Checking the equivalence of context-free session types

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Motivation

```
1 data Tree = Leaf | Node Int Tree Tree
1 sendTree Leaf c =
2 select Leaf c
3 sendTree (Node x | r) c =
4 let c1 = select Node c
5 c2 = send x c1
6 c3 = sendTree | c2
7 c4 = sendTree r c3
8 in c4
```



Plan

Definition (Type equivalence problem)

Given any context-free session types S and T, the type equivalence problem consists in deciding if types S and T are equivalent, i.e., $S \sim T$.

- Implement an algorithm that decides the *type equivalence problem*.
- Prove its soundness and completeness w.r.t. the metatheory of context-free session types proposed by Thiemann and Vasconcelos.
- Provide results on complexity.

Algorithm for checking the equivalence of CFST Main stages

Convert types to a grammar

Translates types into a (finite) set of productions

Prune unnormed productions

Streamlines the grammar by pruning unnormed productions

Simplify and expand

Alternates between simplification and expansion operations, until reaching a successful branch in the expansion tree or concluding that all branches are unsuccessful

We consider a finite set of productions $X \to a \vec{Y}$ where:

- *X*, *Y* represent *non-terminal symbols*
- a is a terminal symbol (a label in the labelled transition system)



Context-free session types are seen as *simple grammars*:

- context-free grammars in Greibach normal form
- s.t. for each X and a there is at most one production $X \to a\widetilde{Y}$

Example

```
S \triangleq (\mu x. \& \{n: x; x; ? \text{ int}, \ell: ? \text{ int}\}); (\mu z.! \text{ int}; z; z)
T \triangleq (\mu y. \& \{n: y; y, \ell: \text{skip}\}; ? \text{ int}); (\mu z.! \text{ int}; z)
```



Example

$$S \triangleq (\mu x. \& \{n: x; x; ? \text{ int}, \ell: ? \text{ int}\}); (\mu z.! \text{ int}; z; z)$$

$$T \triangleq (\mu y. \& \{n: y; y, \ell: \text{ skip}\}; ? \text{ int}); (\mu z.! \text{ int}; z)$$

Type to grammar
.
Prune unnormed productions
<u> </u>
Simplify and expand

Productions for S	Productions for T
$X_1 ightarrow \&n X_1 X_1 X_2 \ X_1 ightarrow \&\ell X_3 \ X_2 ightarrow ? ext{int} \ X_3 ightarrow ? ext{int} \ X_4 ightarrow ! ext{int} X_4 X_4$	$Y_1 ightarrow \&n Y_1 Y_1 Y_2$ $Y_1 ightarrow \&\ell Y_2$ $Y_2 ightarrow ?int$ $Y_3 ightarrow !int Y_3$
$\wedge_4 \rightarrow : \text{IIIL} \wedge_4 \wedge_4$	

Example

$$S \triangleq (\mu x. \& \{n: x; x; ? \text{ int}, \ell: ? \text{ int}\}); (\mu z.! \text{ int}; z; z)$$

$$T \triangleq (\mu y. \& \{n: y; y, \ell: \text{ skip}\}; ? \text{ int}); (\mu z.! \text{ int}; z)$$

Type to grammar
Prune unnormed productions
Simplify and expand

Productions for S	Productions for T
$X \rightarrow !() X_1 X_4$	$Y \rightarrow !() Y_1 Y_3$
$X_1 ightarrow \&n X_1 X_1 X_2$	$Y_1 ightarrow \&n Y_1 Y_1 Y_2$
$X_1 \rightarrow \& \ell X_3$	$Y_1 ightarrow \& \ell \ Y_2$
$X_2 \rightarrow ?int$	$Y_2 \rightarrow ?int$
$X_3 \rightarrow ? int$	$Y_3 \rightarrow ! int\ Y_3$
$X_4 \rightarrow ! int X_4 X_4$	

Algorithm for checking the equivalence of CFST Main stages

Convert types to a grammar

LOHaskellCode \sim 100

Soundness <

- 1. Conversion of types into BPAs is sound^a.
- 2. Conversion of BPAs to Greibach Normal Form without altering the solution is sound^b

Prune unnormed productions

Simplify and expand

^aThiemann and Vasconcelos. Context-free session types. 2016.

^bBaeten et al. Decidability of bisimulation equivalence for process generating context-free languages. 1993.

Prune unnormed productions

Definition ((Un)normed symbols¹)

A sequence of symbols α is normed if there is a path $\alpha \to \cdots \to \varepsilon$. Otherwise, α is said to be unnormed.

Christensen, Huttel, and Stirling¹ noted that: whenever α is unnormed, $\alpha \sim \alpha \beta$.



