

# Automated Reasoning on Consistency Models for Replicated Data Systems with MONA

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# Context

## Consistency models

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**Linearizability:** every operation appears to take place atomically, in some order, consistent with the real-time ordering of those operations

**Eventual consistency:** all replicas converge to the same value eventually

**Read-your-writes:** each process always read its latest write

**Monotonic reads:** once a process has read a value of a data item, its future reads will never return an older value

# Problems

**Problem 1:** Given an implementation of a replicated data system, can we formally and fully automatically verify that it satisfies a specific consistency model?

**Problem 2:** Given a distributed application that uses a (black-box) replicated data system, and assuming this system conforms to a given consistency model, can we formally and fully automatically verify that the application behaves correctly (e.g., is functional or safe)?

**More generally:**

How can we formally and automatically reason about consistency models in replicated data systems?

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**3** Conclusion

# Histories

We define  $\mathcal{H}(\mathbb{P}, \mathbb{T}, \mathbb{O}, \mathbb{V})$  as the set of all well-defined finite histories.

$\mathbb{P}$  is the **finite** set of processes

$\mathbb{T} = \{read, write\}$  is the set of operation types

$\mathbb{O}$  is the **finite** set of objects

$\mathbb{V}$  is the **finite** set of values

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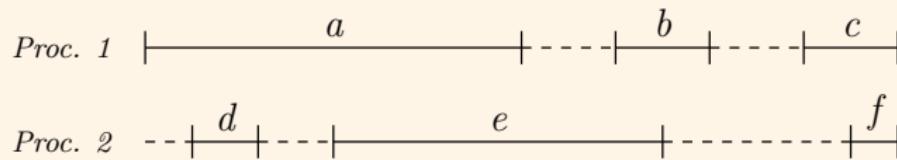
$\mathbb{T} = \{read, write\}$  is the set of operation types

$\mathbb{O}$  is the **finite** set of objects

$\mathbb{V}$  is the **finite** set of values

A history  $H \in \mathcal{H}(\mathbb{P}, \mathbb{T}, \mathbb{O}, \mathbb{V})$  is a set of **operations**; each of its operations having attributes drawn from the sets above.

# Histories



# The MONA tool

- \* an automatic verification tool that analyzes logical formulas
- \* in particular, formulas of a fragment of **weak Monadic Second Order logic (MSO)**
- \* it translates MSO formulas into **finite**-state automata

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**MSO logic** allows  $\forall x, \forall X, \exists x, \exists X, P(x), P(X), P(X, Y), \dots$

**Automata's inputs** are **finite** words of bit vectors

$$\begin{bmatrix} 0 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \end{bmatrix} \dots \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

# MSO logic of words of bit vectors

- A vector is called a **position**
- A row is called a **set of positions**

$$\begin{aligned}\psi := & \forall x.\psi \\| & \exists x.\psi \\| & \forall X.\psi \\| & \exists X.\psi \\| & x = \text{succ}(y) \quad \text{with } \text{succ}(y) := y + 1 \\| & x = y \quad \text{equality of positions} \\| & x \in X \quad \text{position } x \text{ is in the set } X \\| & \psi \wedge \psi \mid \psi \vee \psi \mid \neg\psi \mid (\psi)\end{aligned}$$

# Motivation

## Theorem

The satisfiability of MSO formulas over finite histories is decidable

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*Extending the result to infinite, non Zeno histories, seems easy*

# Monadic second-order logic of histories

Let  $a$  and  $b$  be some operations.

$$\begin{aligned}\phi := & \quad a.proc = b.proc \quad \text{with } a.proc, b.proc \in \mathbb{P} \\ | \quad & a.type = b.type \quad \text{with } a.proc, b.proc \in \mathbb{T} \\ | \quad & a.obj = b.obj \quad \text{with } a.proc, b.proc \in \mathbb{P} \\ | \quad & a.ival = b.ival \\ | \quad & a.oval = b.oval \quad \text{with } a.ival, b.ival, a.ival, b.ival \in \mathbb{V} \\ | \quad & t < t \\ | \quad & \forall a. \phi \\ | \quad & \exists a. \phi \\ | \quad & \forall A. \phi \\ | \quad & \exists A. \phi \\ | \quad & \phi \wedge \phi \mid \phi \vee \phi \mid \neg \phi \mid (\phi) \\ t := & \quad a.stime \\ | \quad & a.rtime\end{aligned}$$

