

PENEX: AdaBoost-Inspired Neural Network Regularization



Friday Talk

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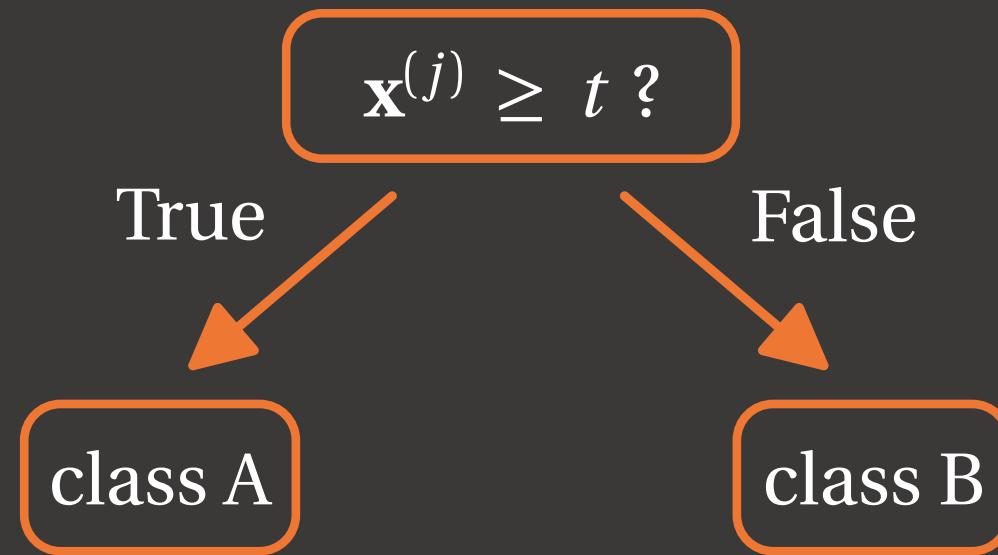
What loss do you use to train your classifier?*



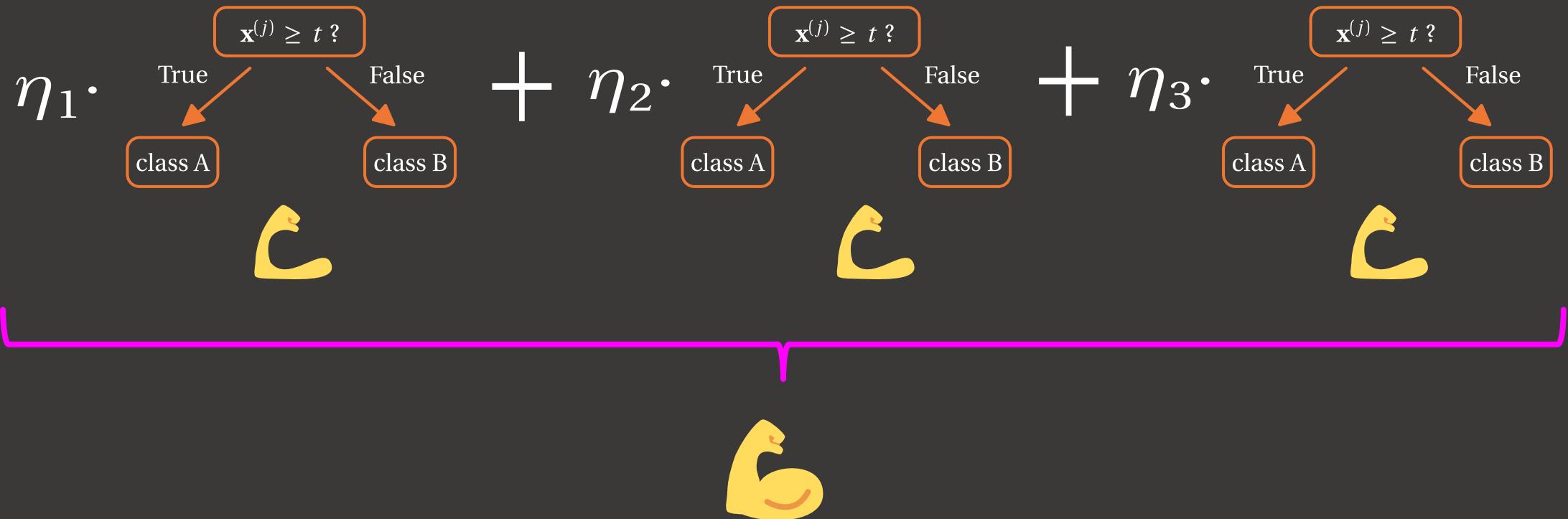
What is AdaBoost?



