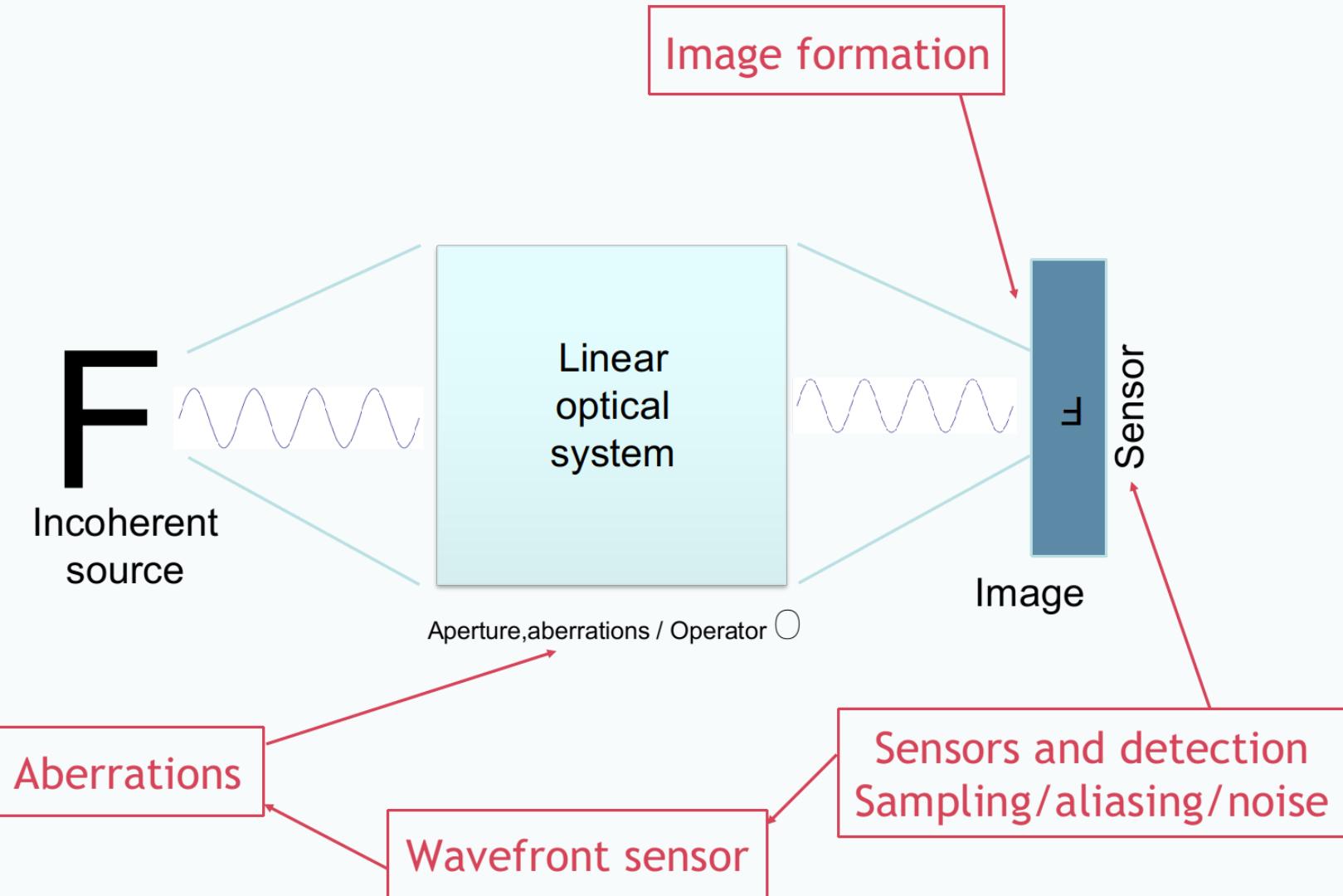


FOURIER OPTICS & FOURIER TRANSFORM

Prof François Rigaut

Research School of Astronomy & Astrophysics
The Australian National University

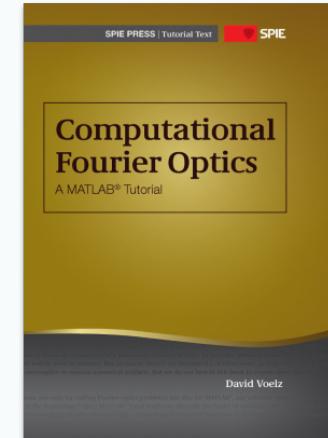
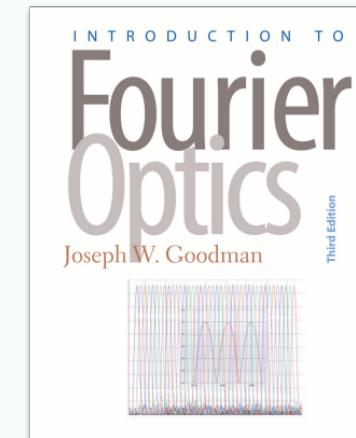
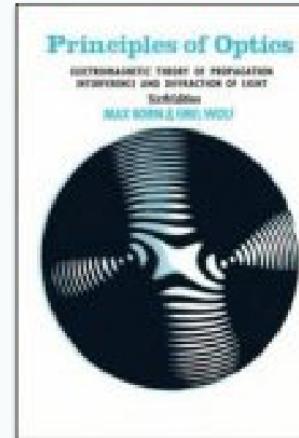
LINEAR OPTICAL SYSTEMS



PREAMBLE

INTRODUCTION: SOURCES

- “**Introduction to Fourier Optics and coherence**”, J.-M. Mariotti, in Diffraction limited imaging with very large telescope, editors D.M.Alloin and J.-M. Mariotti, 1988 (JMM),
- “**Introduction to Fourier Optics**”, Joseph Goodman, 2004 (JG)
- “**Fundamental of Photonics**”, B.E.A Saleh & M.C.Teich, 1991, mostly Chapter 4 (S&T),
- “**Principles of Optics**”, Max Born and Emil Wolf, 1980 (B&W),
- “**Computational Fourier Optics: A MATLAB Tutorial**”, David Voelz
- The web, wikipedia.



HISTORY OF FOURIER OPTICS

- 1660: First observation of diffraction by **Grimaldi**
- 1678: **Huygens** “Traité de la lumière” (published 1690): first wave theory of light. Require finite speed of light.
- 1803: **Thomas Young** two slits interferences experiment.
- 1818: **Fresnel** produces the first theory of diffraction.
- 1822: **Fourier** introduces his transform
- 1850-1950: **Krichhoff, Sommerfeld**, then Quantum Mechanics bring a firm mathematical foundation to the theory.



Grimaldi



Huygens



Fresnel



Fourier

- Of course **Newton** was involved too !

VALIDITY AND LIMIT CONDITIONS

- Previous lectures from PHYS3057 were **1D optics, coherent** (waveguides, lasers). The next lectures with me will be on **2D optics, incoherent sources** (imaging).
- We will consider **light as a scalar field** (B&W 8.4)
- We'll be focusing (pun intended) on **Fraunhofer diffraction**
- **Diffraction occurs with all waves**, including sound, water, electromagnetic (X through radio), elementary particles.
- We'll **browse through the maths**, it is there for reference and those who'd like to dig deeper

NEXT TWO LECTURES IN ONE SLIDE

- Basic understanding of the **Fourier transform** and its properties, **sampling and aliasing** issues
- In Fourier Optics, light is described by a scalar field $\Psi = A \exp^{i\varphi}$
- In **Fraunhofer diffraction**, the **far and near field** complex amplitudes are linked by a Fourier transform $\Psi(P) = \mathcal{F}(\Psi(M))$
- An optical system can be characterised by its **impulse function** H . The impulse function is $H = |\mathcal{F}(\Psi(x))|^2$
- Object O and image \mathcal{I} are linked by the relation $\mathcal{I} = O * H$
- The Optical Transfer Function of a system characterises its spatial frequencies filtering properties $\text{OTF} = \mathcal{F}(H) = \Psi * \Psi^*$

INTRODUCTION TO MODAL EXPANSION

MODAL EXPANSION

$$f = \sum_i a_i \mu_i$$

where:

- f is a discrete function/object
- μ_i are modes that you are going to use to represent
- a_i are the coefficients

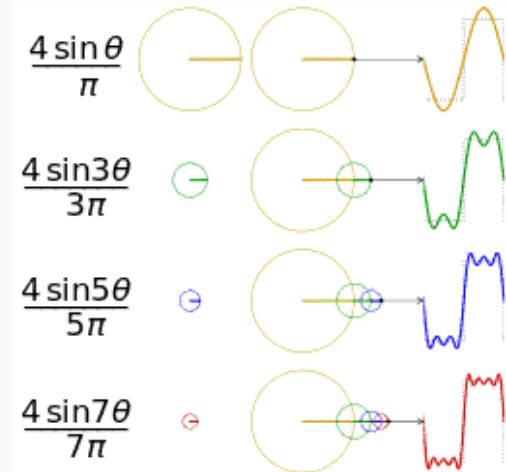
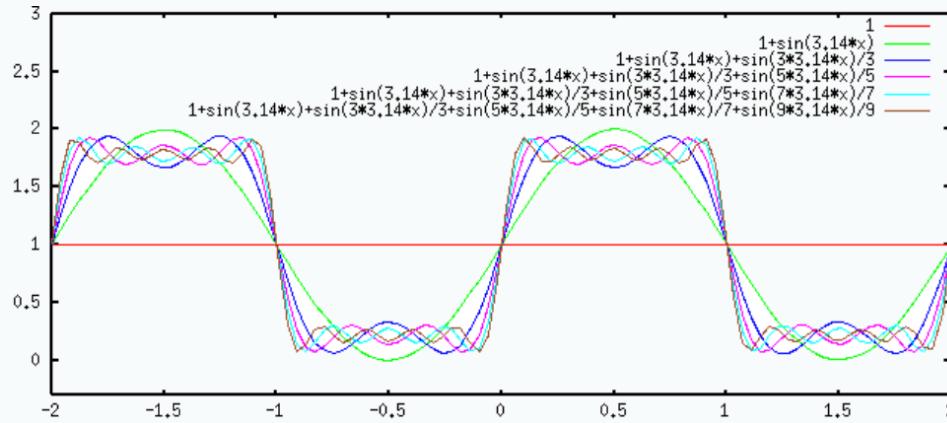
MODAL EXPANSION

- The nature world is **continuous**
- Once measured, a **signal is discrete.**
 - Volt versus time
 - Elevation map
 - Image
- Chose the **modal basis** adapted to your problem.
- Goal is to try to **reduce the number of parameter** to describe function, and make use of convenient properties of this description
- Examples:
 - An optical phase using Zernike modes $\varphi = \sum_i a_i Z_i$
 - Finite Element Model analysis
 - Eigenvalues engenmodes
- Cyclic signals are naturally described by expanding on **sines and cosines**
 $\rightarrow f = \sum_i a_i \cos(i\theta) + b_i \sin(i\theta)$

THE FOURIER TRANSFORM

WHAT IS THE FOURIER TRANSFORM?

