

# Real-Time Programming Languages

## Labtorial 9: Ada Data Structures, Threads & Synchronization

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## 1 General Features

- Control Constructs
- Attributes
- Parameters
- Records
- Aggregates
- Discriminants
- Access
- Generics

## 2 Tasking

- Interactions

## ■ Timeout

## ■ Conditional Entry Call

## ■ Guards

## ■ Termination

## ■ Requeue

## ■ Protected Types

## ■ Asynchronous Transfer of Control

## ■ Timing Events

## ■ Dynamic Tasks

## 3 Exercises

## 4 References



# Section 1

## General Features



The most important ones:

```
1 if condition then statement1; else statement2; end if;
```

```
case X is  
  when 1 => statements1;  
  when 2 => statements2;  
4  when others => statements3;  
end case;
```

```
loop statements; end loop;
```

```
while condition loop statements; end loop;
```

See [http://en.wikibooks.org/wiki/Ada\\_Programming/Control](http://en.wikibooks.org/wiki/Ada_Programming/Control)



- useful to get/set information about an object
- denoted by a single quote, e.g.:
  - `myInteger'First`. Attribute "First" returns lowest possible Integer value
  - `myInteger'Last`. Returns highest possible Integer value
- attribute "Range" can be used with arrays:

```
myArray : array(1..5) of Integer := (2,4,6,8,10);  
for i in myArray'Range loop  
  Put_Line("element " & i'img & "=" & myArray(i)'img);  
4 end loop;
```

- Attribute "img" yields the string representation of the object:

```
1 Put_Line("Value of myInteger is " & myInteger'img);
```

For more see [http://en.wikibooks.org/wiki/Ada\\_Programming/Attributes](http://en.wikibooks.org/wiki/Ada_Programming/Attributes)



- arguments can be handed over in one of the following **modes**:

- **in**: default mode. The callee gets a *constant* copy, i.e., unlike in C value cannot be changed in callee

```
function hello( x : in Integer, y: out Integer) is
begin
  x := 5; -- error! x is constant
4  y := x+1; -- that's ok
end hello;
```

- **in out**: callee gets a reference; i.e., modifications of parameter is reflected in caller
- **out**: callee does *produce* a value for argument, value is passed to caller.



- **named parameters** prevent from switching arguments:
  - in your main...:

```
distance_to_home := getHomeDist(11.4812, 45.77192);
```

- ...and the specification of getHomeDist:

```
function getHomeDist(latitude : float, longitude :  
    float) return float;
```

What happens if the developer decides to switch arguments?



- **named parameters** prevent from switching arguments:
  - in your main...:

```
distance_to_home := getHomeDist(11.4812, 45.77192);
```

- ...and the specification of getHomeDist:

```
function getHomeDist(latitude : float, longitude :  
    float) return float;
```

What happens if the developer decides to switch arguments? **Code runs incorrectly w/o noticing** since latitude and longitude have the same data type

- *named parameters* make it much safer:

```
distance_to_home := getHomeDist(longitude =>  
    11.3512, latitude => 48.877192);
```





- you can build composite data types, like with `struct` in C:

```
4  type Car is record
    Identity      : Long_Long_Integer;
    Paint         : Color;
    Horse_Power_kW : Float range 0.0 .. 2_000.0;
    Consumption    : Float range 0.0 .. 100.0;
  end record;
```

The contents (e.g., `Paint`) are called *components*. Now a new variable with this type can be declared:

```
4  -- ...
    mycar : Car;
begin
    mycar.Consumption := 10.1;
    -- ...
```

Is there a convenient way to assign all components at once?



Is there a convenient way to assign all fields at once? **Yes.**

This is called an *aggregate*:

```
BMW : Car := (2007_752_83992434, Blue, 190.0, 10.1);
```

But like this we could accidentally switch horsepower (190.0) and consumption (10.1). Similar to *named parameters*, we can do this:

```
BMW : Car :=  
  (Identity      => 2007_752_83992434,  
   Horse_Power_kW => 190.0,  
   Consumption    => 10.1,  
   Paint          => Blue);
```

Ada's *full coverage rule* forces you to specify all fields.