Weak learner



Constructing a strong learner



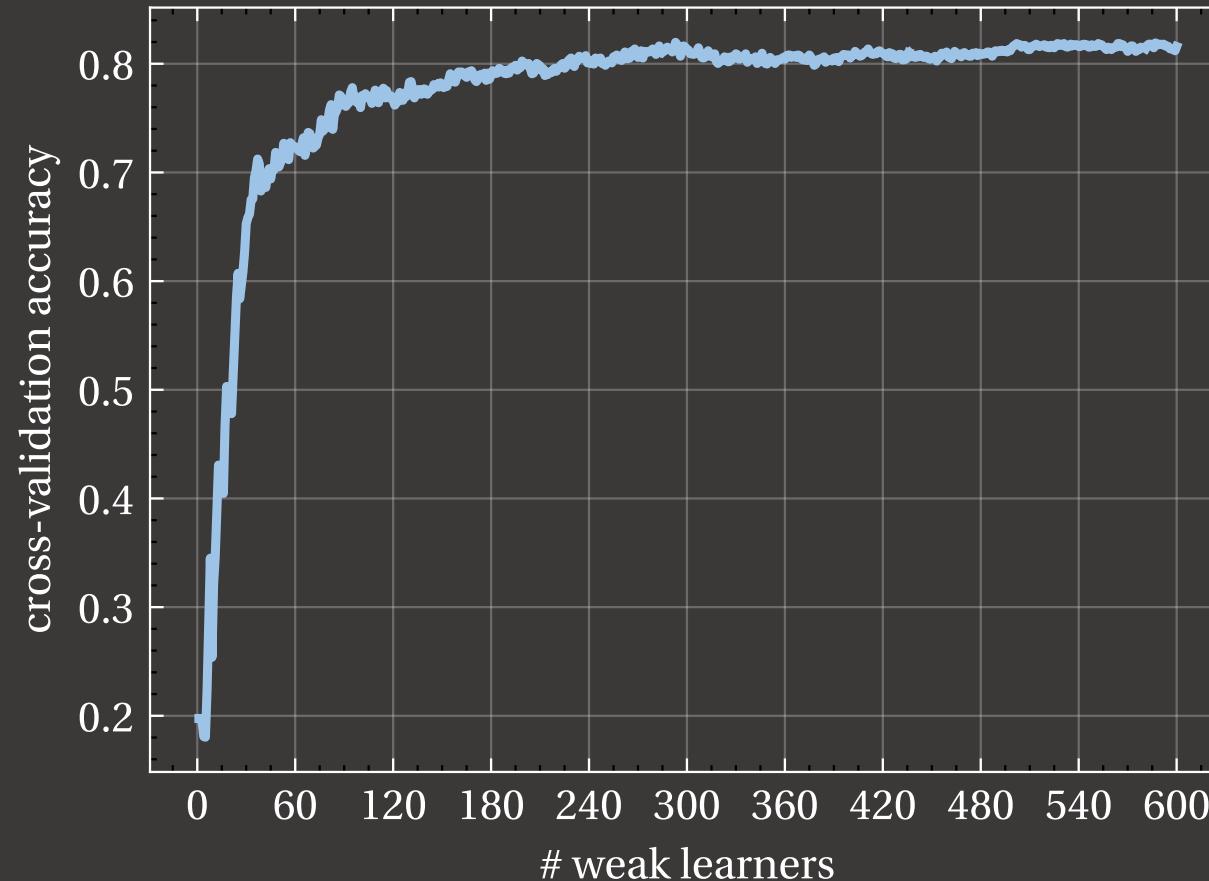
Optimization objective: exponential loss

$$\textcolor{violet}{f}(\mathbf{x}) = \sum_{i=1}^N \eta_i \textcolor{brown}{g}_i(\mathbf{x})$$

