





HW-2

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Convexity

1. Show, that $\mathbf{conv}\{xx^{\top}:x\in\mathbb{R}^n,\|x\|=1\}=\{A\in\mathbb{S}^n_+:\mathrm{tr}(A)=1\}.$ Solution: Let's check if $\mathrm{tr}(\theta_1x_1x_1^{\top}+\ldots+\theta_nx_nx_n^{\top})=1$, where $\sum_{i=1}^n\theta_i=1$

$$\operatorname{tr}(\theta_1 x_1 x_1^\top + \ldots + \theta_n x_n x_n^\top) = \theta_1 \operatorname{tr}(x_1 x_1^\top) + \ldots + \theta_n \operatorname{tr}(x_n x_n^\top) = \theta_1 \operatorname{tr}(x_1 x_1^\top) + \ldots + \theta_n \operatorname{tr}(x_n x_n^\top) = \theta_1 \operatorname{tr}(x_1 x_1^\top) + \ldots + \theta_n \operatorname{tr}(x_n x_n^\top) = \theta_1 \operatorname{tr}(x_1 x_1^\top) + \ldots + \theta_n \operatorname{tr}(x_n x_n^\top) = \theta_1 \operatorname{tr}(x_1 x_1^\top) + \ldots + \theta_n \operatorname{tr}(x_n x_n^\top) = \theta_1 \operatorname{tr}(x_1 x_1^\top) + \ldots + \theta_n \operatorname{tr}(x_n x_n^\top) = \theta_1 \operatorname{tr}(x_1 x_1^\top) + \ldots + \theta_n \operatorname{tr}(x_n x_n^\top) = \theta_1 \operatorname{tr}(x_1 x_1^\top) + \ldots + \theta_n \operatorname{tr}(x_n x_n^\top) = \theta_1 \operatorname{tr}(x_1 x_1^\top) + \ldots + \theta_n \operatorname{tr}(x_n x_n^\top) = \theta_1 \operatorname{tr}(x_1 x_1^\top) + \ldots + \theta_n \operatorname{tr}(x_n x_n^\top) = \theta_1 \operatorname{tr}(x_1 x_1^\top) + \ldots + \theta_n \operatorname{tr}(x_n x_n^\top) = \theta_1 \operatorname{tr}(x_1 x_1^\top) + \ldots + \theta_n \operatorname{tr}(x_n x_n^\top) = \theta_1 \operatorname{tr}(x_1 x_1^\top) + \ldots + \theta_n \operatorname{tr}(x_n x_n^\top) = \theta_1 \operatorname{tr}(x_1 x_1^\top) + \ldots + \theta_n \operatorname{tr}(x_n x_n^\top) = \theta_1 \operatorname{tr}(x_1 x_1^\top) + \ldots + \theta_n \operatorname{tr}(x_n x_n^\top) = \theta_1 \operatorname{tr}(x_1 x_1^\top) + \ldots + \theta_n \operatorname{tr}(x_n x_n^\top) = \theta_1 \operatorname{tr}(x_1 x_1^\top) + \ldots + \theta_n \operatorname{tr}(x_n x_n^\top) + \ldots + \theta_n \operatorname{tr}(x_n x_n^\top) = \theta_1 \operatorname{tr}(x_n x_n^\top) + \ldots + \theta_n \operatorname{tr}(x_n x_n$$

Note, that

$$\operatorname{tr}(xx^{\top}) = \operatorname{tr}(x^{\top}x) = \|x\|_2^2 = 1$$

So

$$=\theta_1+\ldots+\theta_n=1$$

Also we have to check if

$$\theta_1 x_1 x_1^{\top} + \ldots + \theta_n x_n x_n^{\top} \geqslant 0$$

If we show that $xx^\top\geqslant 0$ sum of positive semi-definite matrix

$$yxx^{\top}y = ||x^{\top}y||_{2}^{2} \geqslant 0$$

2. Prove that the set of $\{x\in\mathbb{R}^2\mid e^{x_1}\leq x_2\}$ is convex. **Solution**: If a set is convex then $\forall x,y\in S,\theta\in[0,1]$

$$z = \theta x + (1 - \theta)y \in S$$

We have to show that $e^{z_1} \leqslant z_2$

$$e^{z_1} = e^{\theta x_1 + (1-\theta)y_1} \leqslant \theta e^{x_1} + (1-\theta)e^{y_1} \leqslant \theta x_2 + (1-\theta)y_2 = z_2$$

Here we use that exp is a convex function.