# Monadic second-order logic of histories

**Arbitration:**  $a \xrightarrow{ar} b$  denotes that operation  $a$  is considered to be done before operation  $b$

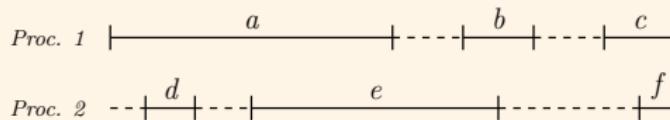
**Visibility:**  $a \xrightarrow{vis} b$  denotes that the effects of operation  $a$  are visible to the client performing  $b$

# The MONA tool for histories

MONA handles **discrete time**, which can be seen as *snapshots*

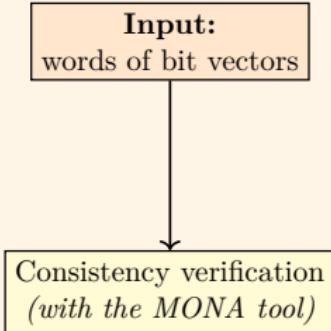
$$\begin{bmatrix} 0 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \end{bmatrix} \dots \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Histories represent **continuous time**, which can be seen as a *timeline*



# Outline

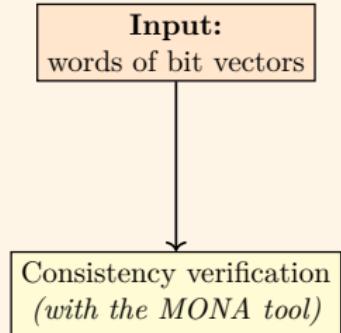
Traces of executions  
called *Histories*



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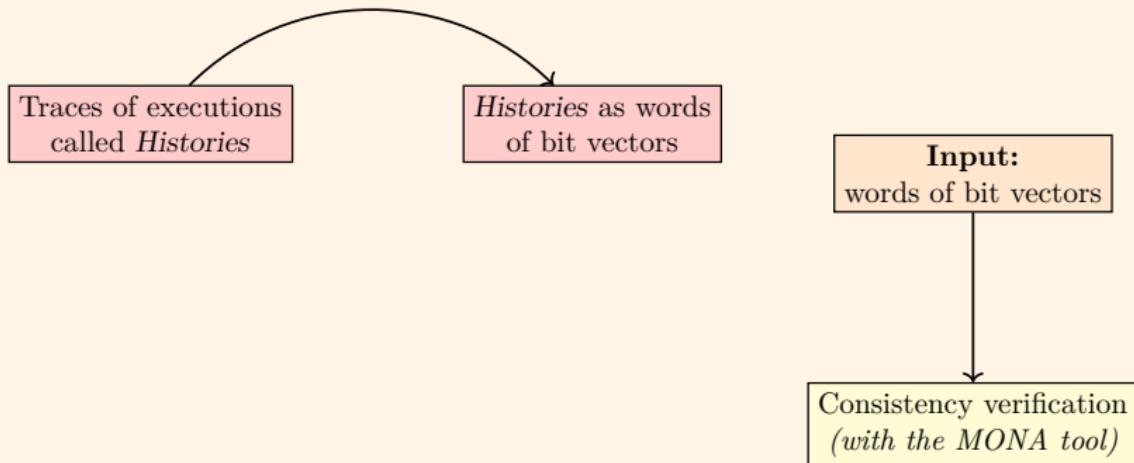
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*Histories* as words  
of bit vectors



