

CS3008: IMAGE AND VIDEO PROCESSING

LABORATORY REPORTS

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Chapter 1

Eye Detection Using OpenCV

1.1 Abstract

This report documents the implementation of an eye detection system using the OpenCV library. The system utilizes Haar cascade classifiers to identify faces and eyes in images and marks them with bounding boxes. The project aims to provide a foundational understanding of image processing techniques and their practical applications.

1.2 Introduction

Eye detection plays a vital role in computer vision applications such as gaze tracking, facial recognition, and user interaction systems. This project implements a detection system using pre-trained Haar cascade classifiers, which efficiently identify facial and ocular features in images.

1.3 Methodology

1.3.1 Data Collection

The input data consists of static images containing human faces. The images were uploaded manually in the Google Colab environment for processing.

1.3.2 Tools and Libraries

- **OpenCV:** For image processing and detection.
- **Google Colab:** For executing Python code and visualizing results.

1.3.3 Detection Algorithm

The steps followed in the implementation are:

1. Convert the input image to grayscale for easier processing.
2. Use the Haar cascade classifier to detect faces in the image.
3. For each detected face, apply the Haar cascade classifier for eyes within the facial region.
4. Highlight the detected features (faces and eyes) using bounding boxes.

1.4 Implementation

The implementation was carried out in Python using OpenCV. The following code snippet demonstrates the detection process:

Listing 1.1: Eye Detection Code

```
1 import cv2
2 face_cascade = cv2.CascadeClassifier(cv2.data.haarcascades +
3     ↪ 'haarcascade_frontalface_default.xml')
4 eye_cascade = cv2.CascadeClassifier(cv2.data.haarcascades +
5     ↪ 'haarcascade_eye.xml')
6 image = cv2.imread('input_image.jpg')
7 gray_image = cv2.cvtColor(image, cv2.COLOR_BGR2GRAY)
8 faces = face_cascade.detectMultiScale(gray_image,
9     ↪ scaleFactor=1.1, minNeighbors=5)
10
11 for (x, y, w, h) in faces:
12     cv2.rectangle(image, (x, y), (x+w, y+h), (255, 0, 0), 2)
13     roi_gray = gray_image[y:y+h, x:x+w]
14     roi_color = image[y:y+h, x:x+w]
15     eyes = eye_cascade.detectMultiScale(roi_gray)
16     for (ex, ey, ew, eh) in eyes:
17         cv2.rectangle(roi_color, (ex, ey), (ex+ew, ey+eh),
18             ↪ (0, 255, 0), 2)
19 cv2.imwrite('output_image.jpg', image)
20 cv2.imshow('Eye Detection', image)
21 cv2.waitKey(0)
22 cv2.destroyAllWindows()
```

1.5 Results and Discussion

The system was tested with several images under various conditions. The results are summarized below:

- Faces were detected accurately in well-lit images.

- Eye detection was successful but occasionally struggled with images where faces were partially obscured.

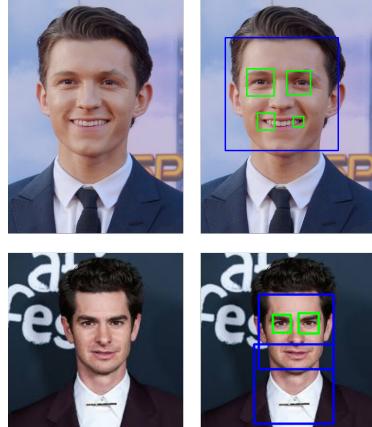


Figure 1.1: Detected faces and eyes in the input image.

1.6 Conclusion

The project successfully implemented an eye detection system using Haar cascades in OpenCV. While the system is efficient for basic detection, future improvements can involve the use of deep learning-based models for enhanced accuracy and robustness.

Chapter 2

Image Processing and Effects

2.1 Abstract

This report documents the implementation of various image processing techniques, including applying filters, resizing, cropping, rotating, and face mask overlays. These tasks showcase the practical applications of computer vision and image manipulation using Python and OpenCV.

2.2 Introduction

Image processing is a cornerstone of computer vision, enabling tasks like object detection, image enhancement, and feature extraction. This project demonstrates the use of OpenCV to apply filters and transformations to images, and overlay masks on detected faces.

2.3 Methodology

2.3.1 Data Collection

The input data consists of static images uploaded manually in the Google Colab environment.

2.3.2 Tools and Libraries

- **OpenCV:** For image processing and transformations.
- **Google Colab:** For executing Python code and visualizing results.
- **NumPy:** For handling numerical operations.

2.3.3 Image Processing Techniques

The project implements the following techniques:

- Grayscale, sepia, negative, and blur effects.
- Edge detection and cartoonification.
- Image resizing, cropping, and rotation.