- The Fourier transform of a signal tells you **what frequencies are present in your signal and in what proportions**



- IMHO, the **most useful mathematical tool for engineers and applied physicists.**
- It is used to:
 - Characterise signals** (1D/2D..) and linear systems. Electronics, optics, acoustics, mechanics, civil engineering, etc, etc...
 - Digitally process data/signals** (filtering, convolving, correlating, etc) in all above disciplines

FOURIER FILTERING

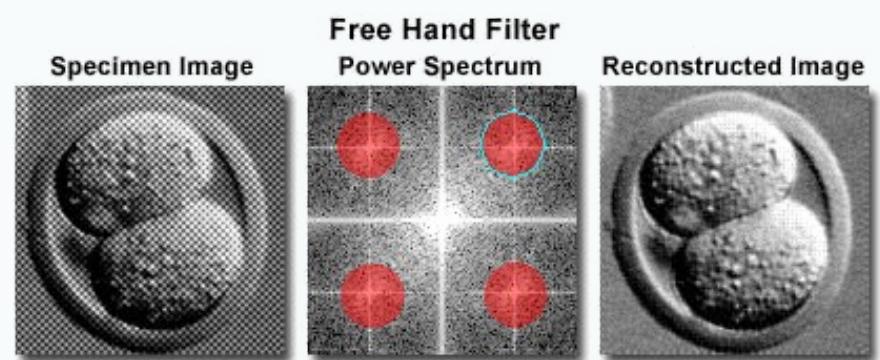
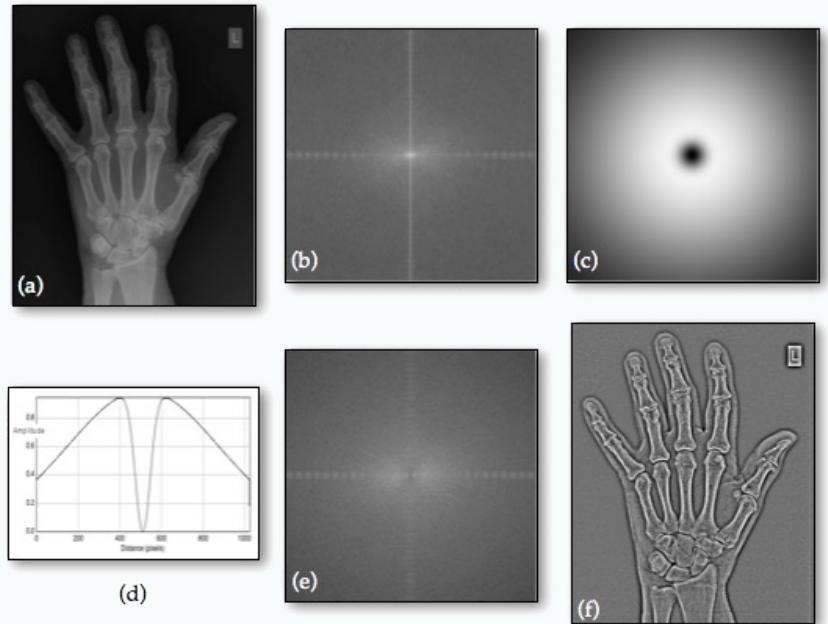
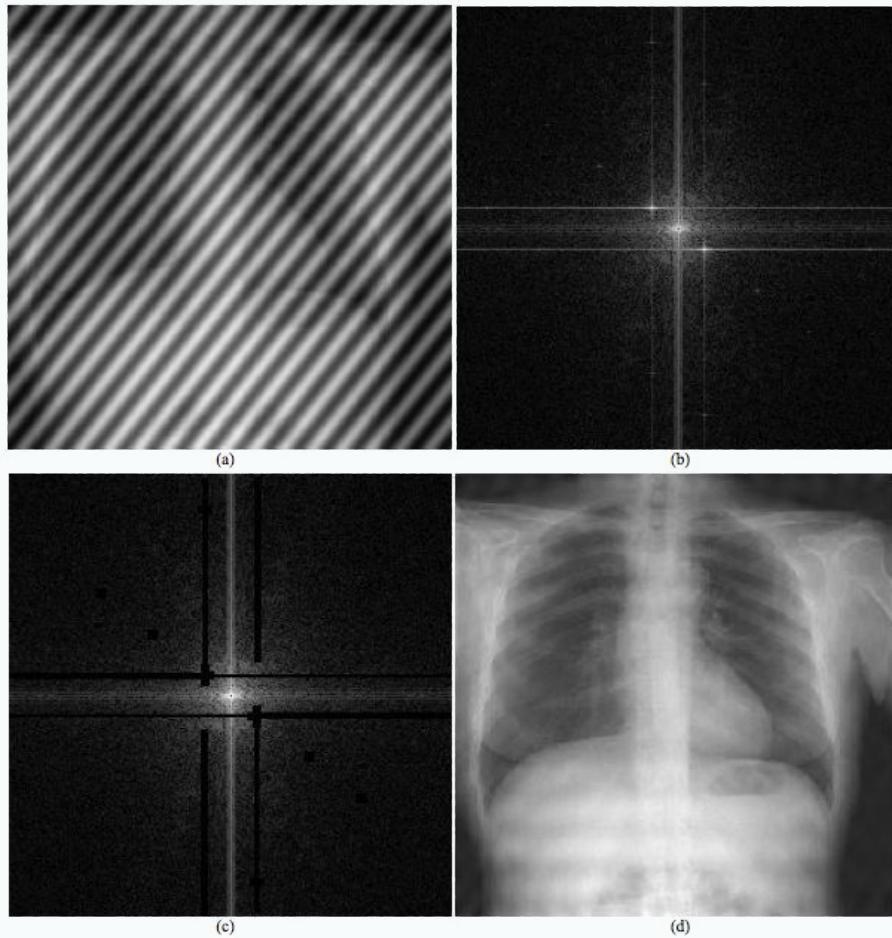


Figure 1

FOURIER TRANSFORM: DEFINITIONS

- We note \hat{f} the **Fourier transform** of f

$$\hat{f}(u) = \int_{-\infty}^{+\infty} f(x) \exp^{-i2\pi ux} dx$$

- The **inverse** Fourier transform is $f(x) = \int_{-\infty}^{+\infty} \hat{f}(u) \exp^{+i2\pi ux} du$
- We will also use the **Fourier operator** \mathcal{F} : $\hat{f}(u) = \mathcal{F}[f(x)]$
- The Fourier transform is **cyclic**: $\mathcal{F}^{-1}[\mathcal{F}[f(x)]] = f(x)$
- To have a Fourier transform, a function must
 - Be absolutely integrable

$$\left| \int_{-\infty}^{+\infty} f(x) dx \right| < \infty$$

- Not have any infinite discontinuity
- Have only a finite number of discontinuities or extrema in any finite interval

FOURIER PAIRS

Function	Fourier Pair
$\exp(-\pi x^2)$	$\exp(-\pi u^2)$
$\text{sinc}(x)$	$\Pi(u)$
$\text{sinc}^2(x)$	$\Lambda(u)$
$\delta(x)$	1
$\text{III}(x)$	$\text{III}(u)$
$\sin(\pi x)$	$\frac{i}{2}\delta(u + \frac{1}{2}) - \frac{i}{2}\delta(u - \frac{1}{2})$

PROPERTIES

Property	Expression
Linearity	if $h(x) = af(x) + bg(x)$ then $\hat{h}(u) = a\hat{f}(u) + b\hat{g}(u)$
Similarity	$\mathcal{F}[f(ax)] = \frac{1}{ a } \hat{f}\left(\frac{u}{a}\right)$
Shift	$\mathcal{F}[f(x - a)] = e^{-i2\pi au} \hat{f}(u)$
Convolution	$\mathcal{F}[f(x) * g(x)] = \mathcal{F}[f(x)] \times \mathcal{F}[g(x)] = \hat{f}(u) \times \hat{g}(u)$
Autocorrelation	$\mathcal{F}[f(x) * f(x)] = \hat{f}(u) ^2$
Parseval	$\int_{-\infty}^{+\infty} f(x) \times g^*(x) dx = \int_{-\infty}^{+\infty} \hat{f}(u) \times \hat{g}^*(u) du$
Power	$\int_{-\infty}^{+\infty} f(x) ^2 dx = \int_{-\infty}^{+\infty} \hat{f}(u) ^2 du$
Derivative	$\mathcal{F}\left[\frac{d}{dx} f(x)\right] = i2\pi u \hat{f}(u)$

2D FT, DFT, FFT, PSD

- Acronyms:
 - FT: Fourier Transform
 - DFT: Discrete FT
 - FFT: Fast FT
 - PSD: Power Spectral Density (modulus square)

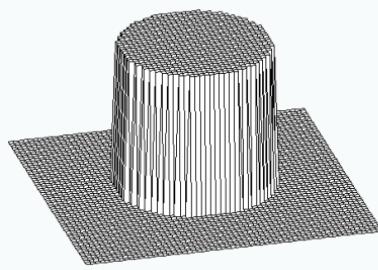
2D FOURIER TRANSFORM

Forward $\hat{f}(u, v) = \iint_{-\infty}^{+\infty} f(x, y) e^{-i2\pi(ux+vy)} dx dy$

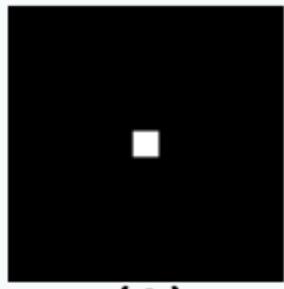
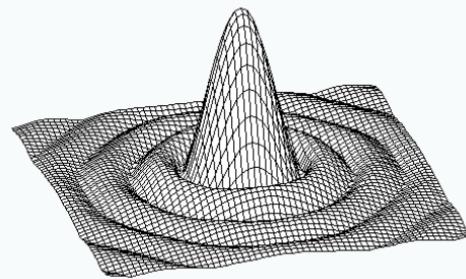
Reverse $f(x, y) = \iint_{-\infty}^{+\infty} \hat{f}(u, v) e^{+i2\pi(ux+vy)} du dv$

- Note that if f can be factorised (convenient) $f(x, y) = g(x).h(y)$ then
 $\hat{f}(u, x) = \hat{g}(u) \times \hat{h}(v)$
 - (but if $f(x, y) = g(r).h(\theta)$ the problem is more complicated ...)
- All other theorems apply as in 1D (linearity, similarity, power, etc)

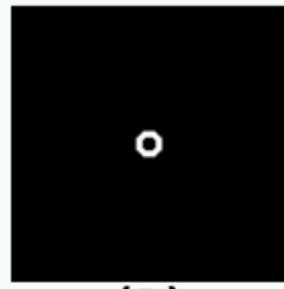
SOME 2D FOURIER PAIRS



$$\Pi\left(\frac{r}{2a}\right) \rightleftharpoons \frac{a J_1(2\pi a \rho)}{\rho}$$



(A)



(B)



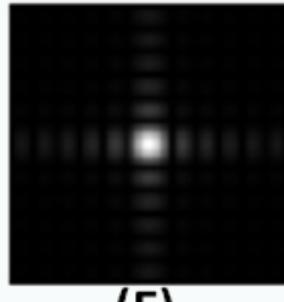
(C)



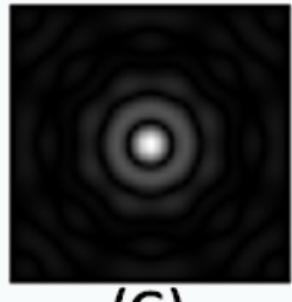
(D)



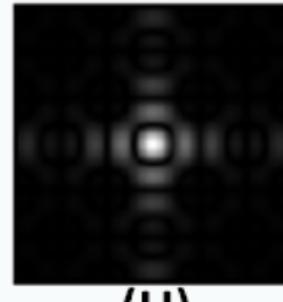
(E)



(F)



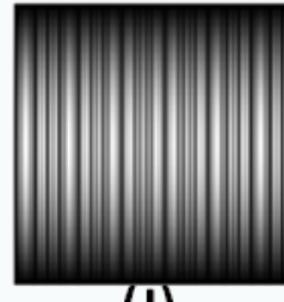
(G)



(H)



(I)



(J)



DISCRETE FT AND FAST FT

- The Fourier transform can be modified for **discrete datasets**, which is extremely useful to represent and analyse **sampled physical signals**. The discrete Fourier transform (DFT) is:

$$\hat{f}(\nu) = \frac{1}{N} \sum_{\tau=0}^{N-1} f(\tau) e^{-i2\pi\nu\tau/N}$$
$$f(\tau) = \sum_{\nu=0}^{N-1} \hat{f}(\nu) e^{+i2\pi\nu\tau/N}$$

- Both τ and ν are discrete variables. Both functions consist of sequences of N samples. All the basic theorems for the FT also apply to the DFT.
- The **Fast Fourier Transform (FFT)** is a DFT that uses a smart algorithm to drastically reduce the number of operations, from N^2 down to $N \log(N)$

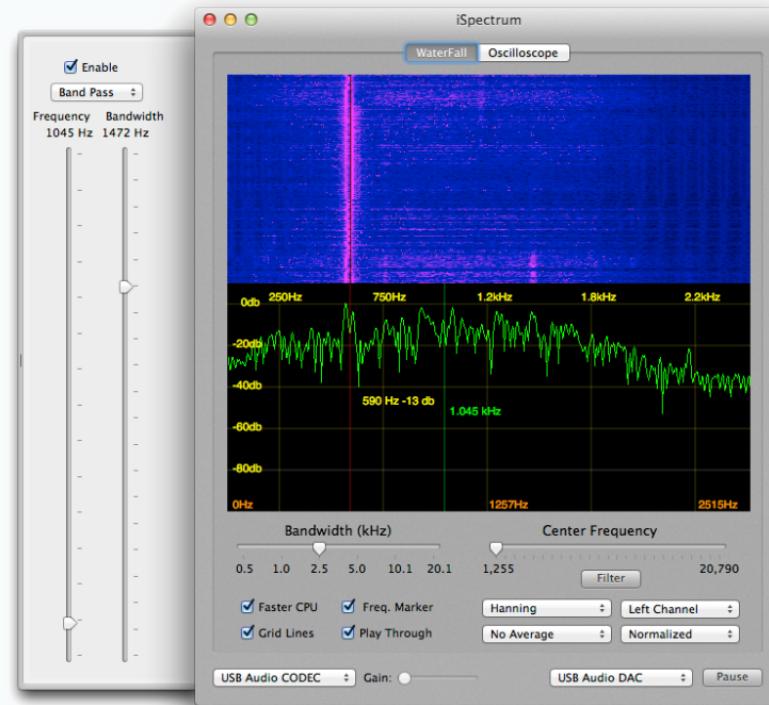
THE POWER SPECTRAL DENSITY (PSD)

- The square modulus of the Fourier transform of a signal

$$\text{PSD}(f) = |\mathcal{F}(f(x))|^2$$

- PSD is insensitive to the phase of the input signal.
 - you get the power (intensity) per frequency bin over the frequency range 0 to cut off frequency
- In a DFT, assuming:
 - the units of x are seconds (s),
 - and the units of f, say, Volts (V)
 - then the PSD units are V^2/Hz .

