	1/TV Ay PLAY Sevent/Typ/ Beley	Objektéiste -TV -Steckdose -Itifi
	Objet le/sub blasse	
	- (Sleebus) - 1 - Play - 1	echologe of this
	Klussen IR Methalen	Ful
		IR SEND (NEC(32(x84)

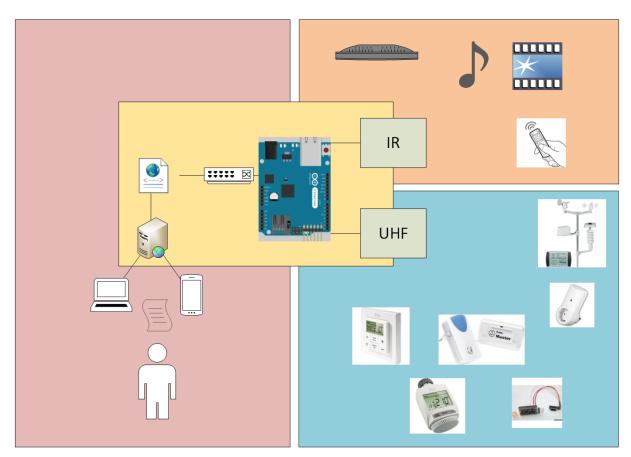
Arduino Projekt

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Ziel des Projektes:

Schaffung einer universellen Plattform zur Hausautomatisierung

- 1. Einbinden verschiedener Steuerungssystemen aus dem Konsumerbereich
 - Verwirklichung eines Universeller Infrarot Sender/Empfängers
 - o TV, Hifi, Lampen usw.
 - o Beliebige Fernbedienungen als Bedienelemente
 - Einbindung von UHF Funktransceivern (433/866 MHz)
 - o Funksteckdosen, Funkdimmer
 - o Empfang von Wetterdaten
- 2. Ansteuerung verschiedener Systeme bündeln
 - · API ähnliche Befehle
 - Abarbeiten von Befehlsketten
 - Ggf. Überwachung und Regelung von Parametern
- 3. HMI Schnittstelle per Webserver



1 Aufgabe 1

{

Listing 1: ../code/InfraredProxy/InfraredProxy.ino // https://www.dpunkt.de/leseproben/3692/5%20Universalfernbedienung.pdf #include <SPI.h> #include <Ethernet.h> #include <IRremote.h> class InfraredProxy IRsend _infrared_sender; void read_line(EthernetClient& client, char* buffer, const int buffer_length) int buffer_pos = 0; 11 while (client.available() && (buffer_pos < buffer_length - 1)) **const char** c = client.read(); if $(c = ' \setminus n')$ break; **if** $(c!= ' \setminus r')$ $buffer[buffer_pos++] = c;$ 19 buffer [buffer_pos] = $' \setminus \theta'$; 21 bool send_ir_data(const char* protocol, const int bits, const long value) 23 bool result = true; if (!strcasecmp(protocol, "NEC")) _infrared_sender.sendNEC(value, bits); else if (!strcasecmp(protocol, "SONY")) _infrared_sender.sendSony(value, bits); else if (!strcasecmp(protocol, "RC5")) _infrared_sender.sendRC5(value, bits); else if (!strcasecmp(protocol, "RC6")) _infrared_sender.sendRC6(value, bits); else result = false;return result; 35 bool handle_command(char* line) 37 strsep(&line, ""); 39 char* path = strsep(&line, ""); char* args [3]; for (char** ap = args; (*ap = strsep(&path, "/")) != NULL;)if $(**ap != ' \setminus \theta')$ 43 **if** (++ap >= &args[3])break; const int bits = atoi(args[1]); **const long** value = atol(args[2]); 47 return send_ir_data(args[0], bits, value); public: void receive_from_server(EthernetServer server) 51 const int MAX_LINE = 256; char line[MAX_LINE]; EthernetClient client = server.available(); 55 if (client)

```
while (client.connected())
59
             if (client.available())
               read_line(client , line , MAX_LINE);
               Serial.println(line);
63
               if (line [0] = 'G' \&\& line [1] = 'E' \&\& line [2] = 'T')
                 handle_command(line);
               if (!strcmp(line, ""))
                  client.println("HTTP/1.1 200 OK \setminus n");
                 break;
71
          delay(1);
          client.stop();
        }
        – ENDE DER DEKLARATION –
    {\color{red} \mathbf{const}} \ {\color{blue} \mathbf{unsigned}} \ {\color{blue} \mathbf{int}} \ {\color{blue} \mathbf{PROXY\_PORT}} = \ 80; \\
   const unsigned int BAUD_RATE = 115200;
   byte mac[] = {
     0x90, 0xA2, 0xDA, 0xOE, 0xDB, 0xAE }; // MAC Arduino Ethernet (David)
   EthernetServer server(PROXY_PORT);
   InfraredProxy ir_proxy;
   void setup()
   {
     // Open serial communications and wait for port to open:
87
     Serial.begin (115200);
     // start the Ethernet connection and the server:
89
     Ethernet.begin(mac);
     server.begin();
91
     Serial.print("server is at ");
     Serial.println(Ethernet.localIP());
93
   }
   void loop()
95
     ir_proxy.receive_from_server(server);
   }
```