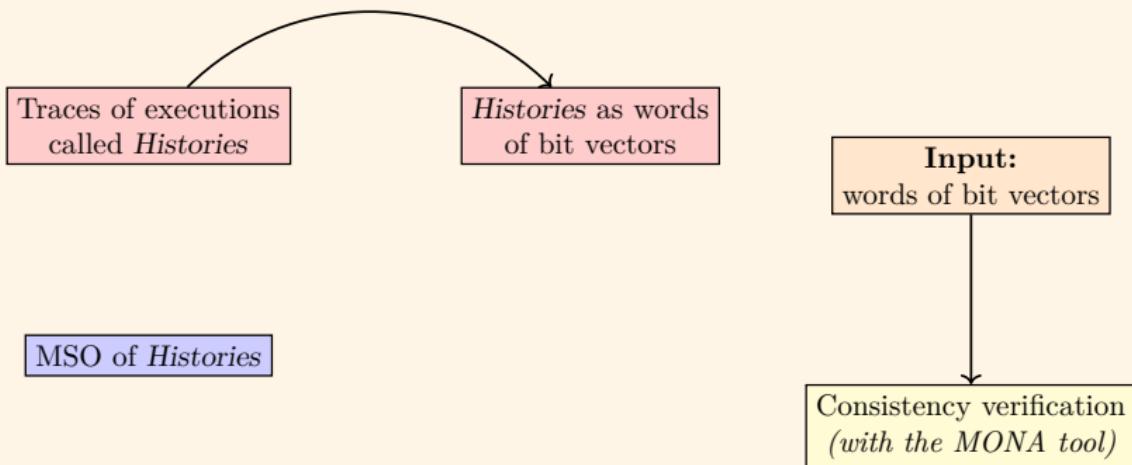
# Outline

Encoding function



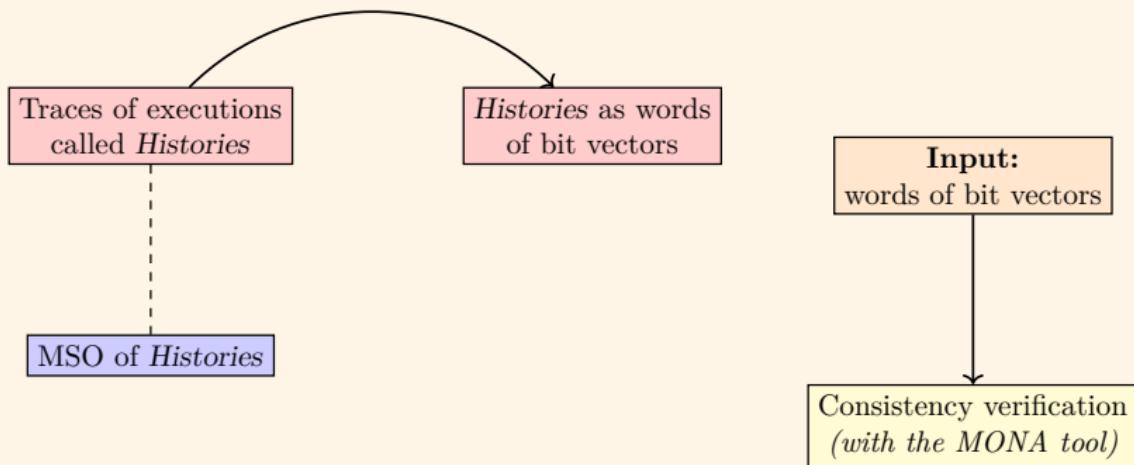
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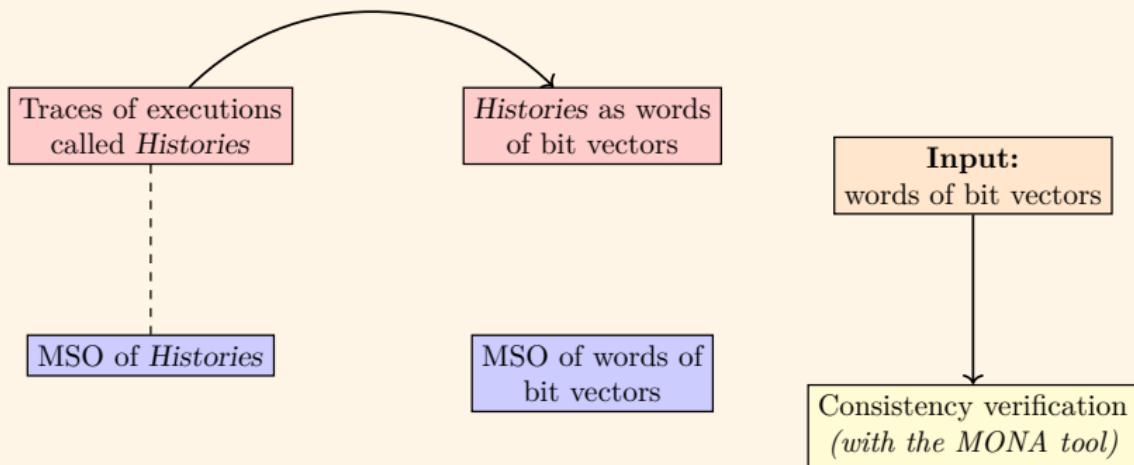
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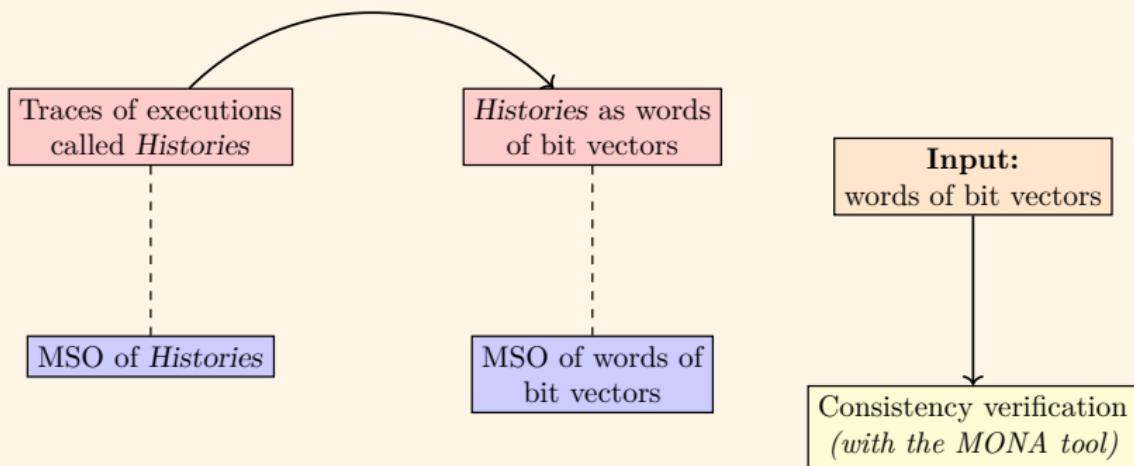
