

Difference-in-Differences with Panel Data

Slides 6: Nonlinear Difference-in-Differences

ESTIMATE: The Reduced Form
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1. Why Nonlinear Difference-in-Differences?
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3. General Common Timing Case
4. Adding Covariates
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1. Why Nonlinear Difference-in-Differences?

- Economic outcomes often are limited in some important way.
- At disaggregated levels, the response variable Y_{it} is often binary.
- At all levels of aggregation, Y_{it} might be a fractional response:

$$0 \leq Y_{it} \leq 1.$$

- Nonnegative outcomes are also important: $Y_{it} \geq 0$.
 - ▶ Could be a count variable, continuous, or mixed.
 - ▶ Zero is often an important value.

- Standard argument for using nonlinear models for limited dependent variables:
 - ▶ They provide a better “fit” than linear models.
 - ▶ Marginal effects are sometimes more plausible.
- In DID settings, using nonlinear mean functions can make the parallel (common) trends assumption more plausible.
- The PT assumption is not generally invariant to transformations.
 - ▶ If PT holds in logs, say, it is unlikely it holds in levels.

- Roth and Sant’Anna (2020, WP) on PT invariance to transformations.
- Athey and Imbens (2006, Econometrica): “Changes-in-Changes” formulations.
 - ▶ With discrete outcomes, only get bounds on the average treatment effect on the treated (ATT).
- With functional form assumptions, can identified ATTs.
- Current work: Extension of linear case in Wooldridge (2021, WP).

2. Nonlinear Models with $T = 2$

- Binary treatment indicator, D .
 - ▶ Treatment in second period.
- Potential outcomes are $Y_t(0), Y_t(1), t \in \{1, 2\}$.
- We want the ATT in $t = 2$:

$$\tau_2 = E[Y_2(1) - Y_2(0) | D = 1]$$

- Impose a no anticipation assumption:

$$Y_1 = Y_1(1) = Y_1(0)$$

- Linear parallel trends (in untreated state):

$$E[Y_1(0)|D] = \alpha + \beta D$$

$$E[Y_2(0)|D] = \alpha + \beta D + \gamma_2$$

$$E[Y_2(0)|D] - E[Y_1(0)|D] = (\alpha + \beta D + \gamma_2) - (\alpha + \beta D) = \gamma_2$$

- ▶ Trend in mean does not depend on D .
- Especially for discrete outcomes, linear parallel trends might be unrealistic.

- For a strictly increasing, continuously differentiable function $G(\cdot)$,

$$E[Y_1(0)|D] = G(\alpha + \beta D)$$

- Treatment can be systematically related to $Y_1(0)$.

- In the second period,

$$E[Y_2(0)|D] = G(\alpha + \beta D + \gamma_2)$$

- A nonlinear transformation of the means satisfies PT:

$$G^{-1}(E[Y_2(0)|D]) - G^{-1}(E[Y_1(0)|D]) = \gamma_2$$

- Suppose $Y_t(0)$ is binary:

$$Y_t(0) = 1[Y_t^*(0) > 0]$$

$$Y_t^*(0) = \alpha + \beta D + \gamma f 2_t + U_{it}$$

U_{it} continuous, independent of D , $t = 1, 2$

U_{i1}, U_{i2} identically distributed (may be correlated) with CDF $F(\cdot)$

- Then

$$\begin{aligned} E[Y_t(0)|D] &= P[Y_t(0) = 1|D] = P[\alpha + \beta D + \gamma_t + U_t > 0|D] \\ &= 1 - F[-(\alpha + \beta D + \gamma_t)] \equiv G(\alpha + \beta D + \gamma_t) \end{aligned}$$

- PT assumption for a linear model holds for the latent variable $Y_t^*(0)$:

$$E[Y_t^*(0)|D] = \alpha + \beta D + \gamma_t, t = 1, 2$$

- ▶ PT fails for $E[Y_t(0)|D]$.

- Exponential example:

$$E[Y_t(0)|D] = \exp(\alpha + \beta D + \gamma_t), t = 1, 2 \quad (\gamma_1 \equiv 0)$$

$$\frac{E[Y_2(0)|D]}{E[Y_1(0)|D]} = \exp(\gamma_2)$$

- ▶ Does not depend on D .
- Equivalently, the growth in the mean does not depend on D :

$$\log\{E[Y_2(0)|D]\} - \log\{E[Y_1(0)|D]\} = \gamma_2$$

- General case with $G(\cdot)$ continuously differentialy, strictly increasing:

$$E[Y_1(0)|D] = G(\alpha + \beta D)$$

- By no anticipation,

$$E(Y_1|D) = E[Y_1(0)|D] = G(\alpha + \beta D)$$

- ▶ So α and β are identified using $t = 1$ data.

- What about identifying the parameter of interest,

$$\tau_2 = E[Y_2(1)|D = 1] - E[Y_2(0)|D = 1]?$$

- We observe D , $Y_1 = Y_1(0) = Y_1(1)$, and

$$Y_2 = (1 - D)Y_2(0) + DY_2(1)$$

- First term in τ_2 is easy:

$$E(Y_2|D = 1) = E[Y_2(1)|D = 1]$$

- Given a random sample of size N , number of treated units is

$$N_1 = \sum_{i=1}^N D_i$$

- As usual, a consistent estimator of $E[Y_2(1)|D = 1]$ is

$$\bar{Y}_{12} = N_1^{-1} \sum_{i=1}^N D_i Y_{i2} = \left(\frac{N_1}{N} \right)^{-1} \left(N^{-1} \sum_{i=1}^N D_i Y_{i2} \right)$$

- ▶ Average of treated units in $t = 2$.

- As usual, the second part is harder.

$$E[Y_2(0)|D] = G(\alpha + \beta D + \gamma_2)$$

$$E[Y_2(0)|D = 1] = G(\alpha + \beta + \gamma_2)$$

- Need to estimate α , β , and γ_2 .
- α and β are identified using $t = 1$ and $D \in \{0, 1\}$:

$$E(Y_1|D) = E[Y_1(0)|D] = G(\alpha + \beta D)$$

- γ_2 is then identified using $t = 2$ and $D = 0$.

$$E(Y_2|D = 0) = E[Y_2(0)|D = 0] = G(\alpha + \gamma_2)$$

- Can estimate all parameters at once.
- Define $f2_t = 1$ if $t = 2$, zero otherwise.
- Time-varying treatment indicator:

$$W_t = D \cdot f2_t, t = 1, 2$$

- ▶ $W_t = 1$ for treated units in period two.
- Use the $W_t = 0$ (“untreated”) observations to estimate α, β, γ_2 .
 - ▶ $D = 0$ in both periods, $t = 1$ for $D = 1$.

- Linear case: Obtain $\hat{\alpha}$, $\hat{\beta}$, $\hat{\gamma}_2$ from the OLS regression

$$Y_{it} \text{ on } 1, D_i, f2_t, \quad t = 1, 2; \quad i = 1, \dots, N \text{ if } W_{it} = 0$$

- Then ATT for $t = 2$ is estimated as

$$\hat{\tau}_2 = \bar{Y}_{12} - (\hat{\alpha} + \hat{\beta} + \hat{\gamma}_2)$$

- This is the previous imputation estimator in the simplest case.
- It produces usual DID estimator:

$$\hat{\tau}_2 = (\bar{Y}_{12} - \bar{Y}_{11}) - (\bar{Y}_{02} - \bar{Y}_{01})$$

- With nonlinear $G(\cdot)$, for robust use quasi-MLE in the linear exponential family (LEF).