$\textcolor{brown}{g}_i$ greedily minimize

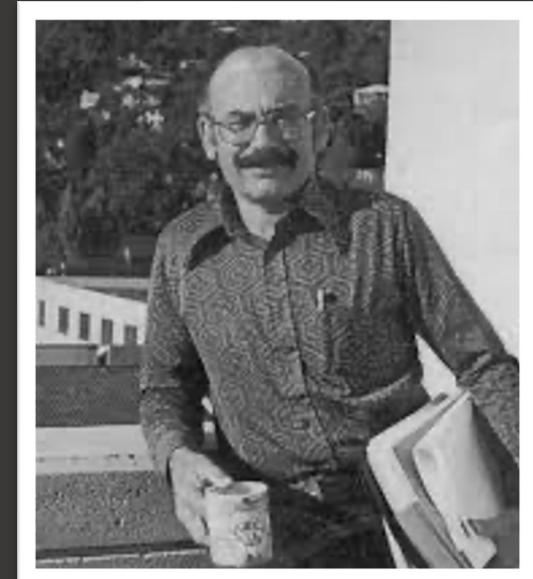
$$\hat{\mathbb{E}}[\exp\{-yf(\mathbf{x})\}], \quad y \in \{-1, 1\}$$

AdaBoost is resilient to “overfitting”



“[AdaBoost with trees is] the best off-the-shelf classifier in the world.”

- Leo Breiman



Can we translate the “AdaBoost magic” to neural networks?



Multiclass exponential loss

Constraints

Penalized exponential loss (PENEX)

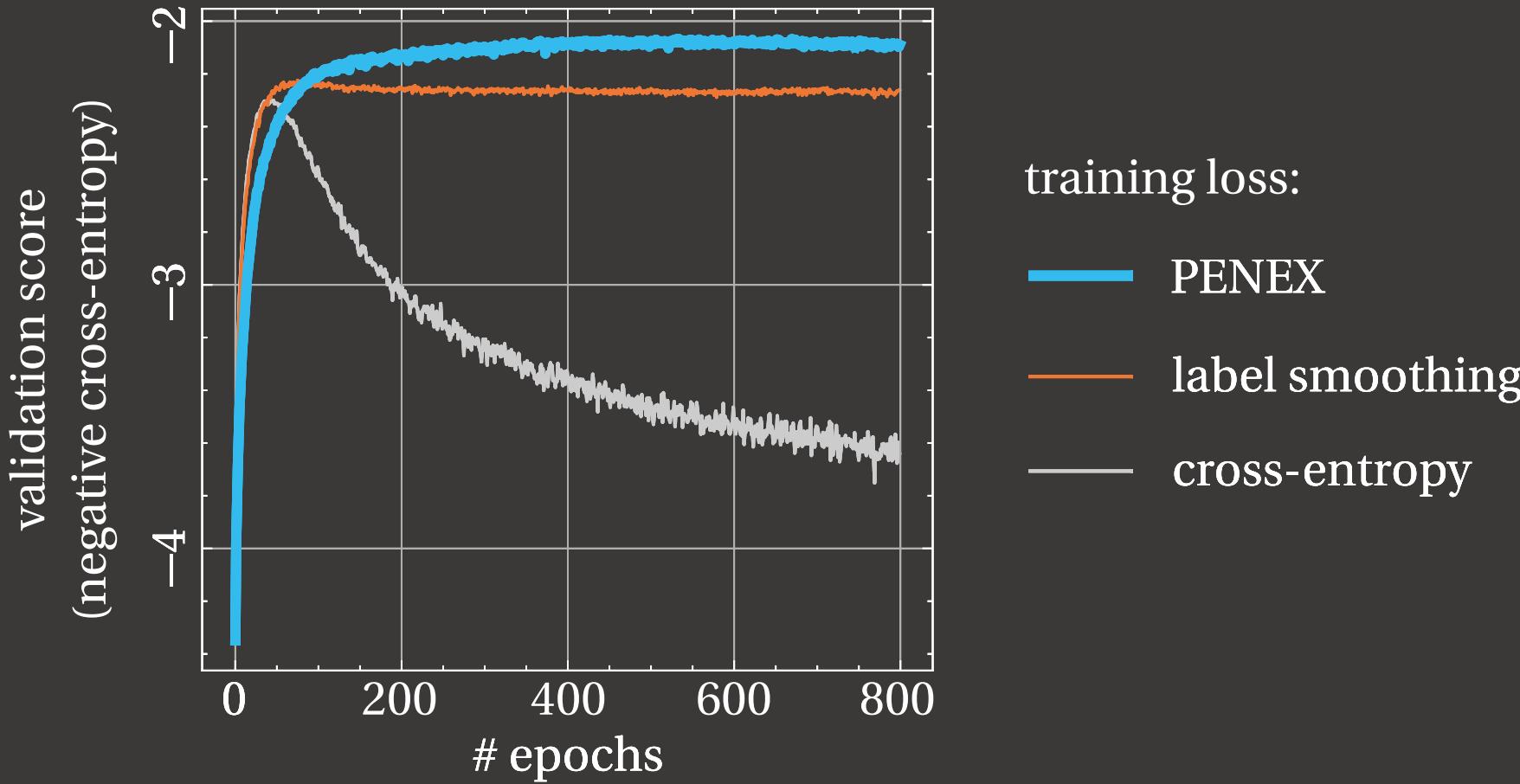
$$\hat{\mathbb{E}} \left[\underbrace{\exp \{-\alpha f^{(y)}(\mathbf{x})\}}_{\text{exponential loss}} + \rho \sum_{j=1}^K \exp \{f^{(j)}(\mathbf{x})\} \right]$$

