

18-S1-Q4

Q(a)  $T = 1$  deadbeat

Solution

$$K = [0 \ 1] W_c^{-1} \mathcal{A}_c(A)$$

$$\mathcal{A}_c(z) = z^2$$

$$A = \begin{bmatrix} 0.3679 & 0 \\ 0.6321 & 1 \end{bmatrix}$$

$$\mathcal{A}_c(A) = A^2 = \begin{bmatrix} 0.1354 & 0 \\ 0.8646 & 1 \end{bmatrix}$$

$$W_c = [B \ AB]$$

$$B = \begin{bmatrix} 1 - e^{-1} \\ e^{-1} \end{bmatrix} = \begin{bmatrix} 0.6321 \\ 0.3679 \end{bmatrix}$$

$$W_c = \begin{bmatrix} 0.6321 & 0.08559 \\ 0.3679 & 0.9144 \end{bmatrix}$$

$$AB = \begin{bmatrix} 0.1354 & 0 \\ 0.8646 & 1 \end{bmatrix} \begin{bmatrix} 0.6321 \\ 0.3679 \end{bmatrix} = \begin{bmatrix} 0.08559 \\ 0.9144 \end{bmatrix}$$

$$W_c^{-1} = \begin{bmatrix} 1.6732 & -0.1566 \\ -0.6732 & 1.1566 \end{bmatrix}$$

$$K = [0 \ 1] \begin{bmatrix} 1.6732 & -0.1566 \\ -0.6732 & 1.1566 \end{bmatrix} \begin{bmatrix} 0.1354 & 0 \\ 0.8646 & 1 \end{bmatrix}$$

$$= [-0.6732 \quad 1.1566] \begin{bmatrix} 0.1354 & 0 \\ 0.8646 & 1 \end{bmatrix}$$

$$= [0.9088 \quad 1.1566]$$

(b)  $z_{1,2} = 0$ , error ~~deadband~~ verify?

Solution

$$L_0 = \alpha_0(A) W_0^{-1} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\alpha_0(z) = (z-0)(z-0) = z^2$$

$$\alpha_0(A) = A^2 = \begin{bmatrix} 0.78 & 0 \\ 0.22 & 1 \end{bmatrix}^2 = \begin{bmatrix} 0.6084 & 0 \\ 0.3916 & 1 \end{bmatrix}$$

$$W_0 = \begin{bmatrix} C \\ C A \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 0.22 & 1 \end{bmatrix}$$

$$C A = [0 \ 1] \begin{bmatrix} 0.78 & 0 \\ 0.22 & 1 \end{bmatrix} = [0.22 \quad 1]$$

$$W_0^{-1} = \begin{bmatrix} -4.5455 & 4.5455 \\ 1 & 0 \end{bmatrix}$$

$$L_0 = \begin{bmatrix} 0.6084 & 0 \\ 0.3916 & 1 \end{bmatrix} \begin{bmatrix} -4.5455 & 4.5455 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} 2.7655 \\ 1.7800 \end{bmatrix}$$

$$\text{assume } x(0) = \begin{bmatrix} a_1 \\ b_1 \end{bmatrix} \quad \bar{x}(0) = \begin{bmatrix} a_2 \\ b_2 \end{bmatrix}$$

我只知道K怎么证明，假设状态 $x(0) = [a \ b]^T$ 然后算 $x(1)$   $x(2)$  一般 $x(3)$  的时候就是零矩阵了，所以deadbeat，但是观测器的不懂怎么搞  $\rightarrow 16.2$

$$x_e(0) = x(0) - \bar{x}(0) = \begin{bmatrix} a_1 - a_2 \\ b_1 - b_2 \end{bmatrix} = \begin{bmatrix} a \\ b \end{bmatrix}$$

$$x_e(k+1) = [A - L_0 C] x_e(k)$$

$$[A - L_0 C] = \begin{bmatrix} 0.78 & 0 \\ 0.22 & 1 \end{bmatrix} - \begin{bmatrix} 2.7655 \\ 1.7800 \end{bmatrix} \begin{bmatrix} 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0.78 & 0 \\ 0.22 & 1 \end{bmatrix} - \begin{bmatrix} 0 & 2.7655 \\ 0 & 1.7800 \end{bmatrix}$$

$$= \begin{bmatrix} 0.78 & -2.7655 \\ 0.22 & -0.78 \end{bmatrix}$$

$$x_e(1) = \begin{bmatrix} 0.78 & -2.7655 \\ 0.22 & -0.78 \end{bmatrix} x_e(0)$$

$$= \begin{bmatrix} 0.78a - 2.7655b \\ 0.22a - 0.78b \end{bmatrix}$$

$$X_e(2) = \begin{bmatrix} 0.78 & -2.7655 \\ 0.22 & -0.78 \end{bmatrix} \begin{bmatrix} 0.78a - 2.7655b \\ 0.22a - 0.78b \end{bmatrix}$$

$$= \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

So verify done

(c)  $A_e = ?$

$$x(k+1) = Ax(k) + Bu(k) \quad (1)$$

$$y(k) = Cx(k) \quad (2)$$

$$\bar{x}(k) = A\bar{x}(k-1) + Bu(k-1) + L_0 \{ y(k) - C(A\bar{x}(k-1) + Bu(k-1)) \} \quad (3)$$

$$x_e(k) = x(k) - \bar{x}(k) \quad (4)$$

$$x_e(k+1) = A_e x_e(k) \quad (5)$$

Solution

$$x_e(k+1) = x(k+1) - \bar{x}(k+1)$$

(1)(3)

$$= Ax(k) + Bu(k) - (A\bar{x}(k) + Bu(k) + L_0 \{ y(k+1) - C(A\bar{x}(k) + Bu(k)) \})$$

$$= A(x(k) - \bar{x}(k)) - L_0 \{ y(k+1) - C(A\bar{x}(k) + Bu(k)) \} \quad (6)$$

$$(2) \quad y(k+1) = Cx(k+1)$$

$$= C(Ax(k) + Bu(k))$$

$$y(k+1) - C(A\bar{x}(k) + Bu(k))$$

$$= CA(x(k) - \bar{x}(k))$$

$$= CAx_e(k) \quad \textcircled{7}$$

$$\textcircled{67} \quad x_e(k+1) = Ax_e(k) - L_0 CAx_e(k) \\ = (A - L_0 CA)x_e(k)$$

$$\text{So } A_e = A - L_0 CA$$