

Context

Consistency models

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Consistency models

Linearizability: every operation appears to take place atomically, in some order, consistent with the real-time ordering of those operations

Eventual consistency: all replicas converge to the same value eventually

Read-your-writes: each process always read its latest write

Monotonic reads: once a process has read a value of a data item, its future reads will never return an older value

Problems

Problem 1: Given an implementation of a replicated data system, can we formally and fully automatically verify that it satisfies a specific consistency model?

Problem 2: Given a distributed application that uses a (black-box) replicated data system, and assuming this system conforms to a given consistency model, can we formally and fully automatically verify that the application behaves correctly (e.g., is functional or safe)?

More generally:

How can we formally and automatically reason about consistency models in replicated data systems?

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Histories

We define $\mathcal{H}(\mathbb{P}, \mathbb{T}, \mathbb{O}, \mathbb{V})$ as the set of all well-defined finite histories.

\mathbb{P} is the **finite** set of processes

$\mathbb{T} = \{read, write\}$ is the set of operation types

\mathbb{O} is the **finite** set of objects

\mathbb{V} is the **finite** set of values

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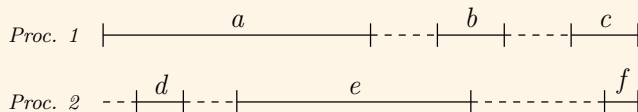
$\mathbb{T} = \{read, write\}$ is the set of operation types

\mathbb{O} is the **finite** set of objects

\mathbb{V} is the **finite** set of values

A history $H \in \mathcal{H}(\mathbb{P}, \mathbb{T}, \mathbb{O}, \mathbb{V})$ is a set of **operations**; each of its operations having attributes drawn from the sets above.

Histories



The MONA tool

- * an automatic verification tool that analyzes logical formulas
- * in particular, formulas of a fragment of **weak Monadic Second Order logic (MSO)**
- * it translates MSO formulas into **finite**-state automata

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MSO logic allows $\forall x, \forall X, \exists x, \exists X, P(x), P(X), P(X, Y), \dots$

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Automata's inputs are **finite** words of bit vectors

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Automata's inputs are **finite** words of bit vectors

$$\begin{bmatrix} 0 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \end{bmatrix} \cdots \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

MSO logic of words of bit vectors

- A vector is called a **position**
- A row is called a **set of positions**

$\psi :=$

- $\forall x.\psi$
- $\exists x.\psi$
- $\forall X.\psi$
- $\exists X.\psi$
- $x = \text{succ}(y)$ with $\text{succ}(y) := y + 1$
- $x = y$ equality of positions
- $x \in X$ position x is in the set X
- $\psi \wedge \psi \mid \psi \vee \psi \mid \neg\psi \mid (\psi)$

Motivation

Theorem

The satisfiability of MSO formulas over finite histories is decidable

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The satisfiability of MSO formulas over finite histories is decidable

Extending the result to infinite, non Zeno histories, seems easy

Monadic second-order logic of histories

Let a and b be some operations.

$$\begin{aligned} \phi := & \ a.proc = b.proc \quad \text{with } a.proc, b.proc \in \mathbb{P} \\ & | \ a.type = b.type \quad \text{with } a.proc, b.proc \in \mathbb{T} \\ & | \ a.obj = b.obj \quad \text{with } a.proc, b.proc \in \mathbb{P} \\ & | \ a.ival = b.ival \\ & | \ a.oval = b.oval \quad \text{with } a.ival, b.ival, a.ival, b.ival \in \mathbb{V} \\ & | \ t < t \\ & | \ \forall a. \phi \\ & | \ \exists a. \phi \\ & | \ \forall A. \phi \\ & | \ \exists A. \phi \\ & | \ \phi \wedge \phi \mid \phi \vee \phi \mid \neg \phi \mid (\phi) \\ t := & \ a.stime \\ & | \ a.rtime \end{aligned}$$

