Topology, symplectic topology, . . . What's next?

Ronen Brilleslijper & Oliver Fabert



O-dimensional objects

Morse theory on smooth manifolds



End

0-dimensional objects

Morse theory on smooth
manifolds



1-dimensional objects

Floer theory on symplectic manifolds





1-dimensional objects

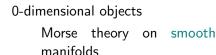
Floer theory on symplectic manifolds



2-dimensional objects

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Introduction





1-dimensional objects

Floer theory on symplectic manifolds



2-dimensional objects
Holomorphic symplectic? Polysymplectic?

Physics motivation

Introduction

0

Symplectic geometry
Mechanics

Physics motivation

Introduction

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Symplectic geometry
Mechanics

Polysymplectic geometry Field theory End

Physics motivation

Symplectic geometry Mechanics **ODEs**

Polysymplectic geometry Field theory

Physics motivation

Symplectic geometry Mechanics **ODEs**

Polysymplectic geometry Field theory **PDEs**

Physics motivation

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Two types of field theory

Minkowski Euclidean

Polysymplectic geometry Introduction

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Physics motivation

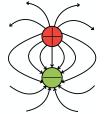
Two types of field theory

Minkowski

Electromagnetism

Wave equation

Hyperbolic PDEs



Euclidean

Physics motivation

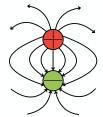
Two types of field theory

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Euclidean

Electrostatics

Laplace equation

Elliptic PDEs



Physics motivation

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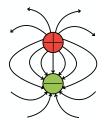
Introduction

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Electromagnetism

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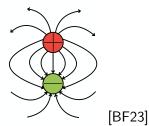
Introduction

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Electromagnetism

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Definition

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Polysymplectic geometry

Introduction

An \mathbb{R}^d -valued 2-form $\Omega = \sum_{i=1}^d \eta_i \otimes \partial_i$ on a manifold M is called a polysymplectic form if it is closed and non-degenerate

Definition

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Polysymplectic geometry

An \mathbb{R}^d -valued 2-form $\Omega = \sum_{i=1}^d \eta_i \otimes \partial_i$ on a manifold M is called a polysymplectic form if it is closed and non-degenerate in the sense that

$$\Omega^{\flat}: TM \to \operatorname{Hom}(TM, \mathbb{R}^d)$$

$$X \mapsto \Omega(X, \cdot)$$

is injective.

Definition

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Polysymplectic geometry

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is injective. Equivalently $\bigcap_i \ker \eta_i^{\flat} = 0$. Given a function $H: M \to \mathbb{R}$ a map $Z: \mathbb{R}^d \to M$ is called a solution if

$$\sum_{i=1}^d \eta_i(\cdot,\partial_i Z) = dH.$$

Example

Let
$$d=2$$
 and $M=\mathbb{R}^3\ni (q,p_1,p_2)$ with

$$\eta_1 = dp_1 \wedge dq$$

$$\eta_2 = dp_2 \wedge dq$$

Introduction

Let d=2 and $M=\mathbb{R}^3\ni (q,p_1,p_2)$ with

$$\eta_1 = dp_1 \wedge dq$$

$$\eta_2 = dp_2 \wedge dq$$

Then
$$Z = (q, p_1, p_2) : \mathbb{R}^2 \to \mathbb{R}^3$$
 is a solution of $H(q, p_1, p_2) = \frac{1}{2}p_1^2 + \frac{1}{2}p_2^2 + V(q)$ if

$$\begin{cases} -\partial_1 p_1 - \partial_2 p_2 &= V'(q) \\ \partial_1 q &= p_1 \\ \partial_2 q &= p_2 \end{cases}$$

Example

Introduction

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Polysymplectic geometry

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\end{cases}$$

$$\iff -(\partial_1^2 + \partial_2^2)q = V'(q)$$

Example (De Donder-Weyl equations)

Let d=2 and $M=\mathbb{R}^3\ni (q,p_1,p_2)$ with

$$\eta_1 = dp_1 \wedge dq \qquad \qquad \eta_2 = dp_2 \wedge dq$$

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Introduction

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Hamiltonians?

• $H: M \to \mathbb{R}$

Hamiltonians?

•
$$H: M \to \mathbb{R}$$
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Hamiltonians?