- sometimes you might want to parametrize a record type, e.g.:

```
type card_deck (Size : Positive Integer) is
  record
    A : array (1 .. Size) of Integer;
  end record;
```

- here this allows to have a record `card_deck` with a user-defined (array) size
- usage:

```
1  -- ...
   skat : card_deck (10); -- array of length 1...10
   patience : card_deck (32); -- array of length 1...32
begin
  -- ...
```



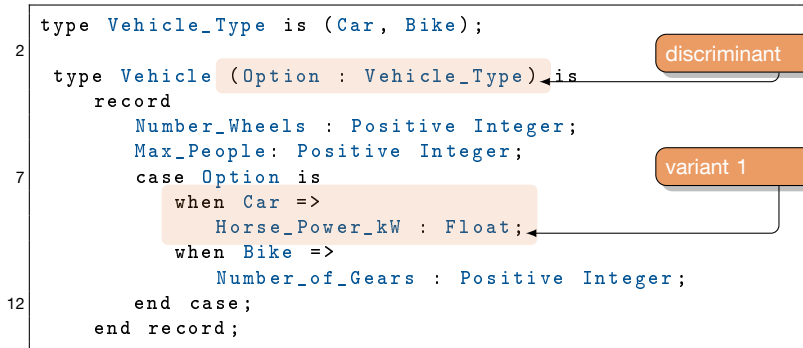
- sometimes not all values in a record are meaningful
- they can be “turned off” depending on a discriminant:

```
type Vehicle_Type is (Car, Bike);  
  
type Vehicle (Option : Vehicle_Type) is  
  record  
5     Number_Wheels : Positive Integer;  
     Max_People: Positive Integer;  
     case Option is  
       when Car =>  
10        Horse_Power_kW : Float;  
       when Bike =>  
        Number_of_Gears : Positive Integer;  
     end case;  
  end record;
```

- asking for Horse\_Power\_kW in a bike will throw an exception

# Variant Record

- sometimes not all values in a record are meaningful
- they can be “turned off” depending on a discriminant:



- asking for Horse\_Power\_kW in a bike will throw an exception



- *access types*=“pointers” in Ada, should be used rarely
- with them a new object can be *allocated* during run-time
- they have their own type, but no arithmetic (“ptr++”)

## Ada:

```
type Int_Access is access
  Integer;
2 ptrFoo, ptrBar : Int_Access;
  ptrFoo := new Integer;
  ptrBar := ptrFoo;
  ptrBar.all := ptrFoo.all;
  ptrFoo.all := 5;
```

## C equivalent:

```
typedef int* int_access;
4 int_access ptrFoo, ptrBar;
  ptrFoo = malloc(sizeof(int));
  ptrBar = ptrFoo;
  *ptrBar = *ptrFoo;
  *ptrFoo = 5;
```

**Warning:** Not all Ada compilers implement garbage collection!  
Allocated objects may have to be free'd manually



**difference to C:** access types by default only can point to dynamically allocated objects (i.e., not to declared variables)

- to obtain access to a declared variable we need to:
  - 1 allow the variable to be accessed with the `aliased` keyword (alias = “s.th. can be addressed with a different name”):

```
myInt : aliased Integer;
```

- 2 define an access type that can point to *all* integers:

```
type Int_Access is access all Integer;
```

- Now we can assign the pointer to the declared variable

```
ptrFoo : Int_Access;  
ptrFoo := myInt'Access;
```



One can restrict the accesses further:

- access all: read and write access
- access constant: read-only access

```
3  type pointer_rw is access all      Integer;
   type pointer_to is access constant Integer;

   var_const: aliased constant Integer := 10;
   var: aliased Integer;
   var_noalias: Integer; -- no alias means no access!

8  p1: pointer_rw := var_const'Access; -- illegal
   p2: pointer_ro := var_const'Access; -- OK, read only
   p3: pointer_rw := var'Access;      -- OK, read and write
   p4: pointer_ro := var'Access;      -- OK, read only
   p5: pointer_ro := var_noalias'Access; -- illegal
13 p6: constant pointer_rw := var'Access; -- r/w only on
    var
```





- Ada is made for large-scale systems; reusability required
- *generics* provide that (similar to *templates* in C++)

```
1  -- this is a normal procedure;  
  -- only works for Integer  
procedure Swap(Left, Right :  
               in out Integer);  
  
6  procedure Swap(Left, Right :  
               in out Integer) is  
  
   Temporary : Integer;  
begin  
   Temporary := Left;  
   Left := Right;  
11  Right := Temporary;  
end Swap;
```

```
generic  
type Element_Type is private;  
3  procedure Generic_Swap(Left,  
   Right : in out  
   Element_Type);  
procedure Generic_Swap(Left,  
   Right : in out  
   Element_Type) is  
   Temporary : Element_Type;  
begin  
   Temporary := Left;  
8   Left := Right;  
   Right := Temporary;  
end Generic_Swap;
```

- now it works for float, unsigned, hex, ...

- Ada is made for large-scale systems; reusability required
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-- this is a normal procedure;  
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5 procedure Swap(Left, Right :  
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    Temporary : Integer;  
begin  
    Temporary := Left;  
10    Left := Right;  
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end Swap;
```

```
generic  
type Element_Type is private;  
3 procedure Generic_Swap(Left,  
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    Element_Type);  
procedure Generic_Swap(Left,  
    Right : in out  
    Element_Type) is  
    Temporary : Element_Type;  
begin  
    Temporary := Left;  
8    Left := Right;  
    Right := Temporary;  
end Generic_Swap;
```

- now it works for float, unsigned, hex, ...



How do we “call” a specific version of `Generic_Swap`?

- we have to *instantiate* a real version from the generic

```
with Generic_Swap;  
procedure main is  
  procedure Swap is new Generic_Swap(Integer);  
  A, B : Integer;  
5 begin  
  A := 5;  
  B := 7;  
  Swap(A, B);  
  -- Now A=7 and B=5.  
10 end main;
```



# Section 2

## Tasking



- a *task* runs concurrently to the rest of the Ada program (=thread)
- main program is also a task
- each task (also called *server*):
  - declaration and body
  - depends on a *master* = its surrounding block
  - terminates only after all its *dependents* terminate

```
task Single is
  -- declaration of exported identifiers
end Single;
-- ...
5 task body Single is
  -- declaration of locals and statements
end Single;
```



tasks can

- 1 exchange messages (“rendezvous”)
- 2 wait for other tasks to complete (“join”)
- 3 use *protected objects* (“mutex”)
- 4 set global variables  $\Rightarrow$  hands away, dangerous!

Details in the next slides...



## How can tasks exchange messages?

- tasks cannot have functions or procedures, but they can have something similar called *entries*
- parameters of entries are the messages

```
procedure main is
  task type My_Task_Type is
3    entry Print (whatever : in integer);
  end My_Task_Type;
  task body My_Task_Type is begin
    loop
      accept Print (whatever : in integer) do
8        Put_Line("message with value=" & whatever'img);
      end Print;
    end loop;
  end My_Task_Type;
  task1 : My_Task_Type;
13 begin
  task1.Print(5); delay (5.0); task1.Print(10);
end main;
```



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  end My_Task_Type;
5  task body My_Task_Type is begin
    loop
      accept Print (whatever : in integer) do
        Put_Line("message with value=" & whatever'image);
        end Print;
10    end loop;
    end My_Task_Type;
    task1 : My_Task_Type;
  begin
    task1.Print(5); delay (5.0); task1.Print(10);
15 end main;
```