3. Show that the set of directions of the non-strict local descending of the differentiable function in a point is a convex cone. **Solution**: The set we work with is

$$D = \{d \in \mathbb{R}^n | \nabla f(x)^\top d \leqslant 0\}$$

For proof that it is a convex set we have to show that linear hull lies in D and D is a cone

1. $\forall d_1, d_2 \in D, \theta_1, \theta_2 > 0$

$$\nabla f(x)^{\top}(\theta_1 d_1 + \theta_2 d_2) = \theta_1 \nabla f(x)^{\top} d_1 + \theta_2 \nabla f(x)^{\top} d_2 \leqslant 0$$

 $\mathbf{2}.\forall d\in D,\theta\in[0,1]$

$$\nabla f(x)^\top(\theta d) = \theta \nabla f(x)^\top d \leqslant 0$$







4. Is the following set convex

$$S = \left\{ a \in \mathbb{R}^k \mid p(0) = 1, |p(t)| \le 1 \text{ for } \alpha \le t \le \beta \right\},\,$$

where

$$p(t) = a_1 + a_2 t + \dots + a_k t^{k-1} ?$$

Solution: Let's $x, y \in S, \theta \in [0, 1]$ and $z = \theta x + (1 - \theta)y$.

$$p_x(t)=x_1+x_2t+\ldots+x_kt^{k-1}$$

$$p_{y}(t) = y_1 + y_2 t + \ldots + y_k t^{k-1}$$

$$\implies p_z(t) = \theta p_x(t) + (1-\theta) p_y(t)$$

Firstly let's check that $p_z(0) = 1$

$$p_z(0) = \theta p_x(0) + (1-\theta) p_y(0) = \theta + (1-\theta) = 1$$

Now lets check that $|p_z(t)| \leq 1$

$$|p_z(t)| = |\theta p_x(t) + (1-\theta)p_y(t)| \leqslant \theta |p_x(t)| + (1-\theta)|p_y(t)| \leqslant \theta + (1-\theta) = 1$$

5. Consider the function $f(x)=x^d$, where $x\in\mathbb{R}_+$. Fill the following table with \checkmark or X. Explain your answers

d	Convex	Concave	Strictly Convex	μ -strongly convex
$-2, x \in \mathbb{R}_{++}$	√	X	✓	X
$-2, x \in \mathbb{R}_{++}$ $-1, x \in \mathbb{R}_{++}$	\checkmark	X	\checkmark	X
0	\checkmark	\checkmark	X	X
0.5	X	\checkmark	X	X
1	\checkmark	\checkmark	X	X
$\in (1;2)$	\checkmark	Χ	\checkmark	X
2	\checkmark	Χ	\checkmark	\checkmark
> 2	\checkmark	Χ	X	X

Solution:

- To check for convexity it was used that $f''(x) \ge 0$
- To check for concavity it was used that $f''(x)\leqslant 0$
- To check for strict convexity it was used that $f^{\prime\prime}(x)>0$
- To check for strong convexity it was used that $f''(x) \geqslant \mu > 0$
- 6. Prove that the entropy function, defined as

$$f(x) = -\sum_{i=1}^n x_i \log(x_i),$$







with $\mathrm{dom}(f)=\{x\in\mathbb{R}^n_{++}:\sum_{i=1}^nx_i=1\}$, is strictly concave. **Solution**: Let's prove that g(x)=-f(x)is strictly convex:

$$g(\theta x + (1-\theta)y) = \sum_{i=1}^n (\theta x_i + (1-\theta)y_i) \log(\theta x_i + (1-\theta)y_i) < 0$$

Now let's prove that $x \log x$ is strictly convex:

$$\frac{\partial}{\partial x^2}(x\log x) = \frac{\partial}{\partial x}(\log x + 1) = \frac{1}{x} > 0$$

Now that we can finish the proof

$$<\theta \sum_{i=1}^n x_i \log x_i + (1-\theta) \sum_{i=1}^n y_i \log y_i = \theta g(x) + (1-\theta)g(y)$$

So if q is strictly convex then f is strictly concave.

7. Show, that the function $f: \mathbb{R}^n_{++} \to \mathbb{R}$ is convex if $f(x) = -\prod_{i=1}^n x_i^{\alpha_i}$ if $\mathbf{1}^T \alpha = 1, \alpha \succeq 0$.

