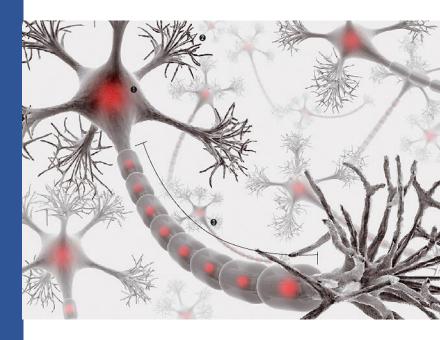
# (RNN) 옷 이미지 분류

## 학습 목표

• 운동화나 셔츠 같은 옷 이미지를 분류하는 RNN 신경망 모델을 만들어 본다.



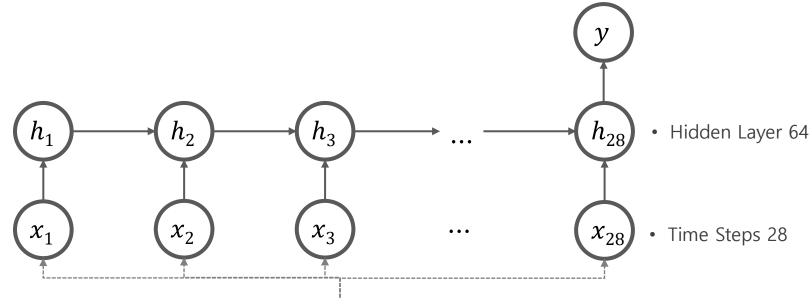
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# 문제



## CNN으로 개발된 Fashion MNIST 모델을 다음의 RNN 모델을 바꿔보자!

 $y = (y_1, y_2, y_3, ..., y_{10})$  0에서 9까지의 클래스에 속할 확률

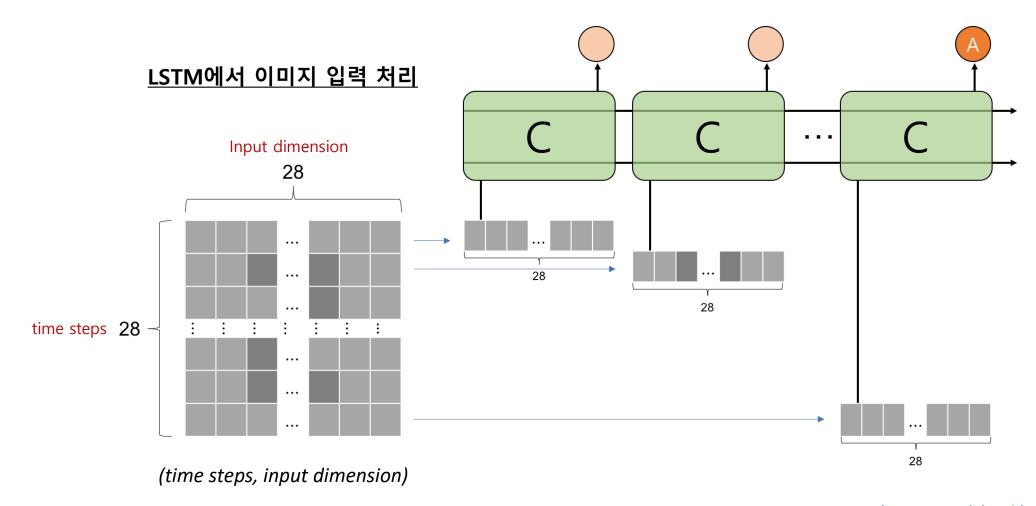


(time steps, input dimension)

28 input dimension



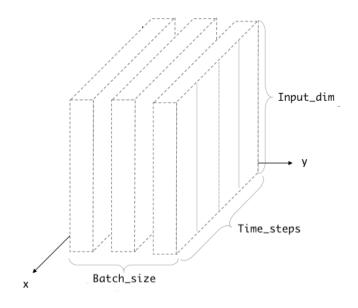
## 참고 Keras LSTM Input



https://pozalabs.github.io/lstm/

## 참고 Keras LSTM Input

### <u>LSTM 입력 형태</u>



(batch size, time steps, input dimension)

• LSTM의 input\_shape에는 (time steps, input dimension)만 기입

keras.layers.LSTM(units=64, input\_shape(28, 28))

