## TDT4136 Assignment 2

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### Preface

#### Visualizer

We implemented the visualizer component from scratch using PyGame. This allowed the A\* algorithm to be performed in "real-time" and animated. Cell state color coding is found in Table 1:

State	Description	Color
STANDARD	Cell is unvisited by A*	Weighted grey <sup>1</sup>
BARRIER	Cell is not visitable by A*	Black
START	Cell is start cell	Red
GOAL	Cell is goal cell	Green
OPEN	Cell is in A* open set	Orange
CLOSED	Cell is in A* closed set	Blue
PATH	Cell is in A* shortest path from START to GOAL	Yellow

Table 1: Cell states.

#### Running the code

To run the code perform the following steps:

- 1. Set up a python3 environment
- 2. Unzip the provided zipfile containing the code
- 3. cd A-star-Visualizer
- 4. pip install -r requirements.txt
- 5. python main.py --cell\_size=n where n is the desired size of each grid cell in pixels. n is set to 16 by default if --cell\_size is not provided.

 $<sup>^{1}</sup>$ Darker shade means higher weight on cell

#### Using the application

When the pygame application has launched by running python main.py a blank map is initialized. Mouse/keyboard actions for the application are listed in Table 2 and 3 respectively. These actions can be performed on all maps. The application is fairly robust to changes during A\* search. For example can maps be changed during A\* search. Barriers can be drawn, but if they are drawn in already searched space, the algorithm does not recognize this. For optimal behaviour, draw/load a map and let the algorithm finish.

Mouse Button Press	Response
Left Mouse Button	Draws standard cell
Right Mouse Button	Draws barrier cell
Middle Mouse Button	Adds/removes start/goal cell

Table 2: Mouse button actions

Keyboard Press	Response
Space	Starts A* algorithm
1-5	Sets map to Assignment task 1-5
0	Sets map to blank 50x50 grid
r	Resets map to current task
р	Takes screenshot <sup>2</sup>
Esc	Quits application

Table 3: Keyboard actions

### A\* algorithm

The implemented A\* algorithm was inspired by pseudo-code found on Wikipedia https://en.wikipedia.org/wiki/A\*\_search\_algorithm.

 $<sup>^2</sup>$ When taking a screen shot, the folder <code>images</code> is created in the current working directory, and a .png is saved there.

