

Digital Communication

Ch3: Digital Modulation Scheme

3-2 Memoryless Modulation

M-PAM

Bandpass Waveform

$$\cdot S_m(t) = \operatorname{Re} \left\{ A_m g(t) e^{j2\pi f_c t} \right\}$$

Pulse-shaping function
等效基頻

$$= A_m g(t) \cos(2\pi f_c t)$$

Basis

$$\cdot \phi_1(t) = \frac{g(t)}{\|g(t)\|} \sqrt{2} \cos(2\pi f_c t)$$

vector

$$\cdot \vec{S}_m = \frac{A_m}{\sqrt{2}} \|g(t)\|$$

Transmit Energy

$$\cdot E_m = \frac{1}{2} A_m^2 E_g$$

PSK

Bandpass Waveform

$$\cdot S_m(t) = \operatorname{Re} \left\{ g(t) e^{j\theta_m} e^{j2\pi f_c t} \right\}$$

$$= g(t) \cos \theta_m \cos(2\pi f_c t) - g(t) \sin \theta_m \sin(2\pi f_c t)$$

Basis

$$\cdot \phi_1(t) = \frac{g(t)}{\|g(t)\|} \sqrt{2} \cos(2\pi f_c t)$$

$$\cdot \phi_2(t) = -\frac{g(t)}{\|g(t)\|} \sqrt{2} \sin(2\pi f_c t)$$

vector

$$\cdot \vec{S}_m = \left[\frac{\|g(t)\|}{\sqrt{2}} \cos(\theta_m), \frac{\|g(t)\|}{\sqrt{2}} \sin(\theta_m) \right]^T$$

Transmit Energy

$$\cdot E_m = \frac{1}{2} E_g$$

優點: Equal Energy

QAM

- 優點: 傳送速度提升
- 缺點: 錯誤率增加

Bandpass Waveform

$$\cdot S(t) = A_{m,i} g(t) \cos(2\pi f_c t) - A_{m,q} g(t) \sin(2\pi f_c t)$$

Basis

$$\cdot \phi_1(t) = \frac{\|g(t)\|}{g(t)} \sqrt{2} \cos(2\pi f_c t)$$

$$\cdot \phi_2(t) = -\frac{\|g(t)\|}{g(t)} \sqrt{2} \sin(2\pi f_c t)$$

vector

$$\cdot \vec{S}_m = \left[\frac{A_{m,i}}{\sqrt{2}} \|g(t)\|, \frac{A_{m,q}}{\sqrt{2}} \|g(t)\| \right]^T$$

Transmit Energy

$$\cdot E_m = \frac{1}{2} E_g (A_{m,i}^2 + A_{m,q}^2)$$

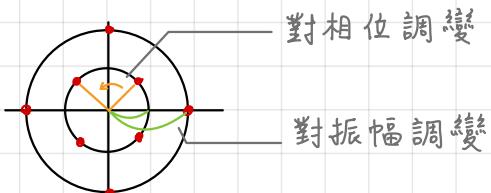
Euclidean Distance

$$\cdot \|\vec{S}_m - \vec{S}_n\| = \frac{1}{\sqrt{2}} \|g(t)\| \sqrt{(A_{m,i} - A_{n,i})^2 + (A_{m,q} - A_{n,q})^2}$$

Minimum Distance

$$\cdot \frac{1}{\sqrt{2}} \|g(t)\| \cdot \sqrt{0^2 + 2^2} = \sqrt{2} E_g \neq$$

$$\text{QAM} = \text{PAM} + \text{PSK}$$



How to create high-dimensional signal?