Monadic second-order logic of histories

Arbitration: $a \xrightarrow{ar} b$ denotes that operation a is considered to be done before operation b

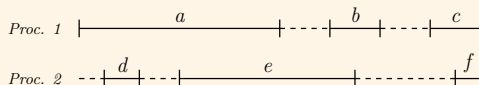
Visibility: $a \xrightarrow{vis} b$ denotes that the effects of operation a are visible to the client performing b

The MONA tool for histories

MONA handles **discrete time**, which can be seen as *snapshots*

$$\begin{bmatrix} 0 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \end{bmatrix} \cdots \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Histories represent **continuous time**, which can be seen as a *timeline*



Outline

Traces of executions
called *Histories*

Input:
words of bit vectors

Consistency verification
(with the *MONA* tool)

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Traces of executions
called *Histories*

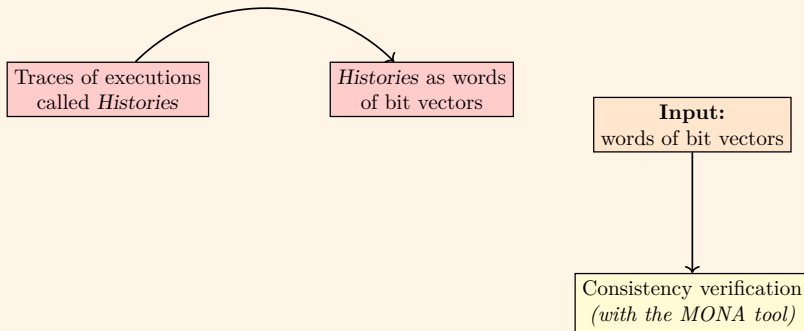
Histories as words
of bit vectors

Input:
words of bit vectors

Consistency verification
(with the *MONA* tool)