► But can use other methods to estimate

$$E(Y_{it}|D_i, W_{it} = 0) = G(\alpha + \beta D_i + \gamma_2 f_{2t})$$

- Benefits if we use the canonical link function in the chosen LEF.
- Then, can show that $\hat{\tau}_2$ is equivalent to the average partial effect of W_t evaluated at $D = 1, f_{2t} = 1$.

- Specifically, let $\hat{\alpha}$, $\hat{\beta}$, $\hat{\gamma}_2$, and $\hat{\delta}_2$ be the QMLEs from using all of the data and estimating the mean function

$$E(Y_{it}|D_i, W_{it}) = G(\alpha + \beta D_i + \gamma_2 f_{2t} + \delta_2 W_{it}), t = 1, 2$$

- ▶ Only needs to be the mean function for $W_t = 0$.
- Then

$$\hat{\tau}_2 = G(\hat{\alpha} + \hat{\beta} + \hat{\gamma}_2 + \hat{\delta}_2) - G(\hat{\alpha} + \hat{\beta} + \hat{\gamma}_2) = \bar{Y}_{12} - G(\hat{\alpha} + \hat{\beta} + \hat{\gamma}_2)$$
- ▶ Convenient for obtaining standard error of $\hat{\tau}_2$.

- Canonical link pairs (mean + LLF):
 - ▶ Linear + Normal (leads to OLS)
 - ▶ Logistic + Bernoulli (binary and fractional)
 - ▶ Logistic + Binomial (nonnegative, known upper bound)
 - ▶ Exponential + Poisson (nonnegative, no natural upper bound)

3. General Common Timing Case

- Allow any $T > 2$. Intervention occurs at $1 < q \leq T$.
- Treatment indicator is D . Potential outcomes are $Y_t(0)$, $Y_t(1)$.
- No anticipation:

$$Y_t = Y_t(0) = Y_t(1), 1 \leq t < q$$

- ATTs for each treated period:

$$\tau_r = E[Y_r(1) - Y_r(0) | D = 1], r = q, q + 1, \dots, T$$

- Common or Parallel Trends Assumption: For a known, strictly increasing, continuously differentiable function $G(\cdot)$ and parameters α , β , and $\gamma_2, \dots, \gamma_T$,

$$E[Y_t(0)|D] = G(\alpha + \beta D + \gamma_t), t = 1, 2, \dots, T \ (\gamma_1 \equiv 0)$$

- Equivalently,

$$G^{-1}(E[Y_t(0)|D]) - G^{-1}(E[Y_{t-1}(0)|D]) = \gamma_t - \gamma_{t-1}, t = 2, \dots, T$$

- Transformation of mean does not depend on D .

- ATTs still have the form

$$\tau_r = E(Y_r|D = 1) - G(\alpha + \beta + \gamma_r), r = q, \dots, T$$

- Time-varying treatment indicator:

$$W_{it} = D_i(fq_t + \dots + fT_t) \equiv D_i p_t$$

- $W_{it} = 1$ for a treated unit in an intervention period.
- $\alpha, \beta, \gamma_2, \dots, \gamma_T$ estimated by pooling $W_{it} = 0$ observations.

$$\hat{\tau}_r = \bar{Y}_{1r} - G(\hat{\alpha} + \hat{\beta} + \hat{\gamma}_r), r = q, \dots, T$$

$$\bar{Y}_{1r} = N_1^{-1} \sum_{i=1}^N D_i Y_{ir}$$

- When $G(\cdot)$ is the canonical link, $\hat{\tau}_r$ can be obtained as estimated APEs with respect to W_{it} in the mean function

$$E(Y_{it}|D_i) = G[\alpha + \beta D_i + \gamma_2 f_2 + \cdots + \gamma_T f_T + \delta_q(W_{it} \cdot f_q) + \cdots + \delta_T(W_{it} \cdot f_T)]$$

- Pooled estimation using all data.

$$\hat{\tau}_r = G(\hat{\alpha} + \hat{\beta} + \hat{\gamma}_r + \hat{\delta}_r) - G(\hat{\alpha} + \hat{\beta} + \hat{\gamma}_r), r = q, \dots, T$$

► Because of algebraic equivalence, $G(\alpha + \beta + \gamma_t)$ only has to be the mean function when $W_t = 0$.

► $W_{it} \cdot f_r = W_{it} \cdot D_i \cdot f_r$ and APE calculations are the same.

4. Adding Covariates

- Still assume no anticipation.
- Parallel trends conditional on \mathbf{X} :

$$E[Y_t(0)|D, \mathbf{X}] = G[\alpha + \beta D + \mathbf{X}\boldsymbol{\kappa} + (D \cdot \mathbf{X})\boldsymbol{\xi} \\ + \gamma_2 f_2 + \cdots + \gamma_T f_T + (f_2 \cdot \mathbf{X})\boldsymbol{\pi}_2 + \cdots + (f_T \cdot \mathbf{X})\boldsymbol{\pi}_T]$$

- ▶ No interactions between D and the f_s .
- ▶ No triple interactions $D \cdot f_s \cdot \mathbf{X}$.

- Still want ATTs for $r = q, q + 1, \dots, T$:

$$\begin{aligned}\tau_r &= E[Y_r(1) - Y_r(0)|D = 1] \\ &= E(Y_r|D = 1) - E[G(\alpha + \beta + \gamma_r + \mathbf{X}(\boldsymbol{\kappa} + \boldsymbol{\xi} + \boldsymbol{\pi}_r))|D = 1]\end{aligned}$$

- $\alpha, \beta, \boldsymbol{\kappa}, \boldsymbol{\xi}, \gamma_2, \dots, \gamma_T, \boldsymbol{\pi}_2, \dots, \boldsymbol{\pi}_T$ can be estimated using a quasi-MLE in the LEF restricted to $W_{it} = 0$.

- Imputation estimator:

$$\begin{aligned}\hat{\tau}_r &= \bar{Y}_{1r} - N_1^{-1} \sum_{i=1}^N D_i G(\hat{\alpha} + \hat{\beta} + \hat{\gamma}_r + \mathbf{X}_i(\hat{\boldsymbol{\kappa}} + \hat{\boldsymbol{\xi}} + \hat{\boldsymbol{\pi}}_r)) \\ \bar{Y}_{1r} &= N_1^{-1} \sum_{i=1}^N D_i Y_{ir}, N_1 = \sum_{i=1}^N D_i, r = q, \dots, T\end{aligned}$$

- In the canonical link case, equivalent to pooling all data to estimate

$$\begin{aligned}
E(Y_{it}|D_i, \mathbf{X}_i) = & G[\alpha + \beta D_i + \mathbf{X}_i \boldsymbol{\kappa} + (D_i \cdot \mathbf{X}_i) \boldsymbol{\xi} \\
& + \gamma_2 f_2 + \cdots + \gamma_T f_T + (f_2 \cdot \mathbf{X}_i) \boldsymbol{\pi}_2 + \cdots + (f_T \cdot \mathbf{X}_i) \boldsymbol{\pi}_T \\
& + \delta_q(W_{it} \cdot f_q) + \cdots + \delta_T(W_{it} \cdot f_T) \\
& + (W_{it} \cdot f_q \cdot \mathbf{X}_i) \boldsymbol{\xi}_q + (W_{it} \cdot f_T \cdot \mathbf{X}_i) \boldsymbol{\xi}_T]
\end{aligned}$$

- For $\hat{\tau}_r$, obtain the APE of W_t at $D = 1, fr_t = 1, fs_t = 0$ all $s \neq r$, and average across the subsample $D_i = 1$.
- Same as using $W_{it} \cdot D_i$ in place of W_{it} .