1. Subdivision of Frequency
2. Subdivision of Time
3. Subdivision of both Frequency & Time

Subdivision of Frequency

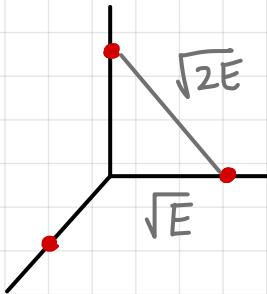
FSK

Bandpass waveform

$S_m(t)$

$$= \operatorname{Re} \left\{ \sqrt{\frac{2E}{T}} e^{j2\pi(m\Delta f)t} \cdot e^{j2\pi f_ct} \right\}$$

$$= \sqrt{\frac{2E}{T}} \cos(2\pi f_ct + 2\pi m\Delta f t)$$



Basis/vector

$$\cdot \phi_m(t) = \frac{1}{\sqrt{E}} S_m(t)$$

$$\cdot \vec{s}_m = [0, 0 \dots \sqrt{E} \dots 0]^T$$

• 到原點距離皆相同: $E_m = E$

• 兩點皆等距: $\sqrt{2E}$

• 頻寬大: $B_T = 2W + (m-1)\Delta f$

頻率正交

• 基頻正交: $\Delta f = \frac{1}{T}$

• 旁頻正交: $\Delta f = \frac{1}{2T}$

$$1. S_{e,m}(t) = \sqrt{\frac{2E}{T}} e^{j2\pi(m\Delta f)t}; \|S_{e,m}(t)\| = \sqrt{2E}$$

2. $P_{e,m,n}$

$$= \frac{\langle S_{e,m}(t), S_{e,n}(t) \rangle}{\|S_{e,m}(t)\| \cdot \|S_{e,n}(t)\|}$$

$$= \frac{1}{T} \int_0^T e^{j2\pi m\Delta f t} e^{j2\pi n\Delta f t} dt$$

$$= \operatorname{sinc}[\underline{T(m-n)\Delta f}] e^{j\pi T(m-n)\Delta f}$$

故基頻正交為 $\Delta f = \frac{1}{T}$

3. $P_{m,n}$

$$= \operatorname{Re}\{P_{e,m,n}\}$$

$$= \frac{\sin(\pi T(m-n)\Delta f)}{\pi T(m-n)\Delta f} \cos(\pi T(m-n)\Delta f)$$

$$= \operatorname{sinc}[\underline{2T(m-n)\Delta f}]$$

射頻正交為 $\Delta f = \frac{1}{2T}$

Euclidean distance between FSK

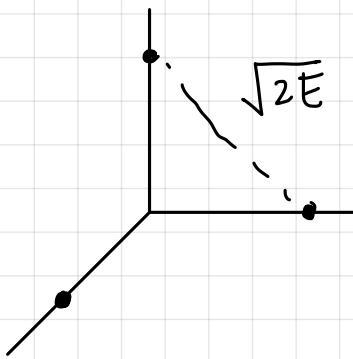
$$[S_1 \ S_2 \ \dots \ S_M] = \begin{bmatrix} \sqrt{E} & 0 & \dots & 0 \\ 0 & \sqrt{E} & & \\ & & \ddots & \\ & & & \sqrt{E} \end{bmatrix}$$

$$\Rightarrow \|S_m - S_n\| = \sqrt{2E}$$

- 到原點距離皆相同: $E_m = E$

- 任2點皆等距: $\sqrt{2E}$

- 頻寬大: $B_T = 2W + (m-1)\Delta f$

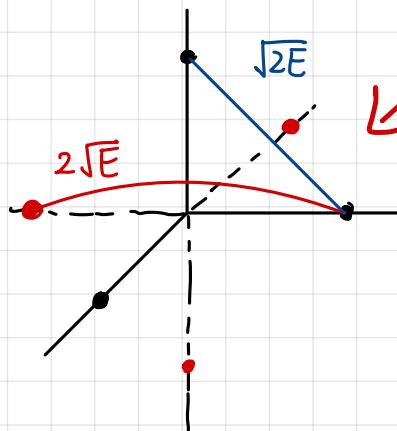


因為浪費頻寬，所以在一個 basis 上傳播 2 個 signal

Biorthogonal multidimensional FSK

$$[S_{-1} \dots S_{-M} \ S_1 \dots S_M] = \begin{bmatrix} -\sqrt{E} & \dots & 0 & \sqrt{E} & \dots & 0 \\ \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ 0 & & \sqrt{E} & 0 & \dots & \sqrt{E} \end{bmatrix}$$

$$\Rightarrow \|S_m - S_n\| = \begin{cases} \sqrt{2E} & ; m \neq n \\ 2\sqrt{E} & ; m = -n \\ 0 & ; m = n \end{cases}$$



