# Filesystem Optimization and Examples

Module 17

## **Space Management**

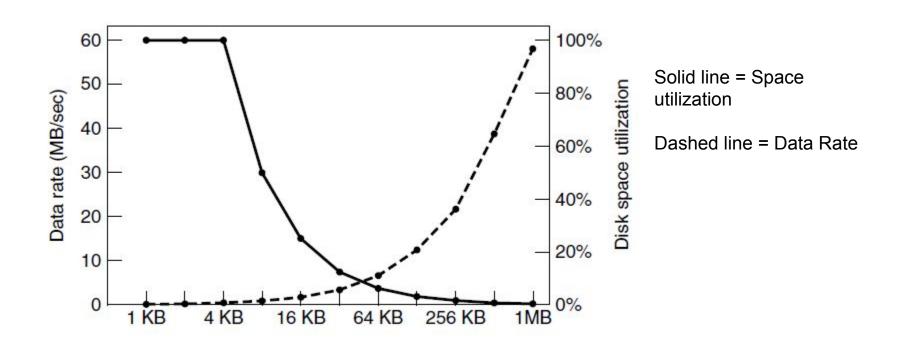
- We know files need to be broken into Blocks
- This prevents external fragmentation
  - ... but it creates internal fragmentation.
- How big should blocks be?
  - We could use device values: sector, track, cylinder
  - We could use page size

#### **Block size considerations**



- Big block sizes are a problem for small files
  - Lots of small files = lots of wasted space
- Small blocks (scattered) require lots of seek time
  - wasted time

## **Block size: Space or Transfer Speed?**



## **Takeaways**

Based on what we know (empirically) about typical file sizes (lots of small files) 1-KB to 4KB has been the standard.

Drives are becoming so big (and cheap) that this might change though.

## File System Recovery / Backup

- Hard-drives are supposed to be permanent
  - Nothing in life is permanent
  - When they break, you could lose all your data!
- Actually there are two reasons for backup:
  - Recover from disaster (physical)
  - Recover from stupidity (far more common)

The problem with backups is they are slow, and expensive...

## **Backup issues**

- Do we want to back up files that can easily be recreated by other means?
  - Objective of the property o
  - We should be able to choose
- What if files haven't changed from the last backup?
  - Incremental backups are far superior
  - Of course... then restoration is a bit more complex

## **Backup Issues**

- Even incremental backups can be huge
  - Compression is often employed here
- When to take a backup?
  - Difficult to do this on a system where files are actively changing
- Then of course... don't lose your backup!
  - Backups need to be stored off-site

#### A series of small failures....

- When an OS crashes, it could have been busy reading/writing blocks.
  - What if a block is removed from a file, and about to be put in the free pool... but crashed!
  - What if a block was about to be allocated it was removed from free pool.. but then crashed!
- We can scan i-nodes and the free pool every block should be accounted for once.
  - If not we have missing blocks or a block that needs to be removed from the free list.

#### **Inconsistent states**

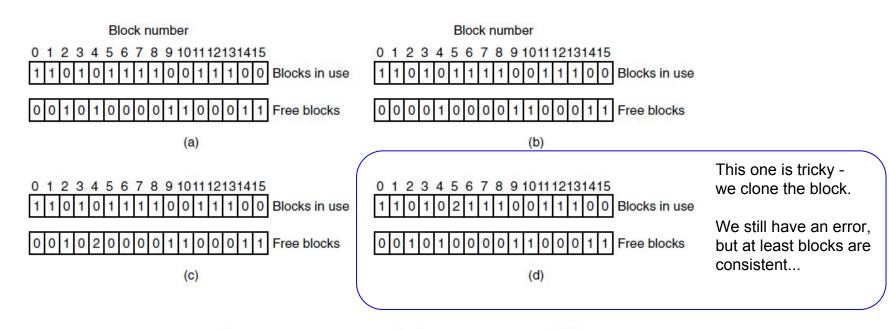


Figure 4-27. File system states. (a) Consistent. (b) Missing block. (c) Duplicate block in free list. (d) Duplicate data block.