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ullet ???? \Longrightarrow vector field

Hamiltonians?

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$$H: M \to \mathbb{R}$$
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• $F: M \to \mathbb{R}^2$? \Longrightarrow vector field

Hamiltonians?

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$$H: M \to \mathbb{R}$$
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• $F: M \to \mathbb{R}^2$ vector field

Definition

A function $F: M \to \mathbb{R}^2$ is called a *current* if there exists a vector field X_F on M such that

$$\Omega(X_F,\cdot)=dF$$

Hamiltonians?

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$$H: M \to \mathbb{R}$$
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• $F \cdot M \rightarrow \mathbb{R}^2$ vector field

Definition

A function $F: M \to \mathbb{R}^2$ is called a *current* if there exists a vector field X_F on M such that

$$\Omega(X_F,\cdot)=dF$$

The flow of these vector fields preserve Ω .

√ Geometric framework for PDEs

- √ Geometric framework for PDEs
- √ Hamiltonian and Lagrangian formalism

- √ Geometric framework for PDEs
- √ Hamiltonian and Lagrangian formalism
- Action functional

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x No Darboux theorem

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- √ Hamiltonian and Lagrangian formalism
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- x No Darboux theorem
- X No holomorphic curve techniques

- √ Geometric framework for PDEs
- √ Hamiltonian and Lagrangian formalism
- √ Action functional

- x No Darboux theorem
- No holomorphic curve techniques
- x Not elliptic

Laplace equation

$$-(\partial_1^2 + \partial_2^2)q = \nabla V(q)$$
 $q = (q_1, q_2) : \mathbb{R}^2 \to \mathbb{R}^{2n}$

Laplace equation

$$egin{align} -(\partial_1^2+\partial_2^2)q &=
abla V(q) & q &= (q_1,q_2): \mathbb{R}^2
ightarrow \mathbb{R}^{2n} \ -4\partial_{\overline{t}}\partial_t q &=
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End

Laplace equation

Introduction

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De Donder-Weyl: 4 momentum vectors $p_i^{\alpha} = \partial_{\alpha} q_i$

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$$p_1 = \partial_1 q_1 + \partial_2 q_2$$
$$p_2 = \partial_1 q_2 - \partial_2 q_1$$

Rigidity

Application

Laplace equation

Polysymplectic geometry

Introduction

$$-(\partial_1^2 + \partial_2^2)q = \nabla V(q)$$
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$$\partial_{q_1} V = -\partial_1 p_1 + \partial_2 p_2$$

$$\partial_{q_2} V = -\partial_1 p_2 - \partial_2 p_1$$

Laplace equation

Introduction

$$-(\partial_1^2 + \partial_2^2)q = \nabla V(q)$$
 $q = (q_1, q_2) : \mathbb{R}^2 \to \mathbb{R}^{2n}$ $-4\partial_{\overline{t}}\partial_t q = \nabla V(q)$ $\partial_t = \frac{1}{2}(\partial_1 - i\partial_2)$

De Donder-Weyl: 4 momentum vectors $p_i^{\alpha} = \partial_{\alpha} q_i$ Only need: $p = 2\partial_t q_i$, $-2\partial_{\overline{t}} p = \nabla V(q)$

$$\partial Z := \begin{pmatrix} 0 & -2\partial_{\overline{t}} \\ 2\partial_t & 0 \end{pmatrix} Z = \nabla H(Z),$$

where

$$Z=(q,p):\mathbb{R}^2 o\mathbb{R}^{4n}$$
 $H(q,p)=rac{1}{2}|p|^2+V(q)$

Polysymplectic formulation

$$\mathscr{J}Z:=egin{pmatrix} 0 & -2\partial_{\overline{t}} \ 2\partial_t & 0 \end{pmatrix}Z=
abla \mathcal{H}(Z) \qquad Z=(q_1,q_2,p_1,p_2)$$

$$\mathscr{D}Z := \begin{pmatrix} 0 & -2\partial_{\overline{t}} \\ 2\partial_t & 0 \end{pmatrix} Z = \nabla H(Z) \qquad Z = (q_1, q_2, p_1, p_2)$$

Define $\Omega = \omega_1 \otimes \partial_1 + \omega_2 \otimes \partial_2$ for

$$\omega_1 = dp_1 \wedge dq_1 + dp_2 \wedge dq_2$$
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Polysymplectic formulation