2.4 Implementation

The implementation was carried out in Python using OpenCV. The following code snippet demonstrates the overall process:

Listing 2.1: Image Processing Code

```
1 import cv2
2 import numpy as np
3 from google.colab.patches import cv2_imshow
4
5 image_path = "content/sample.png"
6 img = cv2.imread(image_path)
7
8 def apply_grayscale(image):
9     return cv2.cvtColor(image, cv2.COLOR_BGR2GRAY)
10
11 def apply_sepia(image):
12     kernel = np.array([[0.393, 0.769, 0.189],
13                     [0.349, 0.686, 0.168],
14                     [0.272, 0.534, 0.131]])
15     return cv2.transform(image, kernel)
16
17 def apply_negative(image):
18     return cv2.bitwise_not(image)
19
20 def apply_blur(image, ksize=(5, 5)):
21     return cv2.GaussianBlur(image, ksize, 0)
22
23 def apply_edge_detection(image):
24     return cv2.Canny(image, 100, 200)
25
26 def apply_cartoonify(image):
27     gray = cv2.cvtColor(image, cv2.COLOR_BGR2GRAY)
28     gray = cv2.medianBlur(gray, 5)
29     edges = cv2.adaptiveThreshold(gray, 255, cv2.
30         ↪ ADAPTIVE_THRESH_MEAN_C, cv2.THRESH_BINARY, 9, 9)
31     color = cv2.bilateralFilter(image, 9, 300, 300)
32     return cv2.bitwise_and(color, color, mask=edges)
```

```

33 def resize_image(image, width=500):
34     aspect_ratio = width / float(image.shape[1])
35     height = int(image.shape[0] * aspect_ratio)
36     return cv2.resize(image, (width, height))
37
38 def crop_image(image):
39     height, width = image.shape[:2]
40     size = min(height, width)
41     center_x, center_y = width // 2, height // 2
42     cropped = image[center_y - size // 2:center_y + size // 
43     ↯ 2, center_x - size // 2:center_x + size // 2]
44     return cropped
45
46 def rotate_image(image, angle=45):
47     height, width = image.shape[:2]
48     center = (width // 2, height // 2)
49     matrix = cv2.getRotationMatrix2D(center, angle, 1)
50     rotated = cv2.warpAffine(image, matrix, (width, height))
51     return rotated
52
53 grayscale_img = apply_grayscale(img)
54 sepia_img = apply_sepia(img)
55 negative_img = apply_negative(img)
56 blur_img = apply_blur(img)
57 edges_img = apply_edge_detection(img)
58 cartoon_img = apply_cartoonify(img)
59 resized_img = resize_image(img)
60 cropped_img = crop_image(img)
61 rotated_img = rotate_image(img)
62
63 cv2.imshow(grayscale_img)
64 cv2.imshow(sepia_img)
65 cv2.imshow(negative_img)
66 cv2.imshow(blur_img)
67 cv2.imshow(edges_img)
68 cv2.imshow(cartoon_img)
69 cv2.imshow(resized_img)
70 cv2.imshow(cropped_img)
71 cv2.imshow(rotated_img)

```

2.5 Results and Discussion

The following observations were made during testing:

- Filters like grayscale, sepia, and negative worked as expected.
- Cartoonification produced visually appealing results by emphasizing edges.

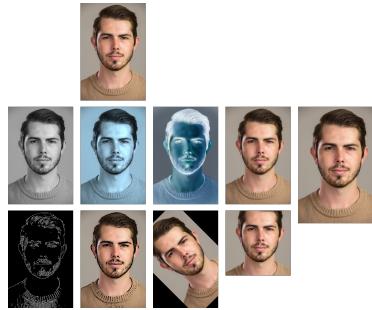


Figure 2.1: Examples of applied filters and transformations.

2.6 Conclusion

This project successfully demonstrated various image processing techniques using OpenCV. Future work could explore integrating deep learning models for more advanced image transformations and processing.

Chapter 3

Image Resolution and Interpolation Studies

3.1 Abstract

This report explores the fundamental concepts of image resolution and interpolation in image processing. The experiments involve converting RGB images to grayscale using a formula, analyzing intensity and spatial resolution changes, and studying image interpolation techniques. The study aims to provide insights into how image transformations affect visual quality and data representation.

3.2 Introduction

Image resolution and interpolation are critical aspects of image processing. Resolution defines the level of detail in an image, while interpolation determines how images are scaled to different dimensions. This project investigates these aspects through practical implementations and analyses their impact on image quality.

3.3 Methodology

3.3.1 Tools and Libraries

- **OpenCV:** For image processing operations.
- **NumPy:** For numerical computations.
- **Google Colab:** For implementation and visualization.

