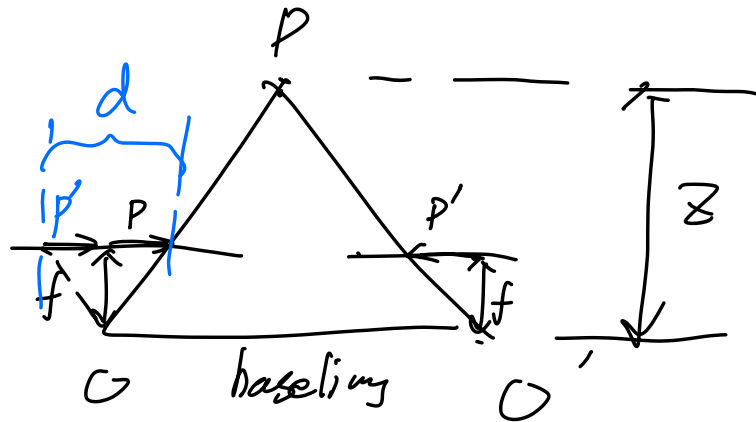


3D stereo matching + d

Depth from Stereo



$$\frac{f}{d} = \frac{Z}{L} \Rightarrow Z = \frac{f \times L}{d}$$

Epipolar Constraint

