

1 Python AIMA

1.1 In order to perform a search, what are the classes that you must define or extend? What are they used for?

We have to create a subclass to the class "Problem" given in the AIMA library. This subclass must implement the method `successor`, and possibly `__init__`, `goal_test`, and `path_cost`. When this is done, we can use the search method on an instance of this subclass.

1.2 In `graph_search` and `tree_search`, what is the effect of the instruction `fringe.extend(node.expand(problem))`. What are the classes and methods involved?

The method `extend` is used on a `FIFOQueue` to add elements at the end of this queue. These elements are the elements returned successively through the `yield` by `node.expand(problem)`. The role of the `expand` method defined in the class `Node` is in term to reach all the children nodes accessible from one particular node.

The classes involved are `FIFOQueue` and more precisely the method `extend`, the class `Node` to access the method `expand` and a `Problem`'s subclass.

1.3 Both `breadth_first_graph` and `depth_first_search` are making a call to the same function. How is their fundamental difference implemented

The differences lies in the way that `fringe` is constructed. If we have a `FIFOQueue`, then the new elements are put in the end of the list, which involve a breadth first traversal. At the opposite, if we have a `stack`, the traversal will be depth first search because `tree_search` fill the stack with children nodes to the current. Thus `pop` call return the child, until the depth one.

1.4 How is the closed list implemented in `graph_search`? What is it used for? What is the technical difference with the fringe? Why are those two specific structures used?

The closed list contains `True` or `False` (nothing is `False`) associated with keys which are the node's state. It's used to keep a trace of which node are already explored. The technical difference with fringe is that fringe contains node which are already been explored or unexplored and the closed list is a `Dictionary` that contains `True` value for nodes that already been explored.

A specific structure is used for fringe to allow breadth first graph search or a depth first graph search. And closed is a `Dictionary` which map each node to a boolean value in order to know if they are explored or not.

1.5 How technically are the elements in the closed list searched? What are the methods involved? What properties must its elements have?

They are searched by the instruction "if `node.state` not in `closed`" which is the same that "if `node.state` not in `closed.keys()`" which search with an iterator among the keys if `node.state` isn't among them. Implicitly, we think that the methods involved are the method `__iter__()` and the method `keys()`. They are handle by Python.

The properties of the elements are couples of `key->value`.

- 1.6 How technically can you use the implementation of the closed list to deal with symmetrical states? (hint : if two symmetrical states are considered to be the same, they will not be visited twice)

2 The Sliding Puzzle Problem

- 2.1 Explain the advantages and weaknesses of each search strategy on this problem (depth first, breadth first, depth limited, iterative deepening, uniform cost). Which one would you choose to solve this problem?

- **depth first** The main advantage of using a depth first search is its space complexity which is better than other because the algorithm is such as only one path must be in memory at a given time. Though, if the tree is infinite, the path also becomes infinite and thus, it is possible to never find the goal and a major part of the tree is unexplored.
- **breadth first** While using this approach, we ensure that we will find the shallowest goal in our tree (which is the one that requires the less actions) but at the cost that all the different states generated during the execution are kept in memory which leads to an exponential time complexity.
- **depth limited** This one acts like the depth first algorithm, though it gets rid of the infinite path problem by setting a maximum depth. It is then possible to explore all the tree up to a certain depth. Sadly it only works well when we have a good idea of the depth of the goal or at least an upper bound.
- **iterative deepening** The strategy of this one is to perform a search on each level one after the previous one using the depth first method, which is following one path at the time. It keeps the advantages of the depth limited way without the disadvantage that we don't know the depth of the goal. The inconvenient of using this method is that it generate slightly more node than the breadth first method.
- **uniform cost** It is a nice way to proceed when some actions are more costly than others. It is basically a breadth first search, although instead of a FIFO Queue, a priority queue is used. While convenient when costs are involved, this method is expensive in space as well as in time.

In order to solve the given problem, we'll choose the iterative deepening strategy over the others for the reason that it is the best algorithm because of its both time and space complexity.

- 2.2 Are there symmetrical (equivalent) states in this problem? What are the potential consequences on the search?

There may be many situations where symmetrical states occur. The consequences of this in the treatment of this problem is that we may build several times the same tree and explore it as many times. It would constitute a useless usage of memory and a loss of time considering it generates and analyses the redundant states before reaching the goal state.

- 2.3 How are you dealing with those symmetrical states?

One way to deal with those symmetrical states is to keep track of the states already generated and analysed and to avoid to analyse its "twins". It is what performs the graph search compared to the tree search.

2.4 What are the advantages and disadvantages of using the tree and graph search for this problem. Which approach would you choose? Which approach allows you to avoid expending twice symmetrical states?

As said above, the graph search present an advantage in comparison to the tree search which is to consider same states but the build of a graph is very costly in term of memory The approach that we shall use is the tree search via the iterative deepening because the space complexity is linear instead of exponential in the case of a graph search. The graph search is the one of the two that can avoid treating symmetrical states because it tests if the state has already been generated earlier.

2.5 Implement this problem in Python3. Extend the Problem class and implement the necessary methods and other class(es) if necessary. Your file must be named puzzle.py. Your program must print to the standard output a solution to the puzzle satisfying the above format

2.6 Experiments must be realized with the 10 instances of the puzzle problem provided. Report in a table the results on the 10 instances for depth-first and breadth first strategies on both tree and graph search (4 settings). You must report the time, the number of explored nodes and the number of steps from root to solution. When no solution can be found by a strategy in a reasonable time (3 min), explain the reason (time-out and/or swap of the memory