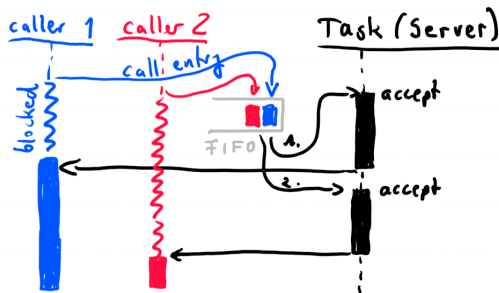
entry



# Rendezvous and Entries



- entry is executed in the thread of the task, not by the caller (major difference to threads in C[++])
  - the caller blocks until the server completed the call:



- if Task1 is not ready to process the call immediately, then main waits in an associated FIFO
- note that entries are therefore never executed concurrently

## Rendezvous and Entries (2)



The task which contains the entries (*server*) is blocking every time the control reaches an `accept` statement. How about this?

```
task body My_Task_Type is begin
  loop
    accept Print (whatever : in integer) do
      Put_Line("message with value=" & whatever'img);
5    end Print;
    accept Scan (whatever : out integer) do
      whatever := Integer'value(Get_Line);
    end Scan;
  end loop;
10 end My_Task_Type;
```

## Rendezvous and Entries (2)



The task which contains the entries (*server*) is blocking every time the control reaches an `accept` statement. How about this?

```
task body My_Task_Type is begin
  loop
    accept Print (whatever : in integer) do
      Put_Line("message with value=" & whatever'img);
5    end Print;
    accept Scan (whatever : out integer) do
      whatever := Integer'value(Get_Line);
    end Scan;
  end loop;
10 end My_Task_Type;
```

Since `accept` blocks every time it is reached, this task enforces alternating calls to `Print` and `Scan`. **What if we do not want this blocking, e.g., to serve multiple entries in any order?**



**What if we do not want blocking, e.g., to serve multiple entries in any order?** This is called a *selective wait*:

```
task body My_Task_Type is begin
  loop
    select
      accept Print (whatever : in integer) do
5         Put_Line("message with value=" & whatever'img);
      end Print;
    or
      accept Scan (whatever : out integer) do
10         whatever := Integer'value(Get_Line);
      end Scan;
    end select;
  end loop;
end My_Task_Type;
```



**What if we do not want blocking, e.g., to serve multiple entries in any order?** This is called a *selective wait*:

```
task body My_Task_Type is begin
2  loop
    select
        accept Print (whatever : in integer) do
            Put_Line("message with value=" & whatever'img);
            end Print;
7  or
        accept Scan (whatever : out integer) do
            whatever := Integer'value(Get_Line);
            end Scan;
    end select;
12 end loop;
end My_Task_Type;
```

alternative 1

alternative 2

**What if we do not want blocking, e.g., to serve multiple entries in any order?** This is called a *selective wait*:

```
task body My_Task_Type is begin
2   loop
      select
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          Put_Line("message with value=" & whatever'img);
        end Print;
7     or
        accept Scan (whatever : out integer) do
          whatever := Integer'value(Get_Line);
        end Scan;
      end select;
12  end loop;
end My_Task_Type;
```

alternative 1

alternative 2

- if only one of alternatives has pending entry call  $\Rightarrow$  accepted this
- if multiple calls pending  $\Rightarrow$  choose freely  $\Rightarrow$  **non-determinism**
- If no alternative is viable  $\Rightarrow$  **error**



*Selective wait* allows a non-blocking server task, but what about the caller?

- as mentioned before, caller waits in a FIFO until server can handle the call
- **can we avoid such blocking of the caller? Yes.**



*Selective wait* allows a non-blocking server task, but what about the caller?