Solution: Let's prove that g(x) = -f(x) is concave: if g is concave than

$$\frac{\theta g(x) + (1-\theta)g(y)}{g(\theta x + (1-\theta)y)} \leqslant 1$$

Now we can divide this in two parts:

$$\frac{g(x)}{g(\theta x+(1-\theta)y)} = \frac{\prod\limits_{i=1}^n x_i^{\alpha_i}}{\prod\limits_{i=1}^n (\theta x_i+(1-\theta)y_i)^{\alpha_i}} = \prod\limits_{i=1}^n \left(\frac{x_i}{\theta x_i+(1-\theta)y_i}\right)^{\alpha_i} \leqslant \sum\limits_{i=1}^n \frac{\alpha_i x_i}{\theta x_i+(1-\theta)y_i}$$

and

$$\frac{g(y)}{g(\theta x+(1-\theta)y)} = \frac{\prod\limits_{i=1}^n y_i^{\alpha_i}}{\prod\limits_{i=1}^n (\theta x_i+(1-\theta)y_i)^{\alpha_i}} = \prod\limits_{i=1}^n \left(\frac{y_i}{\theta x_i+(1-\theta)y_i}\right)^{\alpha_i} \leqslant \sum\limits_{i=1}^n \frac{\alpha_i y_i}{\theta x_i+(1-\theta)y_i}$$

Here we use AM-GM imequality.

So now we can return to first inequality:

$$\begin{split} \frac{\theta g(x) + (1-\theta)g(y)}{g(\theta x + (1-\theta)y)} \leqslant \theta \sum_{i=1}^n \frac{\alpha_i x_i}{\theta x_i + (1-\theta)y_i} + (1-\theta) \sum_{i=1}^n \frac{\alpha_i y_i}{\theta x_i + (1-\theta)y_i} = \\ = \sum_{i=1}^n \frac{\alpha_i (\theta x_i + (1-\theta)y_i)}{\theta x_i + (1-\theta)y_i} = \sum_{i=1}^n \alpha_i = 1 \end{split}$$

So if g is concave then f is convex.







8. Show that the maximum of a convex function f over the polyhedron $P = \operatorname{conv}\{v_1, \dots, v_k\}$ is achieved at one of its vertices, i.e.,

$$\sup_{x \in P} f(x) = \max_{i=1,\dots,k} f(v_i).$$

A stronger statement is: the maximum of a convex function over a closed bounded convex set is achieved at an extreme point, i.e., a point in the set that is not a convex combination of any other points in the set. (you do not have to prove it). Hint: Assume the statement is false, and use Jensen's inequality. Solution: Lets's assume that $\exists x \in P : f(x) \geqslant \max_{i=1,\dots,k} f(v_i)$

So using Jensen's inequality we have:

$$f(x) = f\left(\sum_{i=1}^k \theta_i v_i\right) \leqslant \sum_{i=1}^k \theta_i f(v_i) \leqslant \sum_{i=1}^k \theta_i f(x) = f(x)$$

It means that

$$\sum_{i=1}^k \theta_i f(v_i) = f(x)$$

But we can always find $v^* = \max_{i=1,\dots,k} f(v_i)$ and

$$f(x) = \sum_{i=1}^k \theta_i f(v_i) \leqslant f(v^*)$$

So the statement that x is a maximizer f is false and v^* truly maximizer.

9. Show, that the two definitions of μ -strongly convex functions are equivalent: f(x) is μ -strongly convex \iff for any $x_1, x_2 \in S$ and $0 \le \lambda \le 1$ for some $\mu > 0$:

$$f(\lambda x_1 + (1-\lambda)x_2) \leq \lambda f(x_1) + (1-\lambda)f(x_2) - \frac{\mu}{2}\lambda(1-\lambda)\|x_1 - x_2\|^2$$

f(x) is μ -strongly convex \iff if there exists $\mu>0$ such that the function $f(x)-\frac{\mu}{2}\|x\|^2$ is convex. **Solution**: Firstly, let's show that second statement leads to first. So we know that $f(x) - \frac{\mu}{2} ||x||^2$ is convex for some $\mu > 0$. We can use Jensen's inequality

$$f(\lambda x + (1 - \lambda)y) - \frac{\mu}{2} \|\lambda x + (1 - \lambda)y\|_{2}^{2} \leqslant \lambda f(x) - \lambda \frac{\mu}{2} \|x\|_{2}^{2} + (1 - \lambda)f(y) - (1 - \lambda)\frac{\mu}{2} \|y\|_{2}^{2} \iff f(\lambda x + (1 - \lambda)y) \leqslant \lambda f(x) + (1 - \lambda)f(y) - \frac{\mu}{2} (\lambda \|x\|_{2}^{2} + (1 - \lambda)\|y\|_{2}^{2} - \|\lambda x + (1 - \lambda)y\|_{2}^{2})$$