3.3.2 Experiments Conducted

1. **Convert RGB to Grayscale:** An RGB image is converted to grayscale using the formula:

$$Y = 0.299 \cdot R + 0.587 \cdot G + 0.114 \cdot B$$

2. **Intensity Resolution:** An 8-bit grayscale image is converted into 7, 6, 5, 4, 3, and 2-bit images by reducing the bit depth and analyzing the resulting quality loss.
3. **Spatial Resolution:** A 512x512 image is resized to 256x256, 128x128, 64x64, and 32x32 dimensions to observe the effect of reduced spatial resolution.
4. **Image Interpolation:** A 128x128 image is resized to 256x256 and 512x512 dimensions using bilinear and bicubic interpolation techniques.

3.4 Implementation

The implementation was carried out using Python and OpenCV. The following snippets showcase the key operations:

Listing 3.1: Convert RGB to Grayscale

```
1 import cv2
2 import numpy as np
3 import matplotlib.pyplot as plt
4
5 image = cv2.imread('/content/image.jpg')
6
7 image_rgb = cv2.cvtColor(image, cv2.COLOR_BGR2RGB)
8
9 R = image_rgb[:, :, 0]
10 G = image_rgb[:, :, 1]
11 B = image_rgb[:, :, 2]
12
13 gray_image = 0.299 * R + 0.587 * G + 0.114 * B
14 gray_image = gray_image.astype(np.uint8)
15
16 plt.imshow(gray_image, cmap='gray')
17 plt.title("Grayscale Image (Formula)")
18 plt.axis('off')
19 plt.show()
```

Listing 3.2: Bit Depth Reduction

```
1 import numpy as np
2 import cv2
```

```

3 import matplotlib.pyplot as plt
4
5 image = cv2.imread('/content/image.jpg', cv2.
6   ↪ IMREAD_GRAYSCALE)
7
8 def reduce_intensity_resolution(image, bits):
9   max_intensity = 2**bits - 1
10  return np.uint8((image / 256) * max_intensity)
11
12 bit_depths = [7, 6, 5, 4, 3, 2]
13 for bits in bit_depths:
14   reduced_image = reduce_intensity_resolution(image, bits)
15   plt.imshow(reduced_image, cmap='gray')
16   plt.title(f"{bits}-bit Image")
17   plt.axis('off')
18   plt.show()

```

Listing 3.3: Spatial Resolution Adjustment

```

1 import cv2
2 import matplotlib.pyplot as plt
3
4 image = cv2.imread('/content/penguin.jpg', cv2.
5   ↪ IMREAD_GRAYSCALE)
6
7 def resize_image(image, size):
8   return cv2.resize(image, (size, size), interpolation=cv2
9     ↪ .INTER_LINEAR)
10
11 sizes = [256, 128, 64, 32]
12 for size in sizes:
13   resized_image = resize_image(image, size)
14   plt.imshow(resized_image, cmap='gray')
15   plt.title(f"{size}x{size} Image")
16   plt.axis('off')
17   plt.show()
18   cv2.imwrite(f'{size}x{size}_image.jpg', resized_image)

```

Listing 3.4: Image Interpolation

```

1 import cv2
2 import matplotlib.pyplot as plt
3
4 image = cv2.imread('/content/sunset.jpg', cv2.
5   ↪ IMREAD_GRAYSCALE)
6
7 def upscale_image(image, new_size, interpolation_method):
8   return cv2.resize(image, (new_size, new_size),
9     ↪ interpolation=interpolation_method)
10
11 interpolation_methods = {
12   'nearest': cv2.INTER_NEAREST,
13   'bilinear': cv2.INTER_LINEAR,
14   'bicubic': cv2.INTER_CUBIC,
15   'area': cv2.INTER_AREA,
16   'lanczos': cv2.INTER_LANCZOS4
17 }

```

```

9      'Nearest Neighbor': cv2.INTER_NEAREST,
10     'Bilinear': cv2.INTER_LINEAR,
11     'Bicubic': cv2.INTER_CUBIC
12 }
13
14 sizes = [256, 512]
15 for size in sizes:
16     for method_name, method in interpolation_methods.items()
17         ↪ :
18         upscaled_image = upscale_image(image, size, method)
19         plt.imshow(upscaled_image, cmap='gray')
20         plt.title(f'{size}x{size} Image with {method_name}
21             ↪ Interpolation')
22         plt.axis('off')
23         plt.show()
24         cv2.imwrite(f'{size}x{size}_{method_name}
25             ↪ _interpolation.jpg', upscaled_image)

```

3.5 Results and Discussion

3.5.1 RGB to Grayscale

The grayscale conversion effectively reduced the color data of the image while preserving its luminance, demonstrating the precision of the formula.

3.5.2 Intensity Resolution

The reduction in bit depth showed a gradual loss in image quality. Higher bit depths retained more details, while lower depths introduced noticeable quantization artifacts.

3.5.3 Spatial Resolution

Decreasing the spatial resolution led to a loss of detail and sharpness. However, the images remained recognizable at lower resolutions, demonstrating the trade-off between quality and storage requirements.