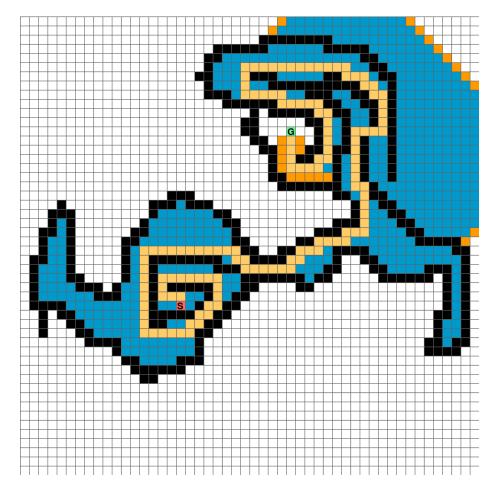


Figure 1: Example search from custom map

# 1 Part 1

## 1.1 Task 1

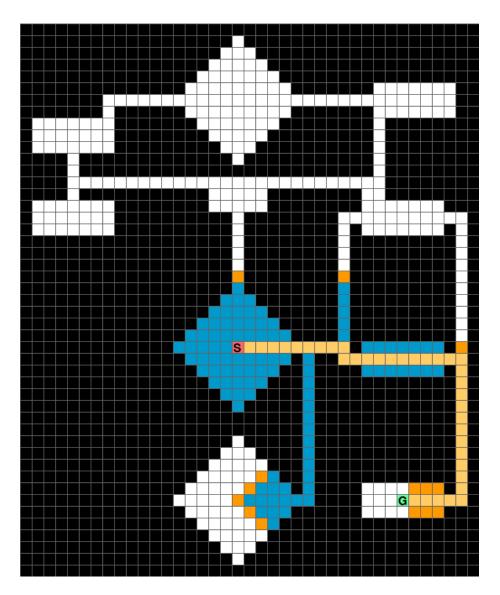


Figure 2: Task 1 visualized

## 1.2 Task 2

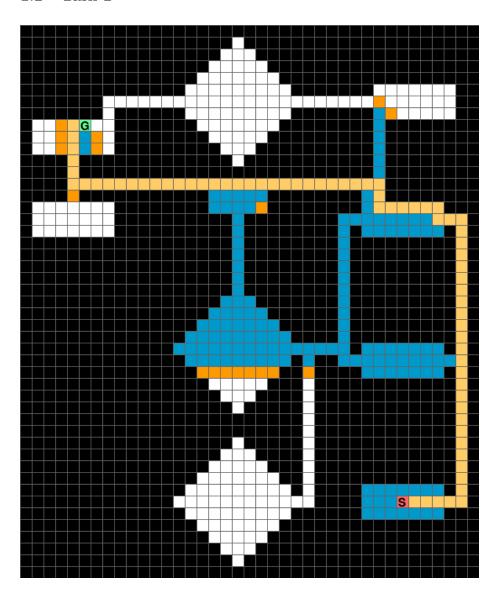


Figure 3: Task 2 visualized

# 2 Part 2

## 2.1 Task 3

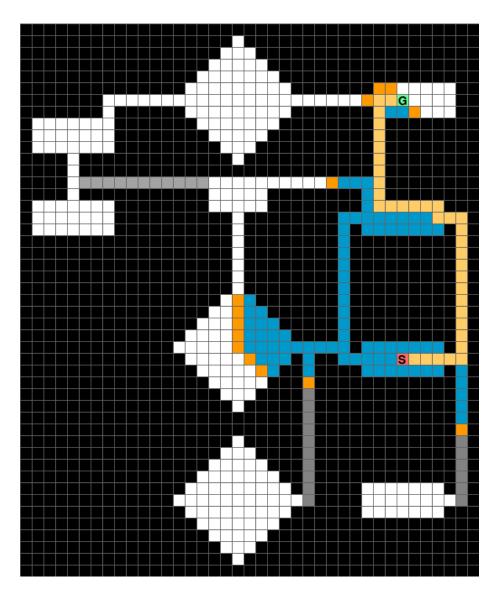


Figure 4: Task 3 visualized

## 2.2 Task 4

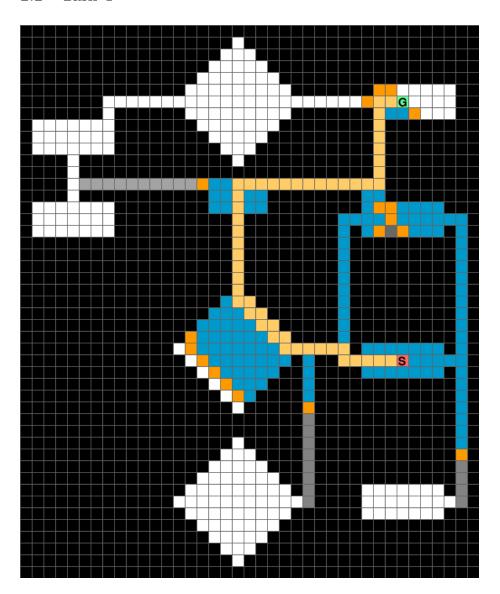


Figure 5: Task 4 visualized

# 3 Part 3

## $3.1 \quad Task5$

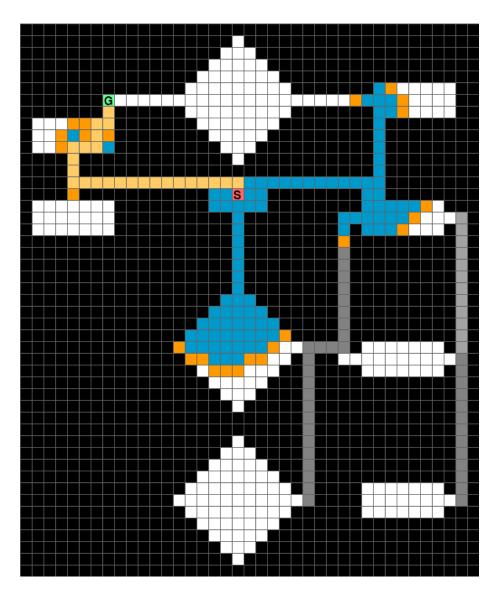


Figure 6: Task 5 visualized