- For $r = q, \dots, T$,

$$\begin{aligned}\hat{\tau}_r &= N_1^{-1} \sum_{i=1}^N D_i \left[G\left(\hat{\alpha} + \hat{\beta} + \hat{\gamma}_r + \hat{\delta}_t + \mathbf{X}_i\left(\hat{\mathbf{k}} + \hat{\xi} + \hat{\pi}_r + \hat{\xi}_r\right)\right) - \right. \\ &\quad \left. G\left(\hat{\alpha} + \hat{\beta} + \hat{\gamma}_r + \mathbf{X}_i\left(\hat{\mathbf{k}} + \hat{\xi} + \hat{\pi}_r\right)\right) \right] \\ &= \bar{Y}_{1r} - N_1^{-1} \sum_{i=1}^N D_i G\left(\hat{\alpha} + \hat{\beta} + \hat{\gamma}_r + \mathbf{X}_i\left(\hat{\mathbf{k}} + \hat{\xi} + \hat{\pi}_r\right)\right)\end{aligned}$$

- In Stata, the `margins` command is convenient.
 - Use `vce(uncond)` to account for sampling error in $\{\mathbf{X}_i : i = 1, \dots, N\}$.

```

logit y i.w#c.fq ... i.w#c.fT
      i.w#c.fq#c.x1 ... i.w#c.fq#c.xK
      ... i.w#c.fT#c.x1 ... i.w#c.fT#c.xK
d x1 ...xK c.d#c.x1 ... c.d#c.xK
f2 ... fT c.f2#c.x1 ... c.f2#c.xK
... c.fT#c.x1 ... c.fT#c.xK,
noomit vce(cluster id)

```

```

margins, dydx(w) at(d = 1 f2 = 0 ... fq_min1 = 0
fq = 1 fq_plus1 = 0 ... fT = 0)
subpop(if d == 1) vce(uncond)
margins, dydx(w) at(d = 1 f2 = 0 ... fq_min1 = 0
fq = 0 fq_plus1 = 1 ... fT = 0)
subpop(if d == 1) vce(uncond)
:
margins, dydx(w) at(d = 1 f2 = 0 ... fq_min1 = 0
fq = 0 fq_plus1 = 0 ... fT = 1)
subpop(if d == 1) vce(uncond)

```

```
. use did_common_6_binary, clear
```

```
. tab year
```

| year | Freq. | Percent | Cum. |
|-------|-------|---------|--------|
| 2001 | 1,000 | 16.67 | 16.67 |
| 2002 | 1,000 | 16.67 | 33.33 |
| 2003 | 1,000 | 16.67 | 50.00 |
| 2004 | 1,000 | 16.67 | 66.67 |
| 2005 | 1,000 | 16.67 | 83.33 |
| 2006 | 1,000 | 16.67 | 100.00 |
| Total | 6,000 | 100.00 | |

```
. tab d if f06
```

| d | Freq. | Percent | Cum. |
|-------|-------|---------|--------|
| 0 | 618 | 61.80 | 61.80 |
| 1 | 382 | 38.20 | 100.00 |
| Total | 1,000 | 100.00 | |

```
. tab y
```

| y | Freq. | Percent | Cum. |
|-------|-------|---------|--------|
| 0 | 3,468 | 57.80 | 57.80 |
| 1 | 2,532 | 42.20 | 100.00 |
| Total | 6,000 | 100.00 | |

```
. * Sample ATTs:
```

```
. sum te_i if d & f04
```

| Variable | Obs | Mean | Std. dev. | Min | Max |
|----------|-----|---------|-----------|-----|-----|
| te_i | 382 | .078534 | .6054086 | -1 | 1 |

```
. sum te_i if d & f05
```

| Variable | Obs | Mean | Std. dev. | Min | Max |
|----------|-----|---------|-----------|-----|-----|
| te_i | 382 | .117801 | .6055278 | -1 | 1 |

```
. sum te_i if d & f06
```

| Variable | Obs | Mean | Std. dev. | Min | Max |
|----------|-----|----------|-----------|-----|-----|
| te_i | 382 | .1099476 | .6177221 | -1 | 1 |


```

. * Linear model (standard errors not adjusted for xbar):
.
. reg y c.d#c.f04 c.d#c.f05 c.d#c.f06 ///
>      c.d#c.f04#c.x_dm c.d#c.f05#c.x_dm c.d#c.f06#c.x_dm ///
>      f02 f03 f04 f05 f06 ///
>      c.f02#c.x c.f03#c.x c.f04#c.x c.f05#c.x c.f06#c.x ///
>      d x c.d#c.x, vce(cluster id)

```

```

Linear regression                                Number of obs    =      6,000
                                                F(19, 999)        =      73.84
                                                Prob > F          =      0.0000
                                                R-squared         =      0.1458
                                                Root MSE         =      .45722

```

(Std. err. adjusted for 1,000 clusters in id)

| | | Robust | | | | |
|--|------------------|-------------|-----------|-------|-------|----------------------|
| | y | Coefficient | std. err. | t | P> t | [95% conf. interval] |
| | c.d#c.f04 | .0462206 | .0367915 | 1.26 | 0.209 | -.0259768 .1184181 |
| | c.d#c.f05 | .0755069 | .0375981 | 2.01 | 0.045 | .0017265 .1492873 |
| | c.d#c.f06 | .0445457 | .0378681 | 1.18 | 0.240 | -.0297645 .118856 |
| | c.d#c.f04#c.x_dm | -.0185417 | .0885739 | -0.21 | 0.834 | -.1923539 .1552704 |
| | c.d#c.f05#c.x_dm | .0453048 | .085807 | 0.53 | 0.598 | -.1230779 .2136875 |
| | c.d#c.f06#c.x dm | .130662 | .0841938 | 1.55 | 0.121 | -.0345549 .2958789 |

| | | | | | | | |
|-----------|--|-----------|----------|-------|-------|-----------|-----------|
| f02 | | .0009375 | .0509461 | 0.02 | 0.985 | -.0990362 | .1009113 |
| f03 | | -.0363479 | .0531606 | -0.68 | 0.494 | -.1406672 | .0679714 |
| f04 | | .0227675 | .0718298 | 0.32 | 0.751 | -.118187 | .1637221 |
| f05 | | .0047325 | .068471 | 0.07 | 0.945 | -.129631 | .1390961 |
| f06 | | .132355 | .0694451 | 1.91 | 0.057 | -.0039201 | .26863 |
| c.f02#c.x | | -.0118991 | .0455013 | -0.26 | 0.794 | -.1011881 | .0773899 |
| c.f03#c.x | | .0392213 | .0484515 | 0.81 | 0.418 | -.0558571 | .1342997 |
| c.f04#c.x | | .0613781 | .0705436 | 0.87 | 0.384 | -.0770525 | .1998087 |
| c.f05#c.x | | .0941201 | .0663857 | 1.42 | 0.157 | -.0361513 | .2243914 |
| c.f06#c.x | | .0185686 | .0705219 | 0.26 | 0.792 | -.1198194 | .1569567 |
| d | | -.3353013 | .0434568 | -7.72 | 0.000 | -.4205783 | -.2500243 |
| x | | .1262778 | .0447227 | 2.82 | 0.005 | .0385166 | .214039 |
| c.d#c.x | | -.0628457 | .0421785 | -1.49 | 0.137 | -.1456143 | .019923 |
| _cons | | .3866191 | .0456444 | 8.47 | 0.000 | .2970492 | .4761891 |

```
. * Pooled logit:
```

```
. logit y i.w#c.d#c.f04 i.w#c.d#c.f05 i.w#c.d#c.f06 ///
> i.w#c.d#c.f04#c.x i.w#c.d#c.f05#c.x i.w#c.d#c.f06#c.x ///
> f02 f03 f04 f05 f06 c.f02#c.x c.f03#c.x c.f04#c.x c.f05#c.x c.f06#c.x ///
> d x c.d#c.x, noomitted vce(cluster id)
```

