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	Objet le/sub blasse	
	- (Sleebus) - 1 - Play - 1	echologe of this
	Klussen IR Methalen	Ful
		IR SEND (NEC(32(x84)

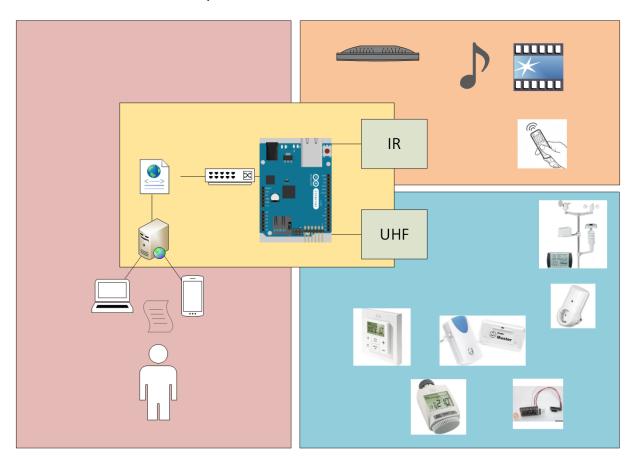
# **Arduino Projekt**

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## Ziel des Projektes:

Schaffung einer universellen Plattform zur Hausautomatisierung

- 1. Einbinden verschiedener Steuerungssystemen aus dem Konsumerbereich
  - Verwirklichung eines Universeller Infrarot Sender/Empfängers
    - o TV, Hifi, Lampen usw.
    - o Beliebige Fernbedienungen als Bedienelemente
  - Einbindung von UHF Funktransceivern (433/866 MHz)
    - o Funksteckdosen, Funkdimmer
    - o Empfang von Wetterdaten
- 2. Ansteuerung verschiedener Systeme bündeln
  - · API ähnliche Befehle
  - Abarbeiten von Befehlsketten
  - Ggf. Überwachung und Regelung von Parametern
- 3. HMI Schnittstelle per Webserver



#### 1 SD Karte

Problem: Fehler: Initialisierung der SD-Karte fehlgeschlagen! Lösung: SD Karte komplett entfernen, SD Karte einstecken, 3s lang den REST Button drücken

### 2 Code

#### 2.1 WEB\_SD\_IR.ino

```
Listing 1: ../code/WEB_SD_IR/WEB_SD_IR.ino
  #include <SPI.h>
  #include <Ethernet.h>
  #include <IRremote.h>
  #include <TextFinder.h>
  #include <SD.h>
   // ### Voraussetzungen ###
   // TSOP Signal-Pin <---> Arduino - Pin 11
   // IR-LED Anode <--> Arduino - Pin 3
   // Test-LED <---> Arduino - Pin 6
   class ControlProxy
13
       IRsend _infrared_sender;
       void read_line(EthernetClient& client, char* buffer, const int buffer_length)
           int buffer_pos = 0;
17
           while (client.available() && (buffer_pos < buffer_length - 1))
               const char c = client.read();
               if (c = ' \setminus n')
                   break;
               if (c!= ' \setminus r')
23
                   buffer[buffer_pos++] = c;
25
           buffer [buffer_pos] = ' \setminus \theta';
       bool send_ir_data(const char* protocol, const int bits, const long value)
           bool result = true;
           if (!strcasecmp(protocol, "NEC"))
31
               _infrared_sender.sendNEC(value, bits);
           else if (!strcasecmp(protocol, "SONY"))
               _infrared_sender.sendSony(value, bits);
           else if (!strcasecmp(protocol, "RC5"))
               _infrared_sender.sendRC5(value, bits);
           else if (!strcasecmp(protocol, "RC6"))
               _infrared_sender.sendRC6(value, bits);
           else
39
               result = false;
           return result;
41
       bool handle_command(char* line)
43
           strsep(&line, "");
           char* path = strsep(&line, "");
           char* args [3];
           if (**ap != ' \setminus \theta')
                   if (++ap >= \&args[3])
```

```
break;
51
            const int bits = atoi(args[1]);
            const long value = atol(args[2]);
            return send_ir_data(args[0], bits, value);
55
   public:
        void receive_from_server(EthernetServer server, File webFile)
57
            const int MAX_LINE = 256;
59
            char line[MAX_LINE];
            EthernetClient client = server.available();
            if (client)
            {
63
                 while (client.connected())
                     if (client.available())
                     {
                         read_line(client , line , MAX_LINE);
                         Serial.println(line);
                         if (line [0] = 'G' \&\& line [1] = 'E' \&\& line [2] = 'T')
                              handle_command(line);
71
                         if (!strcmp(line, ""))
                              // Standard HTTP Header senden
                              client.println("HTTP/1.1 200 OK");
                              client.println("Content-Type: text/html");
                              client.println("Connection: close");
                              client.println();
                              // Website von SD-Karte laden
                              webFile = SD. open ("sd. htm"); // Website laden
                              if (webFile)
                              {
                                while (webFile.available())
                                  client.write(webFile.read()); // Website an Client schicken
                                webFile.close();
                              break;
                         }
                     }
                 delay(1);
                 client.stop();
95
            }
        }

ENDE DER DEKLARATION ——

   const unsigned int PROXY_PORT = 80;
   const unsigned int BAUD_RATE = 19200;
101
   byte \ mac[] = \{ \ 0x90 \,, \ 0xA2 \,, \ 0xDA \,, \ 0x0E \,, \ 0xDB \,, \ 0xAE \ \}; \ \textit{// MAC Arduino Ethernet (David)} \}
   byte ip [] = \{ 192, 168, 3, 100 \};
103
   EthernetServer server (PROXY_PORT);
                                                             // Datei mit HTML-Inhalt
   File webFile;
   ControlProxy ir_proxy;
   void setup()
107
    // Open serial communications and wait for port to open:
109
        Serial.begin(BAUD_RATE);
        // start the Ethernet connection and the server:
111
```

```
Ethernet.begin(mac);
server.begin();
Serial.print("server is at ");
Serial.println(Ethernet.localIP());
}

void loop()
{
    ir_proxy.receive_from_server(server, webFile);
}
```