- Batch size를 매번 다르게 줄 수 있음
- 고정된 Batch size를 명시하려면 batch\_input\_shape을 사용

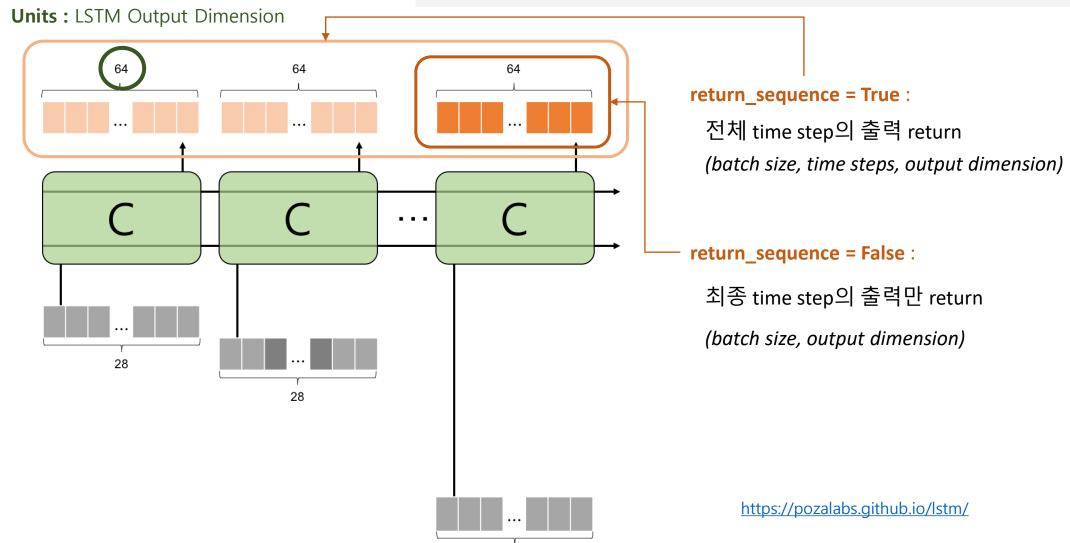
keras.layers.LSTM(units=64, batch\_input\_shape(32, 28, 28))

- Batch size를 다르게 주면 오류가 생김

https://medium.com/@shivajbd/understanding-input-and-output-shape-in-lstm-keras-c501ee95c65e

## 참고 Keras LSTM Output

keras.layers.LSTM(units=64, input\_shape(28, 28), return\_sequence=True)



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# 모델 정의 (문제)



### LSTM을 이용해서 RNN 모델을 정의

(Hint: tf.keras.layers.LSTM, tf.keras.layers.BatchNormalization, tf.keras.layers.Dense 사용)

```
# Each MNIST image batch is a tensor of shape (batch_size, 28, 28).
# Each input sequence will be of size (28, 28) (height is treated like time).
input_dim = 28
timesteps = 28
units = 64
output_size = 10 # labels are from 0 to 9

# Build the RNN model (tf.keras.layers.LSTM)
# Batch Normalization 적용
def build_model():
model = tf.keras.models.Sequential(#your code)
return model
```

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# 참고 tf.keras.layers.LSTM

```
tf.keras.layers.LSTM(
    units, activation='tanh', recurrent_activation='sigmoid', use_bias=True,
    kernel_initializer='glorot_uniform', recurrent_initializer='orthogonal',
    bias_initializer='zeros', unit_forget_bias=True, kernel_regularizer=None,
    recurrent_regularizer=None, bias_regularizer=None, activity_regularizer=None,
    kernel_constraint=None, recurrent_constraint=None, bias_constraint=None,
    dropout=0.0, recurrent_dropout=0.0, implementation=2, return_sequences=False,
    return_state=False, go_backwards=False, stateful=False, time_major=False,
    unroll=False, **kwargs
)
```

- units: Positive integer, dimensionality of the output space.
- return\_sequences: Boolean. Whether to return the last output. in the output sequence, or the full sequence. Default: False.
- **stateful**: Boolean (default False). If True, the last state for each sample at index i in a batch will be used as initial state for the sample of index i in the following batch.

https://www.tensorflow.org/api\_docs/python/tf/keras/layers/LSTM

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# 참고 tf.keras.layers.LSTM

```
inputs = np.random.random([32, 10, 8]).astype(np.float32)
lstm = tf.keras.layers.LSTM(4)

output = lstm(inputs) # The output has shape `[32, 4]`.

lstm = tf.keras.layers.LSTM(4, return_sequences=True, return_state=True)

# whole_sequence_output has shape `[32, 10, 4]`.

# final_memory_state and final_carry_state both have shape `[32, 4]`.

whole_sequence_output, final_memory_state, final_carry_state = lstm(inputs)
```

https://www.tensorflow.org/api\_docs/python/tf/keras/layers/LSTM

# 모델 훈련

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# Thank you!

