

$$21 - s1 - 0.4$$

$$Q: A = \begin{bmatrix} \alpha & -1 \\ -4 & 4 \end{bmatrix} \quad B = \begin{bmatrix} 4 \\ 3 \end{bmatrix} \quad C = [2, 2]$$

(a) (i) $C \rightarrow \alpha$?

$$\text{Solution } |W_c| = |[B \ AB]|$$

$$AB = \begin{bmatrix} \alpha & -1 \\ -4 & 4 \end{bmatrix} \begin{bmatrix} 4 \\ 3 \end{bmatrix} = \begin{bmatrix} 4\alpha - 3 \\ -16 + 12 \end{bmatrix} = \begin{bmatrix} 4\alpha - 3 \\ -4 \end{bmatrix}$$

$$|W_c| = \begin{vmatrix} 4 & 4\alpha - 3 \\ 3 & -4 \end{vmatrix} = -16 - 3(4\alpha - 3)$$

$$= -12\alpha - 7 \neq 0 \Rightarrow \alpha \neq \frac{-7}{12}$$

(ii) Q: $\alpha = 2 \quad z_{12} = \pm j0.25 \Rightarrow k$?

Solution

$$K = [0 \ 1] W_c^{-1} \alpha_c(A)$$

$$W_c^{-1} = \begin{bmatrix} 4 & 5 \\ 3 & -4 \end{bmatrix}^{-1}$$

$$= \frac{1}{-31} \begin{bmatrix} -4 & -5 \\ -3 & 4 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{4}{31} & \frac{5}{31} \\ \frac{3}{31} & \frac{4}{-31} \end{bmatrix}$$

$$\alpha_c(z) = (z - j0.125)(z + j0.125)$$

$$= z^2 + (-j0.125)(j0.125) = z^2 + 0.0625$$

$$a=0 \quad b=-0.125 \quad c=0 \quad d=0.125$$

照抄都 -16 -15
能抄错? = -3)

写完一个式
必须检查两遍

$$(ac - bd, bc - ad)$$

$$= 0.125^2$$

$$= 0.015625$$

$$\alpha_c(z) = z^2 + 0.015625 \quad 0.0625$$

$$\alpha_c(A) = A^2 + 0.015625 I_2 \quad 0.0625$$

$$= \begin{bmatrix} 2 & -1 \\ -4 & 4 \end{bmatrix} \begin{bmatrix} 2 & -1 \\ -4 & 4 \end{bmatrix}$$

$$= \begin{bmatrix} 8 & -6 \\ -24 & 20 \end{bmatrix}$$

$$+ 0.015625 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$4+4$$

$$-8-16 = -24$$

$$-2-4$$

$$4+16$$

$$= \begin{bmatrix} 8.0125 & -6 \\ -24 & 20.0125 \end{bmatrix}$$

$$K = [0 \ 1] W_c^{-1} \alpha_c(A)$$

$$= [0 \ 1] \begin{bmatrix} \frac{4}{31} & \frac{5}{31} \\ \frac{3}{31} & \frac{4}{-31} \end{bmatrix}$$

$$\begin{bmatrix} 8.0125 & -6 \\ -24 & 20.0125 \end{bmatrix}$$

$$-6$$

$$20.0125$$

$$= \begin{bmatrix} \frac{3}{31} & -\frac{4}{31} \end{bmatrix} \begin{bmatrix} 8.0125 & -6 \\ -24 & 20.0125 \end{bmatrix}$$

$$-6$$

$$20.0125$$

$$20.0125$$

$$= \begin{bmatrix} 3.8714 & -3.1622 \end{bmatrix}$$

$$0.09677 \times 8. \sim$$

$$+ (-0.1290) \times (-24)$$

$$= [3.8770, -3.1694]$$

$$\text{法二求 } K \cdot |zI - (A - BK)|$$

$$A - BK = \begin{bmatrix} 2 & -1 \\ -4 & 4 \end{bmatrix} - \begin{bmatrix} 4 \\ 3 \end{bmatrix} [k_1 \ k_2]$$

$$= \begin{bmatrix} 2-4k_1 & -1-4k_2 \\ -4-3k_1 & 4-3k_2 \end{bmatrix}$$

$$\left| zI - (A - BK) \right| = \begin{vmatrix} z-2+4k_1 & 1+4k_2 \\ 4+3k_1 & z-4+3k_2 \end{vmatrix}$$

$$= z^2 + (-4+3k_2 - 2+4k_1)z + (-2+4k_1)(-4+3k_2)$$

$$- (1+4k_2)(4+3k_1)$$

$$= z^2 + (4k_1 + 3k_2 - 6)z + \left[\begin{aligned} & -8 - 6k_2 - 16k_1 + 12k_1k_2 \\ & - 4 - 3k_1 - 16k_2 - 12k_1k_2 \end{aligned} \right]$$