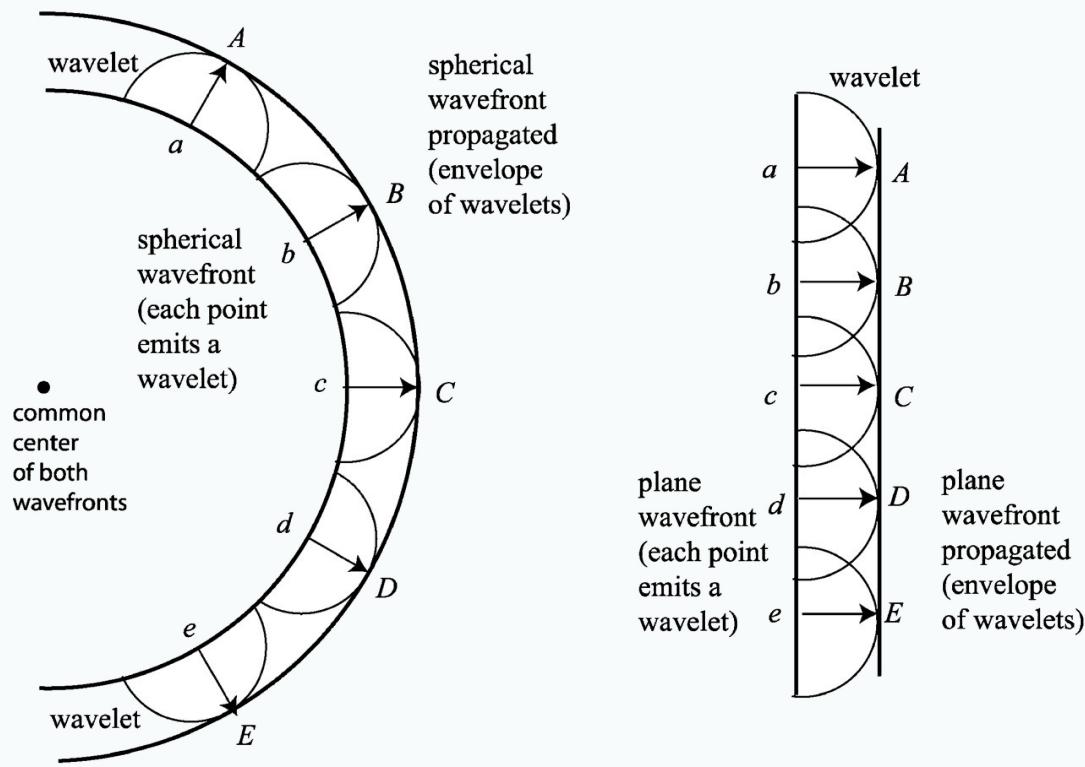
See Spectrum Density Analyser



DIFFRACTION THEORY

HUYGENS PRINCIPLE

- “Every point on a wavefront may be considered a source of secondary spherical wavelets which spread out in the forward direction at the speed of light. The new wavefront is the tangential surface to all of these secondary wavelets.”



(NON) DERIVATION OF THE DIFFRACTED FIELD

- Fresnel, KrichHoff and Sommerfeld, within others, have worked out the math. It's messy, and requires a lot of approximations.
- Applying the Huygens principle and working out the field propagation from the point P_0 through the aperture W in plan M (near field), to the final plan P (far field), it can be demonstrated that the **field in P is the simple Fourier Transform of the field in M :**

$$\Psi(P) = \mathcal{F}(\Psi(M))$$

WAVEFRONT, PSF, OTF

THE IMPULSE FUNCTION

- Recalling the field in P: $\Psi(P) = \mathcal{F}(\Psi(M))$
- At visible wavelengths, it is extremely difficult to measure the complex field itself (for quantum noise reasons) - but we can measure the field intensity (irradiance), the square of the complex field. H is the image of a point, the impulse function, also called the **Point Spread Function (PSF)**:

$$H = \Psi(P) \cdot \Psi^*(P) = \mathcal{F}(\Psi(M)) \cdot \mathcal{F}^*(\Psi(M)) = |\mathcal{F}(\Psi(M))|^2$$

Remember that $\Psi = Ae^{i\varphi}$? So, in absence of aberrations ($\varphi \equiv 0$), we simply have:

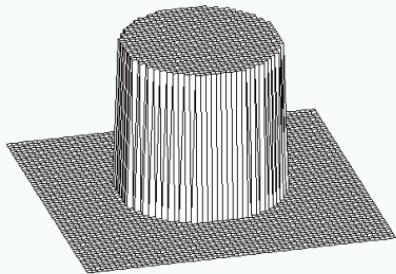
$$H = |\mathcal{F}(A)|^2$$

THE IMPULSE FUNCTION, CIRCULAR APERTURE

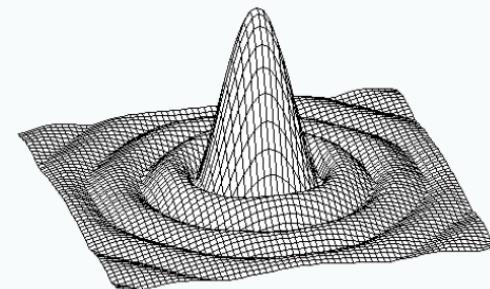
For a circular aperture:

$$\Psi(M) = \Psi(r, \theta) = \Pi\left(\frac{r}{2a}\right) = \begin{cases} 1 & \text{if } r \leq a \\ 0 & \text{if } r > a \end{cases}$$

$$H = |\mathcal{F}(\Psi(M))|^2 = |\mathcal{F}(\Psi(\Pi(r/2a)))|^2 = \left[a \frac{J_1(2\pi a \rho)}{\rho}\right]^2$$

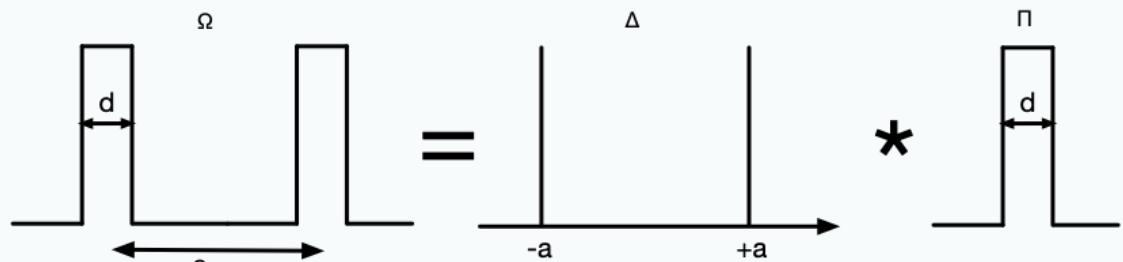


$$\Pi\left(\frac{r}{2a}\right) \Leftrightarrow \frac{a J_1(2\pi a \rho)}{\rho}$$



AN APPLICATION: YOUNG FRINGES

- Armed with this new mathematical description of diffraction, it is now trivial to find, e.g., the expression of the Young fringes.
- The slits can be described as a convolution:

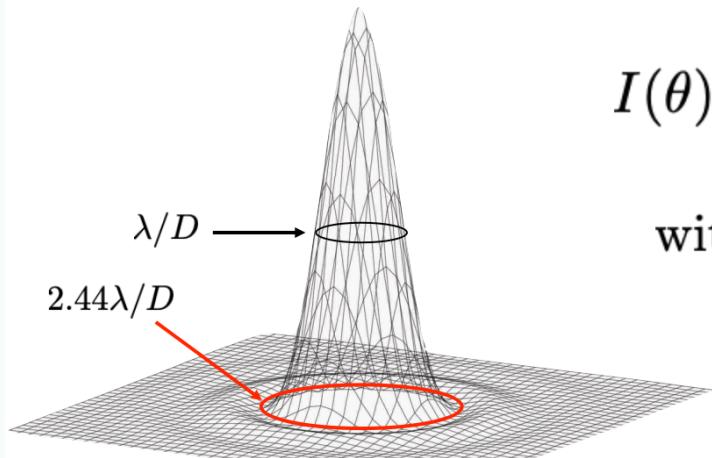


- The near field can be written $\Omega(x) = \Delta(x/a) * \Pi(x/d)$
- The far field is $\hat{\Omega}(u) = \mathcal{F}(\Delta(x/a) * \Pi(x/d)) = \mathcal{F}(\Delta(x/a)) \times \mathcal{F}(\Pi(x/d))$
- $\Delta(x/a) = \delta(x - a) + \delta(x + a)$ hence
 $\mathcal{F}(\Delta(x/a)) = e^{-i2\pi au} + e^{+i2\pi au} = 2 \cos(2\pi au)$
- and $\mathcal{F}(\Pi(x)) = \text{sinc}(u)$ hence $\mathcal{F}(\Pi(x/d)) = \text{sinc}(ud)$

Thus $\hat{\Omega}(u) = 2 \cos(2\pi au) \times \text{sinc}(ud)$ and the intensity (measured)

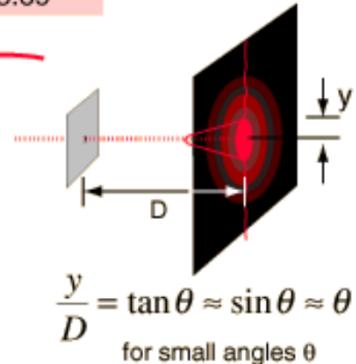
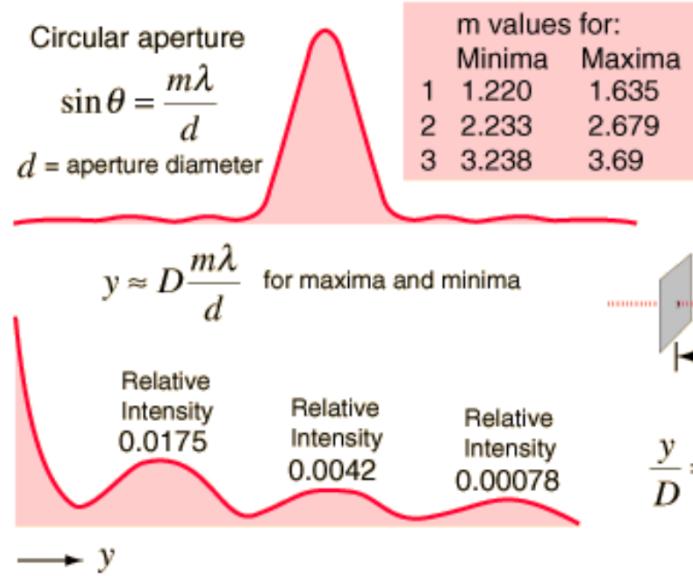
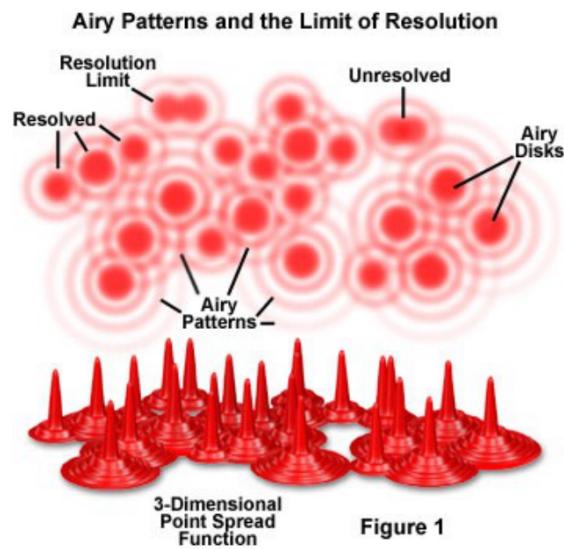
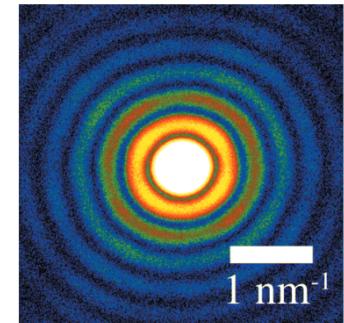
$$|\hat{\Omega}(u)|^2 = 4 \cos^2(2\pi au) \times \text{sinc}^2(ud)$$

