Bachelor thesis in the Computer Science and Media degree programme

Tactical Game AI with shared Knowledge based on Influence Maps

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Abstract

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Contents

Chapter 1

Introduction

1.1 Motivation

I find it very interesting to give an artificial intelligence (AI) agent in the game as much knowledge as you can, but also not so much that it's like cheating. Because seeing how agents react to each other and can fight against each other has always interested me. That's why I wanted to write about influence map (IM) to give the agents an abstract picture of the map and even a kind of memory.

1.2 Scientific question

How much better are AI agents with shared knowledge to agents without shared knowledge.

1.3 Structure of the Thesis

Chapter 2

Related work

In [Champandard, 2021] article discussed how IM works in general. As well as the important part of giving an agent or squad a memory of the current influence range on the map.

Chapter 3

Theoretical background

3.1 Influence Map

All information is taken from the book AI for Games unless otherwise cited in this chapter [Mellington, 2020].

To enable the AI to make good decisions at a higher level, an IM is created to represent the game world abstractly.

3.1.1 Simple Influence

The impact of a unit on the area it stands in varies depending on whether it is a simple foot soldier or an expensive tank or similar. If you take the strength of a unit, it decreases with increasing distance. So the further away you are from the unit, the less influence it has. A linear drop-off model can be used for this. Double the distance and you get half the impact:

$$I_d = \frac{I_0}{1+d}$$

I_d is the influence at a given distance. d and I_0 are the influence at the distance of 0.

3.1.2 Calculating the Influence

For the IM, a large calculation is needed for each unit on the map for each possible position. The execution time would be $O(nm)$ and the memory $O(m)$. m would represent the number of possible positions in the game and n the number of units. Using a linear drop-off formula for the influence of a unit and there being an influence threshold value, after the range of influence is set to zero, then the radius of influence is thus given:

$$r = \frac{I_0}{I_t - 1}$$

Where I_t is the threshold value for the influence. Thus, the influence of each unit is only applied to the places that are within the given radius. This limits the calculation time to $O(nr)$ for the time and to $O(m)$ for the memory. r is the number of locations that are within the average given radius.

3.1.3 Dealing with Unknowns

Hereby we give the unit only their influence to distribute in places they can see by their radius. Thus, an aspect called fog-of-war (FOW) is built in. This is important for investigating whether the shared knowledge of units makes a difference. In this way, units also have a maximum distance they can see and can only build a personal IM based on the friendly or enemy units they can see and incorporate this into their decisions. This can be seen as a problem, as the AI cannot simply assert which unit can be in the FOW as humans can. Furthermore, it becomes important here to see how much influence shared knowledge has among a team and thus the FOW becomes smaller and the unit shares knowledge among itself instead of each unit interacting individually.

3.1.4 Influence Map Setup

All information in this section is quoted from the article [Champandard, 2021]. Otherwise they are cited as such.

For the IM, a 2-dimensional grid is stretched over the map and divided into a grid system. Then all areas that cannot be walked on, such as walls or similar, are excluded from the calculation or ignored. This promotes the unknown, because you cannot see through walls. After that, the cells that are the shortest distance to each agent are injected with their influence in the 2 dimensional grid. This means that these cells are always set to the influence value of the unit regardless of anything else. After setting the values of each agent in the IM, a blur algorithm is applied as explained in the chapter 3.2. It is up to you which one to use. The important thing is to only apply this to cells that are accessible. This way the unknown is applied and the influence of an agent has to spread around obstacles and not just take the distance to them. The value from the blur algorithm is then multiplied by the decay to implement a decay of the influence on the range.

$$I_{xy} = b_{xy} * D$$

I_{xy} is the influence at the point x and y in the grid. This is equal to the blurred value b_{xy} at the point x and y from the algorithm multiplied by the decay value D.

- **Momentum**

- **Decay** Decay is for the decay of the influence value within an IM so a kind of fading memory is built up and the influence continues to decrease depending on how far it is from its point of origin.