$-2 \times (-4) = 8$

$$= z^2 + (4k_1 + 3k_2 - 6)z + [-19k_1 - 22k_2 - 12]$$

$$\begin{cases} 4k_1 + 3k_2 - 6 = 0 \\ 19k_1 - 22k_2 + 12 = 0.0625 \end{cases}$$

$$\begin{cases} 4k_1 + 3k_2 = 6 \\ 19k_1 + 22k_2 = 3.9375 \end{cases}$$

$$\alpha_c(z) = z^2 + 0.0625$$

$$k_2 = \frac{6-4k_1}{3} \text{ 代入 ② 并}$$

$$\begin{cases} k_1 = \cancel{5.4254} 3.8770 \\ k_2 = \cancel{-5.2337} -3.1697 \end{cases}$$

$19k_1 + \frac{22}{3}(6-4k_1) = 3.9375$
 $19k_1 + 44 - \frac{88}{3}k_1 = 3.9375$

$$-\frac{31}{3}k_1 = -\frac{641}{16}$$

$$k_1 = \frac{1923}{496}$$

$$= 3.8770$$

$$k_2 = -\frac{2377}{750}$$

不能代小数
依分数

$$\begin{array}{r} 393 \\ - \\ 124 \end{array}$$

$$= -3.1693 \quad -3.1694$$

(b)(i)

With $\alpha = 2$, A and C are:

$$A = \begin{bmatrix} 2 & -1 \\ -4 & 4 \end{bmatrix}, \quad C = \begin{bmatrix} 2 & 2 \end{bmatrix}$$

We need $L_0 = \begin{bmatrix} l_1 \\ l_2 \end{bmatrix}$ such that the eigenvalues of $A - L_0 C$ are at $z = 0.4 \pm j0.4$. The desired characteristic equation is:

$$z^2 - 0.8z + 0.32 = 0$$

Compute $A - L_0 C$:

$$A - L_0 C = \begin{bmatrix} 2 - 2l_1 & -1 - 2l_1 \\ -4 - 2l_2 & 4 - 2l_2 \end{bmatrix}$$

Set up the characteristic equation and match coefficients:

$$\begin{cases} 2l_1 + 2l_2 - 6 = -0.8 \\ 4 - 16l_1 - 6l_2 = 0.32 \end{cases}$$

Solving these equations:

1. From the first equation:

$$l_1 + l_2 = 2.6$$

2. Substitute $l_2 = 2.6 - l_1$ into the second equation and solve for l_1 , yielding $l_1 \approx -1.192$.
3. Then $l_2 = 2.6 - (-1.192) = 3.792$.

Answer: The estimator gain is $L_0 = \begin{bmatrix} -1.192 \\ 3.792 \end{bmatrix}$.

(b)(ii)

Given $z = 0.4 \pm j0.4$, find the equivalent s -plane poles:

1. Compute the magnitude and angle:

$$|z| = \sqrt{0.4^2 + 0.4^2} = 0.5657, \quad \theta = \arctan\left(\frac{0.4}{0.4}\right) = 45^\circ$$

2. Convert to s -domain using $s = \frac{\ln(z)}{T}$:

$$s = \frac{\ln(0.5657) + j\frac{\pi}{4}}{0.1} = -5.68 \pm j7.854$$

3. Compute the damping ratio:

$$\zeta = \frac{-\operatorname{Re}(s)}{\sqrt{\operatorname{Re}(s)^2 + \operatorname{Im}(s)^2}} = \frac{5.68}{9.688} \approx 0.586$$

Answer: The s -plane poles are at $s = -5.68 \pm j7.854$ with a damping ratio of approximately 0.586.

(c)

Given $A = 1$, $B = 0.8$, $Q = 8$, $r = 1.6$.

Solve the algebraic Riccati equation:

$$0.64S^2 = 8 \times 1.6 + 0.64 \times 8 \times S \implies 0.64S^2 - 5.12S - 12.8 = 0$$

Simplify and solve:

$$S^2 - 8S - 20 = 0 \implies S = 10 \text{ (since } S > 0 \text{)}$$

Compute the optimal gain:

$$K = \frac{BS}{B^2S + r} = \frac{0.8 \times 10}{0.64 \times 10 + 1.6} = \frac{8}{8} = 1$$

Thus, the optimal control law is $u^*(k) = -x(k)$, and the closed-loop equation is:

$$x(k+1) = x(k) + 0.8(-x(k)) = 0.2x(k)$$

Answer: The optimal control law is $u^*(k) = -x(k)$; the closed-loop state equation is $x(k+1) = 0.2x(k)$.