

# Real-Time Programming Languages

## Laborial 10: Ada Ravenscar Profile

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- turns off features of the Ada language
  - e.g., select, abort, delay
- makes certain implementations invalid, e.g., calling of potentially blocking operations from protected entries
- reduces the size of the program
- makes it analyzable and thus certifiable



pragmas can be added at the top of each file, but that's tedious and there is a better way:

- 1 create or open your gps project
- 2 Click on *File > New*
  - this file will hold all pragmas that we want to use
- 3 To activate Ravenscar, write `pragma Profile(Ravenscar);`
- 4 save the file as `config.adc` in your project directory
- 5 Go to *Project > Properties... > General* and select your file as *Global pragmas*
- 6 Save your project.
- 7 All pragmas in `config.adc` are now activated for all files.



To write a valid Ravenscar program, follow the code templates from the lecture slides.

- tasks with single release point
- tasks only at package level
- number of tasks must be fixed
- All data shared between tasks must be put in protected objects
  - the *guards* for entry functions must be simple Boolean variables, i.e.
    - entry `Remove(msg: out Item)` when not `Empty` ... is forbidden, because the guard not `Empty` is rejected, because the variable must be negated
    - instead do this:  
entry `Remove(msg: out Item)` when `Have_Items` is ...
- the package `Ada.Calendar` is forbidden  $\Rightarrow$  all timing must come from `Ada.Real_Time`



- Ravenscar requires fixed-priority preemptive scheduling with immediate priority ceiling, i.e., an RTOS
- this means a standard Linux or Windows does not satisfy the requirement
- **Pitfall:** A Ravenscar program *will* run on a standard Linux, but it **behaves incorrectly**
- Workaround:
  - 1 develop your program with the Ravenscar pragma
  - 2 turn off the pragma and re-compile the program
  - 3 it now runs correctly on a standard operating system, but the run-time environment is much larger
- ...or install the RT patchset if you are on Linux (see first Ada lecture)



- 1 explore and understand the *blinker example* (code on Moodle)
  - identify those parts, which prevent applying the *Ravenscar* profile
- 2 re-write your stopwatch program, such that it is Ravenscar compliant