Now we need to show that

$$\lambda \|x\|_2^2 + (1-\lambda)\|y\|_2^2 - \|\lambda x + (1-\lambda)y\|_2^2 = \lambda (1-\lambda)\|x - y\|_2^2$$

Firstly expand all brackets and simplify left side:

$$\begin{split} \lambda \|x\|_2^2 + (1-\lambda)\|y\|_2^2 - \|\lambda x + (1-\lambda)y\|_2^2 &= \lambda \|x\|_2^2 + (1-\lambda)\|y\|_2^2 - \lambda^2 \|x\|_2^2 - (1-\lambda)^2 \|y\|_2^2 - \\ &- 2\lambda (1-\lambda)\langle x,y\rangle = \lambda (1-\lambda)\|x\|_2^2 + \lambda (1-\lambda)\|y\|_2^2 - 2\lambda (1-\lambda)\langle x,y\rangle \end{split}$$







Now expand all brackets and simplify right side:

$$\lambda(1-\lambda)\|x-y\|_2^2 = \lambda(1-\lambda)\|x\|_2^2 + \lambda(1-\lambda)\|y\|_2^2 - 2\lambda(1-\lambda)\langle x,y\rangle$$

And they match perfectly!

Secondly, let's prove that first statement leads to second. We know that

$$\begin{split} f(\lambda x + (1-\lambda)y) \leqslant \lambda f(x) + (1-\lambda)f(y) - \frac{\mu}{2}\lambda(1-\lambda)\|x - y\|^2 = \\ &= \lambda f(x) + (1-\lambda)f(y) - \frac{\mu}{2}\left(\lambda\|x\|_2^2 + (1-\lambda)\|y\|_2^2 - \|\lambda x + (1-\lambda)y\|_2^2\right) \iff \\ \iff f(\lambda x + (1-\lambda)y) - \frac{\mu}{2}\|\lambda x + (1-\lambda)y\|_2^2 \leqslant \lambda f(x) + (1-\lambda)f(y) - \frac{\mu}{2}\left(\lambda\|x\|_2^2 + (1-\lambda)\|y\|_2^2\right) \end{split}$$

And attentive reader can see that it's Jensen's inequality for function $f(x) - \frac{\mu}{2} ||x||_2^2$. It means that this function is convex for some $\mu > 0$.

Optimality conditions

1. Toy example

$$x^2+1 \to \min_{x \in \mathbb{R}}$$
 s.t. $(x-2)(x-4) \leq 0$

- 1. Give the feasible set, the optimal value, and the optimal solution.
- 2. Plot the objective $x^2 + 1$ versus x. On the same plot, show the feasible set, optimal point, and value, and plot the Lagrangian $L(x, \mu)$ versus x for a few positive values of μ . Verify the lower bound property $(p^* \ge \inf_x L(x, \mu)$ for $\mu \ge 0)$. Derive and sketch the Lagrange dual function g.
- 3. State the dual problem, and verify that it is a concave maximization problem. Find the dual optimal value and dual optimal solution μ^* . Does strong duality hold?
- 4. Let $p^*(u)$ denote the optimal value of the problem

$$x^2+1 \to \min_{x \in \mathbb{R}}$$
 s.t. $(x-2)(x-4) \le u$

as a function of the parameter u. Plot $p^*(u).$ Verify that $\frac{dp^*(0)}{du}=-\mu^*$

Solution:

- 1. $(x-2)(x-4)\leqslant 0 \iff x\in [2,4]$ the feasible set; $x^*=2, p^*=5$
- $2. \ L(x,\mu) = x^2 + 1 + \mu(x-2)(x-4) \ \nabla_x L(x,\mu) = 3x + 2\mu x 6\mu = 0 \implies \hat{x} = \frac{3\mu}{1+\mu} \implies \inf_x L(x,\mu) = \frac{-\mu^2 + 9\mu + 1}{1+\mu} \ 5 \geqslant \frac{-\mu^2 + 9\mu + 1}{1+\mu} \iff 5 + 5\mu \geqslant -\mu^2 + 9\mu + 1 \iff 0 \leqslant (\mu-2)^2 \text{- this is true.}$
- 3. $\frac{-\mu^2+9\mu+1}{1+\mu} \to \max_{\mu\geqslant 0} \implies \frac{\partial}{\partial\mu} = \frac{-\mu^2-2\mu+8}{(1+\mu)^2}, \\ \frac{\partial^2}{\partial\mu^2} = \frac{-18}{(1+\mu)^3} < 0 \text{ for } \mu\geqslant 0 \text{ it is a concave maximization problem} \implies \mu^* = 2 \text{ cause } \mu\geqslant 0 \implies d^* = \frac{-4+18+1}{1+2} = 5$

