Function Document

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Following is the help document of count_lego:

```
>> help count_lego

% This function counts blue 2*4 legos and red 2*2 legos.
  % [Version: MATLAB R2019b]
  %
  % Paraments:
  %    OUTPUT:
  %        numA = the number of blue 2*4 lego.
  %        numB = the number of red 2*2 lego.
  %    INPUT:
  %        I1 = RGB image.
  %
  % Methods:
  %   At first, hsv information is used to select objects in certain color.
  %   Then, the function detects how many circles can be found in a single
  %   lego and determine if it is a target lego or not. In this step, two
  %   circle detection methods are combined to keep the stability and
  %   efficiency. When determining legos, complex judging conditions are
  %   used in order to suit possible different situations (like several same
  %   color legos close to each other). For increasing speed and accuracy,
  %   this function also considers if the outline of the detecting object
  %   is convex or not. Finally, the number of blue 2*4 and red 2*2 legos
  %   can be counted.
  %
  % Procedures:
  %   Color segment based on HSV information --> Detect edge --> Count
  %   circles in each region and determine whether it is a target lego
  %   --> Count target legos
  %
  % Example:
  %   example.m
  %
  % Reference:
  %   https://uk.mathworks.com/help/images/ref/regionprops.html
  %   https://uk.mathworks.com/help/images/detect-and-measure-circular-
 objects-in-an-image.html
```