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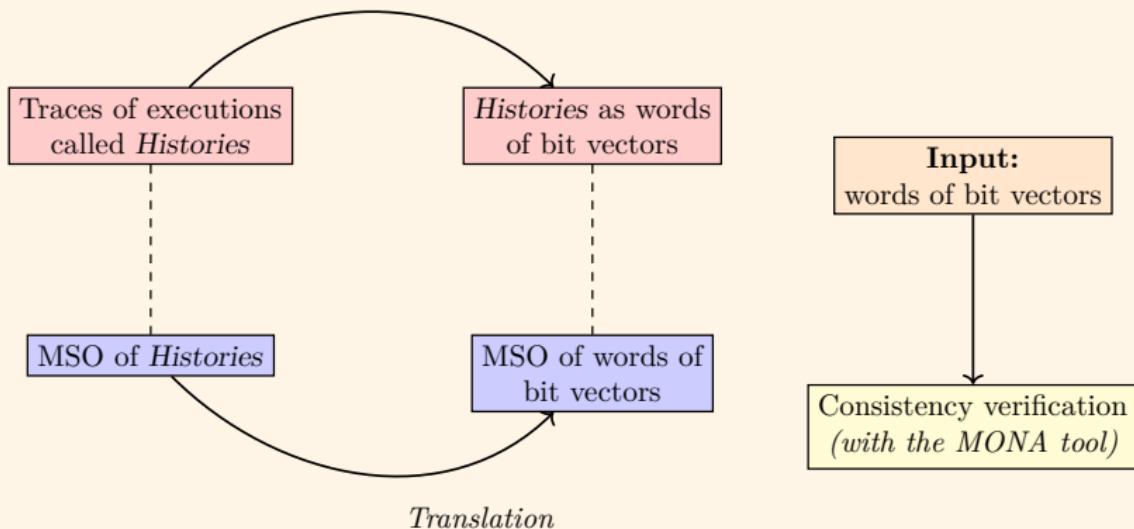
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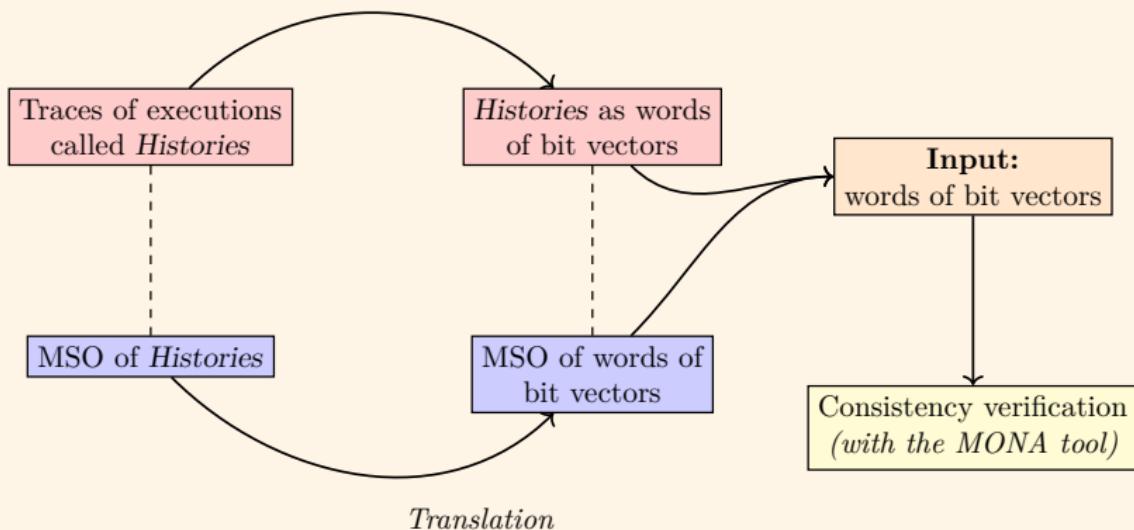
