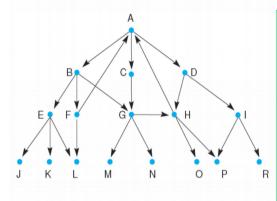
Exercise 3: Backtracking on Graph

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Check CS = Goal?

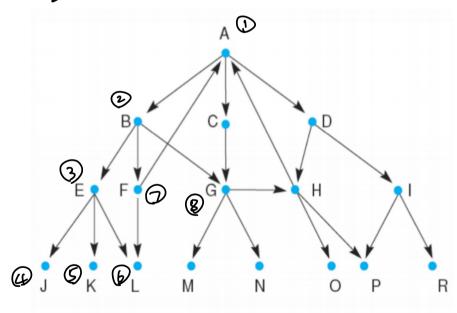
Check if CS has children? Exclude existing ones

Yes: growing NSL (add to left)
reset CS
add CS to SL

NO: remove current CS =>DE
remove CS from SL & NSL
CS reset by 1st from NSL
if CS=1st SL, loop back to NO.
add CS to SL

Assume: there is no goal state in the search space. Initialize: SL=[A];NSL=[A]; DE=[]; CS=A;

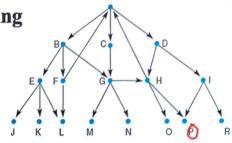
Solution



Iteration	CS	SL	NSL	DE -3
O	A	A	A	СJ
1	B	BA.	BCDA	
2	E	EBA	EFG BCD A	
3	J	JEBA	JKL EFA B	CDA
4	@ K _	S ≯ K E B A	K L EFA BC	LO # QJ
5	L	KEBA	∠ EFA BCC	
	-	⑤ □ 2 A	E F G B C D G	a LKJ
	⊕ E	©EBA FBA	FABCDA	f ELKJ
6 7	F G	GBA	GBC PA	FELKJ

LIFO&FILO Exercise 3: The BackTracking

"Hand run" the backtracking algorithm on the right graph Keep track of the successive values of NSL, SL, CS, DE. We assume there is no goal state in the search space. Initialize: SL=[A];NSL=[A]; DE=[]; CS=A;



Loop	CS	SL	NSL	DE
0	A	[A]	[A]	//check CS =goal? Has new children?
1	В	[B,A]	[B,C,D,A]	//add children to NSL - 'stack'; reset CS; update SL
2	E	[E,B,A]	[E,F,G,B,C,D,A]	//add children to NSL - 'stack'; reset CS; update SL
3	J	[J, E,B,A]	[J,K,L , E,F,G, B,C,D,A]	//J no children: CS=>DE; update SL, NSL; reset CS; update S
4	K	[K,E,B,A]	[K,L,E,F,G, B,C,D,A]	[J]
5	L	[L,E,B,A]	[L,E,F,G, B,C,D,A]	[K, J] // remove L, E
(b)	F	[F, B,A]	[F,G,B,C,D,A]	[E, L, K, J]
7	G	[G,B,A]	[G,B,C,D,A]	[F, E, L, K, J]
8	M	[M,G,B,A]	[M,N,H, G, B,C,D,A]	[F, E, L, K, J]
9	N	[N,G,B,A]	[N,H,G,B,C,D,A]	[M, F, E, L, K, J]
10	H	[H,G,B,A]	[H,G,B,C,D,A]	[N, M, F, E, L, K, J]
11	0	[O,H,G,B,A]	[O,P ,H,G,B,C,D,A]	[N, M, F, E, L, K, J]
(12)	P	[P,H,G,B,A]	[P,H,G,B,C,D,A]	[O, N, M, F, E, L, K, J] // remove P,H,
13	C	[C,A]	[C,D,A]	[B,G,H,P, O, N, M, F, E, L, K, J]
14	D	[D,A]	[D,A]	[C,B,G,H,P, O, N, M, F, E, L, K, J]
15	I	[I,D,A]	[I,D,A]	[C,B,G,H,P, O, N, M, F, E, L, K, J]
16	R	[R,I,D,A]	[R ,I,D,A]	[C,B,G,H,P, O, N, M, F, E, L, K, J]
17	-			[A,D,I,R , C,B,G,H,P, O, N, M, F, E, L, K, J]