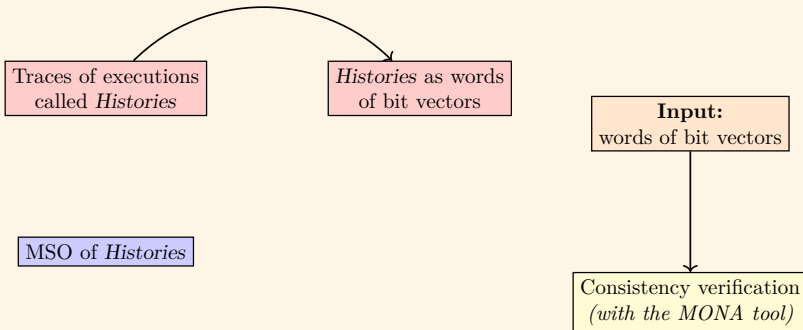
Outline

Encoding function



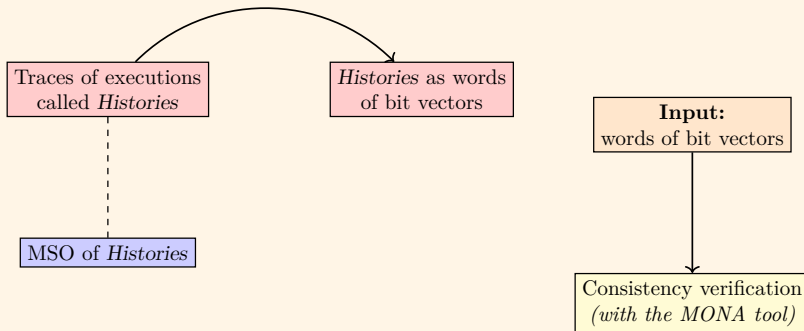
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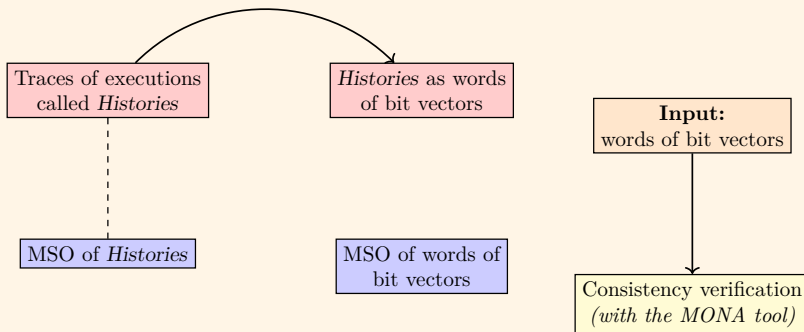
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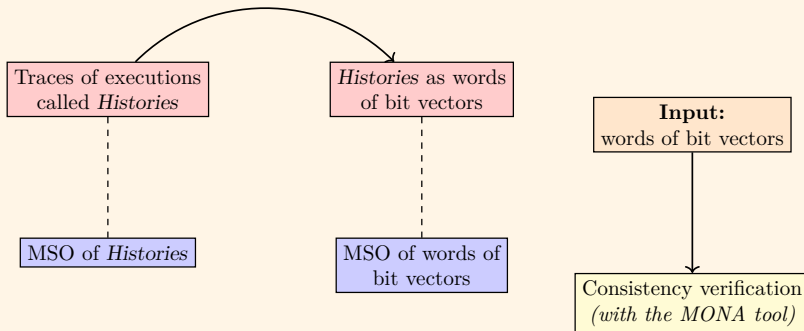
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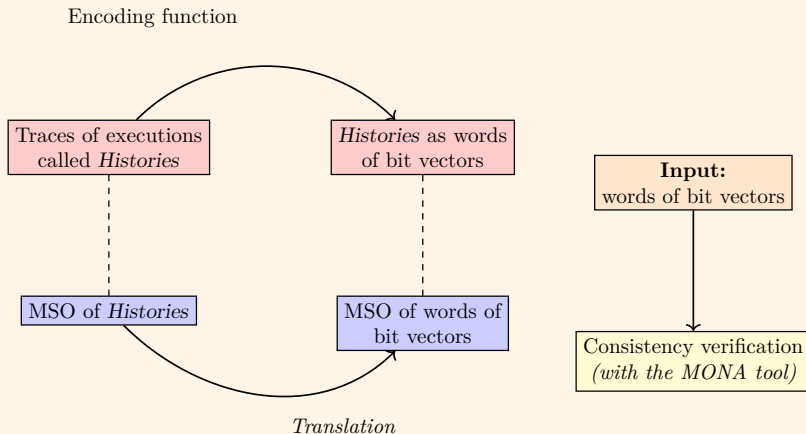


Outline

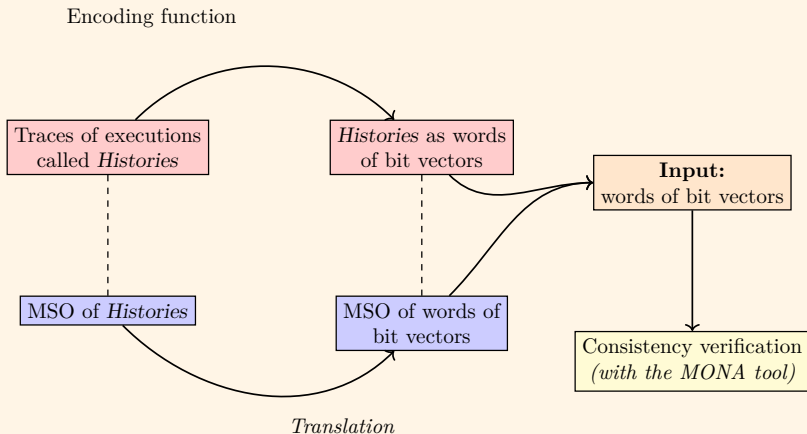
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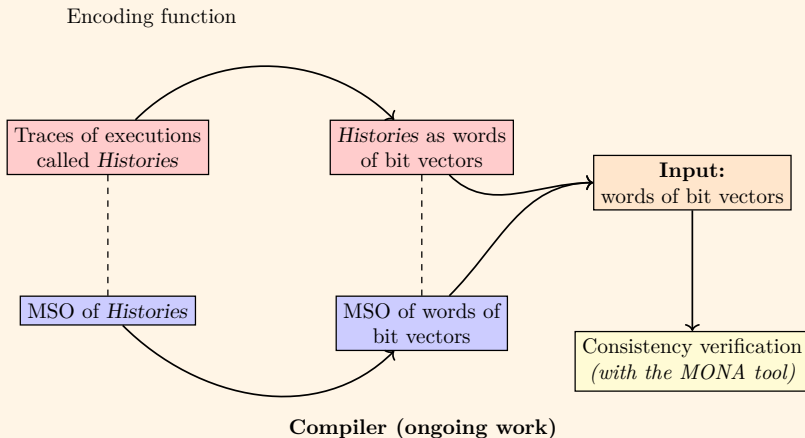
Outline