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The Dirac equation is equivalent to

$$\omega_1(\cdot,\partial_1 Z) + \omega_2(\cdot,\partial_2 Z) = dH$$

Define $\Omega = \omega_1 \otimes \partial_1 + \omega_2 \otimes \partial_2$ for

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 $\omega_2 = dp_1 \wedge dq_2 - dp_2 \wedge dq_1$

Note

Introduction

• Both ω_1 and ω_2 are symplectic forms related by $\omega_2 = -\omega_1(\cdot, I \cdot)$, where

$$I = \begin{pmatrix} i & 0 \\ 0 & i^* \end{pmatrix} = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix}$$

on
$$\mathbb{R}^{4n} = \mathbb{R}^{2n} \times (\mathbb{R}^{2n})^*$$
.

Polysymplectic formulation

Define $\Omega = \omega_1 \otimes \partial_1 + \omega_2 \otimes \partial_2$ for

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on $\mathbb{R}^{4n} = \mathbb{R}^{2n} \times (\mathbb{R}^{2n})^*$.

• Let $\omega^{\mathbb{C}} = dp \wedge dq = \omega_1 + i\omega_2$, then

$$\Omega = \omega^{\mathbb{C}} \otimes \partial_t + \bar{\omega}^{\mathbb{C}} \otimes \partial_{\bar{t}}.$$

Introduction

Definition (B.-F. '24)

Let (W,I) a complex manifold. An \mathbb{R}^2 -valued polysymplectic form $\Omega = \omega_1 \otimes \partial_1 + \omega_2 \otimes \partial_2$ on W is called *complex-regularized* if $\omega_2 = -\omega_1(\cdot,I\cdot)$.

Introduction

Definition (B.-F. '24)

Let (W,I) a complex manifold. An \mathbb{R}^2 -valued polysymplectic form $\Omega = \omega_1 \otimes \partial_1 + \omega_2 \otimes \partial_2$ on W is called *complex-regularized* if $\omega_2 = -\omega_1(\cdot,I\cdot)$.

The triple (W, I, Ω) is called a *complex-regularized polysymplectic* (CRPS) manifold.

Application

End

Example

Introduction

Let (Q, i) a complex manifold and $W = T^*Q$ with induced complex structure I.

End

Example

Introduction

Let (Q, i) a complex manifold and $W = T^*Q$ with induced complex structure *I*. Note $\pi: T^*Q \to Q$ is holomorphic.

Example

Let (Q, i) a complex manifold and $W = T^*Q$ with induced complex structure *I*. Note $\pi: T^*Q \to Q$ is holomorphic. For $Z = (q, p) \in W$ and $X \in T_7W$ define

$$(\theta_1)_Z(X) = p \circ d\pi(X)$$

$$(\theta_2)_Z(X) = p \circ d\pi(IX).$$

Rigidity

Application

End

Example

Introduction

Polysymplectic geometry

Let (Q, i) a complex manifold and $W = T^*Q$ with induced complex structure I. Note $\pi: T^*Q \to Q$ is holomorphic. For $Z = (q, p) \in W$ and $X \in T_Z W$ define

$$(\theta_1)_Z(X) = p \circ d\pi(X)$$

$$(\theta_2)_Z(X) = p \circ d\pi(IX).$$

Then $\Omega = d\theta_1 \otimes \partial_1 - d\theta_2 \otimes \partial_2$ is CRPS on (W, I).

First properties

Lemma

Let $(W, I, \Omega = \omega_1 \otimes \partial_1 + \omega_2 \otimes \partial_2)$ a CRPS manifold. Then both ω_1 and ω_2 are symplectic forms.

First properties

Lemma

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Proof idea: Since
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$$\ker \omega_1^\flat = \ker \omega_2^\flat.$$

First properties

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Proof idea: Since $\omega_2 = -\omega_1(\cdot, I \cdot)$

$$\ker \omega_1^\flat = \ker \omega_2^\flat.$$

So Ω being non-degenerate implies $\ker \omega_1^\flat = \ker \omega_2^\flat = 0$.

End

First properties

Lemma

Let $(W, I, \Omega = \omega_1 \otimes \partial_1 + \omega_2 \otimes \partial_2)$ a CRPS manifold. Then both ω_1 and ω_2 are symplectic forms.