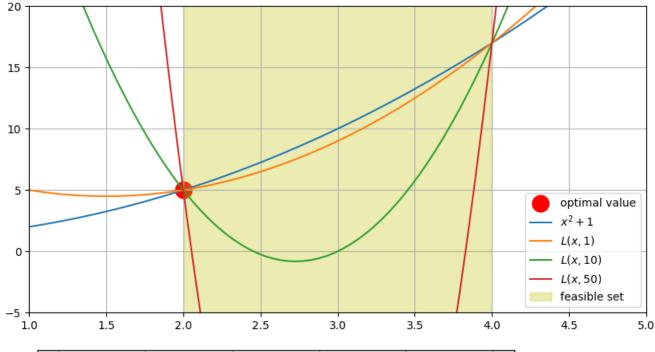


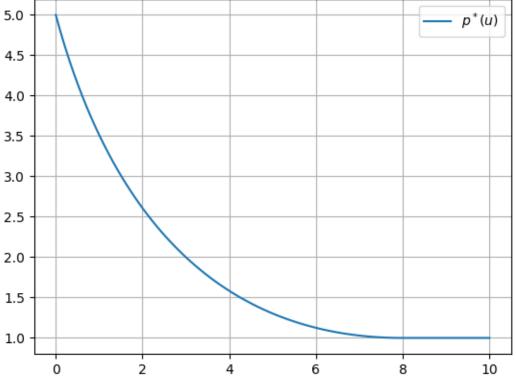




So we can see that strong duality holds.

$$\begin{split} 4. \ &(x-2)(x-4)\leqslant u \implies x^2-6x+8-u=0 \implies x_{1,2}=3\pm\sqrt{1+u} \\ &p^*(u)=f(3-\sqrt{1+u})[3-\sqrt{1-u}\geqslant 0]+f(0)[3-\sqrt{1-u}<0]=\\ &=f(3-\sqrt{1+u})[u\leqslant 8]+f(0)[u>8] \\ &\frac{\partial p^*(0)}{\partial u}=2\cdot(3-\sqrt{1+0})\cdot(-\frac{1}{2\sqrt{1+0}})=-2=-\mu^* \end{split}$$











2. Derive the dual problem for the Ridge regression problem with $A \in \mathbb{R}^{m \times n}, b \in \mathbb{R}^m, \lambda > 0$:

$$\begin{split} \frac{1}{2}\|y-b\|^2 + \frac{\lambda}{2}\|x\|^2 &\to \min_{x \in \mathbb{R}^n, y \in \mathbb{R}^m} \\ \text{s.t. } y &= Ax \end{split}$$

Solution:

$$\begin{split} L(x,y,\mu) &= \frac{1}{2}\|y-b\|^2 + \frac{\lambda}{2}\|x\|^2 + \mu^\top (y-Ax)\frac{\partial L}{\partial x} = \lambda x - A^\top \mu = 0 \implies x^* = \frac{1}{\lambda}A^\top \mu \\ &\frac{\partial L}{\partial y} = y - b + \mu = 0 \implies y^* = b - \mu \end{split}$$

So now we can check if x^* and y^* are the global minimizers:

$$\frac{\partial^2 L}{\partial x^2} = \lambda I > 0$$
$$\frac{\partial^2 L}{\partial y^2} = I > 0$$

3. Derive the dual problem for the support vector machine problem with $A \in \mathbb{R}^{m \times n}$, $\mathbf{1} \in \mathbb{R}^m \in \mathbb{R}^m$, $\lambda > 0$:

$$\begin{aligned} \langle \mathbf{1}, t \rangle + \frac{\lambda}{2} \|x\|^2 &\to \min_{x \in \mathbb{R}^n, t \in \mathbb{R}^m} \\ \text{s.t. } Ax \succeq \mathbf{1} - t \\ t \succeq 0 \end{aligned}$$

Solution:

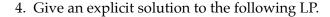
$$\begin{split} L(x,t,\mu_1,\mu_2) &= \langle \mathbf{1},t\rangle + \frac{\lambda}{2}\|x\|^2 - \mu_1^\top (Ax - \mathbf{1} + t) - \mu_2^\top t \\ \frac{\partial L}{\partial x} &= \lambda x - A^\top \mu_1 = 0, \quad \frac{\partial^2 L}{\partial x^2} = \lambda > 0 \implies x^* = \frac{1}{\lambda} A^\top \mu_1 \\ \frac{\partial L}{\partial t} &= 1 - \mu_1 - \mu_2 = 0 \implies \mu_2 = 1 - \mu_1 \in [0,1], \mu_1 \in [0,1] \implies t^* = 0 \text{ or } t^* = \mathbf{1} - Ax \\ t^* &= 0: \quad L(x^*,t^*,\mu_1,\mu_2) = \frac{\lambda}{2} \|x^*\|^2 - \mu_1^\top (Ax^* - \mathbf{1}) \end{split}$$

Another case has the same Lagrange value (pls belive me)

$$g(\mu_1) = \frac{\lambda}{2} \left\| \frac{1}{\lambda} A^\top \mu_1 \right\|^2 - \langle \mu_1, \frac{1}{\lambda} A A^\top \mu_1 - \mathbf{1} \rangle = -\frac{1}{2\lambda} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_1 \in [0,1]^m} \|A^\top \mu_1\|^2 + \langle \mu_1, \mathbf{1} \rangle \to \max_{\mu_$$







$$\begin{split} c^\top x &\to \min_{x \in \mathbb{R}^n} \\ \text{s.t. } 1^\top x &= 1, \\ x \succeq 0 \end{split}$$

This problem can be considered the simplest portfolio optimization problem. **Solution**:

$$\begin{split} L(x,\lambda,\mu) &= c^\top x - \lambda^\top x + \mu (\mathbf{1}^\top x - 1) \\ g(\mu) &= -\mu \to \max \quad \text{s.t.} \ c - \lambda + \mu \mathbf{1} = 0, \ \lambda \geqslant 0 \\ \mu &= \lambda_i - c_i \geqslant - \min_j c_j = \mu^* \\ p^* \geqslant d^* \implies x^* = (0 \dots \underbrace{1}_j \dots 0) \end{split}$$

5. Show, that the following problem has a unique solution and find it:

$$\langle C^{-1},X\rangle - \log \det X \to \min_{x\in \mathbb{R}^{n\times n}}$$
 s.t. $\langle Xa,a\rangle \leq 1,$

where $C \in \mathbb{S}^n_{++}$, $a \in \mathbb{R}^n \neq 0$. The answer should not involve inversion of the matrix C. Solution:

$$\begin{split} L(X,\lambda) &= \langle C^{-1}, X \rangle - \log \det X + \lambda (\langle Xa, a \rangle - 1) \\ \nabla_x L &= C^{-1} - X^{-1} + \lambda a a^\top = 0 \\ \nabla_y L &= \langle Xa, a \rangle - 1 = 0 \end{split}$$

So now we can use Sherman-Morrison equality:

$$C = (X^{-1} - \lambda aa^{\top})^{-1} = X + \frac{\lambda X aa^{\top} X}{1 - \lambda}$$

$$a^{\top} C a = a^{\top} X a + \frac{\lambda}{1 - \lambda} a^{\top} X aa^{\top} X a = \frac{1}{1 - \lambda} \implies \lambda^* = 1 - \frac{1}{a^{\top} C a}$$

$$X = (C^{-1} + \lambda aa^{\top})^{-1} = C \left(I - \frac{aa^{\top} C - \frac{aa^{\top} C}{a^{\top} C a}}{a^{\top} C a} \right)$$

Notice that if $\lambda = 1$ then C is singular but, as you can see, $\lambda^* \neq 1$.

6. Give an explicit solution to the following QP.

$$\begin{split} c^\top x &\to \min_{x \in \mathbb{R}^n} \\ \text{s.t. } (x-x_c)^\top A(x-x_c) &\leq 1, \end{split}$$

where $A \in \mathbb{S}^n_{++}, c \neq 0, x_c \in \mathbb{R}^n$ Solution:

$$\begin{split} L(x,\lambda) &= c^\top x + \lambda ((x-x_c)^\top A(x-x_c) - 1) \\ \nabla_x L &= c + 2\lambda A(x-x_c) = 0 \implies x = x_c - \frac{A^{-1}c}{2\lambda} \end{split}$$





$$\begin{split} \nabla_{\lambda}L &= (x-x_c)^{\intercal}A(x-x_c) - 1 = 0\\ \left(x_c - \frac{A^{-1}c}{2\lambda} - x_c\right)^{\intercal}A\left(x_c - \frac{A^{-1}c}{2\lambda} - x_c\right) &= \frac{1}{4\lambda^2}c^{\intercal}A^{-1}c = 1 \implies \lambda^* = \frac{1}{2}\sqrt{c^{\intercal}A^{-1}c}\\ x^* &= x_c - \frac{A^{-1}c}{\sqrt{c^{\intercal}A^{-1}c}} \end{split}$$