3.5.4 Image Interpolation

Bilinear and bicubic interpolation effectively upscaled the images. Bicubic interpolation provided smoother results but required higher computational resources compared to bilinear interpolation.



Figure 3.1: Conversion RGB to Grayscale



Figure 3.2: Intensity Resolution.



Figure 3.3: Spatial Resolution.

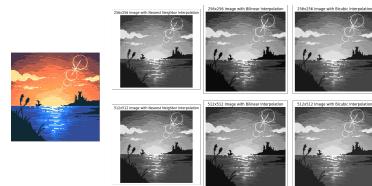


Figure 3.4: Image Interpolation.

3.6 Conclusion

The experiments provided insights into how resolution and interpolation affect image quality. Future work can involve exploring advanced interpolation techniques, such as deep learning-based methods, for higher accuracy and efficiency.

Chapter 4

Filtering and Blurring Techniques

4.1 Abstract

This report details the experiments conducted in Week 4 of the laboratory exercises, focusing on filtering and blurring techniques. Various filters, including box and Gaussian filters, were applied, and concepts like correlation, convolution, and separable filters were studied.

4.2 Introduction

Image filtering and blurring techniques are fundamental operations in image processing. These techniques enhance image quality, simulate natural effects, or prepare images for further analysis. The aim of this experiment was to explore these techniques using different filters and kernel configurations.

4.3 Methodology

4.3.1 Box Filter

A box filter was applied with different kernel sizes (e.g., 3x3, 5x5, 7x7, 9x9, 11x11, 13x13, 15x15). The filtering process involved averaging the pixel values within the kernel to produce a smoothed image.

4.3.2 Defocus Blur Simulation

Defocus blur was simulated by applying a circular averaging filter to mimic the effect of an out-of-focus lens.

4.3.3 Motion Blur

A motion blur kernel was designed to simulate the effect of camera motion. The kernel was applied to the image using convolution.

4.3.4 Correlation vs Convolution

The experiment compared the results of correlation and convolution operations on the same image, highlighting the differences in their mathematical operations and outcomes.

4.3.5 Separable Filters

Separable filters were studied and implemented. A 2D filter was decomposed into two 1D filters for computational efficiency.

4.3.6 Gaussian Distribution

Gaussian filters with varying sigma values (e.g., 0.5, 1, 2) were applied. The Gaussian kernel had a mean of 0 and was constructed using the formula:

$$G(x, y) = \frac{1}{2\pi\sigma^2} e^{-\frac{x^2+y^2}{2\sigma^2}} \quad (4.1)$$

4.4 Implementation

The implementation details for each task are summarized below:

4.4.1 Box Filter

Listing 4.1: Box Filter Implementation

```
1 import cv2
2 import numpy as np
3 import matplotlib.pyplot as plt
4 image = cv2.imread('sample.jpeg', cv2.IMREAD_GRAYSCALE)
5 kernel_sizes = [3, 5, 7, 9, 11, 13, 15]
6 filtered_images = []
7
8 for size in kernel_sizes:
9     kernel = np.ones((size, size), np.float32) / (size *
10                      ↪ size)
11     filtered = cv2.filter2D(image, -1, kernel)
12     filtered_images.append(filtered)
13
14 plt.figure(figsize=(12, 6))
15 for i, filtered in enumerate(filtered_images):
16     plt.subplot(1, len(filtered_images), i + 1)
```

```

16     plt.title(f"Kernel: {kernel_sizes[i]}x{kernel_sizes[i]}"
17             ↪ )
18     plt.imshow(filtered, cmap='gray')
19     plt.axis('off')
20     plt.show()

```

4.4.2 Defocus Blur

Listing 4.2: Defocus Blur Simulation

```

1 image = cv2.imread('sample.jpeg', cv2.IMREAD_GRAYSCALE)
2 def circular_kernel(radius):
3     y, x = np.ogrid[-radius:radius+1, -radius:radius+1]
4     mask = x**2 + y**2 <= radius**2
5     kernel = np.zeros_like(mask, dtype=np.float32)
6     kernel[mask] = 1
7     kernel /= kernel.sum()
8     return kernel
9 radius = [20, 25, 30, 35, 40, 45]
10 for rad in radius:
11     kernel = circular_kernel(rad)
12     blurred_image = cv2.filter2D(image, -1, kernel)
13     plt.figure(figsize=(6, 6))
14     plt.title(f"Defocus Blur with Radius {rad}")
15     plt.imshow(blurred_image, cmap='gray')
16     plt.axis('off')
17     plt.show()