- 到原點的距離仍相同: E

- Crosscorrelation 改變: $P_{mn,l} = \begin{cases} 0 & ; m \neq n \\ -1 & ; m = -n \\ 1 & ; m = n \end{cases}$

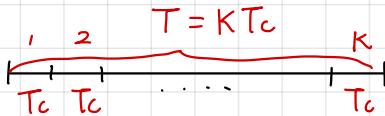
- 傳送速率更佳

沒正交。

Subdivision of Time

$$S_m = [C_{m,0} \ C_{m,1} \ \dots \ C_{m,K-1}]$$

$$\text{where } K T_c = T$$



把訊號在 time-domain 切成 K 份傳送

$$S_m(t) = \sum_{j=0}^{K-1} C_{m,j} \cdot g(t - jT_c)$$

- $C_{m,j} = 1$ represent $+g(t)$ is transmitted during time slot j
- $C_{m,j} = -1$ represent $-g(t)$ is transmitted during time slot j
- $g(t) = \sqrt{\frac{2E_c}{T_c}} \cos(2\pi f_c t) ; 0 \leq t \leq T$

- Transmit energy: $E_m = K E_c$
- Crosscorrelation coefficient (if differ by only one component $C_{m,j}$)

$$\rho_{m,n} = \frac{\langle S_m, S_n \rangle}{\|S_m\| \cdot \|S_n\|} = \frac{(K-1)E_c - E_c}{KE_c}$$

因為 $K-1$ 個皆相同: $(K-1)E_c$
只有 1 個不同 : $-E_c$

- Minimum Euclidean distance (if differ by only one component $C_{m,j}$)

$$\begin{aligned} \min \|S_m - S_n\| &= \min \sqrt{\|S_m\|^2 + \|S_n\|^2 - 2\langle S_m, S_n \rangle} \\ &= \sqrt{KE_c + KE_c - 2(K-2)E_c} \\ &= 2\sqrt{E_c} \end{aligned}$$

- Upper bound on "the number of channel symbol"

- Hadamard signal

$$H_n = \begin{bmatrix} H_{n,1} & H_{n,2} \\ H_{n,2} & -H_{n,1} \end{bmatrix}; H_0 = [1]$$

→ 雖然有 2^n 種組合方式，但為了 orthogonal，故只選 n 種 symbol 作為傳送
設計方式為 Hadamard signal. H_n

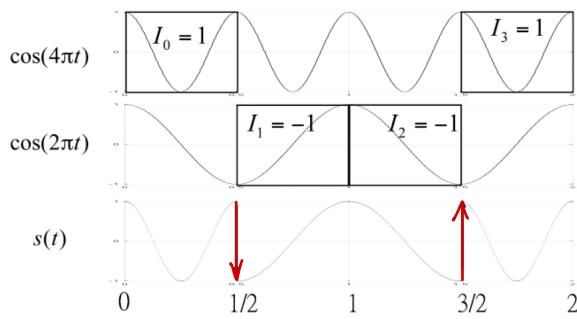
3-3 Signaling scheme with memory

• 傳統 FSK signal 問題 .

$$\cdot S_m(t) = \sqrt{\frac{2E}{T}} \cos(2\pi f_m t + 2\pi(m\Delta f)t)$$

Ex.

$$S(t) = \begin{cases} \cos(2\pi t) & I_n = 1, m=0 \\ \cos(4\pi t) & I_n = -1, m=1 \end{cases}$$



在不同 oscillator 切換時會有高頻的產生 (不連續)

• CPFSK.

$$\cdot \phi(t; I_n) = 4\pi f_a T \underbrace{\int_{-\infty}^t d(\tau) d\tau}_{\text{_____}}$$