- as mentioned before, caller waits in a FIFO until server can handle the call
- **can we avoid such blocking of the caller?** Yes. We can specify a *timeout* as follows:

```
task body My_Task_Type is begin
  loop
    select
4      accept Print ( whatever : in integer ) do
          Put_Line("message with value ="& whatever'img);
        end Print ;
    or
    delay 5.0; -- select ends latest after 5 sec
9      end select;
    end loop;
  end My_Task_Type;
```





**Can we have a timeout with zero delay** (a.k.a. “nonblocking call”)?

- select statement shall return or do s.th. else, if it cannot be served immediately
- **how about that:**

```
4  select
    accept
    -- ...
or
    delay 0.0;
    Do_something_else;
end select;
```



**Can we have a timeout with zero delay** (a.k.a. “nonblocking call”)?

- select statement shall return or do s.th. else, if it cannot be served immediately
- **how about that:**

3

```
select
  accept
-- ...
or
  delay 0.0;
  Do_something_else;
end select;
```

not what we want:

- on a real processor, rendezvous takes (a nonzero) time
- thus delay 0.0 is impossible
- always a timeout



**Can we have a timeout with zero delay** (a.k.a. “nonblocking call”)?

- `select` statement shall return or do s.th. else, if it cannot be served immediately
- for “as fast as possible” delay, Ada offers a *conditional entry call*:

```
3  select
    accept
    -- ...
else
    Do_something_else;
end select;
```

- entry call is not done if the rendezvous is not “immediately” achieved
- else branch is executed instead



Sometimes one might want to disable alternatives. Ada provides *guards* for this:

```
task body My_Task_Type is
    print_ready : Boolean := true;
begin
4   loop
        select
            when print_ready =>
                accept Print ( whatever : in integer ) do
                    Put_Line("message with value "& whatever'img);
9                end Print ;
            or
                delay 5.0; -- select ends latest after 5 sec
            end select;
        end loop;
14 end My_Task_Type;
```

- note guards are not parameters, but internal states of the task



As of now, our tasks do not terminate, therefore their *master* (surrounding block) cannot terminate. **How to fix this?**

- we add a *terminate alternative* to the task:

```
1 task body My_Task_Type is begin
  loop
    select
      accept Print (whatever : in integer) do
        Put_Line("message with value=" & whatever'img);
6      end Print;
    or
      terminate; -- this is what we added
    end select;
  end loop;
11 end My_Task_Type;
```



## Termination (2)

`terminate` is executed when *all* of the following conditions hold true:

- 1 terminate alternative is reachable AND
- 2 no pending calls to entries AND
- 3 all other tasks of the same master are in the same state AND
- 4 master has completed (i.e., control reached end of statements).

### Example: Task from previous slide

main:

```
delay 1.0;
task1.Print(5);
-- task still running
4 delay 1.0;
task1.Print(10);
Put_Line("master complete"
);
-- task terminates
```

output::

```
message with value = 5
message with value = 10
3 master complete

[2014-12-08 15:49:54]
    process terminated
    successfully, elapsed
    time: 02.16s
```



- **recall:** calling an entry on a task means putting yourself in a FIFO queue
- server may decide to redirect the call to another entry (“requeue”)
- the entry which we redirect to must have same parameters

```
loop
  select
    accept Print (whatever : in integer) do
      -- probably do some stuff here
      requeue Real_Print;
    end Print;
  or
    accept Real_Print (whatever : in integer) do
      Put_Line("value=" & whatever'image);
    end Other_Print;
  end select;
end loop;
```



## We have seen that entries serve sequentially (...FIFO)

- Ada requires no explicit mutex to protect the data in a task
- but sometimes it might be too heavy to create a task just for the purpose of protecting data
- for that, Ada provides data objects with protection against data inconsistency (e.g., race condition)
- like a fancy form of a semaphore or mutex
- the protected data can only be accessed through *protected operations*:
  - 1 **protected functions**: provide read-only access
  - 2 **protected procedures**: exclusive read-write access
  - 3 **protected entries**: like procedure, but guarded
- very efficient  $\Rightarrow$  any protected operation should be short and fast