#### **Bad Blocks**

- It's nearly impossible to manufacture disks without some blocks containing flaws
  - Over time, more flaws occur
  - Flaw = a bit that cannot reliably hold it's charge (state)
- Two problems:
  - How do figure out it's happened?
  - O What to do we do?

## Finding a Bad Block

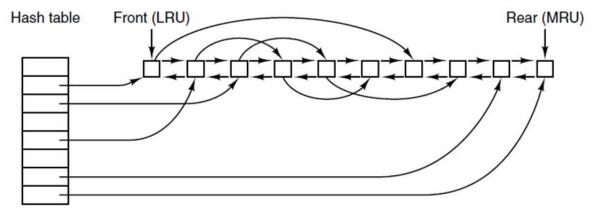
- Each block utilizes a header (overhead)
  - The header contains an ECC
  - On write, generate an ECC of data and write it in the header area of the block.
- On read, look at the data and generate expected ECC.
  - Compare with ECC in header
  - If they don't match, one is bad you've got a bad block.

## **Bad Block Recovery**

- We can't "fix" the block.
  - We must report the file as corrupted
- In addition, we must remember not to assign this block again
  - Most disk controllers handle much of this hiding it from the operating system
  - Replacement blocks are held in reserve
  - Block numbers corresponding to bad blocks are reassigned at the controller level

## **Caching and Performance**

- If we have memory to spare, we can hold copies of disk data in it.
- Block cache allows for read/writes to blocks to be done in memory.



## **Danger of Caches**

- What if we cache an i-node... and we crash!
- What if some blocks are used consistently, but not frequently?

#### We modify LRU:

- 1. Is the block likely to be used again soon?
- 2. Is the block essential to consistency?

## Blocks aren't equal

#### Divide blocks into:

- i-nodes (rarely used again and again)
- directory structures (same thing here)
- full data blocks
- partially full blocks

## Blocks aren't equal

#### Divide blocks into:

- i-nodes (must be written immediately)
- directory structures (same thing here)
- full data blocks
- partially full blocks

## **Forcing Caches to empty**

- System calls like sync (POSIX) can force the cache to be flushed to disk.
  - The OS can do this periodically (every 20 seconds)
  - This is typical for UNIX
- In Windows, "write-through" caches have traditionally been used instead.

#### **Block Read-ahead**

- Another approach used is to "guess" that if block i is being read, block i+1 will be read next.
- This works because it is so often the case that we sequentially read files

## File System Examples

#### **MS-DOS**

- Supported, but no longer common in modern Windows
- Surprisingly common in embedded systems
  - It's actually the FS the iPod uses (not iPhone)
- Each partition assigned a "drive" letter
  - The drive letter is essentially the "root"
  - No common "root" ("Computer")

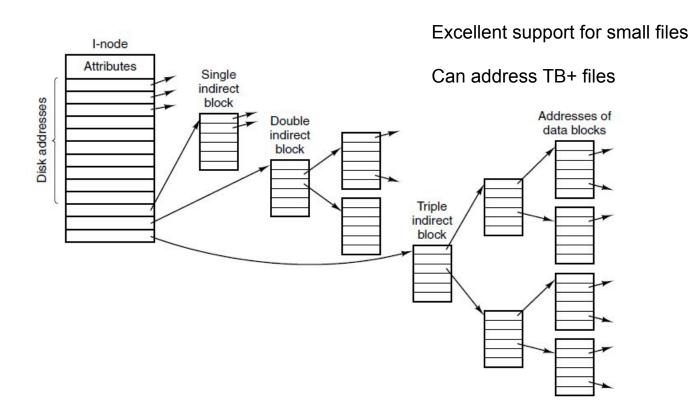
#### **MS-DOS**

- Characterized by:
  - Fixed directory entry sizes (fixed file name length)
  - Directory entries contain attributes directly (no linking)
  - File size is a 32-bit number so no file can be larger than 4GB.
- Uses a FAT (later MS-DOS renamed to FAT-32)
  - exFAT supports larger files, licensed by Apple

#### **UNIX**

- A single root directory ( / ) where all other file-systems can be mounted
- Uses i-node
  - Supports linking (attributes in i-node, not directory entry)

#### i-node structure in UNIX



### Up Next...

Chapter 5 take a look at how the OS interacts with physical devices

There is some overlap with our disk discussion!