• 解決方式 CPFSK

- phase change (the derivative of phase)

$$d(t) = \sum I_n g(t-nT)$$

- Baseband of CPFSK: $\frac{d}{dt} \phi(t) = \sum I_n g(t-nT)$ phase (the integration of phase change)

$$S_L(t) = \sqrt{\frac{2E}{T}} \exp\left(j \left[4\pi T f_d \int_{-\infty}^t d(\tau) d\tau + \phi_0 \right] \right)$$

為了讓相位連續

- f_d : peak frequency deviation
- ϕ_0 : initial phase

- Bandpass of CPFSK: $S_L(t) = \sqrt{\frac{2E}{T}} e^{j\phi(t; I)}$

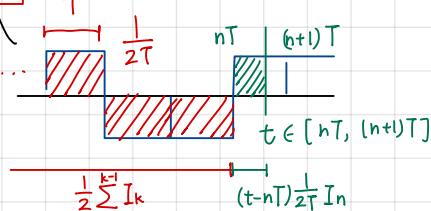
where

$$\phi(t; \{I_n\}) = 4\pi T f_d \int_{-\infty}^t \left[\sum_k I_k g(\tau - kT) d\tau \right] d\tau$$

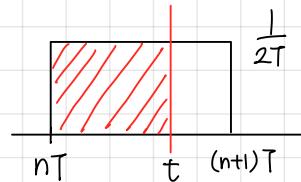
$$= 2\pi T f_d \sum_{k=-\infty}^{n-1} I_k + 2\pi f_d (t-nT) I_n ; t \in [nT, (n+1)T]$$

$$= \underline{\theta_n} + \underline{2\pi h \cdot I_n \cdot g(t-nT)}$$

memory



$$\begin{cases} \cdot h = 2f_d T : \text{modulation index} \\ \cdot \theta_n = \pi h \sum_{k=0}^{n-1} I_k : \text{memory} \\ \cdot q(t) = \begin{cases} 0 & ; t < 0 \\ \frac{t}{2T} & ; 0 < t < T \\ \frac{1}{2} & ; t \geq T \end{cases} \Rightarrow q(t-nT) = \begin{cases} 0 & ; t < nT \\ \frac{t-nT}{2T} & ; nT < t < (n+1)T \\ \frac{1}{2} & ; t \geq (n+1)T \end{cases} \end{cases}$$



CPM (Continuous Phase Modulation)

- CPM is generalization of CPFSK

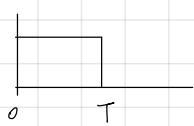
$$\cdot \phi(t; I_n) = 2\pi \sum_{k=1}^n h_k \cdot I_k \cdot q(t-kT)$$

- $\{I_n\}$ is the sequence of PAM symbol in $\{\pm 1, \pm 3, \dots, \pm(M-1)\}$

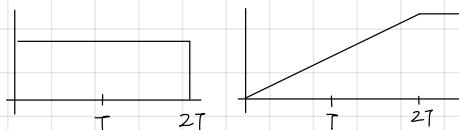
- h_k is modulation index, if varies with k , it is called "multi-h CPM"

- $\begin{cases} \text{If } q(t)=0 \text{ for } t \geq T, S_e(t) \text{ is called full-response CPM} \\ \text{Otherwise, it is called partial-response CPM} \end{cases}$

Full-response



Partial-response



影響前後訊號
→ 頻譜效率更好

MSK (Minimum Shift Keying)

- MSK is a special case of CPFSK with

$$h_k = 2f_d T = \frac{1}{2}, q(t) = \frac{1}{2T} \text{ for } 0 < t < T, I_n \in \{\pm 1\}$$

$$\begin{aligned} \cdot \phi(t; I_n) &= 2\pi \sum_{k=1}^n I_k h_k q(t-kT) \\ &= \frac{\pi}{2} \sum_{k=1}^{n-1} I_k + \pi I_n q(t-nT) \\ &= \theta_n + \pi I_n \left(\frac{t-nT}{2T} \right) \end{aligned}$$

$$\begin{aligned} \cdot S_{MSK}(t) &= \sqrt{\frac{2E}{T}} \cos(2\pi f_c t + \phi(t; I_n)) \\ &= \sqrt{\frac{2E}{T}} \cos\left(2\pi\left(f_c + \frac{I_n}{4T}\right)t - \frac{n\pi I_n}{2} + \theta_0\right) \end{aligned}$$