```

4.4.3 Motion Blur

Listing 4.3: Motion Blur Implementation

```

1 image = cv2.imread('sample.jpeg', cv2.IMREAD_GRAYSCALE)
2 def motion_blur_kernel(size, angle):
3     kernel = np.zeros((size, size), dtype=np.float32)
4     mid = size // 2
5     if angle == 0:
6         kernel[mid, :] = 1
7     elif angle == 90:
8         kernel[:, mid] = 1
9     elif angle == 45:
10        np.fill_diagonal(kernel, 1)
11    else:
12        raise ValueError("Only angles 0, 90, and 45 are
13                         ↪ supported")
13    kernel /= kernel.sum()
14    return kernel

```

```

15 kernel_size = [35, 45, 55, 65]
16 angle = 0
17 for ker in kernel_size:
18     kernel = motion_blur_kernel(ker, angle)
19     motion_blurred_image = cv2.filter2D(image, -1, kernel)
20     plt.figure(figsize=(6, 6))
21     plt.title(f"Motion Blur with Kernel Size {ker}, Angle {
22         ↪ angle}\textdegree")
23     plt.imshow(motion_blurred_image, cmap='gray')
24     plt.axis('off')
25     plt.show()

```

4.4.4 Correlation vs Convolution

Listing 4.4: Correlation and Convolution Study

```

1 from scipy import ndimage
2 image = cv2.imread('sample.jpeg', 0)
3 kernel = np.array([[1,1,1],[1,1,0],[1,0,0]])
4 convolved_image = ndimage.convolve(image, kernel, mode='
    ↪ constant', cval=1.0)
5 correlated_image = cv2.filter2D(image, -1, kernel)
6 plt.figure(figsize=(12, 6))
7 plt.subplot(1, 2, 1)
8 plt.title("Convolution")
9 plt.imshow(convolved_image, cmap='gray')
10 plt.axis('off')
11 plt.subplot(1, 2, 2)
12 plt.title("Correlation")
13 plt.imshow(correlated_image, cmap='gray')
14 plt.axis('off')
15 plt.show()

```

4.4.5 Separable Filters

Listing 4.5: Separable Filter Implementation

```

1 import cv2
2 import numpy as np
3 image = cv2.imread('input_image.jpg', 0)
4 kernel = np.outer([1, 2, 1], [1, 2, 1])
5 kernel = kernel / kernel.sum()
6 separable_result = cv2.sepFilter2D(image, -1, kernel, kernel
    ↪ )
7 cv2.imwrite('separable_filter_output.jpg', separable_result)

```

4.4.6 Gaussian Distribution

Listing 4.6: Gaussian Distribution

```
1 import numpy as np
2 import matplotlib.pyplot as plt
3 mu = 0 # Mean
4 sigma_values = [0.5, 1.0, 1.5, 2.0, 2.5,]
5 x = np.linspace(-5, 5, 1000)
6 plt.figure(figsize=(10, 6))
7 for sigma in sigma_values:
8     y = 1/(sigma * np.sqrt(2 * np.pi)) * np.exp(-(x - mu)**2
9         / (2 * sigma**2))
10    plt.plot(x, y, label=f'Sigma = {sigma}')
11 plt.title('Gaussian Distribution with Mean 0 and Different
12           Sigma Values')
13 plt.xlabel('X')
14 plt.ylabel('Probability density')
15 plt.legend()
16 plt.grid(True)
17 plt.show()
```

4.5 Results and Discussion

The results of the filtering and blurring techniques were as follows:

- Box filtering effectively smoothed the image, with larger kernel sizes producing stronger effects.



Figure 4.1: Box Filtering

- Defocus blur created a natural out-of-focus effect, suitable for simulating depth of field.
- Motion blur simulated linear motion, demonstrating how camera movement affects image clarity.
- Correlation and convolution produced distinct results, highlighting the impact of kernel flipping in convolution.
- Separable filters significantly reduced computational overhead while producing similar results to non-separable filters.
- Gaussian Distribution with different sigma values



Figure 4.2: Defocus Blurring



Figure 4.3: Motion Blurring



Figure 4.4: Correlation vs Convolution



Figure 4.5: Correlation vs Convolution

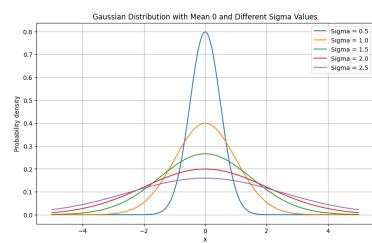


Figure 4.6: Gaussian Distribution

4.6 Conclusion

This experiment explored various image filtering and blurring techniques, providing insights into their applications and computational trade-offs. Future

work could involve applying these techniques to real-world images and comparing their effectiveness.

Chapter 5

Experiment 5 - Gaussian Kernels

5.1 Abstract

This report documents the implementation of Gaussian filtering techniques on images. The experiment involves applying Gaussian blur, generating points from a standard normal distribution, and adding Gaussian noise to images. The goal is to understand the impact of Gaussian kernels in image processing.

5.2 Introduction

Gaussian filters are widely used in image processing to reduce noise and smooth images. This experiment applies Gaussian blurring and noise to images and visualizes the standard normal distribution.

