

$$19-51-24$$

$$Q \quad x(k+1) = \begin{bmatrix} 1 & -4 \\ 1 & 1 \end{bmatrix} x(k) + \begin{bmatrix} 1 \\ 1 \end{bmatrix} u(k)$$

$$y(k) = [0 \ 1] x(k)$$

(i) Q: stable?

Solution ① poles \rightarrow stable

$$\text{pole } \det[zI - A]$$

$$= |zI - A|$$

$$= \begin{vmatrix} z-1 & 4 \\ -1 & z-1 \end{vmatrix}$$

$$= (z-1)^2 - (-4)$$

$$= z^2 - 2z + 1 + 4$$

$$= z^2 - 2z + 5$$

$$z_1 = 1 + 2j \quad z_2 = 1 - 2j$$

$$|z_{1,2}| = \sqrt{1^2 + 2^2} = \sqrt{5} > 1$$

the poles are not inside the unit circle

So, the system isn't stable

(ii) Q: k?

Solution ① Ack

$$K = [0 \ 1] W_c^{-1} \alpha_c(A)$$

$$\alpha_c(z) = [z - (-0.75 + j0.4)][z - (-0.75 - j0.4)]$$

$$= z^2 - z(-0.75 - j0.4) - z(-0.75 + j0.4)$$

$$+ (-0.75 + j0.4)(-0.75 - j0.4)$$

$$= z^2 + 1.5z + 0.75^2 + 0.4^2$$

$$= z^2 + 1.5z + 0.7225$$

$$\alpha_c(A) = A^2 + 1.5A + 0.7225I_2$$

$$= \begin{bmatrix} -0.7775 & -14 \\ 3.5 & -0.7775 \end{bmatrix}$$

Casio

$$W_c^{-1} = [B \ AB]^{-1} = \begin{bmatrix} 1 & -3 \\ 1 & 2 \end{bmatrix}^{-1} = \frac{1}{2+3} \begin{bmatrix} 2 & 3 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} \frac{2}{5} & \frac{3}{5} \\ -\frac{1}{5} & \frac{1}{5} \end{bmatrix}$$

$$AB = \begin{bmatrix} 1 & -4 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -3 \\ 2 \end{bmatrix} = \begin{bmatrix} 0.4 & 0.6 \\ -0.2 & 0.2 \end{bmatrix}$$

$$K = [0 \ 1] \begin{bmatrix} 0.4 & 0.6 \\ -0.2 & 0.2 \end{bmatrix} \begin{bmatrix} -0.7775 & -14 \\ 3.5 & -0.7775 \end{bmatrix}$$

$$= [0.8555 \quad 2.6445]$$

(iii) L_o ?

Solution

$$L_o = \alpha_c(A) W_o^{-1} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\alpha_o(z) = (z - 0.6)^2 = z^2 - 1.2z + 0.36$$

$$\alpha_o(A) = A^2 - 1.2A + 0.36I_2 = \begin{bmatrix} -3.84 & -3.2 \\ 0.8 & -3.84 \end{bmatrix}$$

$$W_o^{-1} = \begin{bmatrix} C \\ CA \end{bmatrix}^{-1} = \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix}^{-1} = \frac{1}{-1} \begin{bmatrix} 1 & -1 \\ -1 & 0 \end{bmatrix} = \begin{bmatrix} -1 & 1 \\ 1 & 0 \end{bmatrix}$$

$$CA = \begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & -4 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 \end{bmatrix}$$

$$L_o = \begin{bmatrix} -3.84 & -3.2 \\ 0.8 & -3.84 \end{bmatrix} \begin{bmatrix} -1 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} -3.84 \\ 0.8 \end{bmatrix}$$

(b) A_T B_T ? C ?

Solution

$$x(k+1) = ax(k) + bu(k)$$

$$\bar{x}(k+1) = a\bar{x}(k) + bu(k) + l_o y(k) - l_o C \bar{x}(k)$$

$$= (a - l_o C) \bar{x}(k) + bu(k) + l_o y(k)$$

$$= (a - l_o C) \bar{x}(k) + bu(k) + l_o C x(k)$$

$$\begin{bmatrix} x(k+1) \\ \bar{x}(k+1) \end{bmatrix} = \begin{bmatrix} a & 0 \\ l_o C & a - l_o C \end{bmatrix} \begin{bmatrix} x(k) \\ \bar{x}(k) \end{bmatrix} + \begin{bmatrix} b \\ b \end{bmatrix} u(k)$$

$$A_T = \begin{bmatrix} a & 0 \\ l_o C & a - l_o C \end{bmatrix} \quad B_T = \begin{bmatrix} b \\ b \end{bmatrix}$$

$$W_C = [B_T \quad A_T B_T] = \begin{bmatrix} b & ab \\ b & ab \end{bmatrix} \quad |W_C| = ab^2 - ab^2 = 0$$

un controllable

$$A_T B_T = \begin{bmatrix} a & 0 \\ b & a-bc \end{bmatrix} \begin{bmatrix} b \\ b \end{bmatrix} = \begin{bmatrix} ab \\ ab \end{bmatrix}$$

$$bcb + ab - bcb = ab$$