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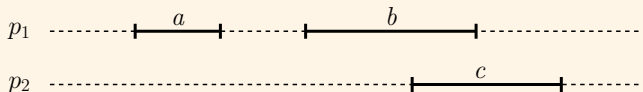
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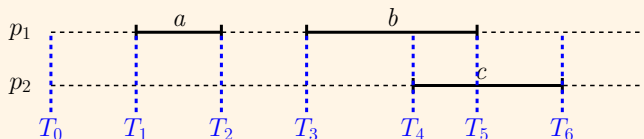
Vector structure

$$\left[\begin{array}{c} p_1 \\ \vdots \\ p_n \\ t \\ v_1 \\ \vdots \\ v_k \\ o_1 \\ \vdots \\ o_\ell \\ \alpha_1 \\ \vdots \\ \alpha_a \\ \nu_1 \\ \vdots \\ \nu_v \end{array} \right] \left\{ \begin{array}{l} \text{processes} \\ \text{type (here } \textit{read} \text{ or } \textit{write}) \\ \text{input or output value} \\ \text{object} \\ \text{arbitration relation} \\ \text{visibility} \end{array} \right.$$

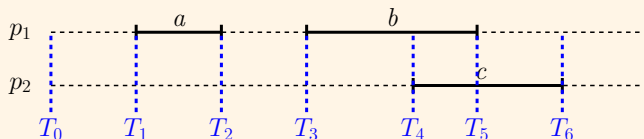
Encoding histories as words



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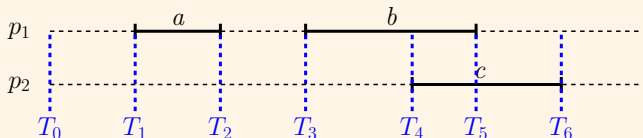


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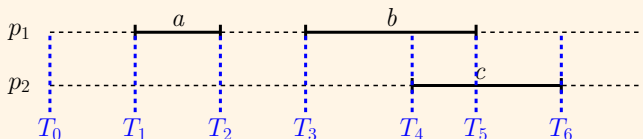
	a	b	c
<i>proc</i>	p_1	p_1	p_2
<i>stime</i>	T_1	T_3	T_4
<i>rtime</i>	T_2	T_5	T_6
<i>type</i>	<i>write</i>	<i>read</i>	<i>write</i>
<i>ival</i>	14	\emptyset	"fly"
<i>oval</i>	\emptyset	"bee"	\emptyset
<i>obj</i>	y	x	x

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<i>proc</i>	p_1	p_1	p_2
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<i>type</i>	1	0	1
<i>ival</i>	00	\emptyset	10
<i>oval</i>	\emptyset	01	\emptyset
<i>obj</i>	1	0	0

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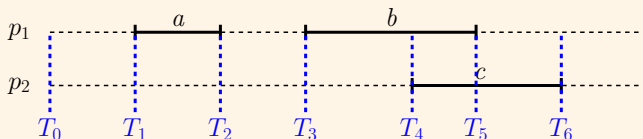