| | | ----- | | | | | |
|-----------------|---|-------------|---------------------|-------|-------|----------------------|----------|
| | y | Coefficient | Robust std. err. | z | P> z | [95% conf. interval] | |
| ----- | | | | | | | |
| w#c.d#c.f04 | 1 | .9412159 | .5137085 | 1.83 | 0.067 | -.0656342 | 1.948066 |
| w#c.d#c.f05 | 1 | .7852733 | .4969686 | 1.58 | 0.114 | -.1887672 | 1.759314 |
| w#c.d#c.f06 | 1 | .2581332 | .4880446 | 0.53 | 0.597 | -.6984167 | 1.214683 |
| w#c.d#c.f04#c.x | 1 | -.3314925 | .4347067 | -0.76 | 0.446 | -1.183502 | .520517 |
| w#c.d#c.f05#c.x | 1 | -.0874416 | .423375 | -0.21 | 0.836 | -.9172414 | .7423582 |
| w#c.d#c.f06#c.x | 1 | .2483893 | .4193698 | 0.59 | 0.554 | -.5735604 | 1.070339 |

| | | | | | | | |
|-----------|--|-----------|----------|-------|-------|-----------|-----------|
| f02 | | .0159557 | .254879 | 0.06 | 0.950 | -.4835981 | .5155094 |
| f03 | | -.1853553 | .2622365 | -0.71 | 0.480 | -.6993293 | .3286188 |
| f04 | | .0539743 | .3137998 | 0.17 | 0.863 | -.5610619 | .6690106 |
| f05 | | -.0386572 | .3041224 | -0.13 | 0.899 | -.6347261 | .5574118 |
| f06 | | .4795352 | .3138648 | 1.53 | 0.127 | -.1356284 | 1.094699 |
| c.f02#c.x | | -.0749433 | .2420313 | -0.31 | 0.757 | -.549316 | .3994294 |
| c.f03#c.x | | .2054979 | .2502045 | 0.82 | 0.411 | -.284894 | .6958897 |
| c.f04#c.x | | .2938375 | .3180849 | 0.92 | 0.356 | -.3295974 | .9172724 |
| c.f05#c.x | | .4540765 | .30813 | 1.47 | 0.141 | -.1498472 | 1.058 |
| c.f06#c.x | | .1561729 | .3322175 | 0.47 | 0.638 | -.4949615 | .8073073 |
| d | | -2.185559 | .2805608 | -7.79 | 0.000 | -2.735448 | -1.63567 |
| x | | .5048528 | .2036075 | 2.48 | 0.013 | .1057896 | .9039161 |
| c.d#c.x | | .0588332 | .2287561 | 0.26 | 0.797 | -.3895205 | .5071869 |
| _cons | | -.4500012 | .2046174 | -2.20 | 0.028 | -.8510439 | -.0489586 |

```
. margins, dydx(w) at(d = 1 f02 = 0 f03 = 0 f04 = 1 f05 = 0 f06 = 0) ///
> subpop(if d == 1) noestimcheck vce(uncond)
```

| | | Unconditional | | | | [95% conf. interval] | |
|-----|--|---------------|-----------|------|-------|----------------------|----------|
| | | dy/dx | std. err. | z | P> z | | |
| 1.w | | .0886639 | .0326848 | 2.71 | 0.007 | .0246029 | .1527249 |

```
. margins, dydx(w) at(d = 1 f02 = 0 f03 = 0 f04 = 0 f05 = 1 f06 = 0) ///
> subpop(if d == 1) noestimcheck vce(uncond)
```

| | | Unconditional | | | | [95% conf. interval] | |
|-----|--|---------------|-----------|------|-------|----------------------|----------|
| | | dy/dx | std. err. | z | P> z | | |
| 1.w | | .1217999 | .0355845 | 3.42 | 0.001 | .0520556 | .1915441 |

```
. margins, dydx(w) at(d = 1 f02 = 0 f03 = 0 f04 = 0 f05 = 0 f06 = 1) ///
> subpop(if d == 1) noestimcheck vce(uncond)
```

| | | Unconditional | | | | [95% conf. interval] | |
|-----|--|---------------|-----------|------|-------|----------------------|----------|
| | | dy/dx | std. err. | z | P> z | | |
| 1.w | | .1073639 | .0371242 | 2.89 | 0.004 | .0346018 | .1801261 |

```
. * Callaway and Sant'Anna (2021, Journal of Econometrics)
```

```
.  
. gen first_treat = 0
```

```
. replace first_treat = 2004 if d  
(2,292 real changes made)
```

```
. csdid y x, ivar(id) time(year) gvar(first_treat)
```

```
.....
```

Difference-in-difference with Multiple Time Periods

Outcome model :

Treatment model:

| | Coefficient | Std. err. | z | P> z | [95% conf. interval] | |
|-------------|-------------|-----------|-------|-------|----------------------|----------|
| g2004 | | | | | | |
| t_2001_2002 | .0395675 | .0423073 | 0.94 | 0.350 | -.0433533 | .1224884 |
| t_2002_2003 | -.009403 | .0413075 | -0.23 | 0.820 | -.0903642 | .0715583 |
| t_2003_2004 | .0278723 | .0461201 | 0.60 | 0.546 | -.0625215 | .1182661 |
| t_2003_2005 | .0610949 | .0457254 | 1.34 | 0.182 | -.0285252 | .150715 |
| t_2003_2006 | .0367104 | .0448462 | 0.82 | 0.413 | -.0511866 | .1246074 |

Control: Never Treated

See Callaway and Sant'Anna (2020) for details

5. Staggered Interventions

- Now we have different treatment cohorts.
- First group (cohort) is $g = q$, last is $g = T$.
- No reversibility.
 - ▶ Potential outcome in the never treated state: $Y_t(\infty)$.
 - ▶ Potential outcome if first treatment period is g : $Y_t(g)$, $g = q, \dots, T$.
- Assume a never treated group.
 - ▶ Easy to relax.

- For $g \in \{q, q+1, \dots, T\}$ we are interested in the following ATTs:

$$\begin{aligned}\tau_{gr} &= E[Y_r(g) - Y_r(\infty) | D_g = 1] \\ &= E[Y_r(g) | D_g = 1] - E[Y_r(\infty) | D_g = 1], \quad r = g, g+1, \dots, T\end{aligned}$$

- Because $Y_r = Y_r(g)$ when $D_g = 1$, $E[Y_r(g) | D_g = 1]$ is always estimable:

$$\bar{Y}_{gr} = N_g^{-1} \sum_{i=1}^N D_{ig} \cdot Y_{ir} = N_g^{-1} \sum_{i=1}^N D_{ig} \cdot Y_{ir}(g) \xrightarrow{p} E[Y_r(g) | D_g = 1]$$

$$N_g = \sum_{i=1}^N D_{ig}$$

- To estimate $E[Y_r(\infty)|D_g = 1]$, we assume the following.

