

All questions may be attempted but only marks obtained on the best **four** solutions will count.

The use of an electronic calculator is **not** permitted in this examination.

Symmetrisation and skew-symmetrisation:

$$T_{(ab)} := \frac{1}{2}(T_{ab} + T_{ba}), \quad T_{[ab]} := \frac{1}{2}(T_{ab} - T_{ba}). \quad (1)$$

Christoffel symbol:

$$\Gamma_{ab}^c = \frac{1}{2}g^{cd}(g_{da,b} + g_{bd,a} - g_{ab,d}). \quad (2)$$

Geodesics parameterised by λ :

$$\frac{d^2 X^a}{d\lambda^2} + \Gamma_{bc}^a \frac{dX^b}{d\lambda} \frac{dX^c}{d\lambda} = 0. \quad (3)$$

Riemann curvature tensor:

$$R_{mnr}{}^s = \Gamma_{mr,n}^s - \Gamma_{nr,m}^s + \Gamma_{mr}^a \Gamma_{an}^s - \Gamma_{nr}^a \Gamma_{am}^s, \quad (4)$$

$$R_{abcd} = -R_{bacd}, \quad R_{abcd} = -R_{abdc}, \quad R_{abcd} = R_{cdab} \\ R_{dabc} + R_{dcab} + R_{dbca} = 0. \quad (5)$$

Ricci tensor and Ricci scalar:

$$R_{mr} = R_{mnr}{}^n, \quad R = g^{mr} R_{mr}. \quad (6)$$

Schwarzschild-de Sitter line element:

$$ds^2 = - \left(1 - \frac{2m}{r} - \frac{\Lambda}{3} r^2 \right) dt^2 + \left(1 - \frac{2m}{r} - \frac{\Lambda}{3} r^2 \right)^{-1} dr^2 + r^2 (d\theta^2 + \sin^2 \theta d\phi^2). \quad (7)$$

1. (a) Describe how a contravariant vector V^a transforms under coordinate transformations between coordinates x^a and x'^a .
- (b) Describe how a covariant vector W_a transforms under coordinate transformations between coordinates x^a and x'^a .
- (c) Let $M^a{}_{bc}$ be a rank 3 tensor. Show that $M^a{}_{ac}$ transforms like a covariant vector under coordinate transformations.
- (d) Let \mathcal{M} be a N -dimensional manifold and let g_{ab} be a metric tensor. What is meant by g^{ab} ? Compute $g_{ab}g^{bc}$ and $g_{ab}g^{ab}$.
- (e) Consider a 3-dimensional manifold and the rank 3 tensor T_{abc} . How many independent components has T_{abc} in general? How many components has $T_{[abc]}$, a totally skew-symmetric tensor?
- (f) Let \mathcal{M} be a 4-dimensional manifold. Consider the rank 2 tensor T_{ab} . Show that the following is a valid equation

$$\text{tr } T g_{ab} + g_{ac} g_{bd} T^{cd} = T_{(ab)} + \frac{1}{8} g^{cd} g_{cd} T_{ab} + g^{cd} T_{(cd)} g_{ab} - \frac{1}{2} T_{ba}.$$

2. (a) Consider a 2-dimensional manifold \mathcal{M} with the following line element

$$ds^2 = dy^2 + z^4 dz^2.$$

For which values of y and z is this line element well defined?

- (b) Find the non-vanishing Christoffel symbols using Eq. (2).
- (c) Obtain the geodesic equations parametrised by λ , say.
- (d) Solve the geodesic equations and suggest an improved coordinate system. What is the metric in the new coordinates? What lines describe the geodesics geometrically?
- (e) What can you say about the Riemann curvature tensor, the Ricci tensor and the Ricci scalar of this manifold?

3. Let K_{abcd} be a rank 4 tensor with the following symmetry properties:

$$\begin{aligned} K_{abcd} + K_{bacd} &= 0, \\ K_{abcd} + K_{abdc} &= 0, \\ K_{dabc} + K_{dcab} + K_{dbca} &= 0. \end{aligned} \quad (*)$$

(a) Show that these three properties imply the following additional symmetry

$$K_{abcd} = K_{cdab}.$$

[Hint: Start by writing out (*) four times with permuted indices.]

Let \mathcal{L}_v be the Lie derivative with respect to the vector v^a . For $f \in C^\infty(\mathcal{M})$ it is defined by $\mathcal{L}_v f = v^a \nabla_a f$. Moreover,

$$\mathcal{L}_v w^a = v^b \nabla_b w^a - w^b \nabla_b v^a,$$

and it satisfies the Leibnitz rule.

(b) Show that $\mathcal{L}_v u_a = v^b \nabla_b u_a + u_b \nabla_a v^b$.

4. The most general static and spherically symmetric metric is given by

$$ds^2 = -a(r)dt^2 + b(r)dr^2 + r^2(d\theta^2 + \sin^2\theta d\phi^2),$$

and results in the following two Einstein tensor components

$$G_t^t = -\frac{b'(r)}{rb(r)^2} + \frac{1}{r^2b(r)} - \frac{1}{r^2}, \quad G_r^r = \frac{a'(r)}{ra(r)b(r)} + \frac{1}{r^2b(r)} - \frac{1}{r^2},$$

where the prime denotes differentiation with respect to r .

- (a) Solve the static and spherically symmetric field equations with cosmological term.
- (b) Discuss the importance of that solution when $\Lambda = 0$: Considering the limit $r \rightarrow \infty$, what does this metric describe?
- (c) Now set $m = 0$ (but $\Lambda \neq 0$) and consider the spatial part of the metric only

$$ds_{\text{spatial}}^2 = \frac{dr^2}{1 - (\Lambda/3)r^2} + r^2 d\Omega^2.$$

Suggest an improved coordinate system to remove the coordinate singularity at $r = \sqrt{3/\Lambda}$.

5. (a) Consider the Lagrangian $L = g_{ab}\dot{X}^a\dot{X}^b$ and show that the resulting Euler-Lagrange equations are the geodesic equations.
- (b) Consider the Schwarzschild-de Sitter line element (7) with $m = 0$ and derive the geodesic equations using the Lagrangian approach for massless and massive particles. You may assume $\theta = \pi/2$.
- (c) How many constants of motion has this system and what is their physical interpretation? Rewrite the Lagrangian using these constants and show that the geodesics can be described analogous to a 1-dimensional classical mechanical system

$$\dot{r}^2/2 + V_{\text{eff}}(r) = C,$$

where C is a constant. Find $V_{\text{eff}}(r)$. What is the meaning of C ?