# 3 Beispiele

#### 3.1 InfraredDumper.ino

Listing 2: ../example/InfraredDumper/InfraredDumper.ino #include <IRremote.h> **const unsigned int** IR\_RECEIVER\_PIN = 11; **const unsigned int** BAUD\_RATE = 19200; IRrecv ir\_receiver(IR\_RECEIVER\_PIN); decode\_results results; void setup() Serial.begin(BAUD\_RATE); 11 ir\_receiver.enableIRIn(); } void dump(const decode\_results\* results) const int protocol = results -> decode\_type; 17 Serial.print("Protocol: "); if (protocol == UNKNOWN) 19 Serial.println("not recognized."); else 23 if (protocol == NEC)Serial.println("NEC"); else if (protocol == SONY) Serial.println("SONY"); 31 else if (protocol == RC5) Serial.println("RC5"); else if (protocol == RC6) { Serial.println("RC6"); 39 Serial.print("Value: "); Serial.print(results->value, HEX); Serial.print("(");  ${\tt Serial.print(results-\!\!\!>\!bits,\ DEC);}$ Serial.println(" bits)"); } } 47 void loop() 49 if (ir\_receiver.decode(&results)) 51 { dump(&results); 53 ir\_receiver.resume(); } 55

## 3.2 InfraredProxy.ino

Listing 3: ../example/InfraredProxy/InfraredProxy.ino

```
#include <SPI.h>
  #include <Ethernet.h>
  #include <IRremote.h>
  // ### Voraussetzungen ###
   // TSOP Signal-Pin <--> Arduino - Pin 11
  // IR-LED Anode <--> Arduino - Pin 3
   class InfraredProxy
   {
       IRsend _infrared_sender;
       void read_line(EthernetClient& client, char* buffer, const int buffer_length)
10
           int buffer_pos = 0;
           while (client.available() && (buffer_pos < buffer_length - 1))
                const char c = client.read();
                if (c = ' \setminus n')
                    break;
                if (c!= ' \ r')
                    buffer[buffer_pos++] = c;
20
           buffer [buffer_pos] = ' \setminus \theta';
22
       bool send_ir_data(const char* protocol, const int bits, const long value)
       {
           bool result = true;
           if (!strcasecmp(protocol, "NEC"))
26
                _infrared_sender.sendNEC(value, bits);
           else if (!strcasecmp(protocol, "SONY"))
                _infrared_sender.sendSony(value, bits);
           else if (!strcasecmp(protocol, "RC5"))
                _infrared_sender.sendRC5(value, bits);
           else if (!strcasecmp(protocol, "RC6"))
32
                _infrared_sender.sendRC6(value, bits);
           else
                result = false;
           return result;
36
       bool handle_command(char* line)
           strsep(&line, "");
40
           char* path = strsep(&line, "");
           char* args[3];
           for (char** ap = args; (*ap = strsep(&path, "/")) != NULL;)
                if (**ap != ' \setminus \theta')
                    if (++ap >= \&args[3])
                        break;
           const int bits = atoi(args [1]);
           const long value = atol(args[2]);
48
           return send_ir_data(args[0], bits, value);
       }
   public:
       void receive_from_server(EthernetServer server)
52
           const int MAX_LINE = 256;
           char line [MAX_LINE];
           EthernetClient client = server.available();
56
           if (client)
```

```
while (client.connected())
                     if (client.available())
62
                         read_line(client , line , MAX_LINE);
                         Serial.println(line);
64
                         if (line [0] = 'G' \&\& line [1] = 'E' \&\& line [2] = 'T')
                             handle_command(line);
66
                         if (!strcmp(line, ""))
                             client.println("HTTP/1.1 200 OK \setminus n");
                             break;
70
                    }
                }
                delay(1);
                client.stop();
            }
        }
78

    ENDE DER DEKLARATION –

   const unsigned int PROXY_PORT = 80;
   const unsigned int BAUD_RATE = 19200;
   byte mac[] = { 0x90, 0xA2, 0xDA, 0x0E, 0xDB, 0xAE }; // MAC Arduino Ethernet (David)
   byte ip [] = \{ 192, 168, 3, 100 \};
   EthernetServer server(PROXY_PORT);
   InfraredProxy ir_proxy;
   void setup()
   // Open serial communications and wait for port to open:
        Serial.begin(BAUD_RATE);
        while (! Serial)
90
            ; // wait for serial port to connect. Needed for Leonardo only
        // start the Ethernet connection and the server:
94
        Ethernet.begin(mac);
        server.begin();
        Serial.print("server is at");
        Serial.println(Ethernet.localIP());
   void loop()
        ir_proxy.receive_from_server(server);
102
```