AIRY PATTERN, CIRCULAR APERTURE PSF



$$I(\theta) = I_0 \left(2 \frac{J_1(ka \sin(\theta))}{ka \sin(\theta)} \right)^2$$

with $k = 2\pi/\lambda$ and $D = 2a$

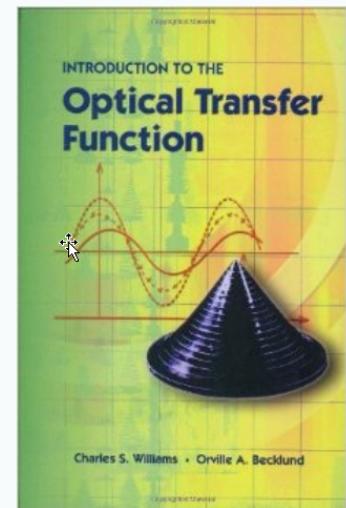
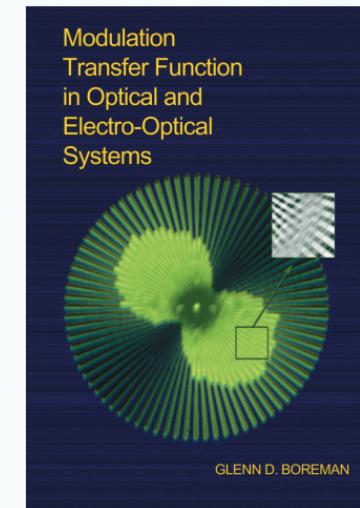
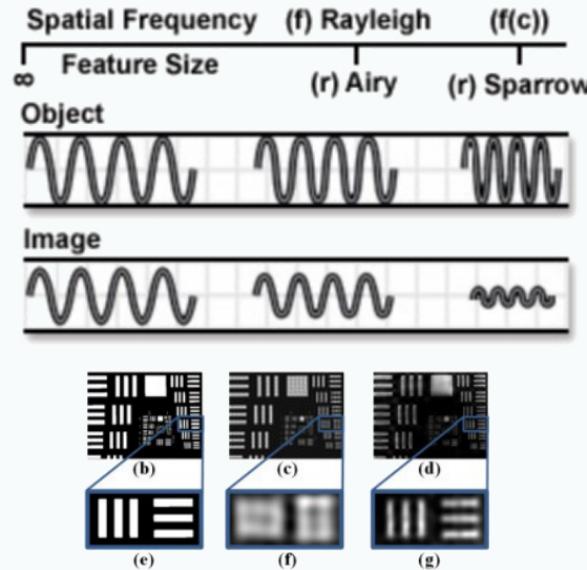
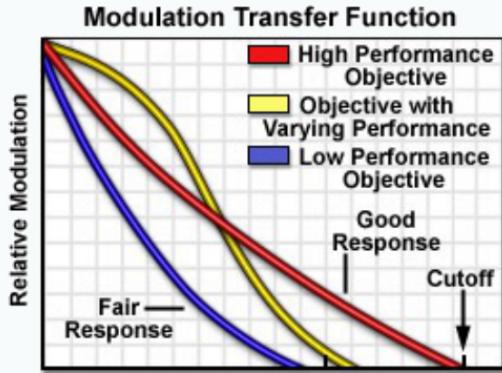


THE OPTICAL TRANSFER FUNCTION

- Also called generically **Modulation Transfer Function (MTF)**

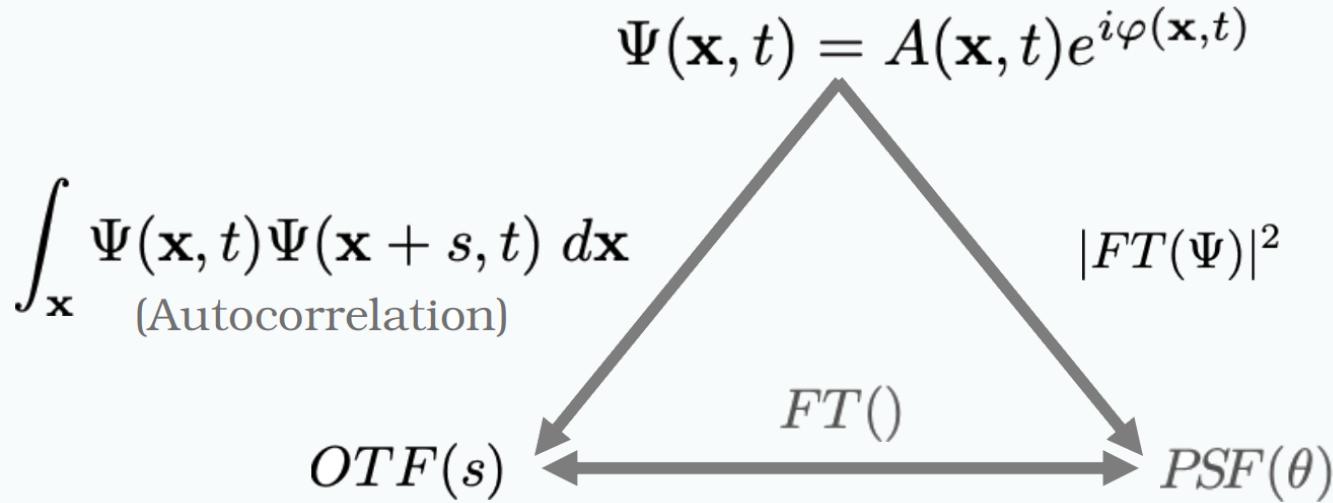
$$\text{OTF} = |\mathcal{F}(H)| = |\Psi * \Psi^*|$$

- Characterises the filtering properties of an optical system, including cut-off frequency
- For a circular aperture, the cut-off frequency is $f_c = D/\lambda$
- People have written books about it...



WAVEFRONT, PSF & OTF ARE LINKED

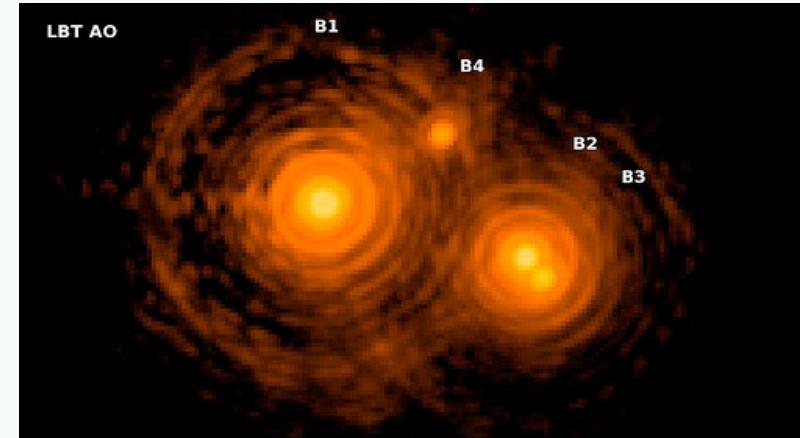
- The wavefront is $\Psi(x, y, t) = A(x, y, t) \exp(i\varphi(x, y, t))$
 - Ψ is the complex field defined by its amplitude and phase
 - A is the amplitude (e.g. pupil function)
 - φ is the phase
- The Optical Transfer Function (or MTF) is the spatial frequency response of the system.
- **Wavefront, PSF and OTF are linked:**



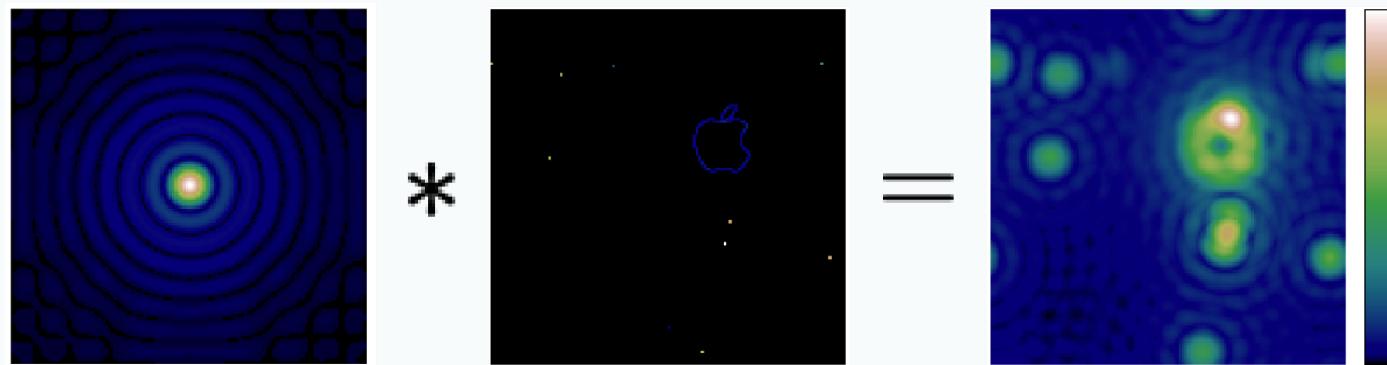
INTERFEROMETRY TO IMAGING ...AND BACK

IMAGE FORMATION FOR INCOHERENT SOURCES

- An object O can be decomposed into an infinite number of dirac function. In the case of an incoherent object (most objects in everyday's life, astronomical objects, medicine,etc), these points **do not interfere**, thus the resulting image is the convolution of the object and the impulse response (PSF)



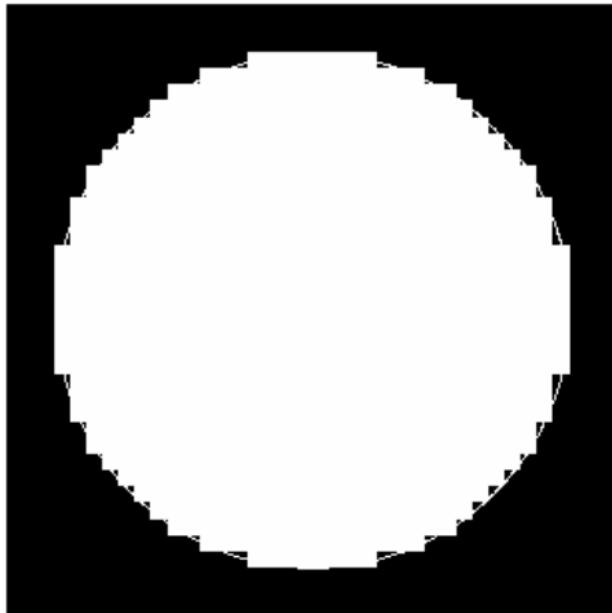
$$\mathcal{I} = O * H$$



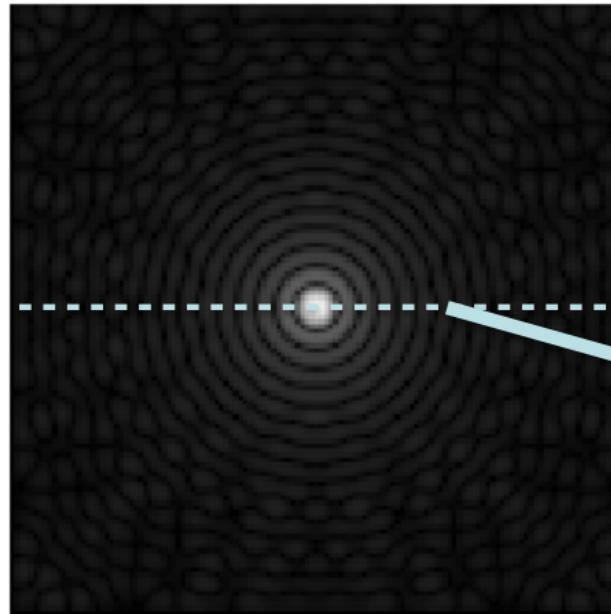
Note that this assumes invariance of PSF with position in the field of view.