¹ Christensen et al. Bisimulation equivalence is decidable for all CF processes. 1995

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Example

$$S \triangleq (\mu x. \& \{n: x; x; ? \text{ int}, \ell: ? \text{ int}\}); (\mu z.! \text{ int}; z; z)$$

Productions for *S*

$$X_1
ightarrow \&n X_1 X_1 X_2$$

$$X_1 \rightarrow \& \ell X_3$$

$$X_2 \rightarrow ?int$$

$$X_3 \rightarrow ?int$$

$$X_4 \rightarrow ! int X_4 X_4$$

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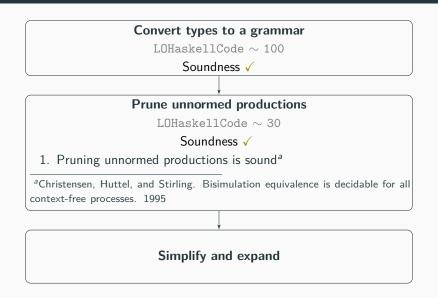
Example

 $S \triangleq (\mu x. \& \{n: x; x; ? \text{ int}, \ell: ? \text{ int}\}); (\mu z.! \text{ int}; z; z)$

Productions for S	Productions for <i>pruned S</i>		
$X_1 \rightarrow \&n X_1 X_1 X_2$	$X_1 ightarrow \&n X_1 X_1 X_2$		
$X_1 ightarrow \& \ell X_3$	$X_1 o \&\ellX_3$		
$X_2 o $?int	$X_2 ightarrow ?$ int		
$X_3 o ?$ int	$X_3 ightarrow ?$ int		
$X_4 ightarrow ! int X_4 X_4$	$X_4 ightarrow ! ext{int } X_4$		

¹ Christensen et al. Bisimulation equivalence is decidable for all CF processes. 1995

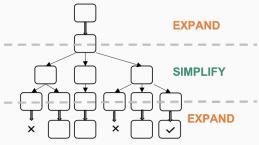
Algorithm for checking the equivalence of CFST Main stages



Following the ideas from Hirshfeld, Jančar, Moller, a bisimulation is seen as an **expansion tree**²³ that alternates between:

- expansion operations
- simplification operations





²Hirshfeld. Bisimulation trees and the decidability of weak bisimulations. 1997

³Jančar and Moller. Techniques for decidability and undecidability of bisimilarity. 1999

An expansion tree alternates between:

 expansion operations - a single derived node results from the expansion of the parent node.

⁴Jančar, Moller. Techniques for decidability and undecidability of bisimilarity. 1999 ⁵Christensen et al. Bisimulation equivalence is decidable for all CF processes. 1995

An expansion tree alternates between:

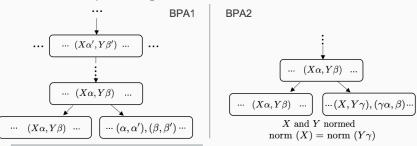
- expansion operations a single derived node results from the expansion of the parent node.
- simplification operations
 - reflexive rule: omit from a node N any reflexive pair.
 - **congruence rule**: omit from a node *N* any pair that belongs to the least congruence containing the ancestors of *N*.

⁴ Jančar, Moller. Techniques for decidability and undecidability of bisimilarity. 1999

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- expansion operations a single derived node results from the expansion of the parent node.
- simplification operations
 - reflexive rule: omit from a node N any reflexive pair.
 - **congruence rule**: omit from a node *N* any pair that belongs to the least congruence containing the ancestors of *N*.
 - basic process algebra rules⁴⁵



⁴Jančar, Moller. Techniques for decidability and undecidability of bisimilarity. 1999 ⁵Christensen et al. Bisimulation equivalence is decidable for all CF processes. 1995

All these transformation rules preserve the *safeness property*:

Safeness property⁵

 $S \sim T$ iff the expansion tree rooted at $\{(S, T)\}$ has a successful branch.

The finite witness property holds⁵:

Finite witness property⁵⁶

If $S \sim T$, then there exists a **finite successful branch** in the expansion tree.

 $^{^6\}mathrm{Christensen}$ et al. Bisimulation equivalence is decidable for all CF processes. 1995

Example

$$\triangleq (\mu x. \& \{n: x; x; ? \text{ int}, \ell: ? \text{ int} \}); (\mu z.! \text{ int}; z; z)$$

$$\triangleq (\mu y. \& \{n: y; y, \ell: \text{ skip} \}; ? \text{ int}); (\mu z.! \text{ int}; z)$$

 (X_1X_4,Y_1Y_3)

Productions for pruned S

 $X_1 \rightarrow \&n X_1 X_1 X_2$ $X_1 \rightarrow \&\ell X_3$ $X_2 \rightarrow ?int$ $X_3 \rightarrow ?int$ $X_4 \rightarrow !int X_4$