1. No anticipation: For cohorts $g = q, \dots, T$,

$$Y_t(g) = Y_t(\infty), t = 1, \dots, g - 1$$

- Can be relaxed.

2. Conditional common or parallel trends: For a known, strictly increasing function $G(\cdot)$,

$$E[Y_{it}(\infty)|D_{iq}, \dots, D_{iT}, \mathbf{X}_i] = G \left[\alpha + \sum_{g=q}^T \beta_g D_{ig} + \mathbf{X}_i \boldsymbol{\kappa} + \sum_{g=q}^T (D_{ig} \cdot \mathbf{X}_i) \boldsymbol{\xi}_g + \sum_{s=2}^T \gamma_s f_{st} + \sum_{s=2}^T (f_{st} \cdot \mathbf{X}_i) \boldsymbol{\pi}_s \right]$$

- No anticipation means we observe $Y_{it}(\infty)$ for eventually treated cohorts prior to intervention.
- Conditional PT means no interactions allowed among D_{ig} and f_{st} .
- Linear case from before: $G(z) \equiv z$.

- To estimate τ_{gr} , we need to estimate

$$E[Y_r(\infty)|D_g = 1] = E\left[G\left(\alpha + \beta_g + \mathbf{X}_i\boldsymbol{\kappa} + \mathbf{X}_i\boldsymbol{\xi}_g + \gamma_r + \mathbf{X}_i\boldsymbol{\pi}_r\right) \middle| D_g = 1\right]$$

- Use an imputation approach.

1. Using $W_{it} = 0$ observations, estimate the parameters

$$\left(\alpha, \beta_q, \dots, \beta_T, \boldsymbol{\kappa}, \boldsymbol{\xi}_q, \dots, \boldsymbol{\xi}_T, \gamma_2, \dots, \gamma_T, \boldsymbol{\pi}_2, \dots, \boldsymbol{\pi}_T\right)$$

using pooled quasi-MLE in the linear exponential family (LEF).

► Bernoulli ($0 \leq Y_{it} \leq 1$), Poisson ($Y_{it} \geq 0$) attractive.

2. Impute $Y_{ir}(\infty)$ for $W_{ir} = 1$:

$$\hat{Y}_{igr}(\infty) \equiv G\left(\hat{\alpha} + \hat{\beta}_g + \mathbf{X}_i\hat{\boldsymbol{\kappa}} + \mathbf{X}_i\hat{\boldsymbol{\xi}}_g + \hat{\gamma}_r + \mathbf{X}_i\hat{\boldsymbol{\pi}}_r\right), r = g, \dots, T$$

- Estimate of τ_{gr} : For $r = g, \dots, T$,

$$\begin{aligned}\hat{\tau}_{gr} &= N_g^{-1} \sum_{i=1}^N D_{ig} [Y_{ir} - \hat{Y}_{igr}(\infty)] \\ &= \bar{Y}_{gr} - N_g^{-1} \sum_{i=1}^N D_{ig} G(\hat{\alpha} + \hat{\beta}_g + \mathbf{X}_i \hat{\mathbf{k}} + \mathbf{X}_i \hat{\boldsymbol{\xi}}_g + \hat{\gamma}_r + \mathbf{X}_i \hat{\boldsymbol{\pi}}_r)\end{aligned}$$

- ▶ Extension of linear imputation estimators.
- ▶ Can obtain an analytical standard error or use bootstrap.
- Can apply to Tobit models, two-part models, and so on.
 - ▶ Replace the index $G(\cdot)$ with the conditional mean from the chosen model.

- With a canonical link in the LEF, same as estimating a conditional mean on the full sample with many interactions.

$$\begin{aligned}
E(Y_{it}|D_{iq}, \dots, D_{iT}, \mathbf{X}_i) = G & \left[\alpha + \sum_{g=q}^T \beta_g D_{ig} + \mathbf{X}_i \boldsymbol{\kappa} + \sum_{g=q}^T (D_{ig} \cdot \mathbf{X}_i) \boldsymbol{\eta}_g \right. \\
& + \sum_{s=2}^T \gamma_s f_{st} + \sum_{s=2}^T (f_{st} \cdot \mathbf{X}_i) \boldsymbol{\pi}_s \\
& + \sum_{g=q}^T \sum_{s=g}^T \delta_{gs} (W_{it} \cdot D_{ig} \cdot f_{st}) \\
& \left. + \sum_{g=q}^T \sum_{s=g}^T (W_{it} \cdot D_{ig} \cdot f_{st} \cdot \mathbf{X}_i) \boldsymbol{\lambda}_{gs} \right]
\end{aligned}$$

- Partial effect still taken with respect to W_t .
- Interactions must include the D_{ig} to get the $\hat{\tau}_{gr}$ as average partial effects.
- Average over the different subsamples determined by the D_g and fr_t .
- Centering the covariates can make the parameters more interpretable, but has no effect on properly computed APEs.
 - In exponential case, useful for estimating percentage effects.
- Correctly done, `margins` in Stata provides proper standard errors.

```
. * Generated data, T = 6, three treated periods.
. * y a corner solution outcome.
```

```
. use did_staggered_6_corner, clear
```

```
. xtset id year
```

Panel variable: id (strongly balanced)

Time variable: year, 2001 to 2006

Delta: 1 unit

```
. sum dinf d4 d5 d6 if year == 2001
```

| Variable | Obs | Mean | Std. dev. | Min | Max |
|----------|-------|------|-----------|-----|-----|
| dinf | 1,000 | .503 | .5002412 | 0 | 1 |
| d4 | 1,000 | .277 | .4477404 | 0 | 1 |
| d5 | 1,000 | .163 | .3695505 | 0 | 1 |
| d6 | 1,000 | .057 | .2319586 | 0 | 1 |

```
. sum y
```

| Variable | Obs | Mean | Std. dev. | Min | Max |
|----------|-------|----------|-----------|-----|----------|
| y | 6,000 | 6.356815 | 30.53533 | 0 | 977.2437 |

```
. count if y == 0
2,194
```

```
. * The sample ATTs:
```

```
.  
. gen te_4i = y4 - yinf
```

```
. sum te_4i if d4 & f04
```

| Variable | Obs | Mean | Std. dev. | Min | Max |
|----------|-----|----------|-----------|-----------|----------|
| te_4i | 277 | 2.079871 | 11.41619 | -31.82291 | 74.87006 |

```
. sum te_4i if d4 & f05
```

| Variable | Obs | Mean | Std. dev. | Min | Max |
|----------|-----|----------|-----------|-----------|----------|
| te_4i | 277 | 5.265336 | 47.0484 | -474.6237 | 402.3652 |

```
. sum te_4i if d4 & f06
```

| Variable | Obs | Mean | Std. dev. | Min | Max |
|----------|-----|----------|-----------|---------|----------|
| te_4i | 277 | 4.622355 | 19.60196 | -37.414 | 168.5657 |


```
. gen te_5i = y5 - yinf
```

```
. sum te_5i if d5 & f05
```

| Variable | Obs | Mean | Std. dev. | Min | Max |
|----------|-----|----------|-----------|-----------|----------|
| te_5i | 163 | 4.392324 | 29.06417 | -41.48495 | 273.8863 |

```
. sum te_5i if d5 & f06
```