7. Consider the equality-constrained least-squares problem

$$\|Ax-b\|_2^2 \to \min_{x \in \mathbb{R}^n}$$
 s.t. $Cx = d$,

where $A \in \mathbb{R}^{m \times n}$ with $\mathbf{rank}A = n$, and $C \in \mathbb{R}^{k \times n}$ with $\mathbf{rank}C = k$. Give the KKT conditions, and derive expressions for the primal solution x^* and the dual solution λ^* . **Solution**:

$$L(x,\lambda) = \|Ax - b\|_2^2 + \lambda^\top (Cx - d)$$

The KKT conditions are

$$\begin{split} \nabla_x L &= 2A^\top (Ax - b) + C^\top \lambda = 0 \\ \nabla_\lambda L &= Cx - d = 0 \end{split}$$

These conditions satisfy the Slater's condition.

$$\begin{split} x &= \frac{1}{2} (A^\top A)^{-1} (2A^\top b - C^\top \lambda) \\ Cx - d &= C \frac{1}{2} (A^\top A)^{-1} (2A^\top b - C^\top \lambda) - d = C (A^\top A)^{-1} A^\top b - \frac{1}{2} C (A^\top A)^{-1} C^\top \lambda - d = 0 \\ \lambda^* &= 2 (C (A^\top A)^{-1} C^\top)^{-1} (C (A^\top A)^{-1} A^\top b - d) \\ x^* &= (A^\top A)^{-1} A^\top b - (A^\top A)^{-1} C^\top (C (A^\top A)^{-1} C^\top)^{-1} (C (A^\top A)^{-1} A^\top b - d) \end{split}$$

8. Derive the KKT conditions for the problem

$$\operatorname{tr} X - \log \det X \to \min_{X \in \mathbb{S}^n_{++}}$$
 s.t. $Xs = y$,

where $y \in \mathbb{R}^n$ and $s \in \mathbb{R}^n$ are given with $y^{\top}s = 1$. Verify that the optimal solution is given by

$$X^* = I + yy^\top - \frac{1}{s^\top s} ss^\top$$

Solution:

$$L(x,\lambda) = \operatorname{tr} X - \log \det X + \lambda^\top (Xs - y)$$

The KKT conditions are

$$\nabla_x L = I - X^{-1} + \lambda s^{\top} = 0$$
$$\nabla_{\lambda} L = Xs - y = 0$$

So we have

$$X = (I + \lambda s^\top)^{-1} \implies Xs = (I + \lambda s^\top)^{-1}s = y \implies \lambda = s - y$$







$$X = (I + \lambda s^\top)^{-1} = I - \frac{\lambda s^\top}{1 + s^\top \lambda} = I + \frac{y s^\top}{s^\top s} - \frac{s s^\top}{s^\top s}$$

Our answer is close to the given optimal solution, so we have to prove that $y=\frac{s}{s^{\top}s}$

$$y = \frac{s}{s^{\top}s} \iff s = s^{\top}sy \iff s^{\top}s = s^{\top}\underbrace{s}_{\in\mathbb{R}}^{\top}y = s^{\top}s\underbrace{s}_{=1}^{\top}y = s^{\top}s$$

So our answer perfectly matches with the given one.