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<i>oval</i>	\emptyset	01	\emptyset
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T_0

$$\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \vdots \end{bmatrix}$$

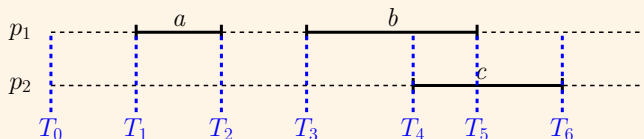
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<i>oval</i>	\emptyset	01	\emptyset
<i>obj</i>	1	0	0

$$\begin{array}{c}
 T_0 \quad T_1 \\
 \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \vdots \end{bmatrix} \quad \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \\ 0 \\ 1 \\ \vdots \end{bmatrix}
 \end{array}$$

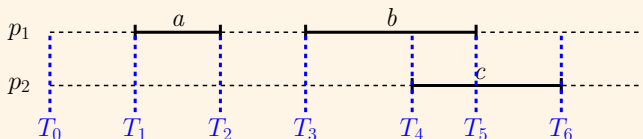
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$$\begin{array}{c}
 T_0 \quad T_1 \quad T_2 \\
 \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \vdots \end{bmatrix} \quad \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \\ 0 \\ \vdots \end{bmatrix} \quad \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \vdots \end{bmatrix}
 \end{array}$$

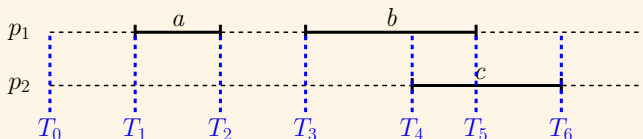
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T_0	T_1	T_2	T_3
$\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \vdots \end{bmatrix}$	$\begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \\ 1 \\ \vdots \end{bmatrix}$	$\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \vdots \end{bmatrix}$	$\begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \\ 0 \\ \vdots \end{bmatrix}$

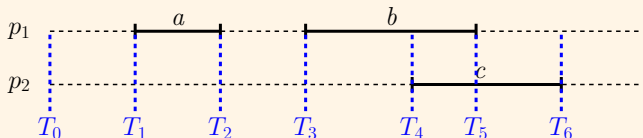
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T_0	T_1	T_2	T_3	T_4
$\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \vdots \end{bmatrix}$	$\begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \\ 1 \\ \vdots \end{bmatrix}$	$\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \vdots \end{bmatrix}$	$\begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \\ 0 \\ \vdots \end{bmatrix}$	$\begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \\ 0 \\ \vdots \end{bmatrix}$

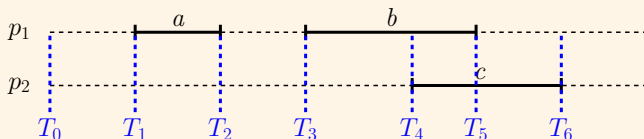
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<i>ival</i>	00	\emptyset	10
<i>oval</i>	\emptyset	01	\emptyset
<i>obj</i>	1	0	0

T_0	T_1	T_2	T_3	T_4	T_5
$\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \vdots \end{bmatrix}$	$\begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \\ 0 \\ \vdots \end{bmatrix}$	$\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \vdots \end{bmatrix}$	$\begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \\ 0 \\ \vdots \end{bmatrix}$	$\begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \\ 0 \\ \vdots \end{bmatrix}$	$\begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ \vdots \end{bmatrix}$

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T_0	T_1	T_2	T_3	T_4	T_5	T_6
$\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \vdots \end{bmatrix}$	$\begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \\ 1 \\ \vdots \end{bmatrix}$	$\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \vdots \end{bmatrix}$	$\begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \\ 0 \\ \vdots \end{bmatrix}$	$\begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \\ 0 \\ \vdots \end{bmatrix}$	$\begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ \vdots \end{bmatrix}$	$\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \vdots \end{bmatrix}$

