

## General Characteristics:

### Motor Configuration

Mechanical Structure

outrunner

Number of pole pairs	7	Speed constant	Vms/krpm	4.1
Number of phases	3	Torque constant	mN/A	45
Winding connection	star	Phase resistance	mOhm	630
Total weight	gram	DQ inductance	uH	140
Rotor inertia	uNm*s <sup>2</sup>	Friction	uN*m*s	0.5

### Thermal Data

Thermal resistance housing-ambient	4.8K/W
Thermal resistance winding-housing	7.1K/W
Ambient temperature	-40~100 °C
Max. winding temperature	120 °C

### Sensoric

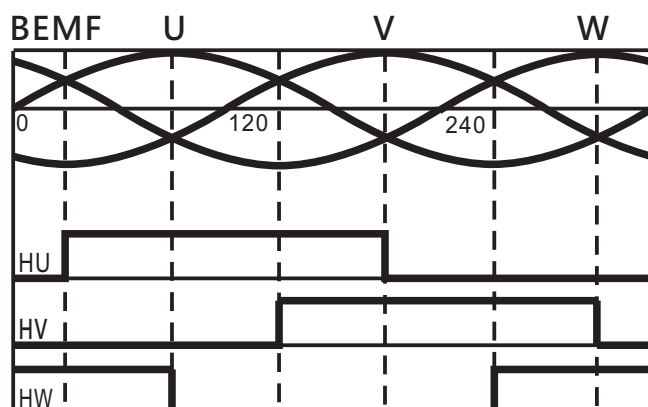
Sensor type	bipolar self-locking hall
Number of halls	3
Supply voltage	5V
Electrical angle	120 degrees

### Nominal & Stall

Nominal voltage	V	24
No load speed	rpm	4800
Noload current	mA	250
Nominal speed	rpm	3500
Nominal torque	mNm	160
Nominal current	A	3.4
Nominal power	W	58.6
Efficiency(Max./Nominal)	85% / 72%	
Stall torque	mNm	400
Stall current	A	9

### Hall sequence regards to back EMF:

Tested in CCW direction



Wire configuration (Left -Right):

HW 1	HV 2	HU 3	5V 4	GND 5	W 6,7,8	V 9,10,11	U 12,13,14
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Pull-up resistance 10k Ohm