5.3 Methodology

5.3.1 Tools and Libraries

- **OpenCV:** For image processing operations.
- **NumPy:** For generating Gaussian noise.
- **Matplotlib:** For visualization.

5.3.2 Implementation Steps

1. Read the input image in grayscale.
2. Apply Gaussian blur using a 5×5 kernel.

3. Generate data from a standard normal distribution and visualize the histogram.
4. Add Gaussian noise to the image and display the results.

5.4 Implementation

The implementation was carried out using Python with OpenCV and NumPy. The following code snippets demonstrate the processing steps:

5.4.1 Applying Gaussian Blur

Listing 5.1: Gaussian Blur

```

1 import cv2
2 import numpy as np
3 import matplotlib.pyplot as plt
4
5 image = cv2.imread('/content/fox_sample.jpeg', cv2.
6     ↪ IMREAD_GRAYSCALE)
7 blurred_image = cv2.GaussianBlur(image, (5, 5), 0)
8 cv2.imwrite('blurred_image.jpg', blurred_image)
9 plt.imshow(blurred_image, cmap='gray')
10 plt.title('Gaussian Blurred Image')
11 plt.show()

```

5.4.2 Generating Points from Standard Normal Distribution

Listing 5.2: Histogram of Standard Normal Distribution

```

1 data = np.random.randn(10000)
2
3 plt.hist(data, bins=50, density=True, alpha=0.6, color='g')
4 plt.title("Histogram of Standard Normal Distribution")
5 plt.xlabel("Value")
6 plt.ylabel("Frequency")
7 plt.show()

```

5.4.3 Adding Gaussian Noise to an Image

Listing 5.3: Adding Gaussian Noise

```

1 mean = 0
2 sigma = 25
3 gaussian_noise = np.random.normal(mean, sigma, image.shape)

```

```

4 noisy_image = np.clip(image + gaussian_noise, 0, 255).astype
   ↪ (np.uint8)
5
6 cv2.imwrite('noisy_image.jpg', noisy_image)
7 plt.imshow(noisy_image, cmap='gray')
8 plt.title('Image with Gaussian Noise')
9 plt.show()

```

5.5 Results and Discussion

The results from the experiment are summarized as follows:

- The Gaussian blur effectively smoothens the image while preserving edges.

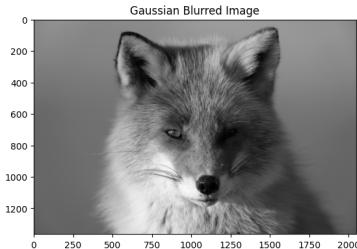


Figure 5.1: Gaussian Blurred Image.

- The histogram of the standard normal distribution follows the expected bell-shaped curve.

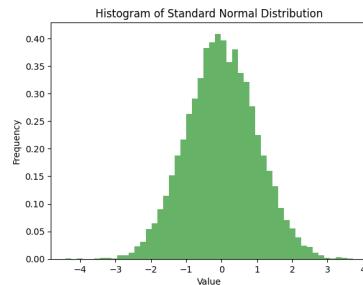


Figure 5.2: Image with Gaussian Noise.

- Adding Gaussian noise alters the image by introducing controlled randomness.

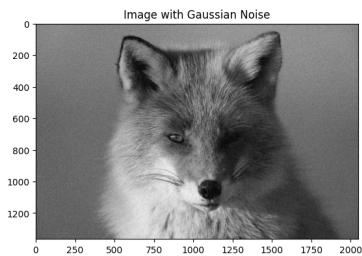


Figure 5.3: Image with Gaussian Noise.

5.6 Conclusion

This experiment successfully demonstrated the application of Gaussian kernels in image processing. Gaussian filtering effectively smoothens images, while Gaussian noise simulates real-world distortions. Future enhancements could include adaptive filtering techniques to preserve important image features while removing noise.

Chapter 6

Experiment 6 - Histogram Equalization

6.1 Introduction

Histogram equalization is a technique used to enhance the contrast of an image by redistributing pixel intensity values. This experiment involves obtaining the histogram of an image, performing histogram equalization, comparing the original and equalized images, and modifying histograms through contrast stretching and histogram specification.

6.2 Methodology

6.2.1 Histogram Computation

To analyze the intensity distribution, the histogram of the grayscale image is computed using pixel intensity values.

6.2.2 Histogram Equalization

Histogram equalization is performed to spread intensity values across the full range, enhancing contrast.

6.2.3 Comparison of Original and Equalized Images

The original and equalized images are visually compared along with their histograms.

6.2.4 Histogram Modification

Contrast stretching and histogram specification are applied to modify the image's histogram for better contrast adjustment.