prevents logits from
diverging

No constraints!



... and it works 🔥



PENEX often works better than other methods

| Method | Metric | CIFAR-10 | Noisy CIFAR-10 | CIFAR-100 | PathMNIST | BBC News |
|--------------------|--------|--------------------------------------|--------------------------------------|--------------------------------------|--------------------------------------|--------------------------------------|
| CE | ACC | 0.785 ± 0.004 | 0.724 ± 0.004 | 0.443 ± 0.004 | 0.826 ± 0.004 | 0.967 ± 0.007 |
| | -ECE | -0.162 ± 0.003 | -0.179 ± 0.003 | -0.287 ± 0.003 | -0.151 ± 0.004 | $\textcolor{blue}{-0.032} \pm 0.006$ |
| | -CE | -1.004 ± 0.024 | -1.125 ± 0.019 | -3.072 ± 0.034 | -2.018 ± 0.130 | -0.109 ± 0.024 |
| | -BRIER | -0.346 ± 0.006 | -0.424 ± 0.006 | -0.794 ± 0.006 | -0.300 ± 0.007 | -0.051 ± 0.011 |
| label smoothing | ACC | 0.789 ± 0.004 | 0.747 ± 0.004 | 0.451 ± 0.005 | 0.829 ± 0.004 | 0.970 ± 0.006 |
| | -ECE | -0.112 ± 0.002 | -0.183 ± 0.003 | $\textcolor{blue}{-0.147} \pm 0.002$ | -0.109 ± 0.002 | -0.033 ± 0.006 |
| | -CE | -0.657 ± 0.011 | -0.889 ± 0.008 | -2.292 ± 0.019 | $\textcolor{blue}{-0.589} \pm 0.012$ | -0.115 ± 0.022 |
| | -BRIER | -0.300 ± 0.005 | -0.384 ± 0.004 | -0.692 ± 0.004 | -0.255 ± 0.005 | -0.049 ± 0.010 |
| confidence penalty | ACC | 0.786 ± 0.004 | 0.733 ± 0.004 | 0.449 ± 0.006 | 0.828 ± 0.004 | $\textcolor{blue}{0.974} \pm 0.006$ |
| | -ECE | -0.130 ± 0.002 | -0.149 ± 0.003 | -0.152 ± 0.002 | -0.110 ± 0.003 | -0.050 ± 0.005 |
| | -CE | -0.731 ± 0.015 | -0.866 ± 0.009 | -2.254 ± 0.018 | -0.917 ± 0.047 | -0.094 ± 0.015 |
| | -BRIER | -0.317 ± 0.005 | -0.385 ± 0.004 | -0.695 ± 0.005 | -0.262 ± 0.005 | $\textcolor{blue}{-0.042} \pm 0.008$ |
| focal loss | ACC | 0.778 ± 0.004 | 0.708 ± 0.004 | 0.428 ± 0.005 | 0.803 ± 0.004 | 0.970 ± 0.006 |
| | -ECE | -0.117 ± 0.002 | -0.165 ± 0.003 | -0.161 ± 0.003 | -0.112 ± 0.003 | -0.051 ± 0.005 |
| | -CE | -0.661 ± 0.010 | -0.905 ± 0.008 | -2.341 ± 0.022 | -0.939 ± 0.050 | $\textcolor{blue}{-0.092} \pm 0.014$ |
| | -BRIER | -0.313 ± 0.005 | -0.423 ± 0.004 | -0.723 ± 0.005 | -0.291 ± 0.006 | $\textcolor{blue}{-0.042} \pm 0.008$ |
| PENEX | ACC | $\textcolor{blue}{0.793} \pm 0.004$ | $\textcolor{blue}{0.766} \pm 0.004$ | 0.460 ± 0.005 | 0.833 ± 0.004 | 0.968 ± 0.006 |
| | -ECE | $\textcolor{blue}{-0.109} \pm 0.002$ | $\textcolor{blue}{-0.131} \pm 0.002$ | $\textcolor{blue}{-0.147} \pm 0.003$ | $\textcolor{blue}{-0.100} \pm 0.003$ | -0.034 ± 0.006 |
| | -CE | $\textcolor{blue}{-0.646} \pm 0.012$ | $\textcolor{blue}{-0.716} \pm 0.009$ | $\textcolor{blue}{-2.140} \pm 0.018$ | -1.200 ± 0.089 | -0.124 ± 0.025 |
| | -BRIER | $\textcolor{blue}{-0.299} \pm 0.005$ | $\textcolor{blue}{-0.332} \pm 0.004$ | $\textcolor{blue}{-0.685} \pm 0.004$ | $\textcolor{blue}{-0.251} \pm 0.006$ | -0.055 ± 0.011 |

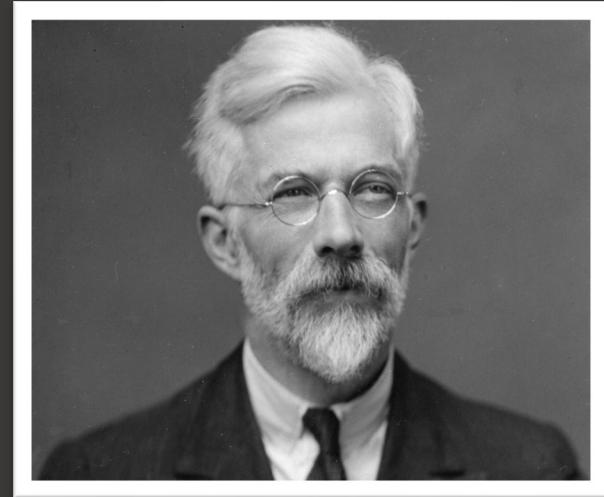
Theoretical properties of PENEX



Fisher consistency

“When applied to the whole population the derived statistic should be equal to the parameter.”

