Curso Inteligência Artificial: do Zero ao Infinito

Evaluation Metrics

Universidade Federal de Mato Grosso

Agenda

- Introduction
- 2 Localization
- Classification
- Precision x Recall
- Mean Average Precision

Introduction

In object detection, evaluation is non trivial, because there are two distinct tasks to measure:

- Determining the location of the object (localization, a regression task).
- Determining whether an object exists in the image (classification)

Fonte: Understanding the mAP Evaluation Metric for Object Detection

3 / 16

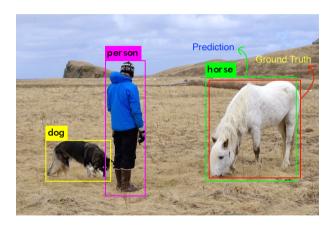
Frederico Oliveira (UFMT) Apresentação

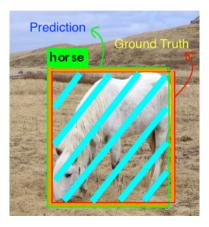
- In order to evaluate the model on the task of object **localization**, we must first determine how well the model predicted the location of the object.
- The localization task is typically evaluated on the Intersection over Union threshold (IoU).

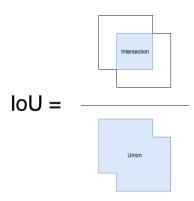
Fonte: Understanding the mAP Evaluation Metric for Object Detection

- Intersection over Union is a ratio between the intersection and the union of the predicted boxes and the ground truth boxes.
- To get the intersection and union values, we first overlay the prediction boxes over the ground truth boxes.
- Now for each class, the area overlapping the prediction box and ground truth box is the intersection area and the total area spanned is the union.

Fonte: Measuring Object Detection models ? mAP ? What is Mean Average Precision?







Classification mAP

- In a typical data set there will be many classes and their distribution is non-uniform.
- For example there might be many more dogs than cats.
- There is the need to associate a "confidence score" with each bounding box detected and to assess a level of confidence.

Fonte: Understanding the mAP Evaluation Metric for Object Detection

Classification mAP

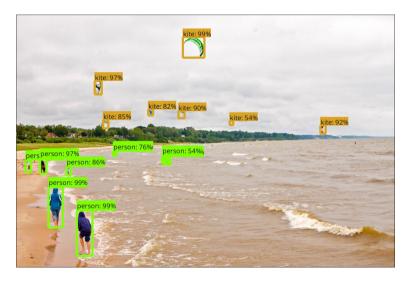
- In order to address these needs, the Average Precision (AP) was introduced.
- To understand the AP, it is necessary to understand the precision and recall of a classifier.

Fonte: Understanding the mAP Evaluation Metric for Object Detection

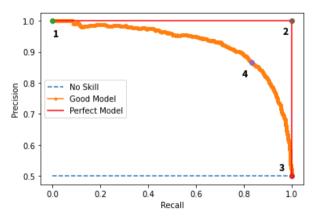
$$Precision = \frac{Actually \; Class \; 1 \cap Predicted \; Class \; 1}{Predicted \; Class \; 1} \; = \frac{True \; Positives}{True \; Positives \; + \; False \; Positives}$$

$$Recall = \frac{Actually \; Class \; 1 \; \cap \; Predicted \; Class \; 1}{Actually \; Class \; 1} = \frac{True \; Positives}{True \; Positives \; + \; False \; Negatives}$$

Fonte: Complete Guide to Understanding Precision and Recall Curves



Fonte: https://github.com/tensorflow/models/tree/master/research/object_detection#tensorflow-object-detection=api



Fonte: Complete Guide to Understanding Precision and Recall Curves

 The mean Average Precision or mAP score is calculated by taking the mean AP over all classes and/or over all IoU thresholds

Fonte: Complete Guide to Understanding Precision and Recall Curves

14 / 16

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Referencias

- Measuring Object Detection models ? mAP ? What is Mean Average Precision?
 https://towardsdatascience.com/
 - what-is-map-understanding-the-statistic-of-choice-for-comparing-object-dete
- Complete Guide to Understanding Precision and Recall Curves
 - https://analyticsindiamag.com/ complete-guide-to-understanding-precision-and-recall-curves/

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