- Since $I_n \in \{\pm 1\}$, $S_{MSK}(t)$ has two freq component

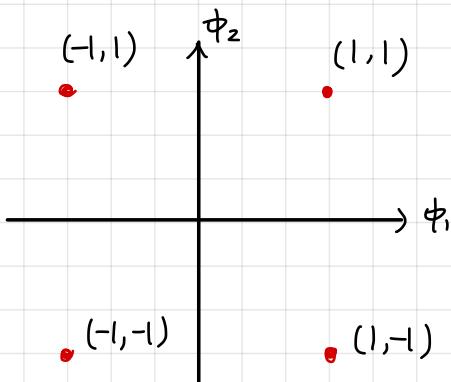
$$\begin{aligned} f_1 &= f_c + \frac{1}{4T} \\ f_2 &= f_c - \frac{1}{4T} \end{aligned} \Rightarrow \Delta f = \frac{1}{2T}$$

FSK 射頻正交時，最小頻率差為 $\Delta f = \frac{1}{2T}$

故稱為 MSK

OQPSK

- 傳統 QPSK 的問題：



ex:

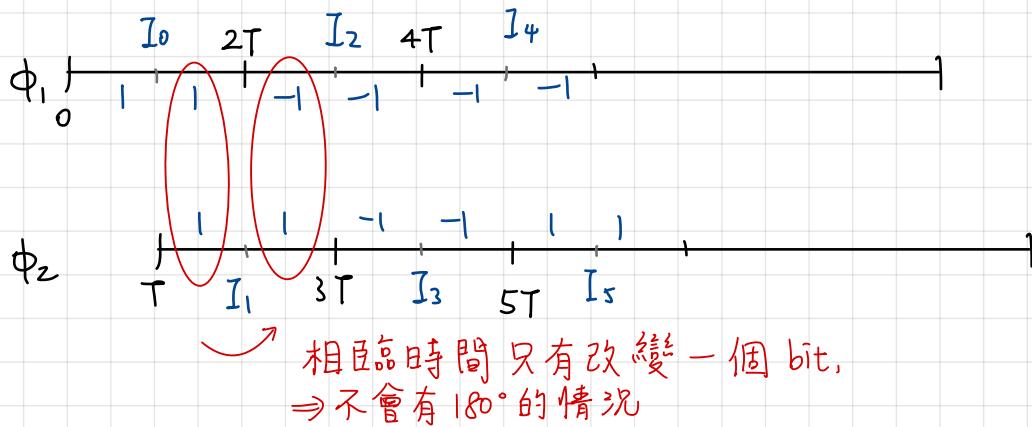
$$\begin{aligned} (I_0 I_1) &= (+1 + 1) \\ (I_2 I_3) &= (-1 - 1) \\ (I_4 I_5) &= (-1 + 1) \end{aligned}$$

$\downarrow 180^\circ$

$$S_{\text{QPSK}}(t) =$$

$$\sum I_{2n} g(t-2nT) \cos(2\pi f_t t) - \sum I_{2n+1} g(t-2nT) \sin(2\pi f_t t)$$

OQPSK



$$S_{\text{OQPSK}}(t) =$$

$$\sum I_{2n} g(t-2nT) \cos(2\pi f_t t) - \sum I_{2n+1} g(t-(2n+1)T) \sin(2\pi f_t t)$$

