From Cellular Automata to the Lattice Boltzmann Method

BGCE Honours Project

Theresa Pollinger, Marcial Gaißert Ferienakademie Sarntal 2017 September 5, 2017

Outline

Introduction

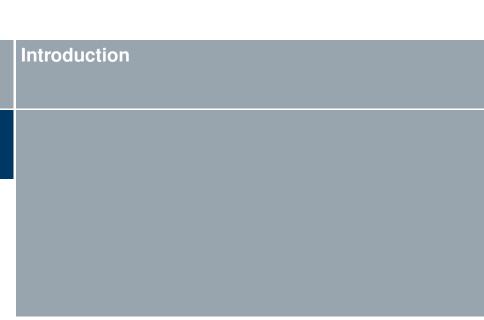
TerraNeo – Implementation of the Finite Element Method Preparations

waLBerla - Implementation of the Lattice Boltzmann Method

LBM - Short Overview

Boundary Conditions

Thermal LBM



Earth Mantle Convection II

Creeping flow, according to weismueller.2015

$$\left. \begin{array}{ll} \mu & \approx 10^{21} \, \mathrm{Pa \cdot s} \\ u & \approx 3 \, \mathrm{cm/a} \\ h & = 2867 \, \mathrm{km} \\ \rho & \approx 4000 \, \mathrm{kg/m}^3 \end{array} \right\} Re = \frac{\rho \cdot u \cdot h}{\mu} \approx 10^{-20} \ll 1$$

$$\mu \Delta \mathbf{u} - \nabla p + \mathbf{f} = 0$$
$$\nabla \cdot \mathbf{u} = 0$$

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- Dominant viscous forces, negligible intertial forces
- Navier-Stokes equations simplify to Stokes equations

$$\mu \Delta \mathbf{u} - \nabla p + \mathbf{f} = 0$$
$$\nabla \cdot \mathbf{u} = 0$$

Construct a divergence-free velocity field

$$\begin{bmatrix} u \\ v \end{bmatrix} = \nabla^{\perp} \Phi = \begin{bmatrix} \sin(2\pi x)\cos(\pi y) \\ -2\cos(2\pi x)\sin(\pi y) \end{bmatrix}$$

$$\mathbf{F} = \begin{bmatrix} f_X \\ f_y \end{bmatrix} = \begin{bmatrix} -\Delta u \\ -\Delta v \end{bmatrix} + \nabla \rho = \begin{bmatrix} 0 \\ ? \end{bmatrix}$$

$$\Rightarrow p = \frac{5}{2}\pi\cos(2\pi x)\cos(\pi y)$$

$$\mathbf{F} = \begin{bmatrix} f_X \\ f_y \end{bmatrix} = \begin{bmatrix} 0 \\ -12.5\pi^2 \cos(2\pi x)\sin(\pi y) \end{bmatrix}$$

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TerraNeo – Implementation of the Finite Element Method

Preparations

- Use CLOCK_MONOTONIC from the system environment for runtime measurement
- Implement "random-noise" initialization
- Implement an approximated L2 norm to ensure comparability with LBM ⇒ Verification by taking the norm of the analytical velocity field
- Calculate the accuracy based on the approximated L2 norm

$$\frac{\| \textbf{\textit{u}} - \textbf{\textit{u}}_{\text{exact}} \|}{\| \textbf{\textit{u}}_{\text{exact}} \|}$$

Use the tolerance 10⁻¹² between two iterations to identify the steady state

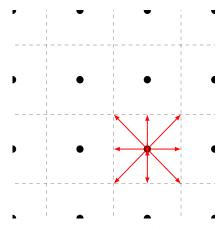
waLBerla – Implementation of the Lattice Boltzmann Method

Discrete particle distribution function

$$f_i = c_i \cdot w_i$$

Discrete particle distribution function

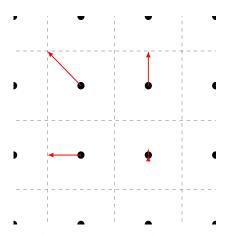
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One streaming step for a D2Q9-stencil

Discrete particle distribution function

$$f_i = \mathbf{c_i} \cdot \mathbf{w_i}$$



One streaming step for a D2Q9-stencil

Collide step: application of the lattice Boltzmann equation

$$f_i(\mathbf{x} + \mathbf{c}_i \Delta t, t + \Delta t) = f_i(\mathbf{x}, t) + \Omega_i(\mathbf{x}, t)$$

$$\rho(\mathbf{x},t) = \sum_{i} f_i(\mathbf{x},t)$$

$$\rho u(x,t) = \sum_{i} c_{i} f_{i}(x,t)$$

Source: kruger.2016

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$$f_i(\mathbf{x} + \mathbf{c}_i \Delta t, t + \Delta t) = f_i(\mathbf{x}, t) + \Omega_i(\mathbf{x}, t)$$

Density and velocity are given locally

$$\rho(\mathbf{x},t) = \sum_{i} f_i(\mathbf{x},t)$$

$$\rho \mathbf{u}(\mathbf{x},t) = \sum_{i} \mathbf{c}_{i} f_{i}(\mathbf{x},t)$$

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Boundary Conditions: Expectations

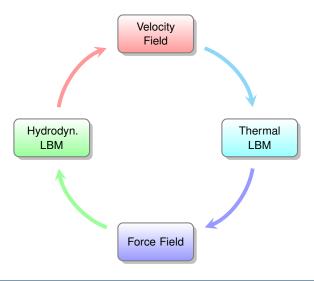
- Free-slip boundary conditions (Neumann Boundary Conditions)
- No-slip / UBB boundary conditions (Dirichlet boundary conditions)

Boundary Conditions: Expectations

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Both are expected to converge with order 2 in Δx

Thermal LBM: Principle



Thanks for listening.

Any questions?



References