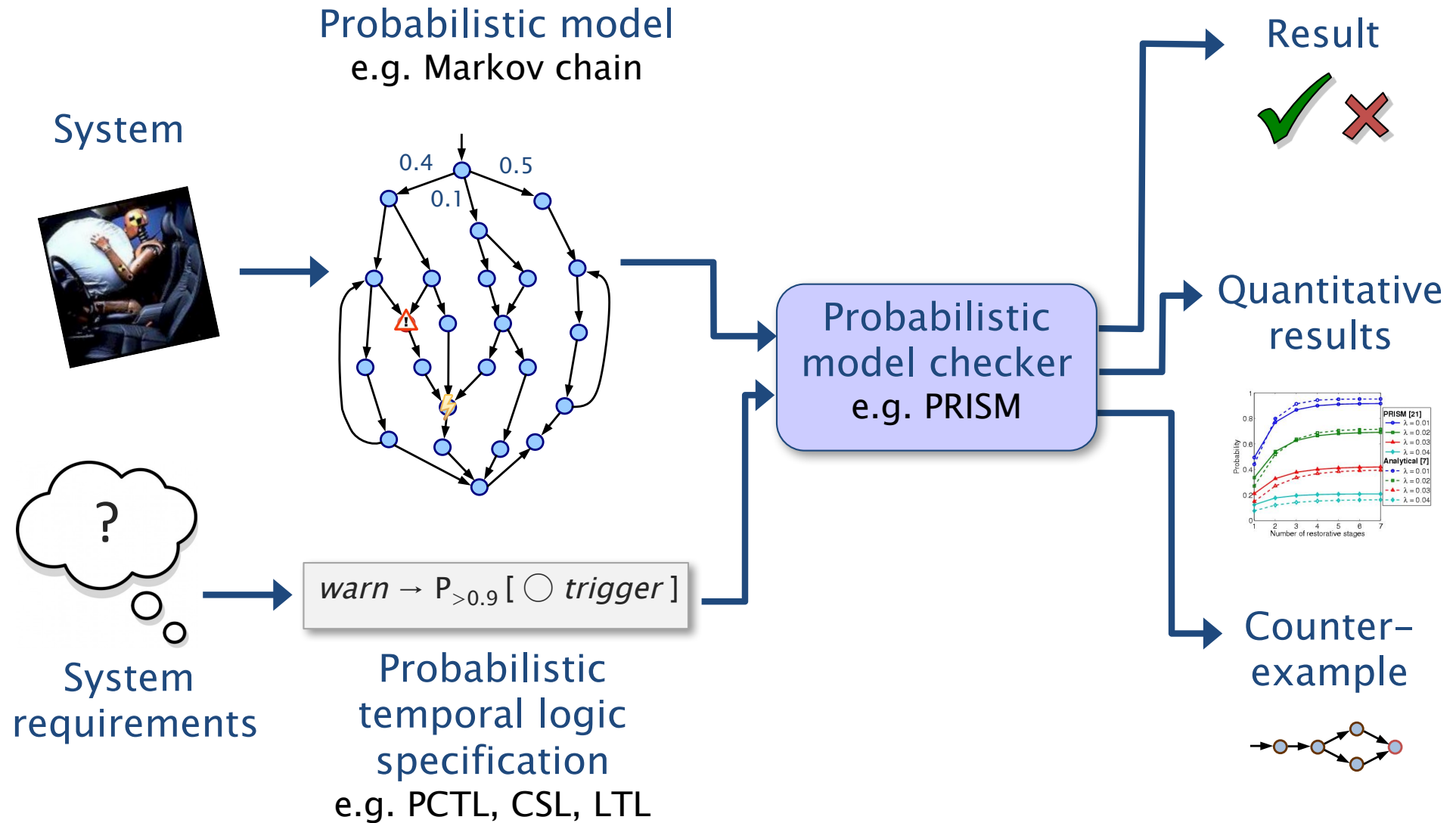


# Probabilistic model checking

- More specification formalisms
  - probabilistic LTL
  - e.g.  $P_{=?} (\Box \Diamond \text{send})$ : “what is the probability that the protocol successfully sends a message infinitely often?”
  - e.g.  $P_{=?} (\neg \text{zone}_3 \text{ U } (\text{zone}_1 \wedge (\Diamond \text{zone}_4)))$ : “ what is the probability of visiting zone 1, without passing through zone 3, and then going to zone 4?”
  - PCTL\* (subsumes PCTL and probabilistic LTL)
  - costs, rewards, ...
- More probabilistic models
  - continuous-time Markov chains
    - adds a notion of real (not discrete) time
  - Markov decision processes...
    - adds nondeterminism

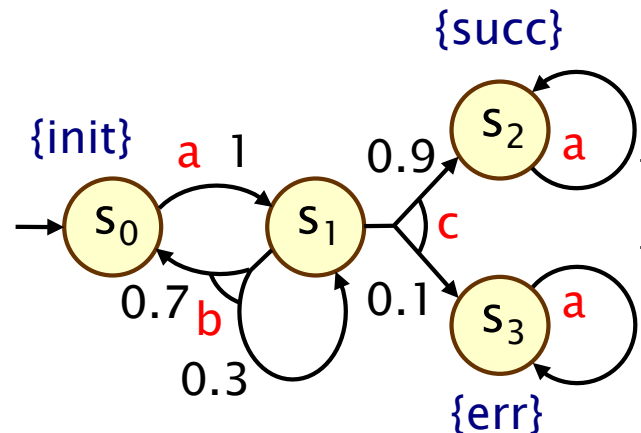


# Probabilistic model checking



# Markov decision processes (MDPs)

- Markov decision processes (MDPs)
  - model **nondeterministic** as well as **probabilistic** behaviour
  - widely used also in: AI, planning, optimal control, ...



- Nondeterminism for:
  - **control**: decisions made by a controller or scheduler
  - **adversarial** behaviour of the environment
  - **concurrency/scheduling**: interleavings of parallel components
  - **abstraction**, or under-specification, of unknown behaviour

# Summary

- Quantitative verification
  - reasoning about probability, time, ...
  - unreliable or unpredictable behaviour, randomisation
  - quantitative "correctness": reliability, timeliness, performance, ...
- Probabilistic model checking
  - discrete-time Markov chains (DTMCs)
  - paths, probability measures
  - probabilistic temporal logic (PCTL)
- PRISM
  - <http://www.prismmodelchecker.org/>