3.4 Power Spectrum of Digital Modulated signal.

• 隨機數位波

$$\circ S_e(u, t) = \sum I_n(u) \cdot g(t - nT)$$

- $I_n(u)$: random sequence

- $g(t)$: pulse shaping function

$$\left\{ \begin{array}{l} E[S_e(t)] = M_I \sum g(t - nT) \text{ mean is time-varying} \\ R_{se}(t + T, t) = R_{se}(t + T + kT, t + kT) \end{array} \right.$$

$$R_{se}(t + T, t) = R_{se}(t + T + kT, t + kT) \text{ autocorrelation with period } T$$

→ cyclostationary process: Mean and autocorrelation are periodic

Time-average autocorrelation function

$$\circ R_{se}(\tau) = \frac{1}{T} \sum_m R_I(m) R_g(\tau - mT)$$

- $R_I(m) = E[I_k(u) I_n^*(u)]$

- $R_g(\tau) = \int_{-\infty}^{\infty} g(t + \tau) g^*(t) dt$

Average Power Spectrum Density

$$\circ \overline{S_{se}}(f) = \frac{1}{T} S_I(f) |G(f)|^2$$

Ex.1

input information is real and mutually uncorrelated

$$R_I(m) = \begin{cases} V_I + M_I & ; m=0 \\ M_I & ; m \neq 0 \end{cases} \quad \leftarrow \text{直流成份}$$

$$\text{Hence, } S_I(f) = V_I^2 + M_I^2 \sum_{m=-\infty}^{\infty} e^{-j2\pi f m T} = V_I^2 + M_I^2 \frac{1}{T} \sum \delta(f - \frac{m}{T})$$

Poisson sum formula :

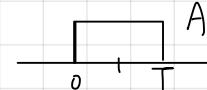
$$\sum e^{-j2\pi f m T} = \frac{1}{T} \sum \delta(f - \frac{m}{T})$$

and $S_{se}(f) = \frac{V_I^2}{T} |G(f)|^2 + \frac{M_I^2}{T^2} \sum |G(\frac{m}{T})|^2 \delta(f - \frac{m}{T})$

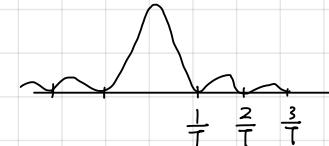
continuous discrete

- 1. discrete term vanish , when input information has zero mean : $M_I = 0$
- 2. With zero mean input information , the average power spectrum density $\overline{S_{se}}(f)$ is determined by $|G(f)|^2$
 $\Rightarrow \overline{S_{se}}(f) = \frac{V_I^2}{T} |G(f)|^2$

Ex1-1. Average Power Spectrum Density for rectangular pulse

• $g(t) = A [u(t) - u(t-T)]$ 

• $G(f) = AT \operatorname{sinc}(fT) e^{-j\pi fT} ; |G(f)|^2 = A^2 T^2 \operatorname{sinc}^2(fT)$



Hence • $S_I(f) = V_I^2 + M_I^2 \frac{1}{T} \sum \delta(f - \frac{m}{T})$

• $\overline{S_{se}}(f) = \frac{1}{T} S_I(f) |G(f)|^2$
 $= V_I^2 A^2 T \operatorname{sinc}^2(fT) + M_I^2 A^2 \delta(f) \propto f^{-2}$

Ex1-2. Average Power Spectrum Density for raised cosine pulse

• $g(t) = \frac{A}{2} \left[1 + \cos\left(\frac{2\pi}{T}(t - \frac{T}{2})\right) \right] (u(t) - u(t-T))$

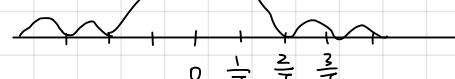
• $G(f) = \frac{AT}{2} \operatorname{sinc}(fT) \frac{1}{1-f^2 T^2} e^{-j\pi fT}$

$$|G(f)|^2 = \frac{A^2 T^2}{4} \operatorname{sinc}^2(fT) \frac{1}{1-2f^2 T^2 + f^4 T^4}$$