| Variable | Obs | Mean | Std. dev. | Min | Max |
|----------|-----|----------|-----------|-----------|----------|
| te_5i | 163 | 5.179047 | 32.92998 | -200.6624 | 179.0408 |

```
. gen te_6i = y6 - yinf
```

```
. sum te_6i if d6 & f06
```

| Variable | Obs | Mean | Std. dev. | Min | Max |
|----------|-----|----------|-----------|-----------|----------|
| te_6i | 57 | 11.63881 | 71.78052 | -19.07541 | 529.1949 |

```
. * did_staggered_6_poisson.do shows the poisson regression with
. * covariates centered.
```

```
. poisson y i.w#c.d4#c.f04 i.w#c.d4#c.f05 i.w#c.d4#c.f06 ///
> i.w#c.d5#c.f05 i.w#c.d5#c.f06 ///
> i.w#c.d6#c.f06 ///
> i.w#c.d4#c.f04#c.x i.w#c.d4#c.f05#c.x i.w#c.d4#c.f06#c.x ///
> i.w#c.d5#c.f05#c.x i.w#c.d5#c.f06#c.x ///
> i.w#c.d6#c.f06#c.x ///
> f02 f03 f04 f05 f06 ///
> c.f02#c.x c.f03#c.x c.f04#c.x c.f05#c.x c.f06#c.x ///
> d4 d5 d6 x c.d4#c.x c.d5#c.x c.d6#c.x, noomitted vce(cluster id)
note: you are responsible for interpretation of noncount dep. variable.
```

| ----- | | | | | | |
|--------------|---|-------------|---------------------|-------|-------|----------------------|
| | y | Coefficient | Robust std. err. | z | P> z | [95% conf. interval] |
| ----- | | | | | | |
| w#c.d4#c.f04 | 1 | .4798855 | .5537199 | 0.87 | 0.386 | -.6053856 1.565157 |
| w#c.d4#c.f05 | 1 | 1.26722 | .5110232 | 2.48 | 0.013 | .2656328 2.268807 |
| w#c.d4#c.f06 | 1 | .6365721 | .5979153 | 1.06 | 0.287 | -.5353202 1.808465 |
| w#c.d5#c.f05 | 1 | .3369498 | 1.14253 | 0.29 | 0.768 | -1.902368 2.576267 |
| w#c.d5#c.f06 | 1 | -.0489807 | .9182506 | -0.05 | 0.957 | -1.848719 1.750757 |
| w#c.d6#c.f06 | 1 | 2.035604 | 1.182908 | 1.72 | 0.085 | -.282853 4.354062 |

| | | | | | | | |
|-------------------------|--|-----------|----------|-------|-------|-----------|----------|
| w#c.d4#c.f04#c.x | | | | | | | |
| 1 | | -.2052884 | .4326644 | -0.47 | 0.635 | -1.053295 | .6427182 |
| | | | | | | | |
| w#c.d4#c.f05#c.x | | | | | | | |
| 1 | | -.1320868 | .4592519 | -0.29 | 0.774 | -1.032204 | .7680304 |
| | | | | | | | |
| w#c.d4#c.f06#c.x | | | | | | | |
| 1 | | .2263718 | .5356826 | 0.42 | 0.673 | -.8235468 | 1.27629 |
| | | | | | | | |
| w#c.d5#c.f05#c.x | | | | | | | |
| 1 | | .9717867 | .9239081 | 1.05 | 0.293 | -.83904 | 2.782613 |
| | | | | | | | |
| w#c.d5#c.f06#c.x | | | | | | | |
| 1 | | 1.201889 | .7255394 | 1.66 | 0.098 | -.2201419 | 2.62392 |
| | | | | | | | |
| w#c.d6#c.f06#c.x | | | | | | | |
| 1 | | -.3027545 | .6868041 | -0.44 | 0.659 | -1.648866 | 1.043357 |
| | | | | | | | |

| | | | | | | | |
|-----------|--|-----------|----------|-------|-------|-----------|----------|
| f02 | | -.1661607 | .5602147 | -0.30 | 0.767 | -1.264161 | .93184 |
| f03 | | .9632906 | .4634932 | 2.08 | 0.038 | .0548607 | 1.871721 |
| f04 | | .543864 | .4113719 | 1.32 | 0.186 | -.26241 | 1.350138 |
| f05 | | .4526241 | .3643914 | 1.24 | 0.214 | -.26157 | 1.166818 |
| f06 | | .4978902 | .3614676 | 1.38 | 0.168 | -.2105733 | 1.206354 |
| c.f02#c.x | | .7084648 | .5577776 | 1.27 | 0.204 | -.3847592 | 1.801689 |
| c.f03#c.x | | -.361231 | .4055552 | -0.89 | 0.373 | -1.156105 | .4336426 |
| c.f04#c.x | | .2070722 | .3604028 | 0.57 | 0.566 | -.4993044 | .9134488 |
| c.f05#c.x | | .1624938 | .3205892 | 0.51 | 0.612 | -.4658495 | .7908371 |
| c.f06#c.x | | .2472584 | .313374 | 0.79 | 0.430 | -.3669434 | .8614602 |
| d4 | | -.4357018 | .4858549 | -0.90 | 0.370 | -1.38796 | .5165563 |
| d5 | | -.3063094 | .6184987 | -0.50 | 0.620 | -1.518545 | .9059257 |
| d6 | | -.9770025 | .5265438 | -1.86 | 0.064 | -2.009009 | .0550044 |
| x | | .3293786 | .1887492 | 1.75 | 0.081 | -.0405631 | .6993202 |
| c.d4#c.x | | -.6559586 | .4395996 | -1.49 | 0.136 | -1.517558 | .2056407 |
| c.d5#c.x | | -.9547599 | .5199871 | -1.84 | 0.066 | -1.973916 | .0643961 |
| c.d6#c.x | | -.2140135 | .4812769 | -0.44 | 0.657 | -1.157299 | .7292719 |
| _cons | | 1.202868 | .229064 | 5.25 | 0.000 | .7539108 | 1.651825 |

```
. margins, dydx(w) at(d4 = 1 d5 = 0 d6 = 0 f02 = 0 f03 = 0 f04 = 1 f05 = 0 f06 = 0) ///
> subpop(if d4 == 1) noestimcheck vce(uncond)
```

| | | Unconditional | | | | |
|-----|--|---------------|-----------|------|-------|----------------------|
| | | dy/dx | std. err. | z | P> z | [95% conf. interval] |
| 1.w | | 1.017501 | 1.033521 | 0.98 | 0.325 | -1.008164 3.043166 |

```
. margins, dydx(w) at(d4 = 1 d5 = 0 d6 = 0 f02 = 0 f03 = 0 f04 = 0 f05 = 1 f06 = 0) ///
> subpop(if d4 == 1) noestimcheck vce(uncond)
```

| | | Unconditional | | | | |
|-----|--|---------------|-----------|------|-------|----------------------|
| | | dy/dx | std. err. | z | P> z | [95% conf. interval] |
| 1.w | | 6.00713 | 2.162626 | 2.78 | 0.005 | 1.76846 10.2458 |

```
. margins, dydx(w) at(d4 = 1 d5 = 0 d6 = 0 f02 = 0 f03 = 0 f04 = 0 f05 = 0 f06 = 1) ///
> subpop(if d4 == 1) noestimcheck vce(uncond)
```