Productions for T

$$Y_1 \rightarrow \&n Y_1 Y_1 Y_2$$

 $Y_1 \rightarrow \&\ell Y_2$
 $Y_2 \rightarrow ?int$
 $Y_3 \rightarrow !int Y_3$

Example
$$S \triangleq (\mu x. \& \{n: x; x; ? \text{ int}, \ell: ? \text{ int}\}); (\mu z.! \text{ int}; z; z)$$
$$T \triangleq (\mu y. \& \{n: y; y, \ell: \text{skip}\}; ? \text{ int}); (\mu z.! \text{ int}; z)$$

Productions for T

 $X_A \rightarrow ! int X_A$

$$Y_1 \rightarrow \&n Y_1 Y_1 Y_2$$

 $Y_1 \rightarrow \&\ell Y_2$
 $Y_2 \rightarrow ?int$
 $Y_3 \rightarrow !int Y_3$

Example $S \triangleq (\mu x. \& \{n: x; x; ? \text{ int}, \ell: ? \text{ int}\}); (\mu z.! \text{ int}; z; z)$ $T \triangleq (\mu y. \& \{n: y; y, \ell: \text{skip}\}; ? \text{ int}); (\mu z.! \text{ int}; z)$

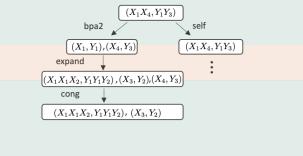


Productions for T

$$Y_1 \rightarrow \&n Y_1 Y_1 Y_2$$

 $Y_1 \rightarrow \&\ell Y_2$
 $Y_2 \rightarrow ?int$
 $Y_3 \rightarrow !int Y_3$

Example $S \triangleq (\mu x. \& \{n: x; x; ? \text{int}, \ell: ? \text{int}\}); (\mu z.! \text{int}; z; z)$ $T \triangleq (\mu y. \& \{n: y; y, \ell: \text{skip}\}; ? \text{int}); (\mu z.! \text{int}; z)$



Productions for <i>pruned S</i>
$X_1 ightarrow \&n X_1 X_1 X_2$
$X_1 \rightarrow \& \ell X_3$
$X_2 \rightarrow ?int$
$X_3 \rightarrow ?int$
$X_4 \rightarrow ! int X_4$

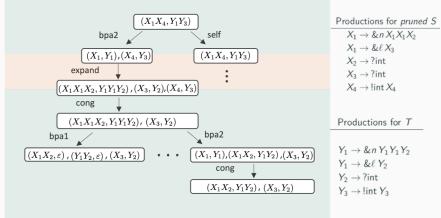
Productions for T

$$Y_1 \rightarrow \&n Y_1 Y_1 Y_2$$

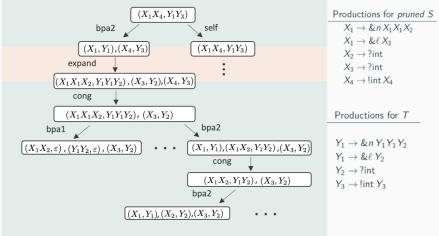
 $Y_1 \rightarrow \&\ell Y_2$
 $Y_2 \rightarrow ?int$
 $Y_3 \rightarrow !int Y_3$

$\triangleq (\mu x. \& \{n: x; x; ? \text{ int}, \ell: ? \text{ int}\}); (\mu z.! \text{ int}; z; z)$ $\triangleq (\mu y. \& \{n: y; y, \ell: \text{skip}\}; ? \text{int}); (\mu z.! \text{ int}; z)$ Example (X_1X_4, Y_1Y_3) Productions for pruned S $X_1 \rightarrow \&n X_1 X_1 X_2$ bpa2 self $X_1 \rightarrow \& \ell X_3$ $(X_1,Y_1),(X_4,Y_3)$ (X_1X_4, Y_1Y_3) $X_2 \rightarrow ?int$ expand $X_3 \rightarrow ?int$ $X_A \rightarrow ! int X_A$ $|(X_1X_1X_2, Y_1Y_1Y_2), (X_3, Y_2), (X_4, Y_3)|$ cong $(X_1X_1X_2, Y_1Y_1Y_2), (X_3, Y_2)$ Productions for T bpa2 bpa1 $Y_1 \rightarrow \&n Y_1 Y_1 Y_2$ $(X_1, Y_1), (X_1X_2, Y_1Y_2), (X_3, Y_2)$ $[(X_1X_2,arepsilon)$, $(Y_1Y_2,arepsilon)$, (X_3,Y_2) $Y_1 \rightarrow \& \ell Y_2$ $Y_2 \rightarrow ?int$ $Y_3 \rightarrow ! int Y_3$