## Protected Types (“mutex”) (2)

```
protected type Protected_Buffer_Type is
  entry Insert (An_Item : in Item);
3  entry Remove (An_Item : out Item);
private
  Buffer : Item;
  Empty : Boolean := True;
end Protected_Buffer_Type;
8  protected body Protected_Buffer_Type is
  entry Insert (An_Item : in Item) when Empty is
  begin
    Buffer := An_Item;
    Empty := False;
13 end Insert;
  entry Remove (An_Item : out Item) when not Empty is
  begin
    An_Item := Buffer;
    Empty := True;
18 end Remove;
end Protected_Buffer_Type;
```

guarded

If guard evaluates to *false*, the caller waits in the FIFO

# Protected Types (“mutex”) (3)

```
1  procedure main is
    mybuf : Protected_Buffer_Type;
    task type OtherTask is end OtherTask;
    task body OtherTask is
        i : Integer := 0;
6  begin
        loop
            delay 1.0;
            mybuf.Insert(i);
            Put_Line("insert " & i'img);
11         i := i + 1;
        end loop;
    end OtherTask;
    task1 : OtherTask;
    o : Integer;
16 begin
        loop
            mybuf.Remove(o);
            Put_Line("remove " & o'img);
        end loop;
21 end main;
```

these two tasks are  
running concurrently  
without any mutex



- **avoid using this** (rather use asynchronous `select`)



- reacting to the arrival of a point in time – like an interrupt
- e.g., execute some task starting at exactly 7.00am
- usually you would need an appropriate `delay` statement
  - concurrency overhead unnecessary and inefficient
- **secondary in this lecture**, if you are interested study the blinker example (`Set_Handler()` in `Timer_Setup::Pulser`)



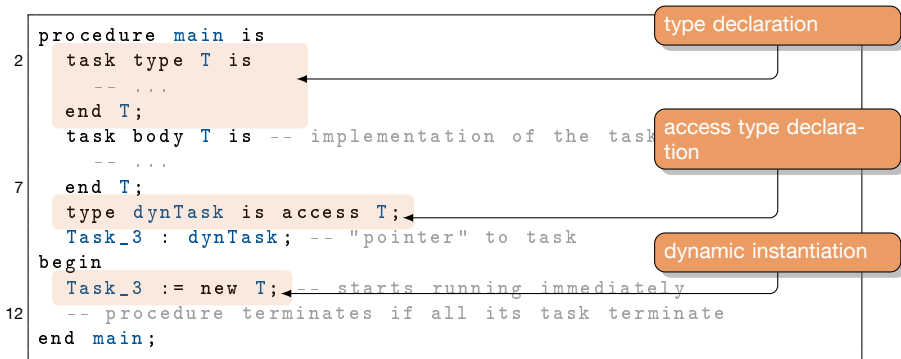
- need a task type
- need an access type (cmp. with C: for creating threads you need a pointer, and pointers are types in Ada)
- use `new` keyword

```
procedure main is
  task type T is
    -- ...
4  end T;
  task body T is -- implementation of the task of task
    -- ...
  end T;
  type dynTask is access T;
9  Task_3 : dynTask; -- "pointer" to task
begin
  Task_3 := new T; -- starts running immediately
  -- procedure terminates if all its task terminate
end main;
```

# Dynamically Created Tasks



- need a task type
- need an access type (cmp. with C: for creating threads you need a pointer, and pointers are types in Ada)
- use new keyword





## Section 3

## Exercises

# Exercises for Today (1)



- 1 finish tasks from last lab (calendar, stop watch)
- 2 explore and understand the *blinker example* (code on Moodle)





# Section 4

## References



- *Ada Glossary*, Bard S. Crawford, <http://www.cs.uni.edu/~mccormic/AdaEssentials/glossary.htm>
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All online resources as of December 2014.