| | | Unconditional | | | | |
|-----|--|---------------|-----------|------|-------|----------------------|
| | | dy/dx | std. err. | z | P> z | [95% conf. interval] |
| 1.w | | 4.569667 | 1.369919 | 3.34 | 0.001 | 1.884675 7.254658 |

```
. margins, dydx(w) at(d4 = 0 d5 = 1 d6 = 0 f02 = 0 f03 = 0 f04 = 0 f05 = 1 f06 = 0) ///
> subpop(if d5 == 1) noestimcheck vce(uncond)
```

| | Unconditional | | | | | |
|-----|---------------|-----------|------|-------|----------------------|----------|
| | dy/dx | std. err. | z | P> z | [95% conf. interval] | |
| 1.w | 7.170127 | 3.355386 | 2.14 | 0.033 | .5936913 | 13.74656 |

```
. margins, dydx(w) at(d4 = 0 d5 = 1 d6 = 0 f02 = 0 f03 = 0 f04 = 0 f05 = 0 f06 = 1) ///
> subpop(if d5 == 1) noestimcheck vce(uncond)
```

| | Unconditional | | | | | |
|-----|---------------|-----------|------|-------|----------------------|----------|
| | dy/dx | std. err. | z | P> z | [95% conf. interval] | |
| 1.w | 7.185492 | 2.781751 | 2.58 | 0.010 | 1.73336 | 12.63762 |

```
. margins, dydx(w) at(d4 = 0 d5 = 0 d6 = 1 f02 = 0 f03 = 0 f04 = 0 f05 = 0 f06 = 1) ///
> subpop(if d6 == 1) noestimcheck vce(uncond)
```

| | Unconditional | | | | | |
|-----|---------------|-----------|------|-------|----------------------|----------|
| | dy/dx | std. err. | z | P> z | [95% conf. interval] | |
| 1.w | 13.73294 | 10.32555 | 1.33 | 0.184 | -6.504777 | 33.97065 |

```
. * Imputation is the same (no standard errors):
.
. poisson y f02 f03 f04 f05 f06 ///
>      c.f02#c.x c.f03#c.x c.f04#c.x c.f05#c.x c.f06#c.x ///
>      d4 d5 d6 x c.d4#c.x c.d5#c.x c.d6#c.x if ~w
note: you are responsible for interpretation of noncount dep. variable.
```

| | y | Coefficient | Std. err. | z | P> z | [95% conf. interval] | |
|--|-----------|-------------|-----------|-------|-------|----------------------|-----------|
| | f02 | -.1661604 | .0602748 | -2.76 | 0.006 | -.2842969 | -.0480239 |
| | f03 | .9632911 | .0596965 | 16.14 | 0.000 | .846288 | 1.080294 |
| | f04 | .5438644 | .0602786 | 9.02 | 0.000 | .4257205 | .6620082 |
| | f05 | .4526244 | .0628473 | 7.20 | 0.000 | .329446 | .5758028 |
| | f06 | .4978898 | .0619736 | 8.03 | 0.000 | .3764238 | .6193557 |
| | c.f02#c.x | .7084644 | .0556699 | 12.73 | 0.000 | .5993535 | .8175753 |
| | c.f03#c.x | -.3612316 | .0586636 | -6.16 | 0.000 | -.4762102 | -.2462529 |
| | c.f04#c.x | .2070717 | .0574569 | 3.60 | 0.000 | .0944582 | .3196852 |
| | c.f05#c.x | .1624933 | .0600223 | 2.71 | 0.007 | .0448518 | .2801349 |
| | c.f06#c.x | .247259 | .0592517 | 4.17 | 0.000 | .1311277 | .3633902 |

| | | | | | | |
|----------|-----------|----------|--------|-------|-----------|-----------|
| d4 | -.4357019 | .0682781 | -6.38 | 0.000 | -.5695245 | -.3018793 |
| d5 | -.3063131 | .0773811 | -3.96 | 0.000 | -.4579772 | -.154649 |
| d6 | -.9770024 | .1088114 | -8.98 | 0.000 | -1.190269 | -.7637361 |
| x | .329379 | .0475337 | 6.93 | 0.000 | .2362146 | .4225435 |
| c.d4#c.x | -.6559584 | .0624641 | -10.50 | 0.000 | -.7783858 | -.5335309 |
| c.d5#c.x | -.954755 | .0718444 | -13.29 | 0.000 | -1.095567 | -.8139425 |
| c.d6#c.x | -.2140135 | .0791491 | -2.70 | 0.007 | -.3691428 | -.0588841 |
| _cons | 1.202868 | .0492831 | 24.41 | 0.000 | 1.106275 | 1.299461 |

```
. predict double yh
(option n assumed; predicted number of events)

. gen teyh = y - yh

. sum teyh if d4 & f04
```

| Variable | Obs | Mean | Std. dev. | Min | Max |
|----------|-----|----------|-----------|-----------|----------|
| teyh | 277 | 1.017501 | 12.06767 | -3.527664 | 81.15445 |


```
. sum teyh if d4 & f05
```

| Variable | Obs | Mean | Std. dev. | Min | Max |
|----------|-----|---------|-----------|-----------|----------|
| teyh | 277 | 6.00713 | 37.30788 | -3.129414 | 399.5018 |

```
. sum teyh if d4 & f06
```

| Variable | Obs | Mean | Std. dev. | Min | Max |
|----------|-----|----------|-----------|----------|----------|
| teyh | 277 | 4.569665 | 20.86058 | -3.46407 | 175.1626 |

```
. sum teyh if d5 & f05
```

| Variable | Obs | Mean | Std. dev. | Min | Max |
|----------|-----|----------|-----------|-----------|----------|
| teyh | 163 | 7.170124 | 43.97455 | -3.200809 | 411.3746 |

```
. sum teyh if d5 & f06
```

| Variable | Obs | Mean | Std. dev. | Min | Max |
|----------|-----|----------|-----------|-----------|----------|
| teyh | 163 | 7.185487 | 36.58664 | -3.444643 | 305.0844 |

```
. sum teyh if d6 & f06
```

| Variable | Obs | Mean | Std. dev. | Min | Max |
|----------|-----|----------|-----------|-----------|----------|
| teyh | 57 | 13.73293 | 78.90365 | -4.725423 | 570.4094 |

. * Linear Model:

```
. reg y i.w#c.d4#c.f04 i.w#c.d4#c.f05 i.w#c.d4#c.f06 ///
> i.w#c.d5#c.f05 i.w#c.d5#c.f06 ///
> i.w#c.d6#c.f06 ///
> i.w#c.d4#c.f04#c.x_dm4 i.w#c.d4#c.f05#c.x_dm4 i.w#c.d4#c.f06#c.x_dm4 ///
> i.w#c.d5#c.f05#c.x_dm5 i.w#c.d5#c.f06#c.x_dm5 ///
> i.w#c.d6#c.f06#c.x_dm6 ///
> f02 f03 f04 f05 f06 ///
> c.f02#c.x c.f03#c.x c.f04#c.x c.f05#c.x c.f06#c.x ///
> d4 d5 d6 x c.d4#c.x c.d5#c.x c.d6#c.x, noomitted vce(cluster id)
```