- **Update Frequency** This parameter describes how often the influence is updated.

3.2 Blur algorithm

For the calculation of the influence in maps with small corridors and narrow spaces Champandard [2021] a blur algorithm can be used as well as flooding functions. In this work, a boxblur algorithm was applied. But it would work just as well with a Gaussian blur. This is open to the individual preferences of how the influence should spread.

0.000	0.000	0.000	0.000	0.000
0.000	**1.000**	0.000	0.000	0.000
0.000	0.000	0.000	0.000	0.000
0.000	0.000	0.000	0.000	0.000
0.000	0.000	**-1.000**	0.000	0.000

Table 3.1: Boxblur influence example grid - Iteration 0

The Box Blur is a spatial domain linear filter. This takes a pixel (or in our case a cell) from the grid and takes itself and its surrounding pixels and calculates the average as the new value. A 3 by 3 box blur (radius 1) can also be described here as a matrix:

$$K = \frac{1}{9}\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

K is the average value of pixel and its surrounding values.[Handwiki, 2021]

0.250	0.200	0.200	0.030	0.008
0.240	**1.000**	0.160	0.006	0.007
0.210	0.180	0.150	0.040	0.002
0.060	-0.040	-0.070	-0.100	-0.010
0.005	-0.170	**-1.000**	-0.200	-0.078

Table 3.2: Boxblur influence example grid - Iteration 1

0.420	0.370	0.290	0.080	0.025
0.400	**1.000**	0.250	0.009	0.027
0.300	0.250	0.140	0.030	-0.007
0.068	-0.057	-0.130	-0.15	-0.069
-0.039	-0.221	**-1.000**	-0.271	-0.142

Table 3.3: Boxblur influence example grid - Iteration 2

Through this box blur, the influence is gradually expanded with 1,000 and -1,000 and then stagnates after a certain iteration. The Celle with 1.000 means that there is an allied unit that places its influence there and -1.000 means that there is an enemy unit.

3.3 Waypoints

Waypoints are positions distributed around the game world. With waypoints, the AI can use this for its pathfinder in order to progress in the game world. Tactical waypoints require more data describing these points in order to make a correct decision about which waypoint to use [Mellington, 2020].

Chapter 4

Experimental setup

The experiment is a match against two sides in the style of "conquest" as in games of Battlefield. In Conquest, there are a certain number of places that a side tries to capture. At the beginning, each place is still uncaptured. When a team has taken a point, it always gets points added to their points account at certain time intervals. The team that has reached a certain number of points first after a certain time has won. One side will consist of a squad of five agents, the other side of five squads of one agent each. A squad always knows where its agents are and whether a unit sees a friendly or enemy agent and can thus build up an IM. Each time a team wins, this is saved in a file and the next match starts from the beginning. This allows you to run this several thousand times so that the result is not falsified.

4.1 Assumption

I think the side with the squad and its five agents has a slightly higher win rate than the side with the 5 squads with one agent each. This is because it has more information to decide, for example, which of the points to attack first or which point may have no enemy units.

4.2 Rules of the game

The goal of one side is to reach 100 points to win the game. This means that there will always be 3 points distributed on the map, each of which can be captured. A point is captured when an agent is in a certain area without any other enemy agents. Each point adds one point to the score every 5 seconds. Each agent has the option to shoot and kill an enemy agent. Each agent has 100 lives and can shoot a projectile with 10 damage every 3 seconds. If the projectile hits a wall or another enemy agent it is destroyed. If an agent has 0 life it is destroyed and after 10 seconds it is re-instantiated at a random location on the map but not in a capturable point and thus rejoins the game.

4.2.1 Playing field construction

4.2.2 Randomness factor

Chapter 5

Results

Chapter 6

Discussion

Chapter 7

Conclusion

Chapter 8

Lists

List of Acronyms

IM influence map

FOW fog-of-war

AI artificial intelligence

List of Figures

List of Tables

Bibliography

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