9. Supporting hyperplane interpretation of KKT conditions. Consider a convex problem with no equality constraints

$$f_0(x) \to \min_{x \in \mathbb{R}^n}$$
 s.t. $f_i(x) \leq 0, \quad i = [1, m]$

Assume, that $\exists x^* \in \mathbb{R}^n, \mu^* \in \mathbb{R}^m$ satisfy the KKT conditions

$$\begin{split} &\nabla_x L(x^*,\mu^*) = \nabla f_0(x^*) + \sum_{i=1}^m \mu_i^* \nabla f_i(x^*) = 0 \\ &\mu_i^* \geq 0, \quad i = [1,m] \\ &\mu_i^* f_i(x^*) = 0, \quad i = [1,m] \\ &f_i(x^*) \leq 0, \quad i = [1,m] \end{split}$$

Show that

$$\nabla f_0(x^*)^\top (x - x^*) \ge 0$$

for all feasible x. In other words, the KKT conditions imply the simple optimality criterion or $\nabla f_0(x^*)$ defines a supporting hyperplane to the feasible set at x^* . **Solution**: If conditions inactive this means that $\mu = 0$ and this leads to $\nabla f_i = 0$. So

$$\nabla f_0(x^*)^{\top}(x-x^*) = 0(x-x^*) = 0 \geqslant 0$$

Else we can find at least one active condition $\implies f_i(x^*) = 0$. Now we have 2 cases:

1) If feasible x for $f_i(x)$ greater that x^* then $f_0(x) < f_0(x^*)$. In this case $\nabla f_0(x^*) \geqslant 0$ and finally

$$f_0(x^*)^\top(x-x^*)\geqslant 0$$

2) If feasible x for $f_i(x)$ less that x^* then $f_0(x) > f_0(x^*)$. In this case $\nabla f_0(x^*) \leq 0$ and finally

$$f_0(x^*)^\top(x-x^*)\geqslant 0$$

10. A penalty method for equality constraints. We consider the problem of minimization

$$f_0(x) \to \min_{x \in \mathbb{R}^n}$$
 s.t. $Ax = b$,

where $f_0(x): \mathbb{R}^n \to \mathbb{R}$ is convex and differentiable, and $A \in \mathbb{R}^{m \times n}$ with $\mathbf{rank} A = m$. In a quadratic penalty method, we form an auxiliary function

$$\phi(x) = f_0(x) + \alpha \|Ax - b\|_2^2,$$







where $\alpha>0$ is a parameter. This auxiliary function consists of the objective plus the penalty term $\alpha\|Ax-b\|_2^2$. The idea is that a minimizer of the auxiliary function, \tilde{x} , should be an approximate solution to the original problem. Intuition suggests that the larger the penalty weight α , the better the approximation \tilde{x} to a solution of the original problem. Suppose \tilde{x} is a minimizer of $\phi(x)$. Show how to find, from \tilde{x} , a dual feasible point for the original problem. Find the corresponding lower bound on the optimal value of the original problem. Solution: First things first let's find optimal α^*

$$\begin{split} \nabla_x \phi(\tilde{x}) &= \nabla_x f_0(\tilde{x}) + 2\alpha A^\top (A\tilde{x} - b) = 0 \\ 2\alpha A^\top (A\tilde{x} - b) &= -\nabla_x f_0(\tilde{x}) \\ 2\alpha (A^\top (A\tilde{x} - b))^\top A^\top (A\tilde{x} - b) &= -(A^\top (A\tilde{x} - b))^\top \nabla_x f_0(\tilde{x}) \\ \alpha &= -\frac{1}{2} \Big((A^\top (A\tilde{x} - b))^\top A^\top (A\tilde{x} - b) \Big)^{-1} (A^\top (A\tilde{x} - b))^\top \nabla_x f_0(\tilde{x}) \end{split}$$

We can't say anything about right part but $\alpha > 0$, so let's

$$\alpha^* = \max\left(\varepsilon, -\frac{1}{2}\Big((A^\top(A\tilde{x}-b))^\top A^\top(A\tilde{x}-b)\Big)^{-1}(A^\top(A\tilde{x}-b))^\top \nabla_x f_0(\tilde{x})\right)$$

Now about lower bound: we know that

$$\begin{split} f_0(x) \geqslant \inf L(x,\lambda) \\ L(x,\lambda) &= f_0(x) + \lambda^\top (Ax - b) \\ \nabla_x L &= \nabla_x f_0(x) + A^\top \lambda = 0 \\ A \nabla_x f_0(x) &= -AA^\top \lambda \\ \lambda &= -(AA^\top)^{-1} A \nabla_x f_0(x) = 2\alpha^* (AA^\top)^{-1} A A^\top (A\tilde{x} - b) = 2\alpha^* (A\tilde{x} - b) \end{split}$$

And finally

$$f_0(x) \geqslant L(\tilde{x}, \lambda^*) = f_0(\tilde{x}) + 2\alpha^* (A\tilde{x} - b)^{\top} (A\tilde{x} - b) = f_0(\tilde{x}) + 2\alpha^* ||A\tilde{x} - b||^2$$