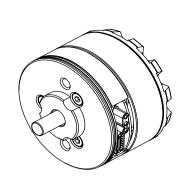
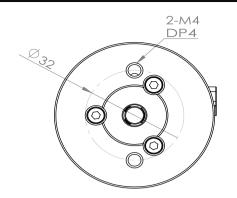
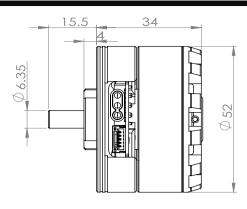
Unit: mm









Signal connector (P1): GH1.25-F-5P Signal cable: GH5P-M-28AWG-15cm Phase connector (P2): AMASS MR30PW-F

AMASS MR30PW-F Pin definition(left to right):

Р1.

P2:

Phase cable: MR30-M-20AWG-15cm

**P1**: 1.HW 2.HV 3.HU 4.VCC 5.GND **P2**: 1.W 2.V 3.U

## General Characteris

<b>Motor Configuration</b>	Unit	
Mechanical structure		outrunner
Number of pole pairs		7
Number of phases		3
Winding connection		star
Total weight	g	220
Rotor inertia	uNm*s <sup>2</sup>	6.5

	Unit	
Ingress protection		IP 54
Speed constant	KV	200
Torque constant	mNm/A	65
Single phase resistance mOhm		320
DQ inductance	uН	110
Friction	uN*m*s	0.5

## **Thermal Data**

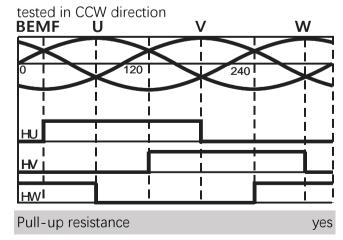
Thermal resistance houing -ambient	4.2K/W
Thermal resistance winding-housing	6.5K/W
Ambient temperature	-20 °C - 60 °C
Maximal winding temperature	120 °C

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Sensor type	bipolar self-locking hall
Number of halls	3
Supply voltage	5V
Electrical angle	120 degrees

Nominal & Stall	Unit	
Nominal voltage	V	24
No load speed	rpm	4860
No load current	mA	340
Nominal speed	rpm	3500
Nominal torque	mNm	370
Nominal current	Α	6.8
Maximal power	W	160
Maximal efficiency		85%
Stall torque	mNm	700
Stall current	А	13

## Hall sequence regards to back EMF



ATTENTION: Stall operation is not recommended, please do necessary protection to avoid irreparable damage. \*In case specific shaft, connector, or any other features need to be customized, please visit www.damoto.tech and contact us.