INTERFEROMETRY TO IMAGING...

- From "slit" to full aperture



Near field
= Aperture
= Pupil



Far field
= Focal plane Image

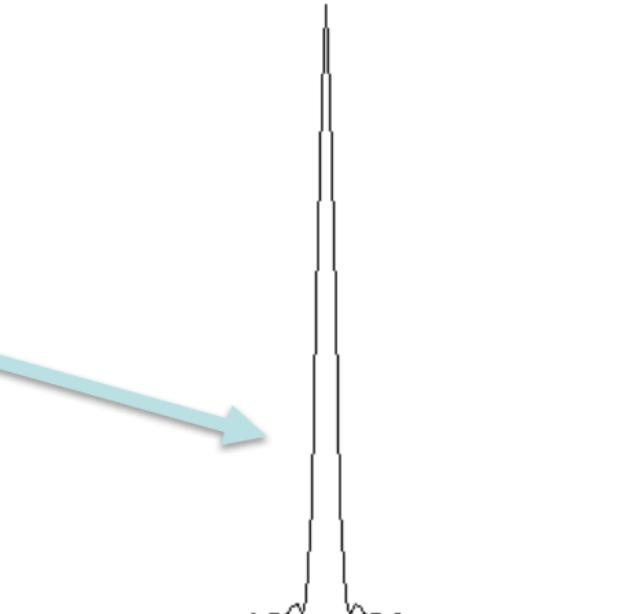
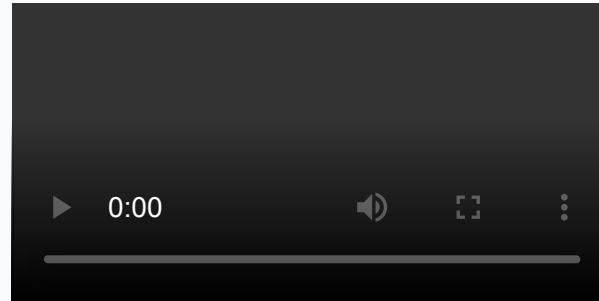


Image cross section

INTERFEROMETRY TO IMAGING...



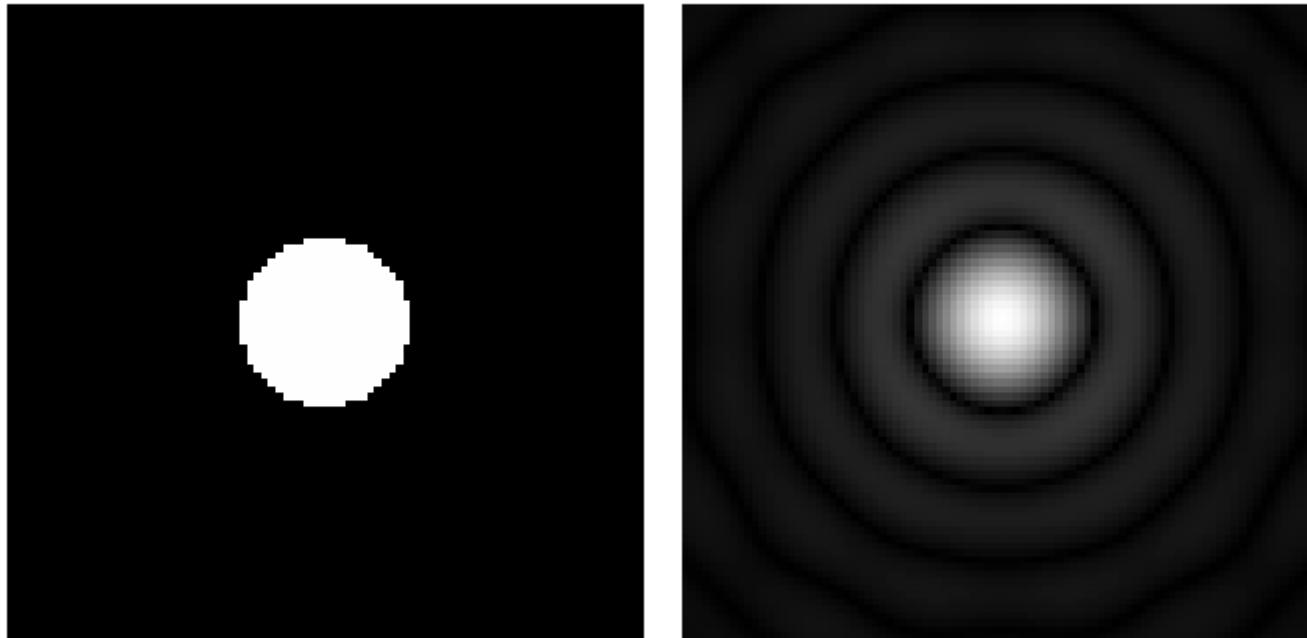
- From "slit" to full aperture

Near field
= Aperture
= Pupil

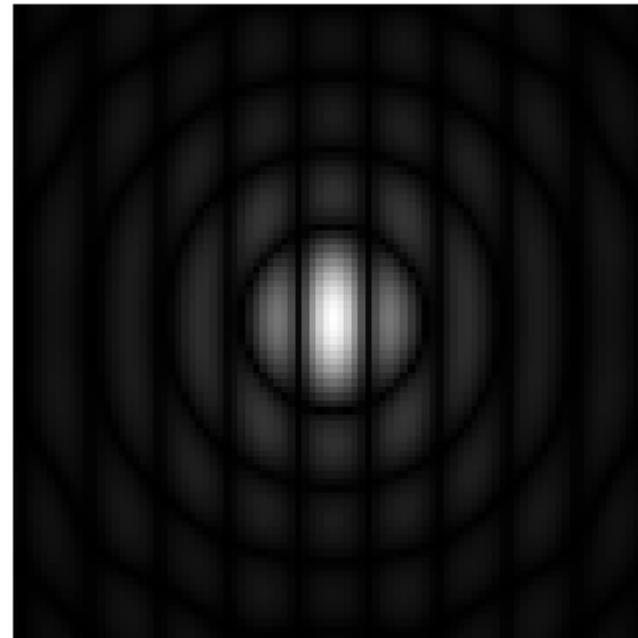
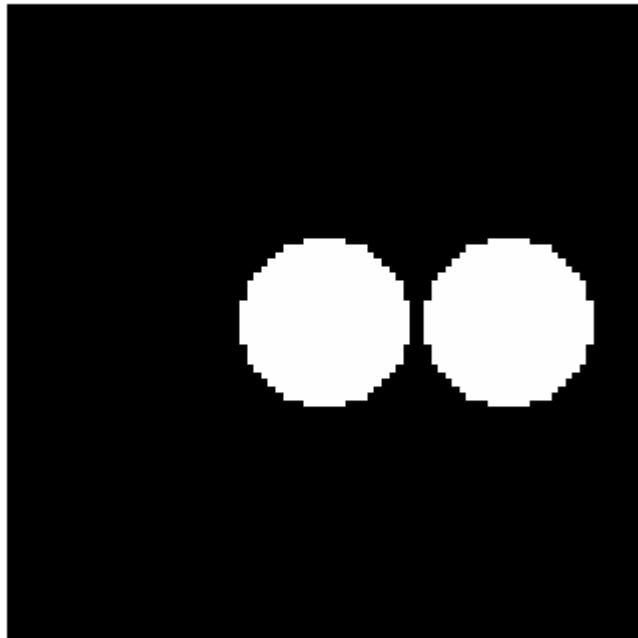
Far field
= Focal plane Image

Image cross section

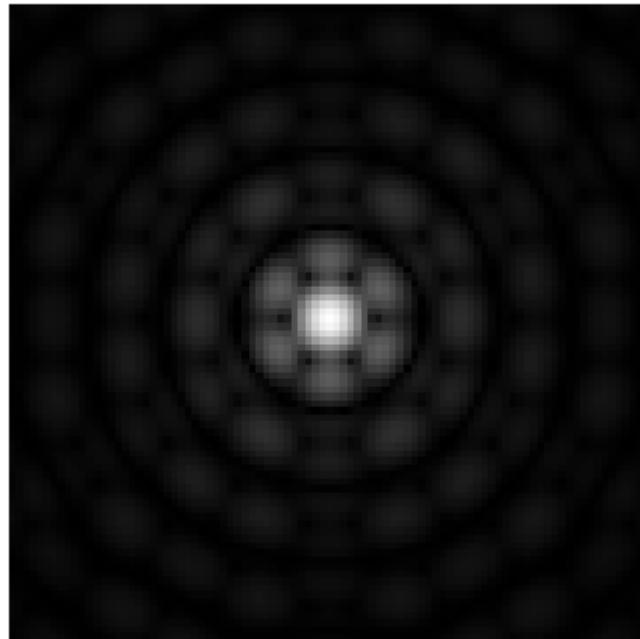
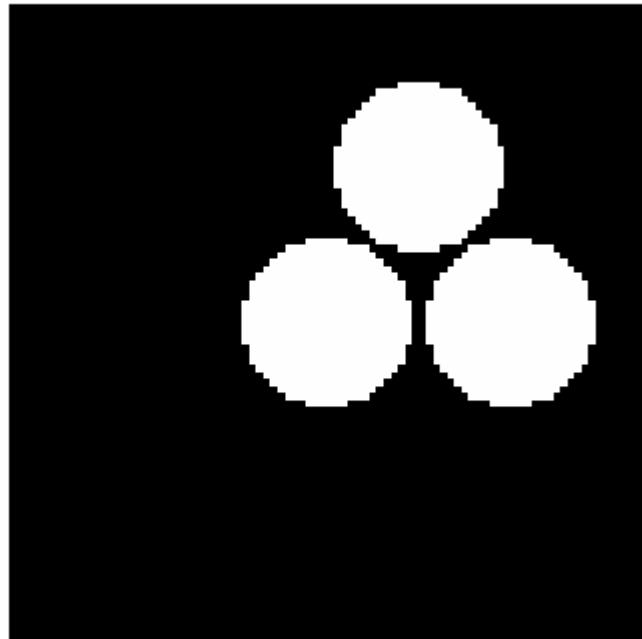
... AND IMAGING TO INTERFEROMETRY



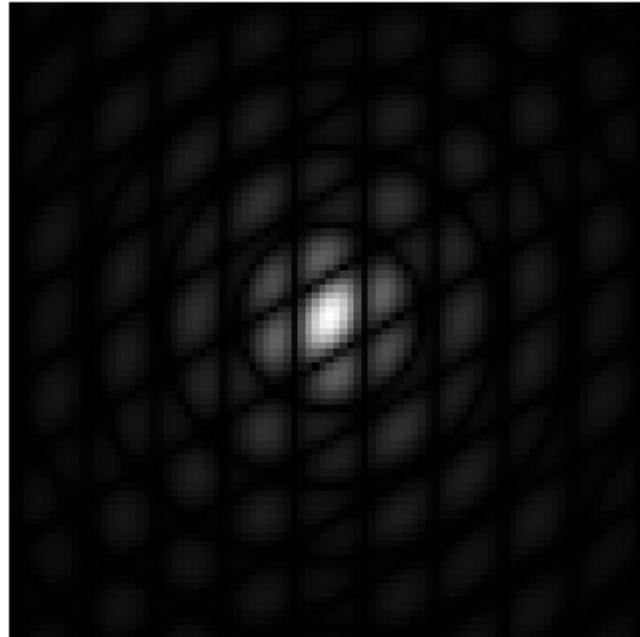
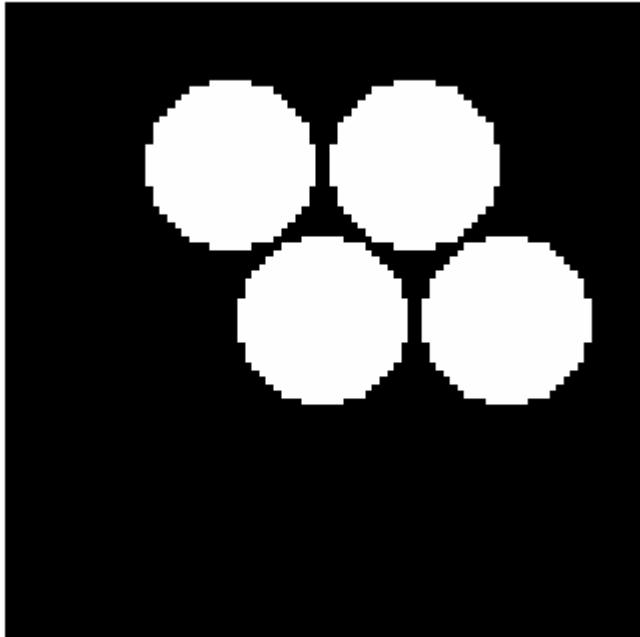
... AND IMAGING TO INTERFEROMETRY



