

Unit: mm

# **General Characteris**

<b>Basic Dimensions</b>	Unit		<b>Motor Features</b>	Unit
Diameter	mm	42/48	Motor type	BLDC outrunner
Body length	mm	56.8	Motor model	MXL4825KV200HA
Output shaft diam.	mm	8	Pole pairs	5
Output shaft length	mm	22	Number of phases	3

#### **Controller Features**

Control type:	Square-wave/o	penloop	Pin definition(left to right):	
Rated voltage:	24V(8\	/-25.2V)	1.Blue-PWM 2.Black-GND 3.Yellow-F/l	R 4.Green-FG 5.Red-VCC
Over Currunt Prote	ction (OCP):	4.5 A	PWM frequency:	10K -20K Hz
Signal voltage leve	l:	5V	Frequency Generator(FG):	5 PPR

### **Gearbox Features** Unit

Gearbox model		GP48L1A
Gearbox type		Planetary
Gearbox ratio	K	3.7
Gearbox stages		1
Gearbox diameter	mm	42
Gearbox length	mm	25.6
Gearbox efficiency		80-90%
Operating torque	kg*cm	20
Brakeing torque	kg*cm	60

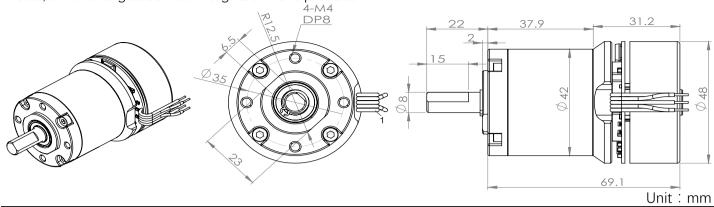
# Nominal & Stall Unit

Gearbox ratio	K	3.7
Nominal voltage	V	24
Noload speed	rpm	1194
Nominal speed	rpm	1001
Nominal torque	Nm	0.4
Nominal current	Α	3.0
Maximal power	W	54
Maximal efficiency		65%
Stall torque*	Nm	1.3
Stall current*	Α	8

<sup>\*</sup>Attention: Stall operation is only for reference due to Over Current Protection.

<sup>\*</sup>In case specific shaft, connector, or any other features need to be customized, please visit www.damoto.tech and contact us.





# **General Characteris**

# **Basic Dimensions** Unit

Diameter	mm	42/48
Body length	mm	69.1
Output shaft diam.	mm	8
Output shaft length	mm	22

# Motor Features Unit

Motor type	BLDC outrunner
Motor model	MXL4825KV200HA
Pole pairs	5
Number of phases	3

#### **Driver Features**

Control type:	Square-wave	openloop/
Rated voltage:	24V	(8V-25.2V)
Over Currunt Protecti	ion (OCP):	4.5 A
Signal voltage level:		5V

# Pin definition(left to right):

1.Blue-PWM 2.Black-GND 3.Yellow-F/R 4.Green-FG 5.Red-VCC

PWM frequency: 10K -20K Hz

Frequency Generator(FG): 5 PPR

#### Gearbox Features Unit

Gearbox model		GP48L2A
Gearbox type		Planetary
Gearbox ratio	K	10.2/13.7/19.2
Gearbox stages		2
Gearbox diameter	mm	42
Gearbox length	mm	69.1
Gearbox efficiency		80%
Operating torque	kg*cm	60
Brakeing torque	kg*cm	180

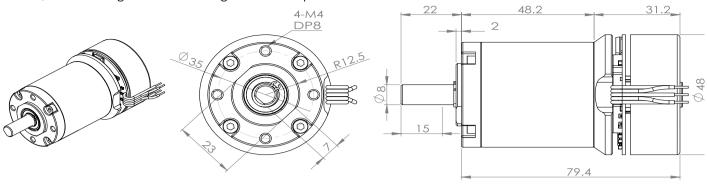
### Nominal & Stall Unit

Gearbox ratio	K	10.2	13.7	19.2
Nominal voltage	V	24	24	24
Noload speed	rpm	433	322	230
Nominal speed	rpm	363	270	193
Nominal torque	Nm	1.1	1.5	2.1
Nominal current	Α	3.0	3.0	3.0
Maximal power	W	54	54	54
Maximal efficiency		59%	59%	59%
Stall torque*	Nm	3.7	4.9	6.9
Stall current*	Α	8	8	8

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## Unit: mm

# **General Characteris**

**Basic Dimensions** 

Diameter	mm	42/48
Body length	mm	79.4
Output shaft diam.	mm	8
Output shaft length	mm	22

Unit

# Motor Features Unit

Motor type	BLDC outrunner
Motor model	MXL4825KV200HA
Pole pairs	5
Number of phases	3

#### **Driver Features**

Control type:	Square-way	/e/openloop
Rated voltage:	24	V(8V-25.2V)
Over Currunt Protect	ction (OCP):	4.5 A
Signal voltage leve	l:	5V

