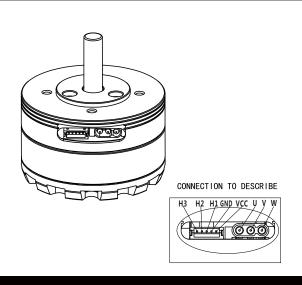
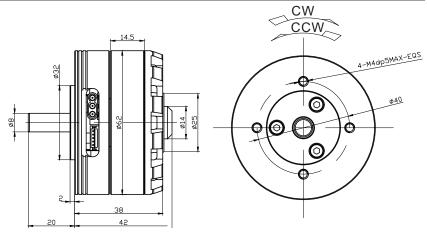
N/A







General Characteristics:

Stall torque

Stall current

Motor Configuration				
lechanical Structure outrunner				
Number of pole pairs		7	Speed constan	t Vms/krpm 7.6
Number of phases		3	Torque constar	nt mN/A 100
Winding connection		star	Phase resistan	ce mOhm 360
Total weight	gram	300	DQ inductance	mH 0.2
Rotor inertia	uNm*s²	8.2	Friction	uN*m*s 5.41
Thermal Data			Sensoric	
Thermal resistance housing-ambient	6.42K/W		Sensor type	bipolar self-locking hall
Thermal resistance winding-housing	3.84K/W		Number of halls 3	
Ambient temperature	-40~100 °C		Supply voltage	5V
Max. winding temperature	120 ° C		Electrical angle	e 120 degrees
Nominal & Stall			Hall sequen	ce regards to back EMF:
Nominal voltage	V	24	BEMF U	V W
No load speed	rpm	2500		
Noload current	mA	230		120 240
Nominal speed	rpm	2000		<u> </u>
Nominal torque	mNm	280	H1	
Nominal current	А	3	H2	
Nominal power	W	60	Н3	
Efficiency(Max./Nominal)	85%	/ 83%	This is tested in	n CCW direction

Ν

Α

1.4

14

Pull-up resistance