- Ronald A. Fisher



PENEX is Fisher consistent

$$\hat{\mathbb{E}} \left[\exp \left\{ -\alpha f^{(y)}(\mathbf{x}) \right\} + \rho \sum_{j=1}^K \exp \left\{ f^{(j)}(\mathbf{x}) \right\} \right]$$

PENEX is Fisher consistent

$$\mathbb{E} \left[\exp \left\{ -\alpha f^{(y)}(\mathbf{x}) \right\} + \rho \sum_{j=1}^K \exp \left\{ f^{(j)}(\mathbf{x}) \right\} \right]$$

Minimize w.r.t. $f \rightarrow f_*$

$$P(y | \mathbf{x}) \propto \exp \left\{ (1 + \alpha) f_*^{(y)}(\mathbf{x}) \right\}, \quad \forall \mathbf{x}$$

Common regularizers fail Fisher consistency

$$\mathcal{L}_{\text{CE}}(f) + \lambda \Omega(f)$$

Encompasses label smoothing, L2 regularization, confidence penalty, ...

Intuition: Regularization term $\Omega(f)$ pushes the solution off the Bayes-optimal predictor

$\mathcal{L}_{\text{PENEX}}(f)$ $\mathcal{L}_{\text{CE}}(f) + \lambda \Omega(f)$ 

(nice car with five seats)

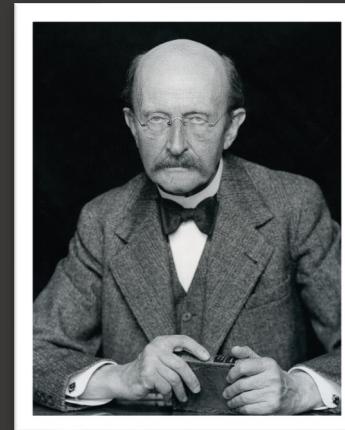


(nice car with two seats
and two extra seats
mounted on top)