6.3 Implementation

The experiment was implemented using Python and OpenCV. The following steps were performed:

- Load a grayscale image.
- Compute and plot the histogram of the original image.
- Apply histogram equalization and plot the equalized histogram.
- Compare the original and equalized images with their histograms.
- Perform contrast stretching to enhance contrast.
- Implement histogram specification using a reference histogram.

6.4 Code Implementation

```
1 import cv2
2 import numpy as np
3 import matplotlib.pyplot as plt
4
5 def plot_histogram(image, title, subplot_pos):
6     plt.subplot(1, 2, subplot_pos)
7     plt.hist(image.ravel(), bins=256, range=[0, 256], color=
8             'black')
8     plt.title(title)
9     plt.xlabel("Pixel Value")
10    plt.ylabel("Frequency")
11
12 image = cv2.imread('sample.jpeg', cv2.IMREAD_GRAYSCALE)
13 plt.figure(figsize=(12, 5))
14 plot_histogram(image, "Histogram", 1)
15 plt.show()
16
17 # Histogram Equalization
18 image = cv2.imread('sample.jpeg', cv2.IMREAD_GRAYSCALE)
19 equalized_image = cv2.equalizeHist(image)
20 plt.figure(figsize=(12, 5))
21 plot_histogram(equalized_image, "Equalized Histogram", 2)
22 plt.show()
23
```

```

24 # Contrast Stretching
25 def contrast_stretching(image):
26     min_val = np.min(image)
27     max_val = np.max(image)
28     stretched = ((image - min_val) / (max_val - min_val) *
29                  ↪ 255).astype(np.uint8)
30     return stretched
31
32 stretched_image = contrast_stretching(image)
33
34 plt.figure(figsize=(15, 5))
35 plt.subplot(1, 4, 1)
36 plt.imshow(image, cmap='gray')
37 plt.title("Original Image")
38 plt.axis("off")
39
40 plt.subplot(1, 4, 2)
41 plt.imshow(stretched_image, cmap='gray')
42 plt.title("Contrast Stretched")
43 plt.axis("off")
44 plt.show()

```

6.5 Results

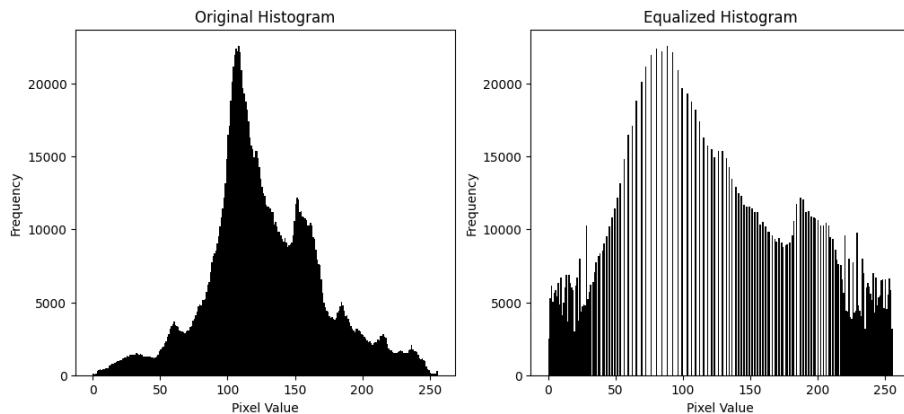


Figure 6.1: Comparison between original and equalized histogram

6.6 Conclusion

Histogram equalization enhances image contrast by redistributing pixel intensities. Contrast stretching and histogram specification provide additional means



Figure 6.2: Comparison of Image Transformations

for modifying image contrast based on specific requirements. The results demonstrate significant improvement in image visibility and details.

Chapter 7

Experiment 7 - Frequency Domain Filters

7.1 Introduction

Frequency domain filtering is a fundamental technique in image processing where an image is transformed into the frequency domain using the Fourier Transform. The frequency components are modified using different filters before transforming back to the spatial domain. This experiment explores box filters, Gaussian filters, and low-pass filters in the frequency domain.

7.2 Methodology

7.2.1 Fourier Transform

The Fourier Transform converts an image into its frequency components, allowing filtering operations to be applied selectively.

7.2.2 Filter Types

- **Box Filter:** A simple frequency domain filter that retains all frequencies within a specified cutoff.
- **Gaussian Filter:** Uses a Gaussian function to smoothly attenuate frequencies beyond the cutoff.
- **Low-Pass Filter:** Retains only low-frequency components, removing high-frequency details.

7.3 Implementation

The experiment was implemented using Python with OpenCV and NumPy. The following steps were performed:

- Load a grayscale image.
- Apply Fourier Transform to obtain frequency domain representation.
- Create and apply filters (Box, Gaussian, and Low-Pass).
- Perform inverse Fourier Transform to obtain filtered images.
- Display results and compare effects of different filters.