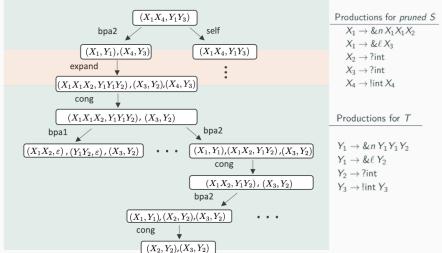
Example $S \triangleq (\mu x. \& \{n: x; x; ? \text{int}, \ell: ? \text{int}\}); (\mu z.! \text{int}; z; z)$ $T \triangleq (\mu y. \& \{n: y; y, \ell: \text{skip}\}; ? \text{int}); (\mu z.! \text{int}; z)$



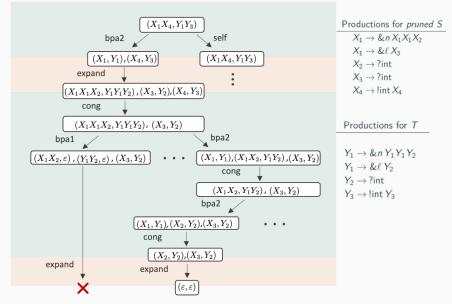
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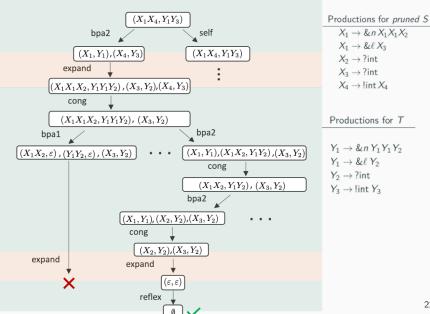
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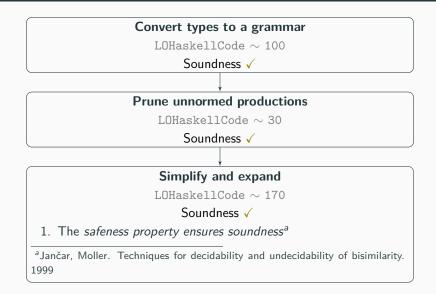
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$\triangleq (\mu x. \& \{n: x; x; ? \text{ int}, \ell: ? \text{ int}\}); (\mu z.! \text{ int}; z; z)$ $\triangleq (\mu y. \& \{n: y; y, \ell: skip\}; ? int); (\mu z.! int; z)$ Example



Algorithm for checking the equivalence of CFST Main stages



Implementation strategies

Implementation choice:

Breadth-first search on the tree

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Strategic options that can enhance performance:

- Instead of looking for a fixed point, iterate the simplification phase
- Apply BPA rules wrapped with blocks of reflexive and congruence rules

Implementation strategies

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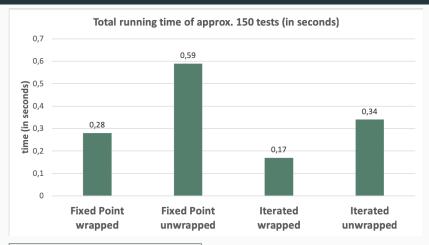
Strategic options that can enhance performance:

- Instead of looking for a fixed point, iterate the simplification phase
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We showcase runtimes for four scenarios:

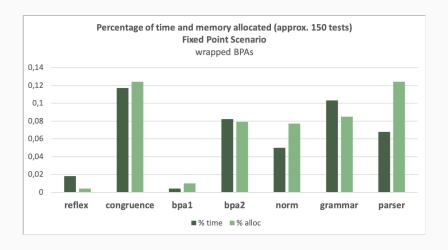
	Fixed Point Scenario		Iterated Scenario	
	wrapped	unwrapped	wrapped	unwrapped
Simplification	find fixed point		iterate	
BPAs wrapped	✓	×	✓	×

Running times (~ 150 tests)





Time and memory allocated



Towards completeness...

Finite witness property⁷⁸

If $S \sim T$, then there exists a **finite successful branch** in the expansion tree.

Implementation choices aiming to achieve completeness:

- Instead of looking for a fixed point, iterate the simplification phase (there may not be a fixed point)
- Use double ended enqueue, prepending promising nodes, as opposed to queuing all new nodes

 $^{^7\}mathrm{Christensen}$ et al. Bisimulation equivalence is decidable for all CF processes. 1995

 $^{^8\}mathrm{Jan}\check{\mathrm{car}},\ \mathrm{Moller}.\ \mathrm{Techniques}\ \mathrm{for}\ \mathrm{decidability}\ \mathrm{and}\ \mathrm{undecidability}\ \mathrm{of}\ \mathrm{bisimilarity}.\ 1999$

Ongoing Work

- Soundness ✓
- Completeness? ... on our way to achieve it.
- Complexity? ... in practice it does not seem to take much longer than parsing.
- Lines of Haskell code: approx. 300

Coming soon:

FreeST, a compiler for context-free session types! $({\tt demos\ on\ demand})$

Thank you!