Lemma

Let $\psi: (W, I, \Omega) \to (W', I', \Omega')$ a diffeomorphism between CRPS manifolds, such that

$$\psi^*\Omega'=\Omega.$$

Then ψ is holomorphic with respect to I and I'.

Quick recap

Introduction

Definition

A holomorphic 2-form $\omega^{\mathbb{C}}$ on a complex manifold (W, I) is called a holomorphic symplectic form if it is closed and its restriction to $T^{(1,0)}W$ is non-degenerate.

Quick recap

Introduction

Definition

A holomorphic 2-form $\omega^{\mathbb{C}}$ on a complex manifold (W,I) is called a holomorphic symplectic form if it is closed and its restriction to $T^{(1,0)}W$ is non-degenerate.

A holomorphic Hamiltonian system is a tuple $(W, I, \omega^{\mathbb{C}}, F)$, where $F:W\to\mathbb{C}$ is holomorphic.

Quick recap

Introduction

Definition

A holomorphic 2-form $\omega^{\mathbb{C}}$ on a complex manifold (W, I) is called a holomorphic symplectic form if it is closed and its restriction to $T^{(1,0)}W$ is non-degenerate.

A holomorphic Hamiltonian system is a tuple $(W, I, \omega^{\mathbb{C}}, F)$, where $F:W\to\mathbb{C}$ is holomorphic. It induces a holomorphic vector field \mathcal{X}_{F} by

$$\omega^{\mathbb{C}}(\mathcal{X}_{F},\cdot)=dF.$$

Relation to CRPS manifolds

Proposition

Introduction

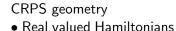
For a complex manifold (W, I) there is a bijection

 $\{CRPS \text{ forms}\} \stackrel{1-1}{\longleftrightarrow} \{\text{holomorphic symplectic forms}\}$

Given by

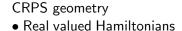
$$\omega_1 \otimes \partial_1 + \omega_2 \otimes \partial_2 \mapsto \omega_1 + i\omega_2$$
$$\omega^{\mathbb{C}} \otimes \partial_t + \bar{\omega}^{\mathbb{C}} \otimes \partial_{\bar{t}} \longleftrightarrow \omega^{\mathbb{C}}$$

Holomorphic symplectic geometry



Holomorphic symplectic geometry

End



Introduction

Holomorphic symplectic geometry
• Holomorphic Hamiltonians

Application

End

Introduction

- Real valued Hamiltonians
- Holomorphic symplectic geometryHolomorphic Hamiltonians
- **Recall:** $F:(W,I,\Omega)\to\mathbb{R}^2$ is a current if there exists X_F such that $\Omega(X_F,\cdot)=dF$.

Real valued Hamiltonians

Holomorphic symplectic geometry

Holomorphic Hamiltonians

Holomorphic symplectic geometry

Recall: $F:(W,I,\Omega)\to\mathbb{R}^2$ is a current if there exists X_F such that $\Omega(X_F,\cdot)=dF$.

Lemma

Introduction

Let $(W, I, \omega_1 \otimes \partial_1 + \omega_2 \otimes \partial_2)$ a CRPS manifold and $\omega^{\mathbb{C}} = \omega_1 + i\omega_2$. By identifying $\mathbb{R}^2 \cong \mathbb{C}$ and $TW \cong T^{(1,0)}W$ we get that $F:W\to\mathbb{R}^2\cong\mathbb{C}$ is a current if and only if it is a holomorphic function.

Real valued Hamiltonians

Holomorphic symplectic geometry

• Holomorphic Hamiltonians

Recall: $F:(W,I,\Omega)\to\mathbb{R}^2$ is a current if there exists X_F such that $\Omega(X_F,\cdot)=dF$.

Lemma

Introduction

Let $(W, I, \omega_1 \otimes \partial_1 + \omega_2 \otimes \partial_2)$ a CRPS manifold and $\omega^{\mathbb{C}} = \omega_1 + i\omega_2$. By identifying $\mathbb{R}^2 \cong \mathbb{C}$ and $TW \cong T^{(1,0)}W$ we get that $F: W \to \mathbb{R}^2 \cong \mathbb{C}$ is a current if and only if it is a holomorphic function. In this case $X_F = \mathcal{X}_F$.