Hence • $S_I(f) = V_I^2 + M_I^2 \frac{1}{T} \sum \delta(f - \frac{m}{T})$

• $\overline{S_{se}}(f) = \frac{1}{T} S_I(f) |G(f)|^2 \propto f^{-6}$



When $\{I_n\}$ is correlated : $I_n = b_n + b_{n-1}$

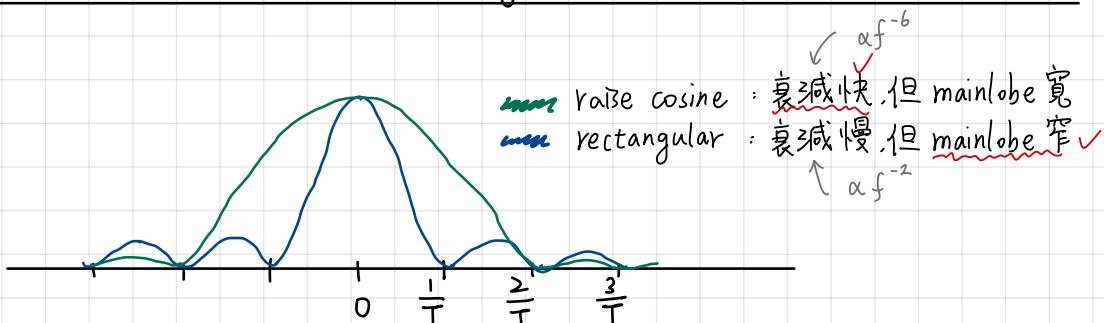
$$\bullet R_I(m) = \begin{cases} 2 & ; m=0 \\ 1 & ; m=\pm 1 \\ 0 & ; \text{other} \end{cases} \quad |G(f)|^2 = A^2 T^2 \sin^2(\pi f T)$$

$$\bullet S_I(f) = 2 + e^{j2\pi fT} + e^{-j2\pi fT} = 2(1 + \cos(2\pi fT)) = 4 \cos^2(\pi fT)$$

$$\bullet \overline{S}_{se}(f) = \frac{1}{T} S_I(f) \cdot |G(f)|^2 = \frac{4}{T} \cos^2(\pi fT) |G(f)|^2$$

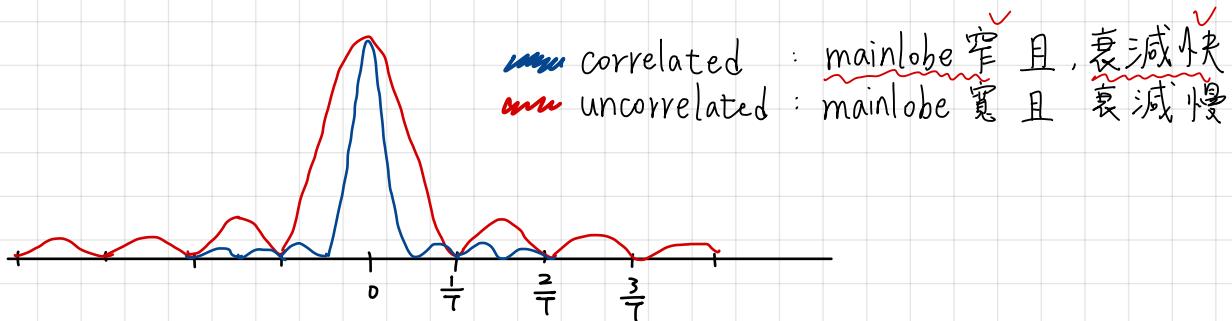
觀念彙總：

(i) 同為 uncorrelated, rectangular 和 raised cosine 的差異



→ The smoother pulse shaping \Rightarrow the greater bandwidth efficiency
 (raise cosine)

(ii) 同為 rectangular, correlated 和 uncorrelated 的差異



(iii) • Modulation index h :

The lower modulation index h
 → The higher bandwidth efficiency \leftarrow MSK 的 $h=0.5$

• Pulse shape $g(t)$:

The smoother $g(t)$
 → The greater bandwidth efficiency \leftarrow

raise cosine result in
 higher bandwidth efficiency than
 rectangular