# Pin definition(left to right):

1.Blue-PWM 2.Black-GND 3.Yellow-F/R 4.Green-FG 5.Red-VCC

PWM frequency: 10K -20K Hz

Frequency Generator(FG): 5 PPR

#### **Gearbox Features** Unit

Gearbox model		GP48L3A
Gearbox type		Planetary
Gearbox ratio	K	32.5/50.9/71.2
Gearbox stages		3
Gearbox diameter	mm	42
Gearbox length	mm	48.2
Gearbox efficiency		70%
Operating torque	kg*cm	120
Brakeing torque	kg*cm	360

# Nominal & Stall Unit

Gearbox ratio	K	32.5	32.5	50.9	50.9	71.2	71.2
Nominal voltage	V	12	24	12	24	12	24
Noload speed	rpm	68	136	43	87	31	62
Nominal speed	rpm	53	114	34	73	24	52
Nominal torque	Nm	2.6	3.5	4.1	5.5	5.8	7.7
Nominal current	Α	2.0	2.8	2.0	2.8	2.0	2.8
Maximal power	W	20	54	20	54	20	54
Maximal efficiency		51%	53%	51%	53%	51%	53%
Stall torque*	Nm	9	12	14	18	19	26
Stall current*	Α	6	8	6	8	6	8

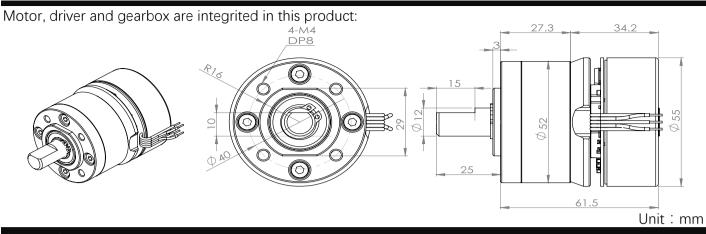
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5

3





#### **General Characteris Basic Dimensions** Unit **Motor Features** Unit Diameter 52/55 Motor type **BLDC** outrunner mm Body length 61.5 Motor model MXL5520KV190HA mm 12 Output shaft diam. Pole pairs mm Number of phases Output shaft length mm 25

#### **Driver Features**

Gearbox length

Gearbox efficiency

Operating torque

Brakeing torque

Control type:	Square-wav	e/openloop	Pin definition(left to	right):		
Rated voltage:	2	4V(8V-25V)	1.PWM 2.GND 3.F/R			
Over Currunt Protection (OCP) 9 A			PWM frequency:			10K -20K Hz
Signal voltage level:		5V	Frequency Generate	or(FG):		5 PPR
<b>Gearbox Features</b>	Unit		Nominal & Stall	Unit		
			Gearbox ratio	K	3.7	
Gearbox model		GP52L2A	Nominal voltage	V	24	
Gearbox type		Planetary	Noload speed	rpm	1144	
Gearbox ratio	K	3.7	Nominal speed	rpm	873	
Gearbox stages		1	Nominal torque	Nm	0.7	
Gearbox diameter	mm	52	Nominal current	Α	5.5	

Maximal power

Stall torque\*

Stall current\*

Maximal efficiency

Dia definition/left to right)

W

Nm

Α

81

65%

1.8

12

mm

kg\*cm

kg\*cm

27.3

90%

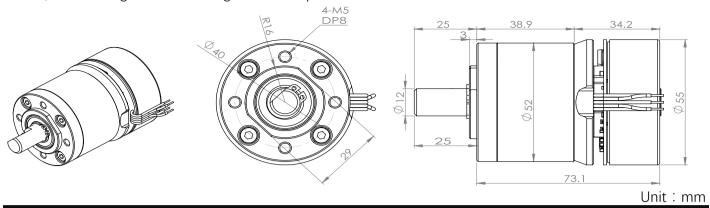
20

60

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# **General Characteris**

<b>Basic Dimensions</b>	Unit		Motor Features	Unit
Diameter	mm	52/55	Motor type	BLDC outrunner
Body length	mm	73.1	Motor model	MXL5520KV190HA
Output shaft diam.	mm	12	Pole pairs	5
Output shaft length	mm	25	Number of phases	3

### **Controller Features**

Control type:	Square-	wave/openloop	Pin definition(left to right):					
Rated voltage:		24V(8V-25V)	1.PWM 2.GND 3.F/R 4FG 5.VCC					
Over Currunt Protec	tion (OCF	P) 9 A	PWM frequency:				10K -20K Hz	
Signal voltage level: 5V			Frequency Generator(FG):				5 PPR	
<b>Gearbox Features</b>	Unit		Nominal & Stall	Unit				
			Gearbox ratio	K	13.7	19.2	26.9	
Gearbox model		GP52L2A	Nominal voltage	V	24	24	24	
Gearbox type		Planetary	Noload speed	rpm	309	220	157	
Gearbox ratio	K	13.7/19.2/26.9	Nominal speed	rpm	236	168	120	
Gearbox stages		2	Nominal torque	Nm	2.8	3.9	5.4	
Gearbox diameter	mm	52	Nominal current	Α	5.4	5.5	5.6	
Gearbox length	mm	38.9	Maximal power	W	81	81	81	
Gearbox efficiency		80%	Maximal efficiency		62%	62%	62%	
Operating torque	kg*cm	80	Stall torque*	Nm	6.6	9.2	12.9	
Brakeing torque	kg*cm	240	Stall current*	Α	12	12	12	

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