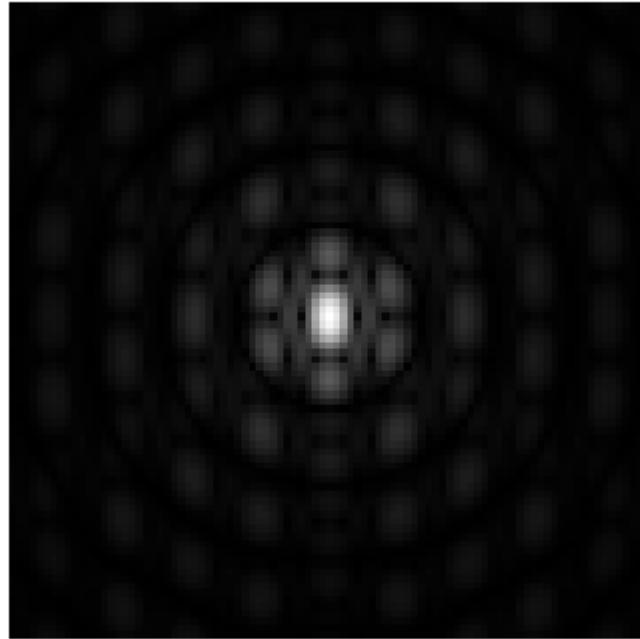
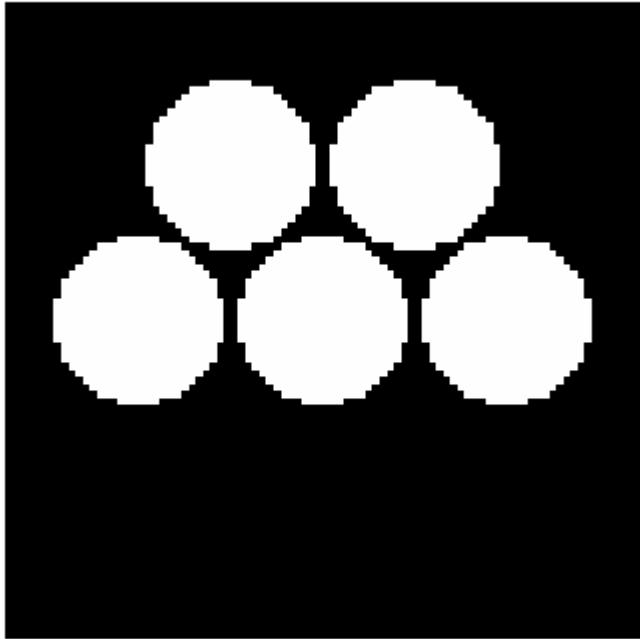
... AND IMAGING TO INTERFEROMETRY



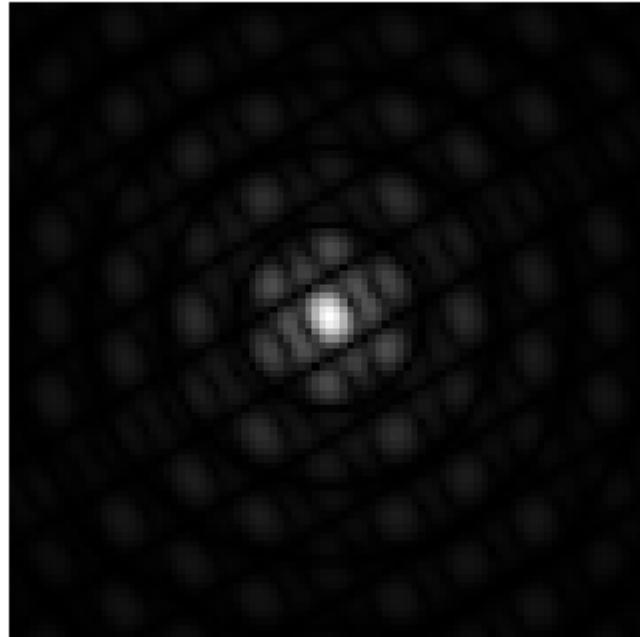
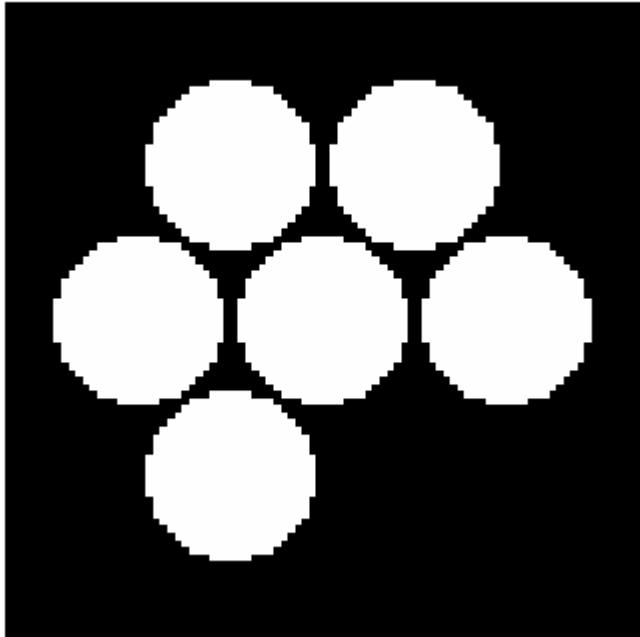
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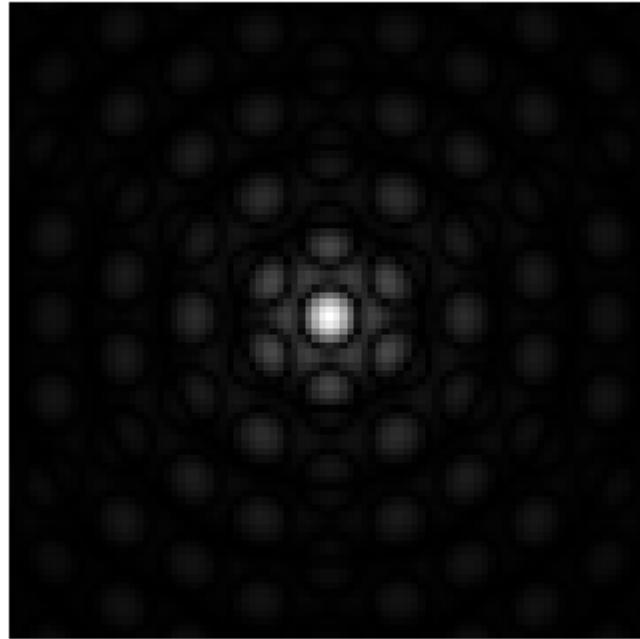
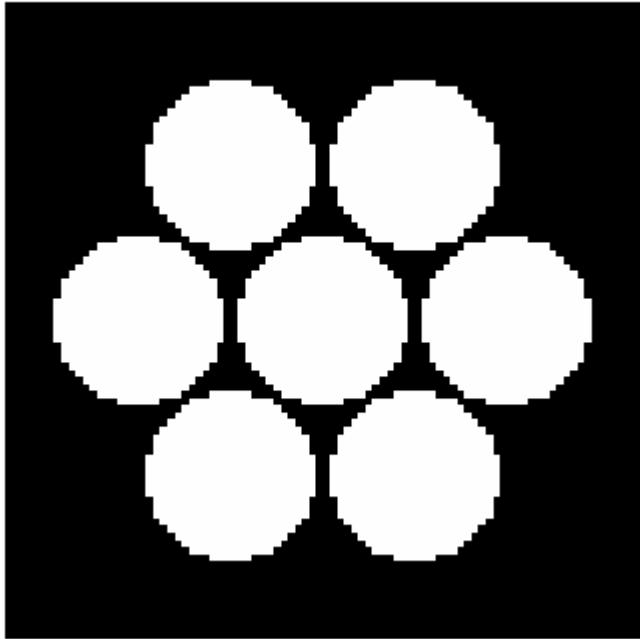
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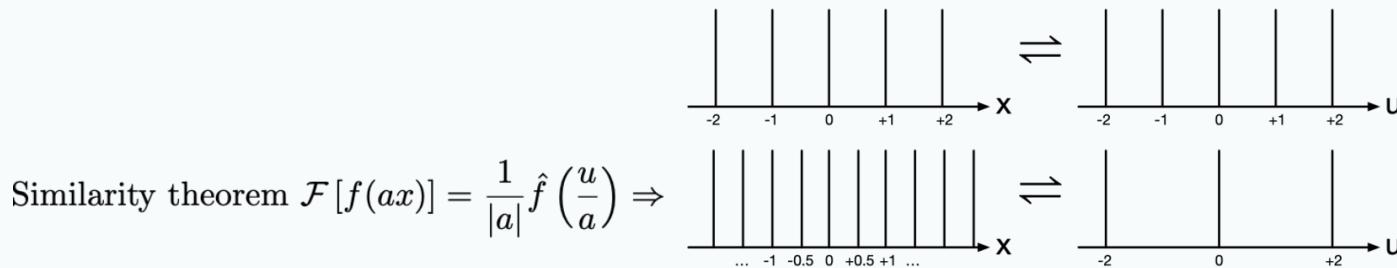
ELEMENTS OF SAMPLING THEORY

SAMPLING & ALIASING (SHANNON/NYQUIST)

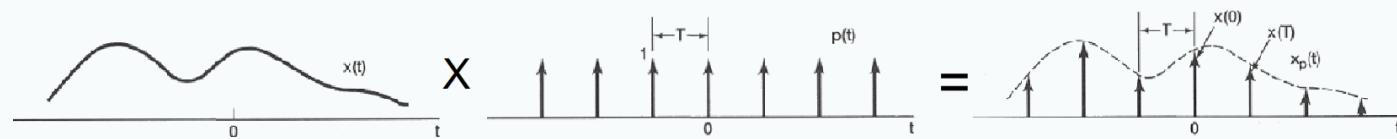
If a continuous, band-limited function $f(x)$ contains no frequency component higher than f_c , then it can be fully specified by a set of samples at frequency of $2 \times f_c$ or larger.