Darboux theorem

Corollary

Introduction

Let (W, I, Ω) a CRPS manifold. Around every point in W there exist coordinates $\{q_1^{\alpha}, q_2^{\alpha}, p_1^{\alpha}, p_2^{\alpha}\}$ where $\alpha = 1, \dots, n$ such that

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$$I\frac{\partial}{\partial q_1^{\alpha}} = \frac{\partial}{\partial q_2^{\alpha}} \qquad \qquad I\frac{\partial}{\partial p_1^{\alpha}} = -\frac{\partial}{\partial p_2^{\alpha}}$$

and

$$egin{aligned} \omega_1 &= \sum_lpha \left(dp_1^lpha \wedge dq_1^lpha + dp_2^lpha \wedge dq_2^lpha
ight) \ \omega_2 &= \sum_lpha \left(dp_1^lpha \wedge dq_2^lpha - dp_2^lpha \wedge dq_1^lpha
ight). \end{aligned}$$

Darboux theorem

Corollary

Introduction

$$I\frac{\partial}{\partial q_1^{\alpha}} = \frac{\partial}{\partial q_2^{\alpha}} \qquad I\frac{\partial}{\partial p_1^{\alpha}} = -\frac{\partial}{\partial p_2^{\alpha}}$$

and

$$egin{aligned} \omega_1 &= \sum_lpha \left(extit{d} p_1^lpha \wedge extit{d} q_1^lpha + extit{d} p_2^lpha \wedge extit{d} q_2^lpha
ight) \ \omega_2 &= \sum_lpha \left(extit{d} p_1^lpha \wedge extit{d} q_2^lpha - extit{d} p_2^lpha \wedge extit{d} q_1^lpha
ight). \end{aligned}$$

Proof: Follows from the Darboux theorem for holomorphic symplectic manifolds (see thesis of Wagner for proof).

End

Action functional

Assume $\Omega = d\Theta$ on W is exact.

Action functional

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Let $d\mathcal{V}=dt_1\wedge dt_2=-\frac{1}{2i}dt\wedge d\bar{t}$ the volume form on \mathbb{T}^2 .

Introduction

Assume $\Omega = d\Theta$ on W is exact.

Let $d\mathcal{V} = dt_1 \wedge dt_2 = -\frac{1}{2i}dt \wedge d\bar{t}$ the volume form on \mathbb{T}^2 .

Contract $\Theta = \theta_1 \otimes \partial_1 + \theta_2 \otimes \partial_2$ with $d\mathcal{V}$ to give

$$ilde{\Theta} = heta_1 \wedge dt_2 - heta_2 \wedge dt_1 \in \Lambda^2\left(W imes \mathbb{T}^2
ight).$$

Introduction

Polysymplectic geometry

Let $d\mathcal{V} = dt_1 \wedge dt_2 = -\frac{1}{2i}dt \wedge d\bar{t}$ the volume form on \mathbb{T}^2 . Contract $\Theta = \theta_1 \otimes \partial_1 + \theta_2 \otimes \partial_2$ with $d\mathcal{V}$ to give

$$\tilde{\Theta} = \theta_1 \wedge \textit{dt}_2 - \theta_2 \wedge \textit{dt}_1 \in \Lambda^2 \left(\textit{W} \times \mathbb{T}^2 \right).$$

For $Z: \mathbb{T}^2 \to W$ define $\tilde{Z} = Z \times \text{id} : \mathbb{T}^2 \to W \times \mathbb{T}^2$ and

$$egin{aligned} \mathcal{A}(Z) &= \int_{\mathbb{T}^2} ilde{\mathcal{Z}}^* ilde{\Theta} \ &= \int_{\mathbb{T}^2} \left(heta_1(\partial_1 Z) + heta_2(\partial_2 Z)
ight) \ d\mathcal{V} \end{aligned}$$

End

Action functional

$$\mathcal{A}(Z) = \int_{\mathbb{T}^2} ig(heta_1(\partial_1 Z) + heta_2(\partial_2 Z)ig) \; d\mathcal{V}$$

End

Introduction

Action functional

$$\mathcal{A}(Z) = \int_{\mathbb{T}^2} \left(heta_1(\partial_1 Z) + heta_2(\partial_2 Z) \right) \ d\mathcal{V}$$

• The action is real-valued so we may study its gradient lines.