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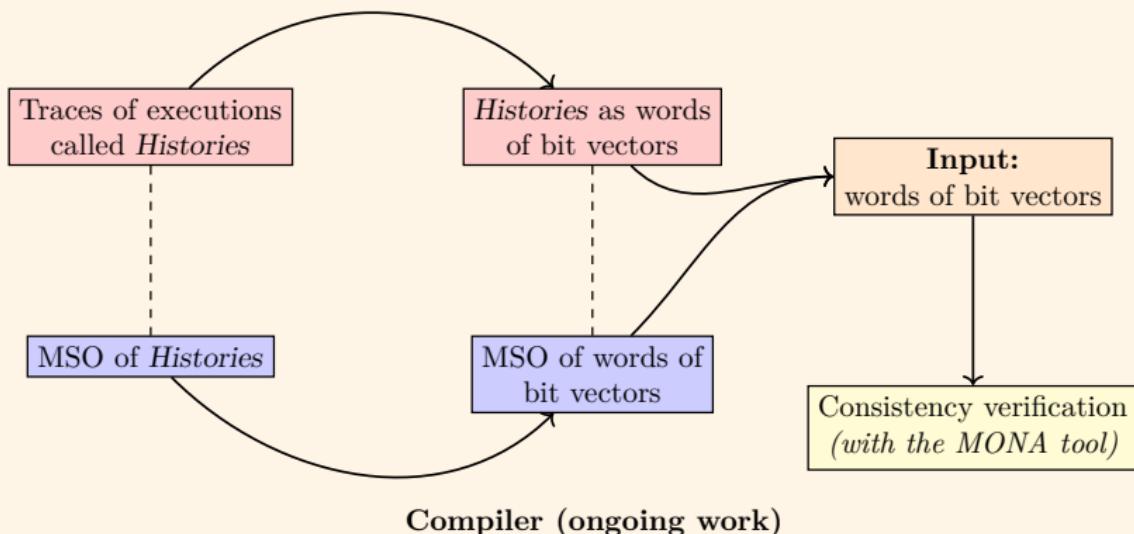
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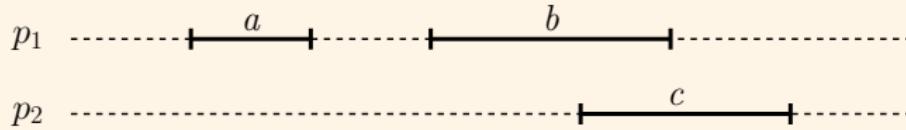
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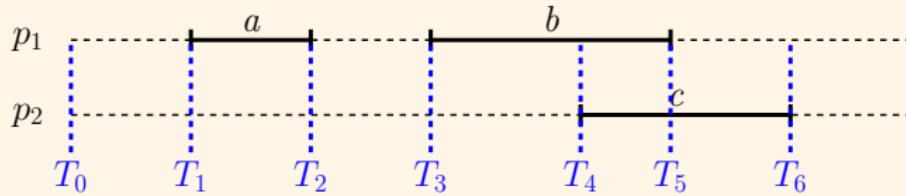
# Vector structure