THE SHAH FUNCTION III(X)

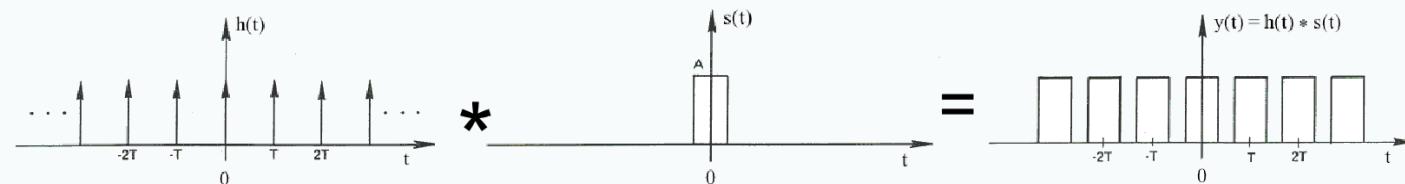
1. III(x) is its own Fourier transform



2. The act of sampling is taking value at discrete points \equiv Multiplication by III

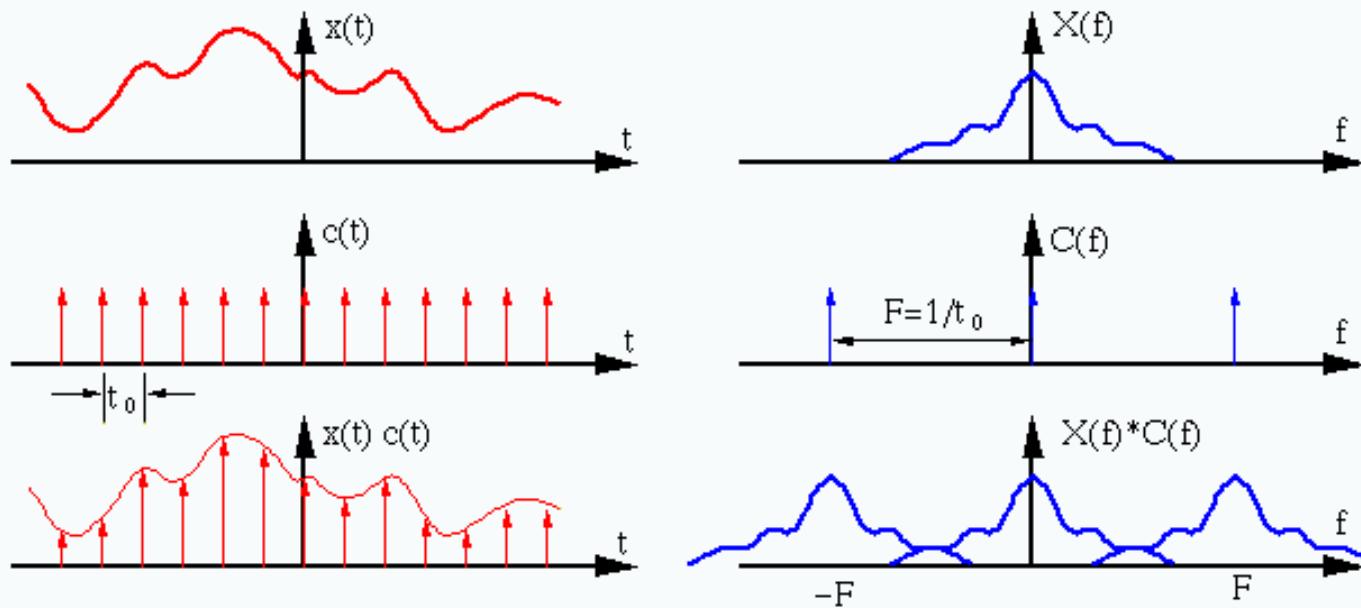


3. Convolution by III is equivalent to creating an infinite number of shifted replicas of the original functions



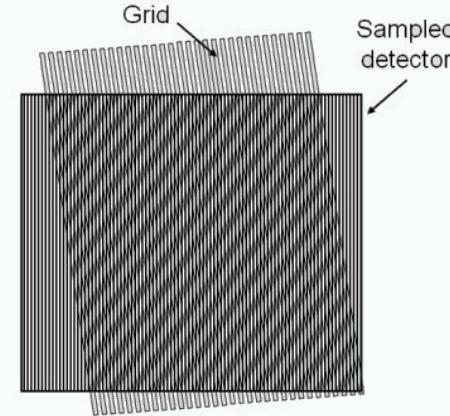
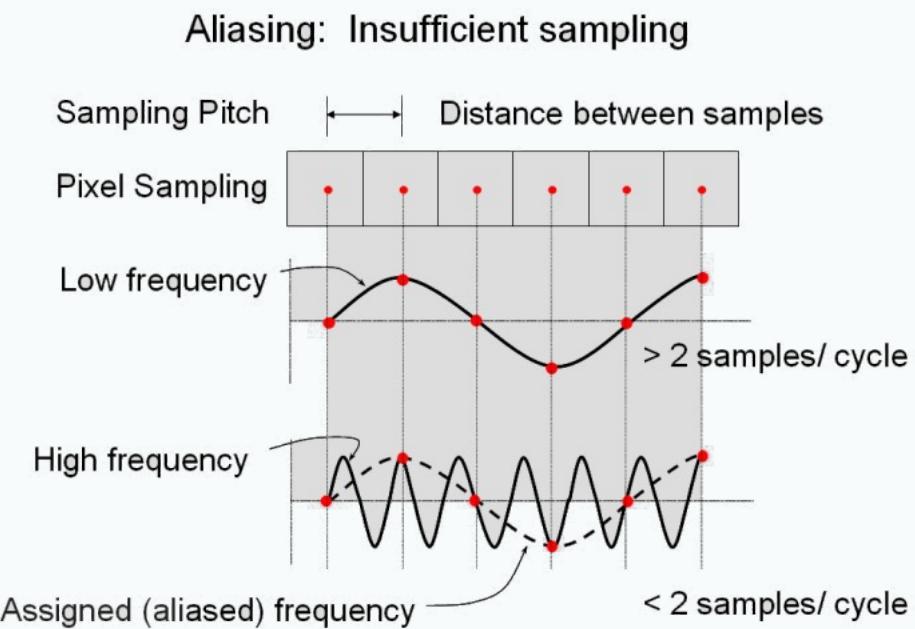
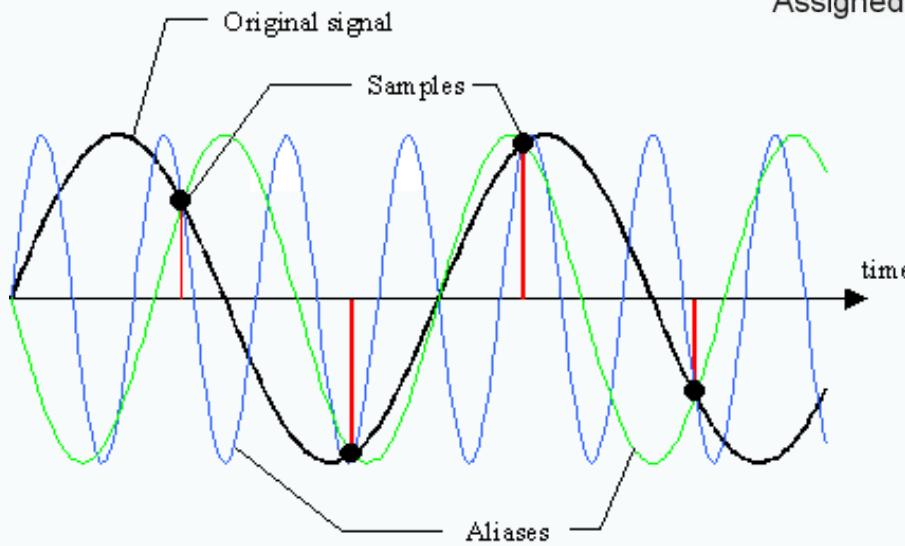
ALIASING

Fourier view: In the DFT/FFT space, the function spectrum is replicated at intervals $2 \times f_c$. If the spectrum spills over $\pm f_c$, then the spectrum replicas will overlap, resulting in a mixed signal (original lost).



ALIASING

- Can be spatial, temporal, angular, etc
- Can be solved/mitigated by pre-filtering the signal before sampling



PROOF OF THE SAMPLING THEOREM

From $f(x)$ we obtain the sampled $f_s(x)$ with sampling interval τ by:

$$f_s(x) = \text{III}\left(\frac{x}{\tau}\right) \cdot f(x)$$

In the Fourier domain:

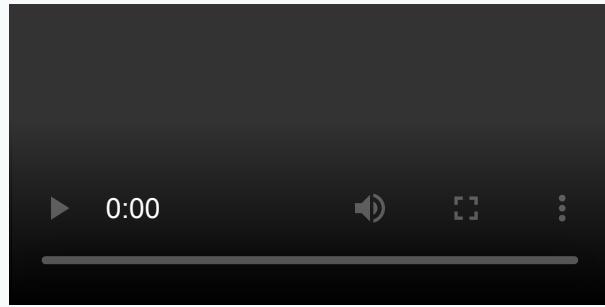
$$\hat{f}_s(u) = \tau \text{III}(\tau u) * \hat{f}(u) = \tau \sum_{-\infty}^{+\infty} \hat{f}\left(u - \frac{n}{\tau}\right)$$

The spectrum of the sampled function consists of an infinite sum of replicas of $\hat{f}(u)$. If $\tau^{-1} < 2f_c$, the replicas are separated by distances larger than their width and do not overlap (if not, they do and it creates in aliasing). Hence the information on $\hat{f}(u)$ and thus on $f(x)$ is preserved if the sampling condition $\tau \leq 1/(2f_c)$ is met. We can retrieve the original spectrum by multiplying $\hat{f}(u)$ by a rectangle function (gate) $\Pi(\tau u)$ in order to eliminate all replicas but one:

$$\left[\tau \text{III}(\tau u) * \hat{f}(u) \right] \times \Pi(\tau u) = \hat{f}(u)$$

which yields by inverse Fourier transform

$$[\text{III}(x/\tau) \cdot f(x)] * \tau^{-1} \text{sinc}(x/\tau) = f_s(x) * \tau^{-1} \text{III}(x/\tau) = f(x)$$



MAIN POINTS OF PAST TWO LECTURES

- Basic understanding of the **Fourier transform** and its properties, **sampling and aliasing** issues
- In Fourier Optics, light is described by a scalar field $\Psi = A \exp^{i\varphi}$
- In **Fraunhofer diffraction**, the **far and near field** complex amplitudes are linked by a Fourier transform $\Psi(P) = \mathcal{F}(\Psi(M))$
- An optical system can be characterised by its **impulse function** H . The impulse function is $H = |\mathcal{F}(\Psi(x))|^2$
- Object O and image \mathcal{I} are linked by the relation $\mathcal{I} = O * H$
- The Optical Transfer Function of a system characterises its spatial frequencies filtering properties $\text{OTF} = \mathcal{F}(H) = \Psi * \Psi^*$