Introduction

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Holomorphic symplectic geometry

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Gradient lines are given by the Fueter equation

$$I\partial_5 Z + K\partial_1 Z - J\partial_2 Z = 0.$$

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Theorem (B.-F. '24)

Let $Q = \mathbb{T}^{2n}$ and $W = T^*Q$ with the standard CRPS form $\omega_1 \otimes \partial_1 + \omega_2 \otimes \partial_2$.

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Let $Q=\mathbb{T}^{2n}$ and $W=T^*Q$ with the standard CRPS form

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If $H: \mathbb{T}^2 \times W \to \mathbb{R}$ is given by $H(t, q, p) = \frac{1}{2}|p|^2 + h(t, q, p)$ for $h: \mathbb{T}^2 \times W \to \mathbb{R}$ smooth with finite C^2 -norm,

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has at least (2n+1) solutions.

Holomorphic symplectic geometry

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Corollary

When $V: Q \to \mathbb{R}$ has finite C^2 -norm then $-\Delta g = \nabla V(g)$ has at least (2n+1) solutions.

Overview of proof of Arnold conjecture

Follows from studying Floer curves

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$$\partial_s Z + J \partial_1 Z + K \partial_2 Z = \nabla H(Z).$$

- C⁰-bounds for solutions and for Floer curves.
- Moduli space of Floer curves is a compact 1-dimensional manifold for generic choice of h.
- Rest of the proof follows the line of reasoning of the cuplength results from Albers-Hein.

End

Non-squeezing

Introduction

Let $(W, I, \Omega = \omega_1 \otimes \partial_1 + \omega_2 \otimes \partial_2)$ a CRPS manifold and $\psi:W\to W$ a diffeomorphism.

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Theorem

Let $\psi: \mathbb{R}^{4n} \to \mathbb{R}^{4n}$ a diffeomorphism preserving Ω such that

$$\psi(B_r^{4n}) \subseteq B_R^2 \times \mathbb{R}^{4n-2}$$

where B_R^2 is the R-ball in the $(q_i^{\alpha}, p_j^{\alpha})$ -plane for some $i, j \in \{1, 2\}$ and $\alpha \in \{1, \ldots, n\}$.

Then $r \leq R$.

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Corollary

Let $\psi_{\nu}:W\to W$ a sequence of diffeomorphisms preserving Ω that converge to a diffeomorphism $\psi:W\to W$ in the C^0 -limit. Then $\psi^*\Omega = \Omega$.

Question: Given a holomorphic symplectic manifold $(W^{4n}, \omega^{\mathbb{C}})$ and a closed complex manifold L^{2n} , is there a holomorphic embedding $\iota: L \hookrightarrow W$ such that $\iota^*\omega^{\mathbb{C}} = 0$.

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Real symplectic manifolds

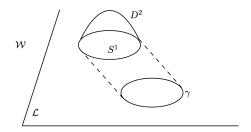
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Real symplectic manifolds

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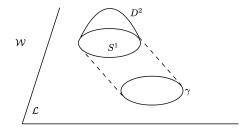


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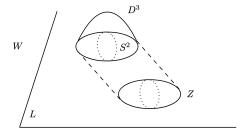


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Morse theory of minimal spheres on L



Harmonic maps \rightarrow holomorphic Lagrangians

Question: Given a Kähler manifold (Q, i, g), does there exist a minimal surface $\Sigma \to Q$ with boundary $\partial \Sigma$ in some submanifold $\Gamma \subset Q$?

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Existence of geodesics with boundary on $\Gamma \subseteq Q$ $H(q,p) = \frac{1}{2}|p|_{g}^{2} \text{ on } T^{*}Q$ Boundary fixed to the conormal bundle $N^*\Gamma \subset T^*Q$

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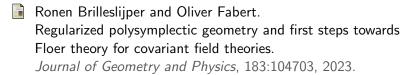
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Minimal surface case

Existence of harmonic maps with boundary on $\Gamma \subseteq Q$ $H(q,p) = \frac{1}{2}|p|_{g}^{2} \text{ on } T^{*}Q$ Boundary fixed to the conormal bundle $N^*\Gamma \subset T^*Q \rightarrow$ holomorphic Lagrangian if Γ is a complex submanifold

Introduction

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Thank you!