$$\left[ \begin{array}{c} p_1 \\ \vdots \\ p_n \\ t \\ v_1 \\ \vdots \\ v_k \\ o_1 \\ \vdots \\ o_\ell \\ \alpha_1 \\ \vdots \\ \alpha_a \\ \nu_1 \\ \vdots \\ \nu_v \end{array} \right] \quad \begin{array}{l} \} \text{ processes} \\ \} \text{ type (here } \textit{read} \text{ or } \textit{write} \text{)} \\ \} \text{ input or output value} \\ \} \text{ object} \\ \} \text{ arbitration relation} \\ \} \text{ visibility} \end{array}$$

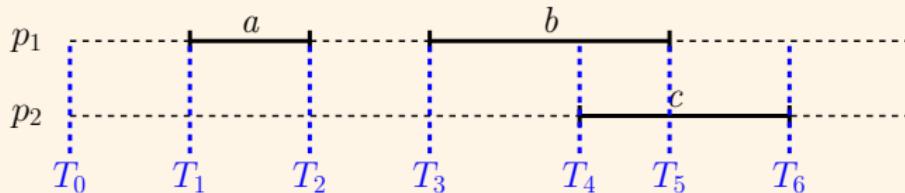
# Encoding histories as words



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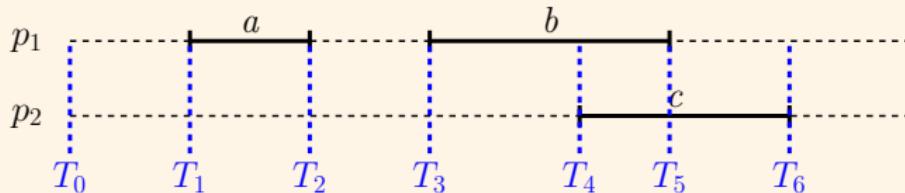


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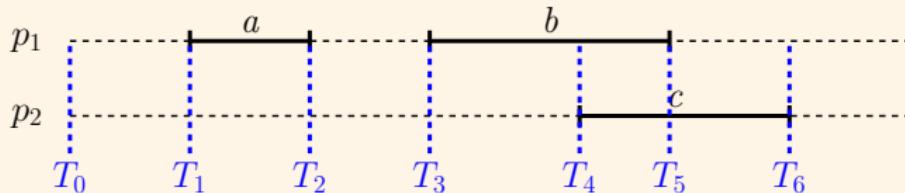
	$a$	$b$	$c$
$proc$	$p_1$	$p_1$	$p_2$
$stime$	$T_1$	$T_3$	$T_4$
$rtime$	$T_2$	$T_5$	$T_6$
$type$	<i>write</i>	<i>read</i>	<i>write</i>
$ival$	14	$\emptyset$	"fly"
$oval$	$\emptyset$	"bee"	$\emptyset$
$obj$	$y$	$x$	$x$

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	$a$	$b$	$c$
$proc$	$p_1$	$p_1$	$p_2$
$stime$	$T_1$	$T_3$	$T_4$
$rtime$	$T_2$	$T_5$	$T_6$
$type$	1	0	1
$ival$	00	$\emptyset$	10
$oval$	$\emptyset$	01	$\emptyset$
$obj$	1	0	0