7.4 Code Implementation

```
1 import cv2
2 import numpy as np
3 import matplotlib.pyplot as plt
4
5 def apply_filter(image, filter_type, cutoff):
6     if len(image.shape) == 3:
7         image = cv2.cvtColor(image, cv2.COLOR_BGR2GRAY)
8
9     rows, cols = image.shape
10    crow, ccol = rows // 2, cols // 2
11
12    dft = np.fft.fft2(image)
13    dft_shift = np.fft.fftshift(dft)
14    magnitude_spectrum = np.log(1 + np.abs(dft_shift))
15
16    mask = np.zeros((rows, cols), np.float32)
17
18    for u in range(rows):
19        for v in range(cols):
20            D = np.sqrt((u - crow) ** 2 + (v - ccol) ** 2)
21            if filter_type == 'box':
22                mask[u, v] = 1 if D <= cutoff else 0
23            elif filter_type == 'gaussian':
24                mask[u, v] = np.exp(-(D**2) / (2 * (cutoff
25                                ** 2)))
26            elif filter_type == 'lowpass':
27                mask[u, v] = 1 if D <= cutoff else 0
28
29    filtered_dft = dft_shift * mask
30    dft_ishift = np.fft.ifftshift(filtered_dft)
31    img_back = np.fft.ifft2(dft_ishift)
32    img_back = np.abs(img_back)
```

```

32     return magnitude_spectrum, mask, np.log(1 + np.abs(
33         ↪ filtered_dft)), img_back
34
35 image = cv2.imread('sample.jpg', cv2.IMREAD_GRAYSCALE)
36 filters = ['box', 'gaussian', 'lowpass']
37 cutoff = 50
38
39 fig, axs = plt.subplots(len(filters), 4, figsize=(16, 12))
40
41 for i, filter_type in enumerate(filters):
42     F_uv, H_uv, G_uv, result = apply_filter(image,
43         ↪ filter_type, cutoff)
44
45     axs[i, 0].imshow(F_uv, cmap='gray')
46     axs[i, 0].set_title(f'F(u,v) - {filter_type}')
47     axs[i, 0].axis('off')
48
49     axs[i, 1].imshow(H_uv, cmap='gray')
50     axs[i, 1].set_title(f'H(u,v) - {filter_type}')
51     axs[i, 1].axis('off')
52
53     axs[i, 2].imshow(G_uv, cmap='gray')
54     axs[i, 2].set_title(f'G(u,v) - {filter_type}')
55     axs[i, 2].axis('off')
56
57     axs[i, 3].imshow(result, cmap='gray')
58     axs[i, 3].set_title(f'Inverse Transform - {filter_type}',
59         ↪ )
60     axs[i, 3].axis('off')
61
62 plt.tight_layout()
63 plt.show()

```

7.5 Results

7.6 Conclusion

Frequency domain filtering allows selective modification of image frequency components. The experiment demonstrated how box, Gaussian, and low-pass filters affect image frequency content. Gaussian filtering provided smoother transitions, whereas box filtering retained sharp cutoffs. These techniques are essential for applications in image enhancement and noise reduction.

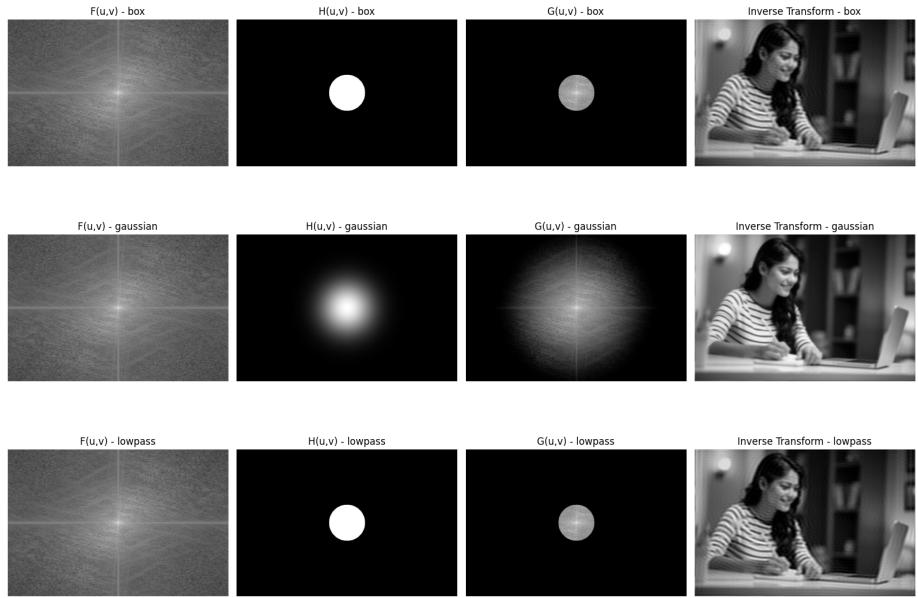


Figure 7.1: Comparison of Image Transformations