Encoding arbitration

$$\begin{array}{c} p_1 \\ \vdots \\ p_n \end{array} \left[\begin{array}{cccc} p_1 & \dots & \dots & p_n \\ 0 & \alpha_{12} & \dots & \alpha_{1n} \\ \neg \alpha_{12} & & \ddots & \\ \vdots & & & \vdots \\ \neg \alpha_{1n} & \dots & \neg \alpha_{(n-1)n} & 0 \end{array} \right]$$

A variable α_{ij} is set to 1 if the operation on process i is arbitrated before the operation on process j , and is set to 0 if not

Encoding arbitration

$$\begin{array}{c} p_1 \\ \vdots \\ p_n \end{array} \left[\begin{array}{cccc} p_1 & \dots & \dots & p_n \\ 0 & \alpha_{12} & \dots & \alpha_{1n} \\ \neg \alpha_{12} & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \alpha_{(n-1)n} \\ \neg \alpha_{1n} & \dots & \neg \alpha_{(n-1)n} & 0 \end{array} \right]$$

$$\begin{bmatrix} \alpha_{12} \\ \alpha_{13} \\ \alpha_{14} \\ \vdots \\ \alpha_{23} \\ \alpha_{24} \\ \vdots \\ \alpha_{(n-1)n} \end{bmatrix}$$

A variable α_{ij} is set to 1 if the operation on process i is arbitrated before the operation on process j , and is set to 0 if not

Encoding visibility

A way to represent visibility with respect to an operation a , is to encode, for each process p , the most recent operation initiated on p that is visible to a .

$$\left[\begin{array}{c} \# \\ \vdots \\ \# \\ p_{1,1} \\ \vdots \\ p_{1,S} \\ \vdots \\ p_{n,1} \\ \vdots \\ p_{n,S} \end{array} \right] \left. \begin{array}{l} \vphantom{\left[\begin{array}{c} \# \\ \vdots \\ \# \\ p_{1,1} \\ \vdots \\ p_{1,S} \\ \vdots \\ p_{n,1} \\ \vdots \\ p_{n,S} \end{array} \right]} \\ \vphantom{\left[\begin{array}{c} \# \\ \vdots \\ \# \\ p_{1,1} \\ \vdots \\ p_{1,S} \\ \vdots \\ p_{n,1} \\ \vdots \\ p_{n,S} \end{array} \right]} \\ \vphantom{\left[\begin{array}{c} \# \\ \vdots \\ \# \\ p_{1,1} \\ \vdots \\ p_{1,S} \\ \vdots \\ p_{n,1} \\ \vdots \\ p_{n,S} \end{array} \right]} \end{array} \right\} \begin{array}{l} \text{previous encoding} \\ \\ \text{most recent operation initiated on } p_1 \text{ that is visible to } a \\ \\ \text{most recent operation initiated on } p_n \text{ that is visible to } a \end{array}$$

Compiler

MSO of histories \rightarrow MSO of words of bit vectors

Compiler

MSO of histories \rightarrow MSO of words of bit vectors

Input:

forall X. exists x. exists y. x in X and x.type=y.type

Output:

```
var2 Process2;
var2 Process1;
var2 TypeRow;
var2 ObjectRow1;
var2 ValueRow1;
pred op(var1 x)= x in Process2 & ex1 y: y + 1 = x & (~y in
Process2) | x in Process1 & ex1 y: y + 1 = x & (~y in
Process1);
all2 X: ((all1 a: a in X => op(a)) => ex1 x: op(x) & ex1
y: op(y) & x in X & (x in TypeRow <=> y in TypeRow));
```

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- ▷ formal and automatic reasoning about consistency models in replicated data systems

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Ongoing work: compiler for translation (in OCaml)

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Future work:

First part: extend to infinite histories (should be easy)

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- ▷ formal and automatic reasoning about consistency models in replicated data systems

Ongoing work: compiler for translation (in OCaml)

Future work:

First part: extend to infinite histories (should be easy)

Second part: weaker assumptions (visibility and arbitration)

Thank you