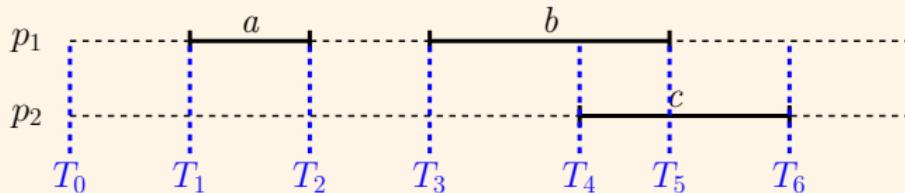
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$$\begin{matrix} T_0 \\ \left[ \begin{array}{c} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \vdots \end{array} \right] \end{matrix}$$

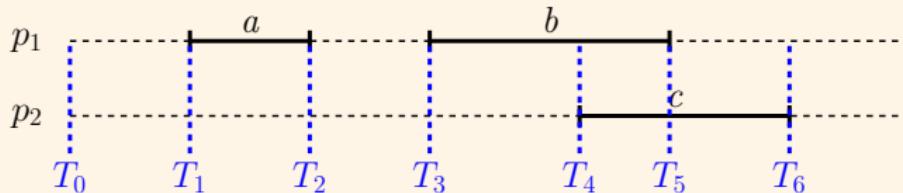
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$$\begin{bmatrix} T_0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \vdots \end{bmatrix}, \begin{bmatrix} T_1 \\ 1 \\ 0 \\ 1 \\ 0 \\ 0 \\ \vdots \end{bmatrix}$$

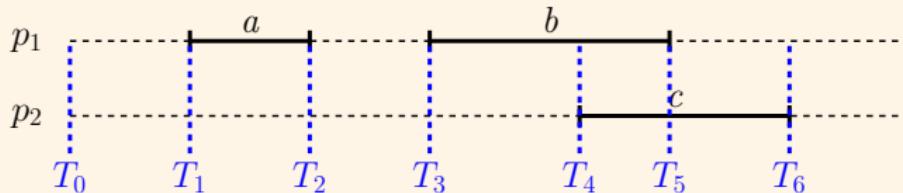
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$T_0$	$T_1$	$T_2$
0	1	0
0	0	0
0	1	0
0	0	0
0	0	0
0	1	0
⋮	⋮	⋮

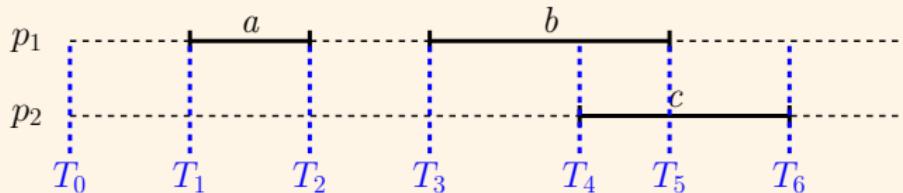
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$T_0$	$T_1$	$T_2$	$T_3$
0	1	0	1
0	0	0	0
0	1	0	0
0	0	0	0
0	0	0	1
0	1	0	0
⋮	⋮	⋮	⋮

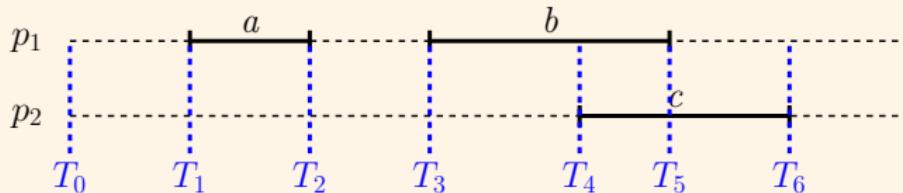
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$T_0$	$T_1$	$T_2$	$T_3$	$T_4$
0	1	0	1	1
0	0	0	0	1
0	1	0	0	1
0	0	0	0	1
0	0	0	1	0
0	1	0	0	0
⋮	⋮	⋮	⋮	⋮