| ----- | | | | | | |
|--------------|--|-------------|-----------|-------|-------|----------------------|
| | | Robust | | | | |
| y | | Coefficient | std. err. | t | P> t | [95% conf. interval] |
| ----- | | | | | | |
| w#c.d4#c.f04 | | | | | | |
| 1 | | -.1455549 | 1.671318 | -0.09 | 0.931 | -3.425251 3.134142 |
| w#c.d4#c.f05 | | | | | | |
| 1 | | 5.288825 | 2.478633 | 2.13 | 0.033 | .4249014 10.15275 |
| w#c.d4#c.f06 | | | | | | |
| 1 | | 2.816552 | 2.138228 | 1.32 | 0.188 | -1.379381 7.012485 |
| w#c.d5#c.f05 | | | | | | |
| 1 | | 6.697316 | 3.623153 | 1.85 | 0.065 | -.4125477 13.80718 |
| w#c.d5#c.f06 | | | | | | |
| 1 | | 5.562791 | 3.329713 | 1.67 | 0.095 | -.971242 12.09682 |
| w#c.d6#c.f06 | | | | | | |
| 1 | | 12.0696 | 10.58551 | 1.14 | 0.254 | -8.702791 32.842 |

| | | | | | | |
|---------------------------|-----------|----------|-------|-------|-----------|----------|
| w#c.d4#c.f04#c.x_dm4 1 | -1.534406 | 2.608612 | -0.59 | 0.557 | -6.653393 | 3.584581 |
| w#c.d4#c.f05#c.x_dm4 1 | -2.391267 | 3.602391 | -0.66 | 0.507 | -9.460388 | 4.677855 |
| w#c.d4#c.f06#c.x_dm4 1 | -.3870517 | 5.016994 | -0.08 | 0.939 | -10.23211 | 9.458004 |
| w#c.d5#c.f05#c.x_dm5 1 | 6.001162 | 10.44713 | 0.57 | 0.566 | -14.49967 | 26.50199 |
| w#c.d5#c.f06#c.x_dm5 1 | 8.149612 | 7.926036 | 1.03 | 0.304 | -7.403976 | 23.7032 |
| w#c.d6#c.f06#c.x_dm6 1 | -1.548522 | 9.214616 | -0.17 | 0.867 | -19.63074 | 16.5337 |

| | | | | | | |
|-----------|-----------|----------|-------|-------|-----------|----------|
| f02 | -1.432423 | 3.368666 | -0.43 | 0.671 | -8.042895 | 5.178049 |
| f03 | 4.808135 | 2.685276 | 1.79 | 0.074 | -.461293 | 10.07756 |
| f04 | 2.574639 | 2.6855 | 0.96 | 0.338 | -2.695229 | 7.844507 |
| f05 | 2.058054 | 2.334671 | 0.88 | 0.378 | -2.523368 | 6.639476 |
| f06 | 1.717605 | 3.16678 | 0.54 | 0.588 | -4.496699 | 7.93191 |
| c.f02#c.x | 3.707984 | 3.898847 | 0.95 | 0.342 | -3.942884 | 11.35885 |
| c.f03#c.x | -2.24394 | 2.146963 | -1.05 | 0.296 | -6.457014 | 1.969134 |
| c.f04#c.x | 1.070393 | 2.568546 | 0.42 | 0.677 | -3.969972 | 6.110759 |
| c.f05#c.x | .7396578 | 2.404356 | 0.31 | 0.758 | -3.97851 | 5.457825 |
| c.f06#c.x | 2.432101 | 3.621197 | 0.67 | 0.502 | -4.673923 | 9.538126 |
| d4 | -.6732229 | 3.071511 | -0.22 | 0.827 | -6.700577 | 5.354131 |
| d5 | -.647893 | 3.189825 | -0.20 | 0.839 | -6.907419 | 5.611633 |
| d6 | -2.281338 | 2.931903 | -0.78 | 0.437 | -8.034733 | 3.472056 |
| x | 3.560941 | 2.190103 | 1.63 | 0.104 | -.736789 | 7.858671 |
| c.d4#c.x | -4.43147 | 3.546717 | -1.25 | 0.212 | -11.39134 | 2.528399 |
| c.d5#c.x | -5.120498 | 3.631408 | -1.41 | 0.159 | -12.24656 | 2.005565 |
| c.d6#c.x | -3.426569 | 3.452896 | -0.99 | 0.321 | -10.20233 | 3.349192 |
| _cons | 2.326338 | 1.7649 | 1.32 | 0.188 | -1.136999 | 5.789674 |

6. Some Simulations

Common Intervention, Logit Mean

- $Y_{it}(0)$ a binary variable, generated to depend on heterogeneity, C_i .
- Logit mean is correctly specified.
- All serial correlation due to C_i .
- $P(D_i = 1) \approx 0.39$.
- $P[Y_{it}(0) = 1] \approx 0.38$; $P[Y_{it}(1) = 1] \approx 0.46$.
- $N = 1,000$, $T = 6$, 1,000 Monte Carlo Replications.

| | Sample ATT | Logit (Pooled Bernoulli) | | Linear (Pooled OLS) | | CS (2021) | |
|-------------|------------|--------------------------|-------|---------------------|-------|-----------|-------|
| $N = 1,000$ | Mean | Mean | SD | Mean | SD | Mean | SD |
| τ_4 | 0.082 | 0.081 | 0.021 | -0.043 | 0.029 | -0.041 | 0.036 |
| τ_5 | 0.120 | 0.119 | 0.025 | -0.027 | 0.032 | -0.025 | 0.039 |
| τ_6 | 0.166 | 0.165 | 0.027 | 0.0005 | 0.032 | 0.0026 | 0.039 |

Staggered Intervention, Exponential Mean

- $Y_{it}(g)$ a count variable, generated to depend on heterogeneity, C_i .
- Exponential mean is correctly specified.
- Conditional distribution of $Y_{it}(g)$ is mixture of Poisson and lognormal.
- All serial correlation due to C_i .
- $N = 500$, $T = 6$, 1,000 Monte Carlo Replications.

| | Sample ATT | Exponential (Pooled Poisson) | | Linear (Pooled OLS) | | CS (2021) | |
|-------------|------------|------------------------------|------|---------------------|------|-----------|------|
| $N = 500$ | Mean | Mean | SD | Mean | SD | Mean | SD |
| τ_{44} | 5.35 | 5.34 | 0.73 | 3.93 | 0.94 | 3.99 | 0.97 |
| τ_{45} | 13.20 | 13.21 | 1.61 | 10.31 | 1.94 | 10.37 | 1.87 |
| τ_{46} | 20.07 | 20.07 | 2.38 | 14.72 | 2.90 | 15.62 | 2.78 |
| τ_{55} | 12.02 | 12.03 | 1.66 | 9.67 | 2.01 | 10.50 | 1.93 |
| τ_{56} | 24.91 | 24.91 | 3.30 | 19.86 | 3.88 | 21.75 | 3.66 |
| τ_{66} | 4.72 | 4.76 | 1.15 | -0.04 | 2.11 | 3.05 | 1.93 |

7. Extensions

- Without a never treated group, drop terms depending on D_{iT} , which is always unity.
- Under NA, all effects for $t < T$ are still ATTs with respect to $Y_t(\infty)$.
- For $t = T$, estimate with respect to $Y_t(T)$ under a modified PT assumption.
- Can test/correct for violations of PT by adding

$$D_{ig} \cdot t, \dots, D_{iT} \cdot t$$

to any of the nonlinear models.

- Might even add

$$D_{ig} \cdot t \cdot \mathbf{X}_i, \dots, D_{iT} \cdot t \cdot \mathbf{X}_i$$