

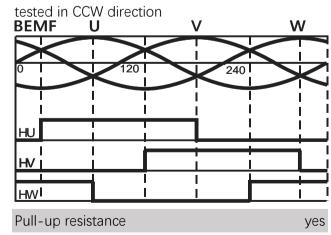
General Characteris los					
Motor Configuration	Unit			Unit	
Mechanical structure		outrunner	Ingress protection		IP 54
Number of pole pairs		7	Speed constant	KV	125
Number of phases		3	Torque constant	mNm/A	68
Winding connection		star	Single phase resistance	Ohm	1.75
Total weight	g	130	DQ inductance	uН	450
Rotor inertia	uNm*s ²	1.8	Friction	uN*m*s	0.5

Thermal Data	
Thermal resistance houing -ambient	4.8K/W
Thermal resistance winding-housing	7.1K/W
Ambient temperature	-20 °C - 70 °C
Maximal winding temperature	120 °C

Nominal & Stall	Unit		
Nominal voltage	V	12	24
No load speed	rpm	1500	3000
No load current	mA	90	150
Nominal speed	rpm	1100	2100
Nominal torque	mNm	54	117
Nominal current	Α	0.8	1.6
Maximal power	W	8	30
Maximal efficiency		80%	82%
Stall torque	mNm	300	320
Stall current	А	3.5	4.5

Selisoric	
Sensor type	bipolar self-locking hall
Number of halls	3
Supply voltage	5V
Electrical angle	120 degrees

Hall sequence regards to back EMF



ATTENTION: Stall operation is not recommended, please do necessary protection to avoid irreparable damage. *In case specific shaft, connector, or any other features need to be customized, please visit www.damoto.tech and contact us.