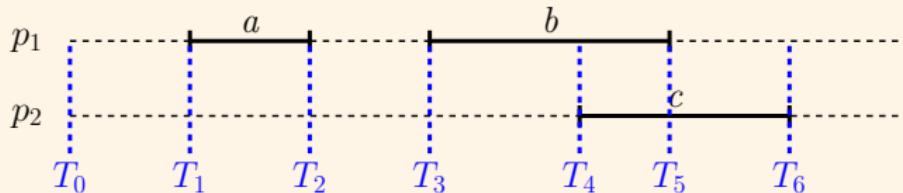
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$T_0$	$T_1$	$T_2$	$T_3$	$T_4$	$T_5$
0	1	0	1	1	0
0	0	0	0	1	1
0	1	0	0	1	0
0	0	0	0	1	0
0	0	0	1	0	0
0	1	0	0	0	0
:	:	:	:	:	:

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0	1	0	1	1	0	0
0	0	0	0	1	1	0
0	1	0	0	1	0	0
0	0	0	0	1	0	0
0	0	0	1	0	0	0
0	1	0	0	0	0	0
:	:	:	:	:	:	:

# Encoding arbitration

$$\begin{matrix} & p_1 & \dots & \dots & \dots & p_n \\ p_1 & \left[ \begin{array}{cccccc} 0 & \dots & \alpha_{12} & \dots & \dots & \alpha_{1n} \\ \vdots & \ddots & \ddots & \ddots & \ddots & \vdots \\ -\alpha_{12} & \ddots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \ddots & \vdots \\ p_n & -\alpha_{1n} & \dots & \dots & -\alpha_{(n-1)n} & 0 \end{array} \right] \\ \vdots & & & & & \end{matrix}$$

A variable  $\alpha_{ij}$  is set to 1 if the operation on process  $i$  is arbitrated before the operation on process  $j$ , and is set to 0 if not

# Encoding arbitration

$$\begin{array}{c} p_1 \dots p_n \\ \vdots \\ p_n \end{array} \left[ \begin{array}{cccccc} 0 & \dots & \alpha_{12} & \dots & \dots & \alpha_{1n} \\ \vdots & \ddots & \ddots & \ddots & \ddots & \vdots \\ -\alpha_{12} & \dots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \ddots & \vdots \\ -\alpha_{1n} & \dots & -\alpha_{(n-1)n} & \dots & 0 & \alpha_{(n-1)n} \end{array} \right] \quad \left[ \begin{array}{c} \alpha_{12} \\ \alpha_{13} \\ \alpha_{14} \\ \vdots \\ \alpha_{23} \\ \alpha_{24} \\ \vdots \\ \alpha_{(n-1)n} \end{array} \right]$$

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# Encoding visibility

A way to represent visibility with respect to an operation  $a$ , is to encode, for each process  $p$ , the most recent operation initiated on  $p$  that is visible to  $a$ .

$$\left[ \begin{array}{c} \# \\ \vdots \\ \# \\ p_{1,1} \\ \vdots \\ p_{1,S} \\ \vdots \\ p_{n,1} \\ \vdots \\ p_{n,S} \end{array} \right] \quad \left. \begin{array}{l} \text{previous encoding} \\ \text{most recent operation initiated on } p_1 \text{ that is visible to } a \\ \text{most recent operation initiated on } p_n \text{ that is visible to } a \end{array} \right\}$$

# Compiler

MSO of histories → MSO of words of bit vectors

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MSO of histories → MSO of words of bit vectors

## Input:

forall X. exists x. exists y. x in X and x.type=y.type

## Output:

```
var2 Process2;  
var2 Process1;  
var2 TypeRow;  
var2 ObjectRow1;  
var2 ValueRow1;  
pred op(var1 x)= x in Process2 & ex1 y: y + 1 = x & ~(y in  
Process2) | x in Process1 & ex1 y: y + 1 = x & ~(y in  
Process1);  
all2 X: ((all1 a: a in X => op(a)) => ex1 x: op(x) & ex1  
y: op(y) & x in X & (x in TypeRow <=> y in TypeRow));
```

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**Ongoing work:** compiler for translation (in OCaml)

**Future work:**

**First part:** extend to infinite histories (should be easy)

**Second part:** weaker assumptions (visibility and arbitration)

*Thank you*