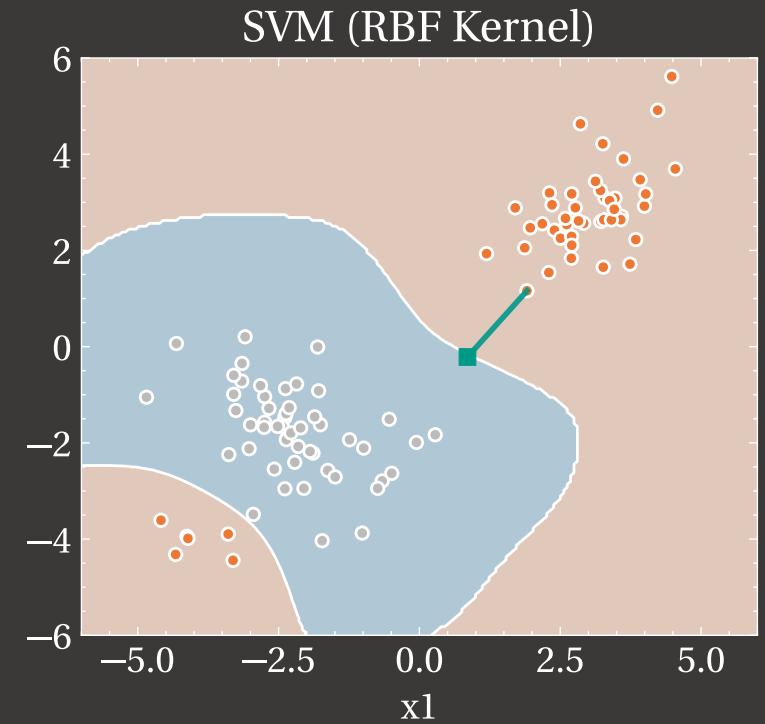
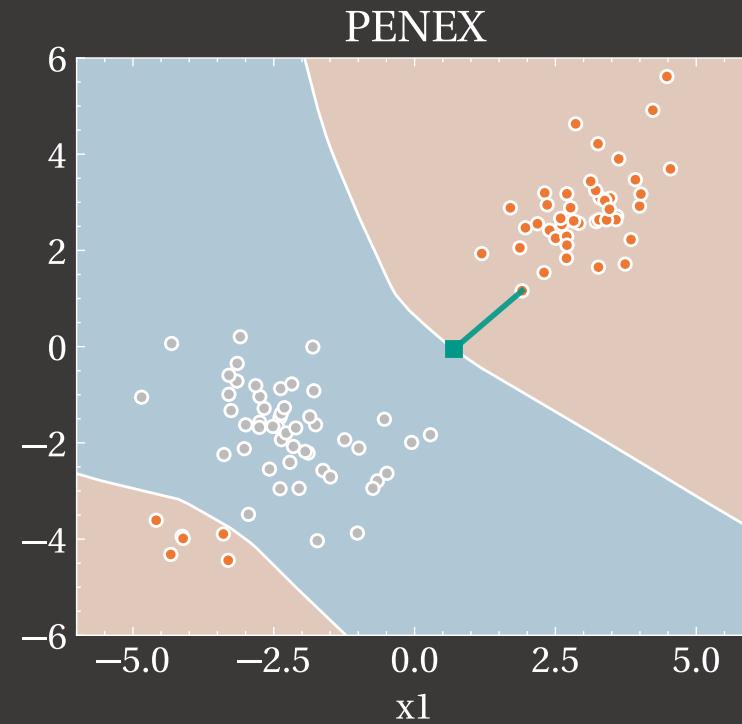
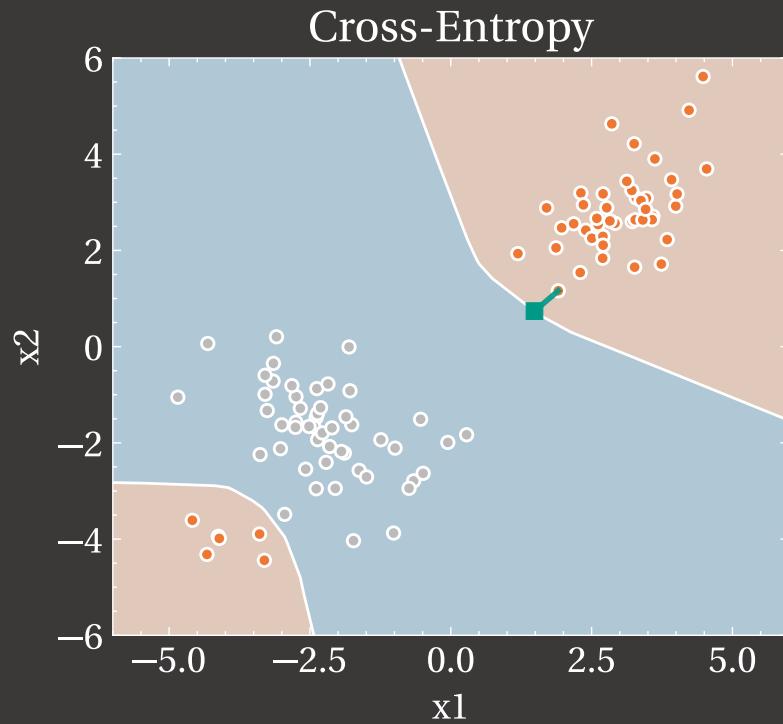
So why does it work?

“Insight must precede application.”

- Max Planck



Implicit margin maximization



PENEX provably maximizes margins

Defining the margin for example (\mathbf{x}, y) as

$$m_f(\mathbf{x}, y) := f^{(y)}(\mathbf{x}) - \max_{j \neq y} f^{(j)}(\mathbf{x}),$$

we show that

$$\mathbb{P}(m_f(\mathbf{x}, y) \leq \gamma) \leq e^{\gamma \frac{\alpha}{\alpha+1}} \rho^{-\frac{\alpha}{\alpha+1}} \mathbb{E}[\mathcal{L}_{\text{PENEX}}(f; \alpha, \rho)].$$

Key take-aways



- The “AdaBoost magic” can be translated to NNs
- Regularization is not at odds with Fisher consistency
- PENEX implicitly maximizes margins
- Let’s question the very foundations!

Preprint:



Code: 

