# Fredrik Gustafsson

M.Sc. Student in Electrical Engineering

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- I am an engineering student whose main interests include autonomous robots, computer vision, deep learning and Bayesian filtering. I aim to be a key contributor in the development of fully autonomous vehicles and hope to experience the day when we can safely say:

"Do you remember when people used to get killed in traffic?".



Gothenburg, Sweden

### **Education**

Stanford University Sep. 2016 - Jun. 2017

GRADUATE EXCHANGE STUDENT IN ELECTRICAL ENGINEERING [4.15/4.30]

• Coursework included deep learning, Bayesian filtering and optimal control.

Linköping University Aug. 2013 - Jun. 2018

MASTER OF SCIENCE IN ELECTRICAL ENGINEERING | BACHELOR OF SCIENCE IN APPLIED PHYSICS AND ELECTRICAL ENGINEERING

· Master's profile: Control and Information Systems.

Please see fregu856.com for complete coursework.

## **Recent Projects**

SMAUGS - Autonomous Minesweeping System (Ground Vehicle & Drone)

Sep. 2017 - Dec. 2017

Course Project at Linköping University | C++, Python, ROS

Object Detection for Autonomous Driving - TensorFlow Implementation of SqueezeDet Aug. 2017 - Sep. 2017

PERSONAL PROJECT | PYTHON, TENSORFLOW

Semantic Segmentation for Autonomous Driving - TensorFlow Implementation of ENet Aug. 2017 - Sep. 2017

PERSONAL PROJECT | PYTHON, TENSORFLOW

The SE-Sync Algorithm for Pose-Graph SLAM May 2017 - Jun. 2017

COURSE PROJECT AT STANFORD UNIVERSITY | C++, ROS, MATLAB

Neural Image Captioning for Intelligent Vehicle-to-Passenger Communication Jan. 2017 - Mar. 2017

Course Project at Stanford University | Python, TensorFlow

Rasperino - Autonomous/Web Controlled Raspberry Pi & Arduino Robot Jun. 2016 - Aug. 2016

PERSONAL PROJECT | PYTHON, C, HTML, JAVASCRIPT

Spider Pig - Autonomous Hexapod Robot Jan. 2016 - Jun. 2016

Bachelor thesis project at Linköping University  $\mid$  C

Please see fregu856.com for further information.

## Relevant Experience\_

Software Engineer Jul. 2018 -

BMW Group Munich, Germany

• Feature development for autonomous driving and advanced driver assistance systems.

Master's Thesis Student Jan. 2018 - Jun. 2018

ZENUITY

3D object detection and domain adaptation for autonomous driving, using deep learning.

Deep Learning InternJun. 2017 - Aug. 2017ZENUITYGothenburg, Sweden

• Developed a deep learning demo/test platform based on a standard 1/10 scale RC car.

Algorithm Engineer Jun. 2016 - Aug. 2016

T Engineering AB Trollhättan, Sweden

• Developed a web tool for analysis and visualization of car engine sensor data for a fleet of test vehicles, using Python (Flask) and MySQL.

#### **Skills**

**Software (advanced)** Python (NumPy, PyTorch, TensorFlow, Flask), C/C++, ROS, MATLAB.

SQL, HTML, ETEX, Linux, Git, Simulink, JavaScript, Scheme.

**Languages** Swedish, English.

Other Swedish driver's license (B).