IMAGE METRICS, ABERATIONS

PRACTICAL OPTICAL SYSTEMS

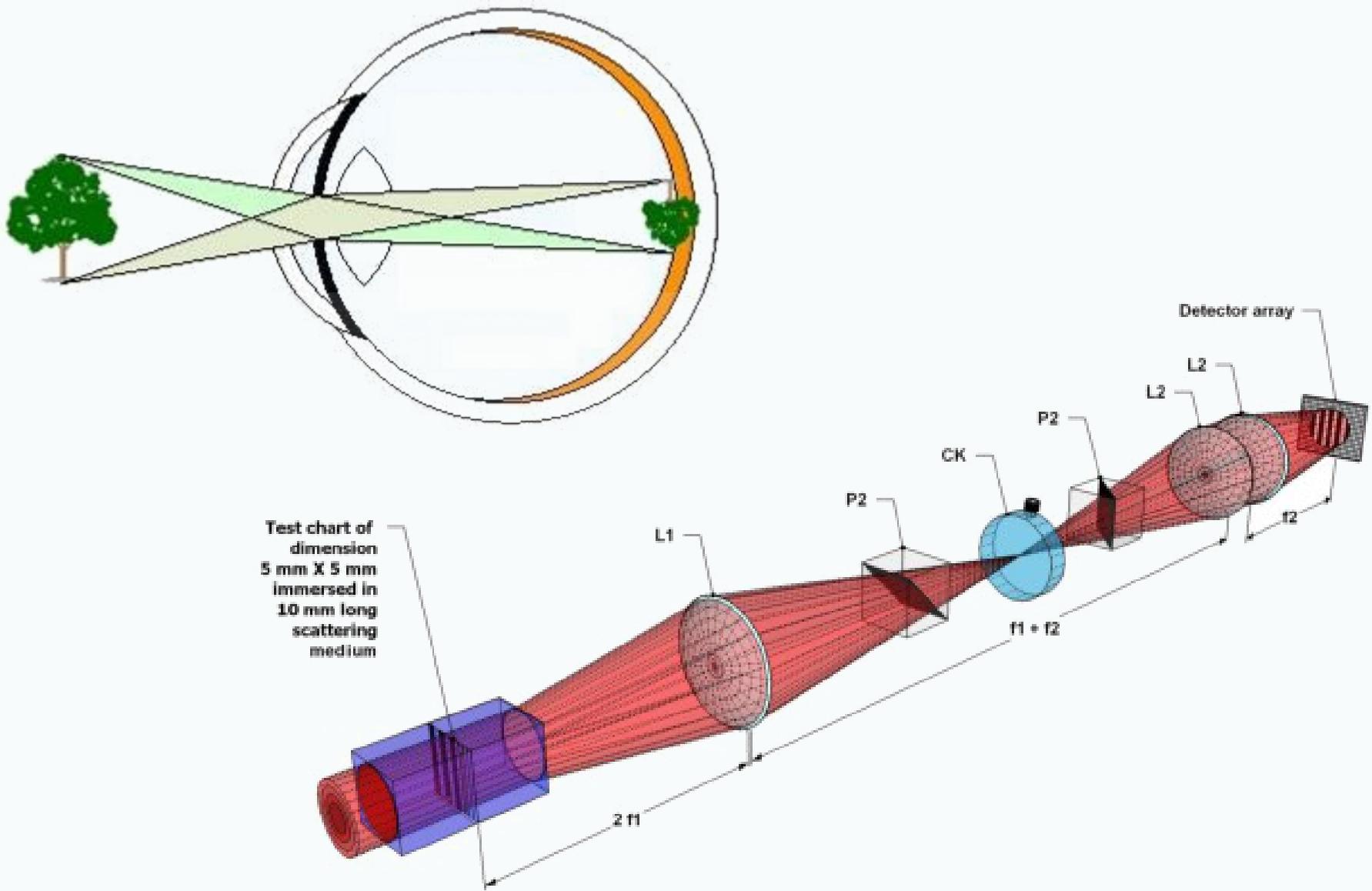
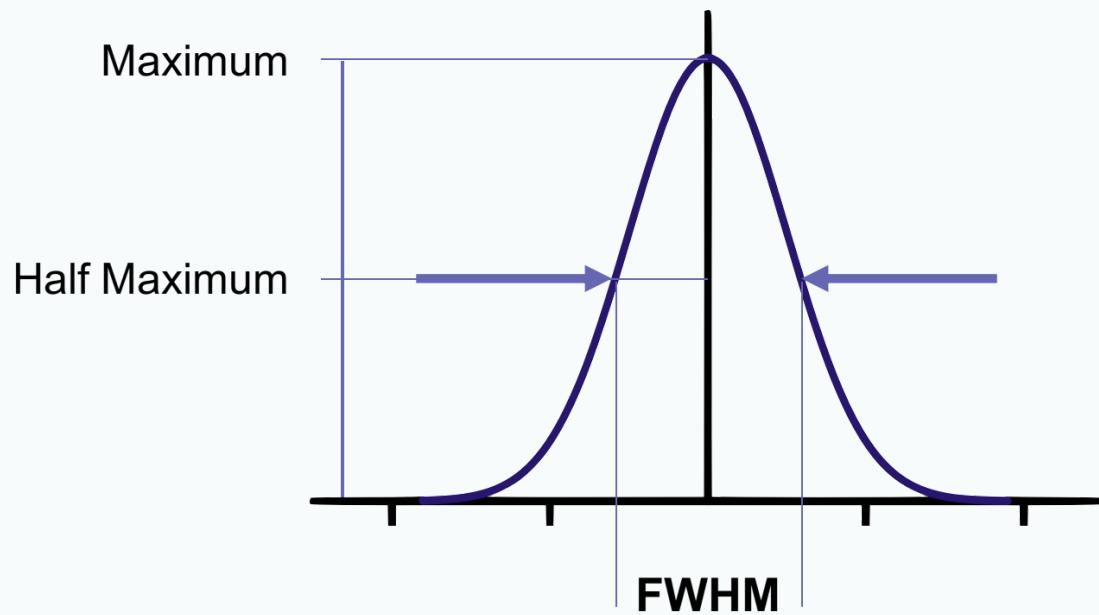
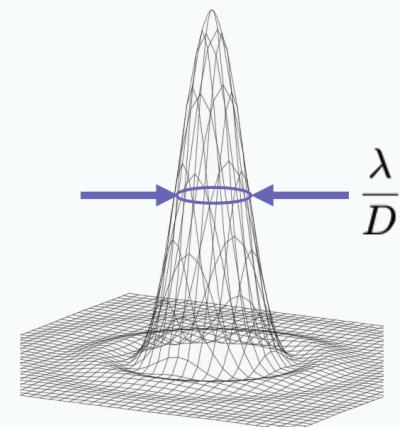


IMAGE METRIC: FULL-WIDTH AT HALF-MAXIMUM

- The width of the image at half its maximum. Often written FWHM
- For instance, a cross section of a gaussian image



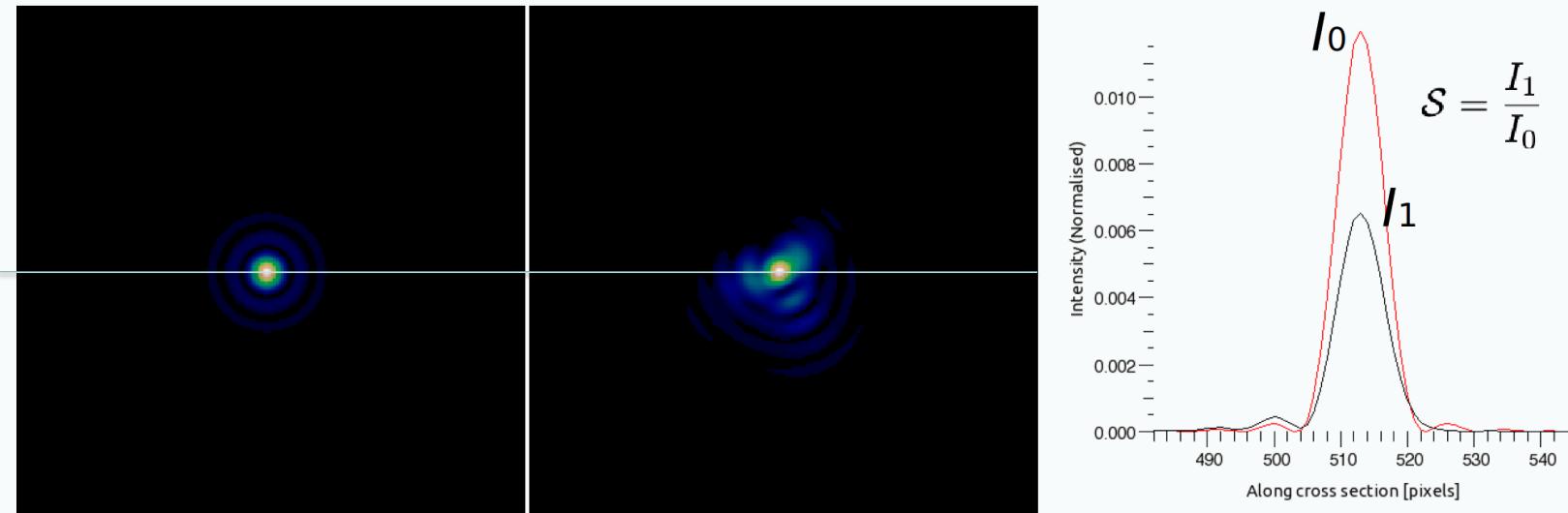
The FWHM of an airy pattern is λ/D



- The FWHM is often naturally expressed as an angle (e.g. arcsec) or a distance (e.g. mm), as it often characterise a resolution

IMAGE METRIC: STREHL RATIO \mathcal{S}

- The ratio between the maximum intensity in the actual image to the maximum in a diffraction limited image.



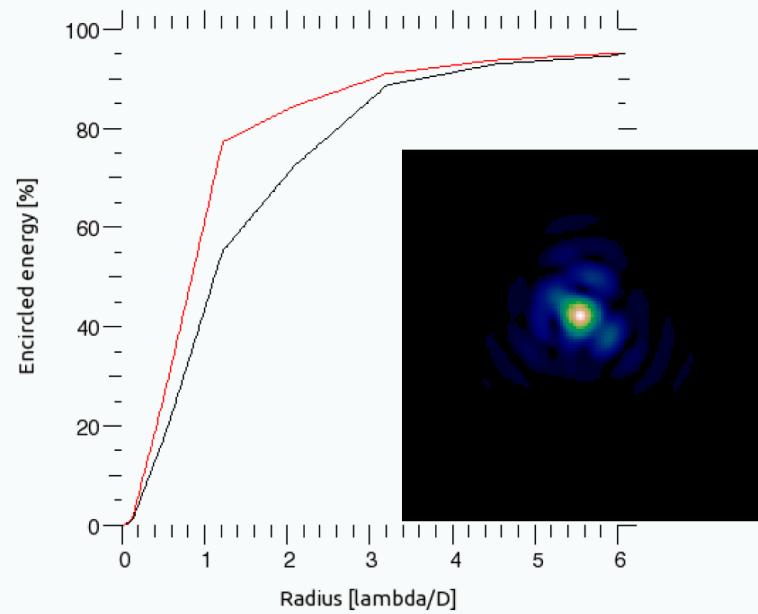
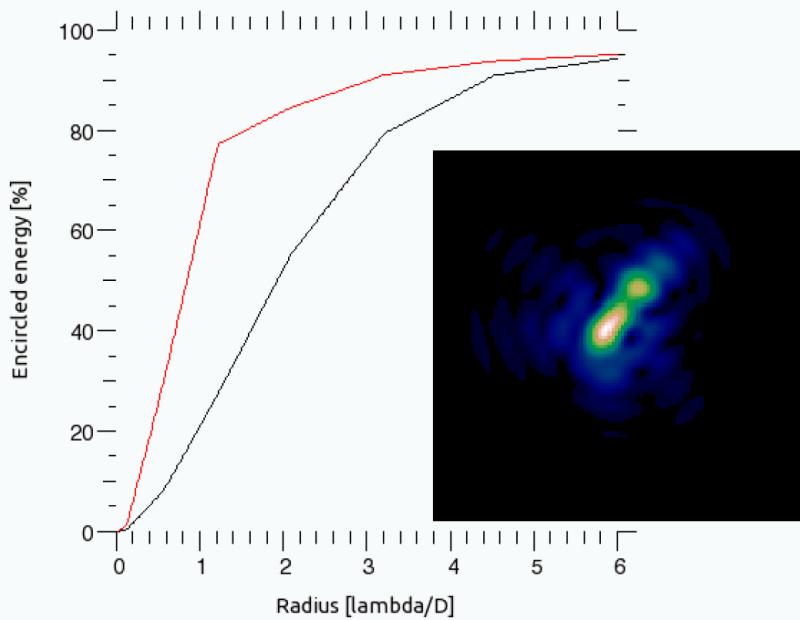
- A measure of how much energy is in the diffraction limited core
- For $\mathcal{S} \geq 0.2$, $\mathcal{S} = \exp(-\sigma_\varphi^2)$
- $0 \leq \mathcal{S} \leq 1$. The Strehl ratio is often expressed in % ($0 < \mathcal{S} < 100\%$)

$$\sigma_\varphi^2 = \frac{1}{S} \iint_S (\varphi(x, y) - \bar{\varphi})^2 ds \text{ is the phase variance}$$

IMAGE METRIC: ENCIRCLED ENERGY

- Intensity within a certain radius normalised by total intensity of the image

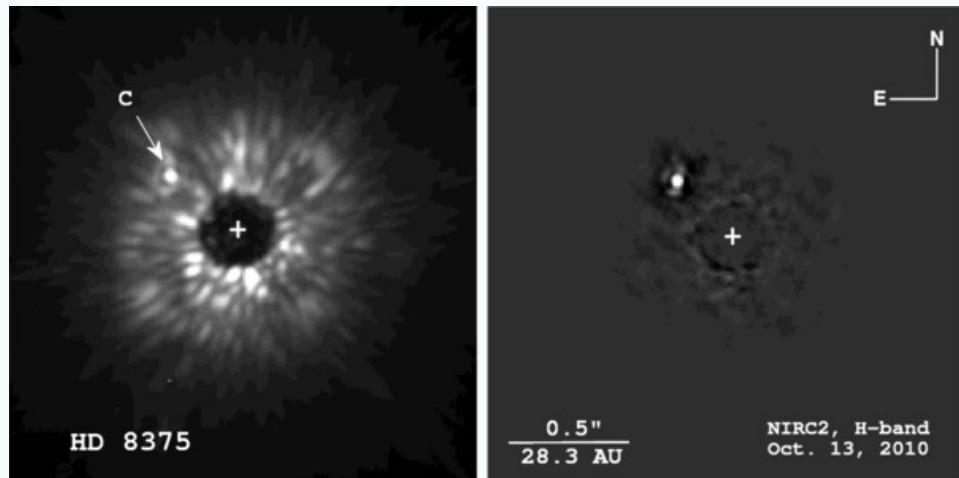
$$\varepsilon(r) = \frac{\int_{\theta=0}^{2\pi} \int_{\rho=0}^r \mathcal{I}(\rho, \theta) \rho d\rho d\theta}{\int_{\theta=0}^{2\pi} \int_{\rho=0}^{\infty} \mathcal{I}(\rho, \theta) \rho d\rho d\theta}$$



BEYOND "SIMPLE" METRICS

- High contrast imaging required the development of new metrics and new techniques to improve contrast performance
- Speckle control (next page is one of them)

HD8375. J.Crepp et al 2013



HR8799. T.Currie et al 2012

