

Example

Q  $m = 1000 \text{ kg}$

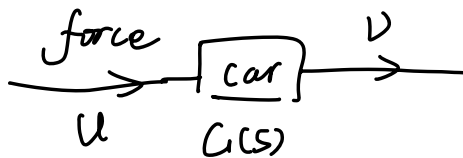
$$b = 100$$

ss  $0 \rightarrow 100 \text{ km/h}$

overshoot  $< 2\%$

plant is car

Solution



力-摩擦

$$V - b\dot{V} = m\ddot{V} \quad V(s) - b s V(s) = m s^2 V(s)$$

$$G(s) = \frac{V(s)}{u(s)} = \frac{1}{m + bs}$$

$$e^{-\frac{\zeta\omega_n}{\sqrt{1-\zeta^2}}} < 0.2$$

$$-\frac{\zeta\omega_n}{\sqrt{1-\zeta^2}} < \ln 0.2$$

$$\frac{\zeta\omega_n}{\sqrt{1-\zeta^2}} > 1.6094$$

$$\omega_n > 1.6094 \sqrt{1-\zeta^2}$$

$$\omega_n^2 \zeta^2 > 1.6094^2 (1-\zeta^2)$$

$$(\omega_n^2 + 1.6094^2) \zeta^2 > 1.6094^2$$

$$\zeta^2 > 0.2079 \quad \zeta > 0.4559$$

choose  $\xi = 0.7$

② 5% settling time      2%      1% ✓

$$t_s = \frac{3}{\xi \omega_n}$$

$$t_s = \frac{4}{\xi \omega_n}$$

$$t_s = \frac{4.6}{\xi \omega_n}$$

$$\xi = \frac{4.6}{0.7 \omega_n} \Rightarrow \omega_n = 0.821$$

$$\begin{aligned} H_{\text{desired}}(s) &= \frac{0.82^2}{s^2 + 2 \times 0.7 \times 0.82 s + 0.82^2} \\ &= \frac{0.67}{s^2 + 1.15 s + 0.67} \end{aligned}$$

PID controller       $C(s) = k_p + \frac{k_i}{s}$

$$G(s) = \frac{Y(s)}{U(s)} \quad C(s) = \frac{U(s)}{R(s) - Y(s)}$$

$$U = \frac{Y}{G} = CR - CY \Rightarrow Y = CGR - CAY \Rightarrow (1 + CG)Y = CGR$$

$$\frac{Y}{R} = \frac{CG}{1 + CG}$$

$$H(s) = \frac{Y(s)}{R(s)} = \frac{G(s) C(s)}{1 + G(s) C(s)}$$

$$G(s) = \frac{1}{ms + b} = \frac{1}{1000s + 100}$$

$$H(s) = \frac{\frac{1}{1000s + 100} \left( k_p + \frac{k_i}{s} \right)}{1 + \frac{1}{1000s + 100} \left( k_p + \frac{k_i}{s} \right)}$$

$$= \frac{s k_p + k_i}{1000s^2 + 100s + s k_p + k_i}$$

$$= \frac{0.001 k_p s + 0.001 k_i}{s^2 + (0.1 + 0.001 k_p)s + 0.001 k_i}$$

$$\begin{cases} 0.1 + 0.001 k_p = 1.15 \\ 0.001 k_i = 0.67 \end{cases} \Rightarrow \begin{cases} k_p = 1050 \\ k_i = 670 \end{cases}$$

PI controller  $C(s) = 1050 + \frac{670}{s}$

$$C(s) \rightarrow C(z) \text{ 选 T}$$

$$H(j\omega) = \frac{1.05(j\omega) + 0.67}{(j\omega)^2 + 1.15(j\omega) + 0.67}$$

$$|H(j\omega)| = \left| \sim \right|$$

$$dB = 20 \log_{10} |H(j\omega)| = f(\omega)$$

$$\text{let } f(\omega) = -3$$

$$\Rightarrow \omega = 1.8 \text{ rad/s} = \frac{1.8}{2\pi} = 0.3 \text{ Hz}$$

$$T \text{ 取 30 倍的 } \frac{1}{20\omega} = \frac{1}{30 \times 0.3} = \frac{1}{9} \approx 0.1 \text{ s}$$

$$S = \frac{2}{T} \left( \frac{z-1}{z+1} \right)$$

$$C(z) = \frac{1050 \frac{2}{T} \left( \frac{z-1}{z+1} \right) + 870}{\frac{2}{T} \left( \frac{z-1}{z+1} \right)} = \frac{1083.5z - 1016.5}{z-1}$$