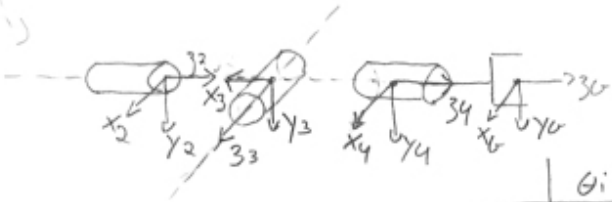


Punho esférico 3 DOF



P - 0 sigma
R - 1 sigma



	θ_i	a_i	α_i	d_i	σ_i	offset	
0-1	0°	0	-90°	d_1	0	0	z_1
1-2	0°	0	0	d_2	0	0	x_1
2-3	θ_3	0	90°	0	1	0°	z_3
3-4	θ_4	0	-90°	0	1	0°	x_3
4-5	θ_5	0	0	L_1	1	0°	z_4

• Robot 2

